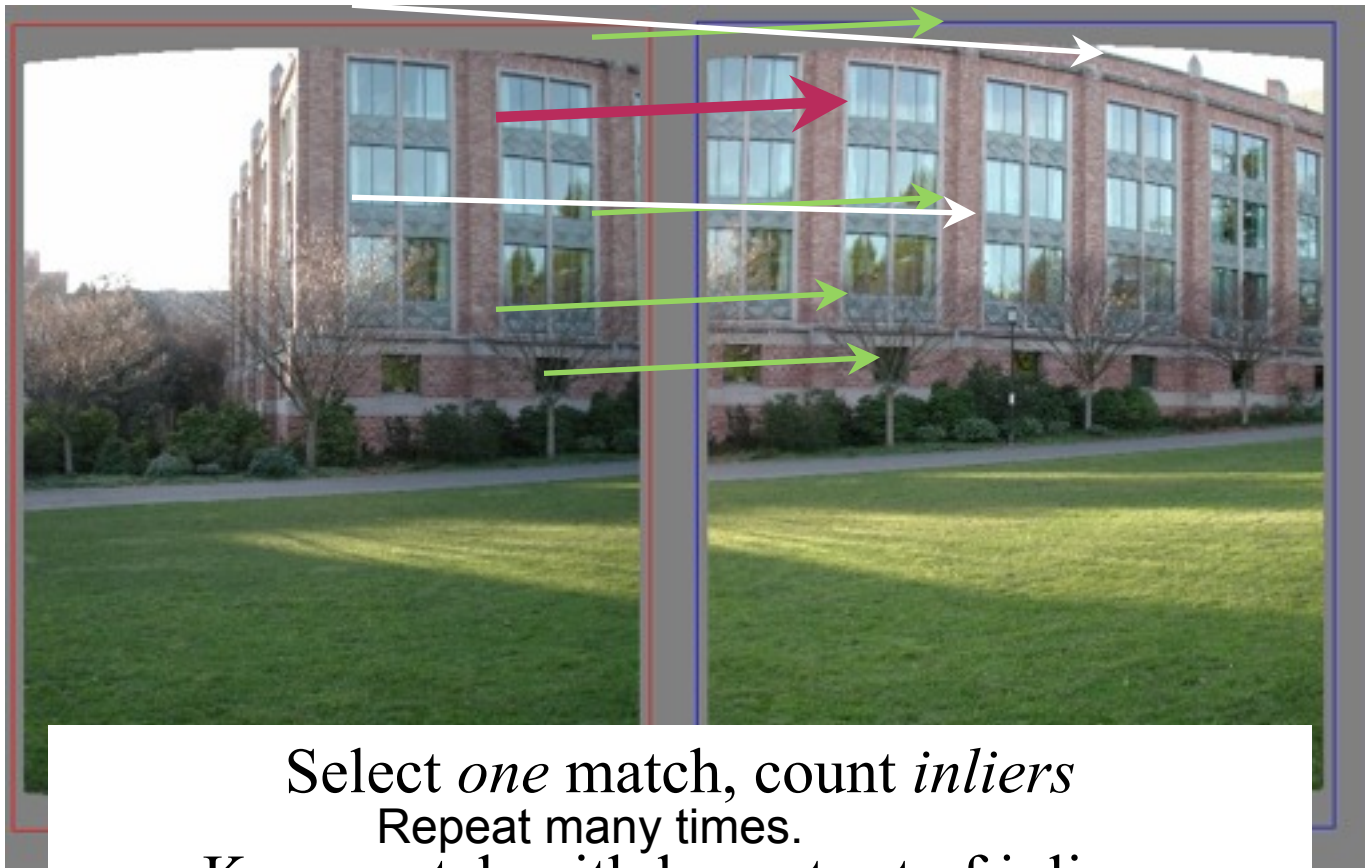


M. A. Fischler, R. C. Bolles. Random Sample Consensus:
A Paradigm for Model Fitting with Applications to Image Analysis
and Automated Cartography. Comm. of the ACM, Vol 24, pp 381-395, 1981.

RANdom SAmples Consensus

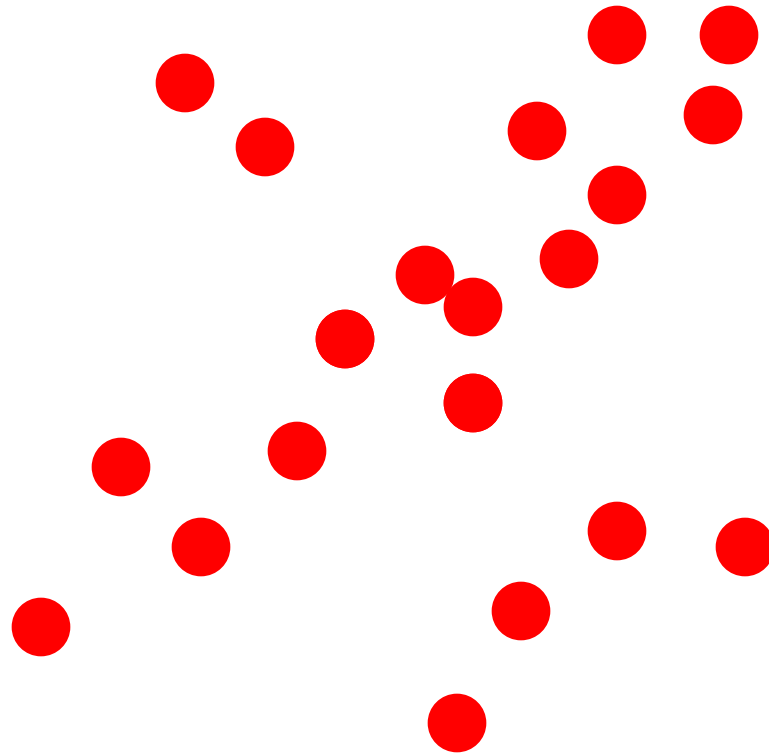


Basic Philosophy

(voting scheme)

- Elemental subset (minimum number of points) randomly picked up for each hypothesis.
- The standard deviation of the inlier noise has to be given before by the user!
- **Assumption 1:** Outlier features will not vote consistently for any single model.
- **Assumption 2:** There are enough features to agree on a good model.

RANSAC

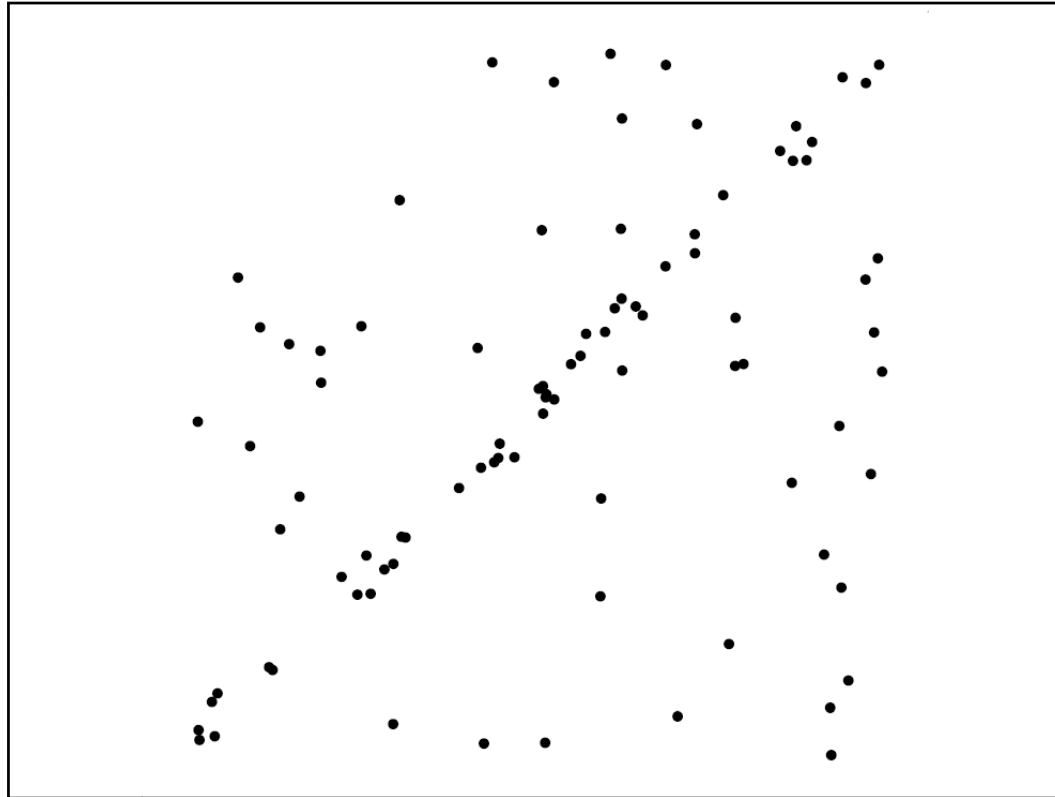


Sample set = set of points in 2D

Algorithm:

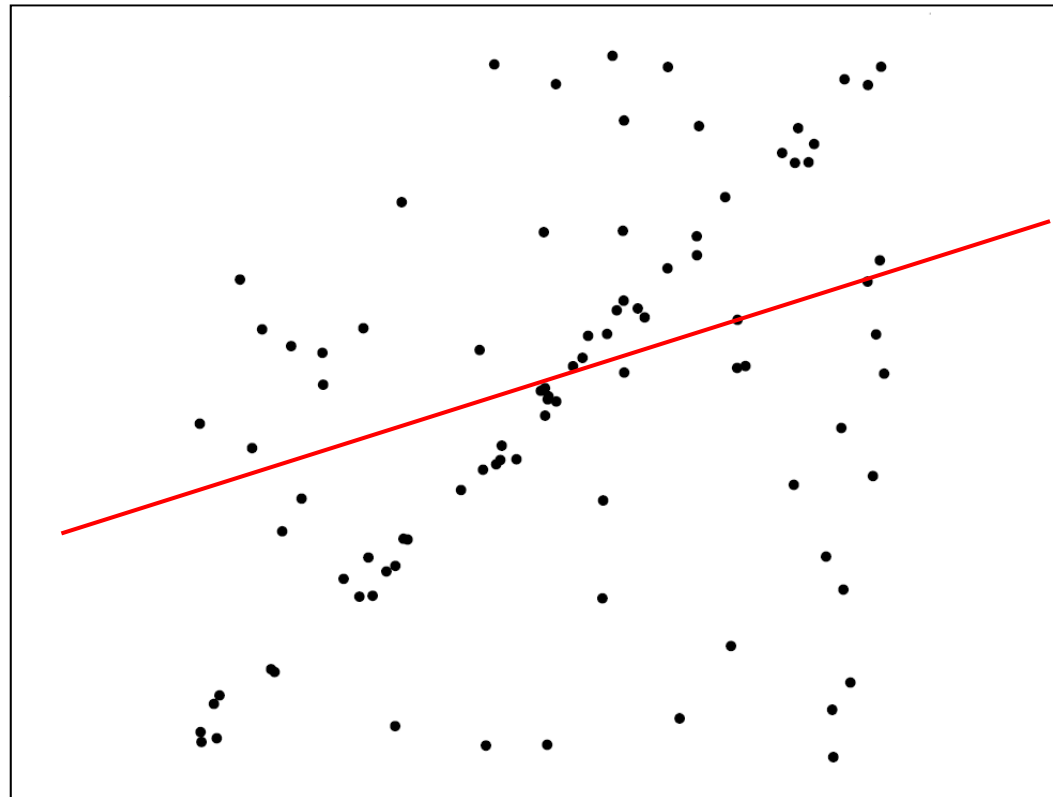
1. Select random sample of minimum required size to fit model
 2. Compute a putative model from sample set
 3. Compute the set of inliers to this model from whole data set
- Repeat 1-3 until model with the most inliers over all samples is found

RANSAC for line fitting example



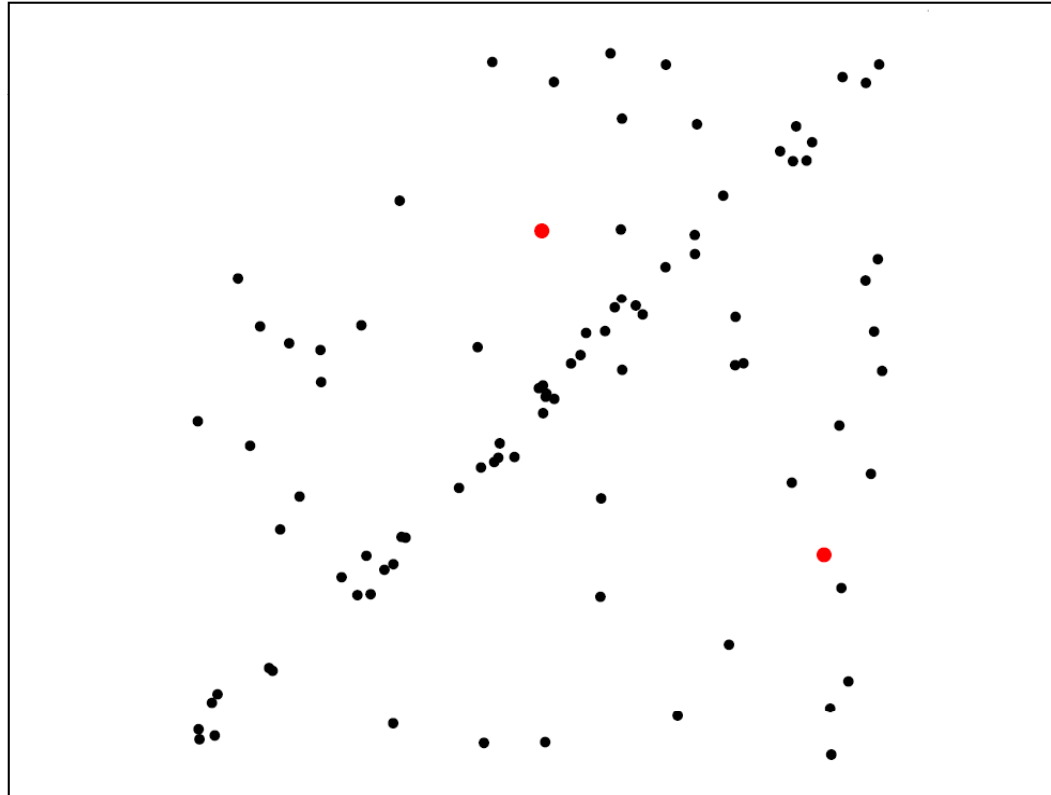
Source: R. Raguram

RANSAC for line fitting example



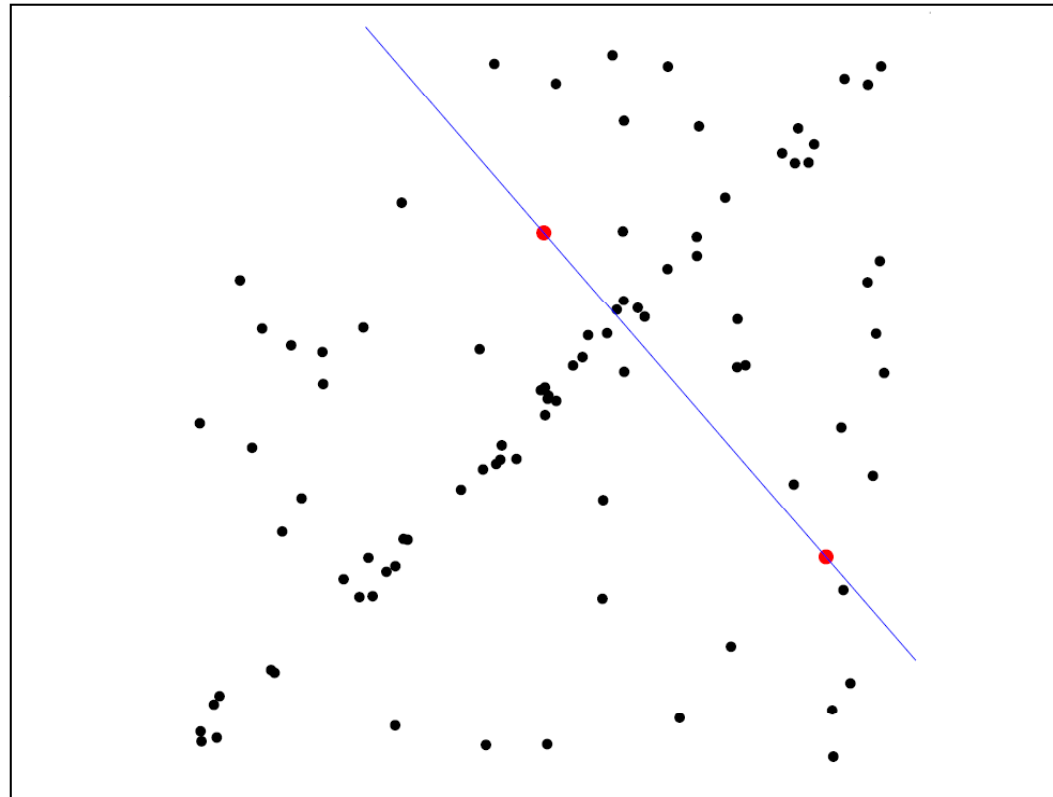
Least-squares fit

RANSAC for line fitting example



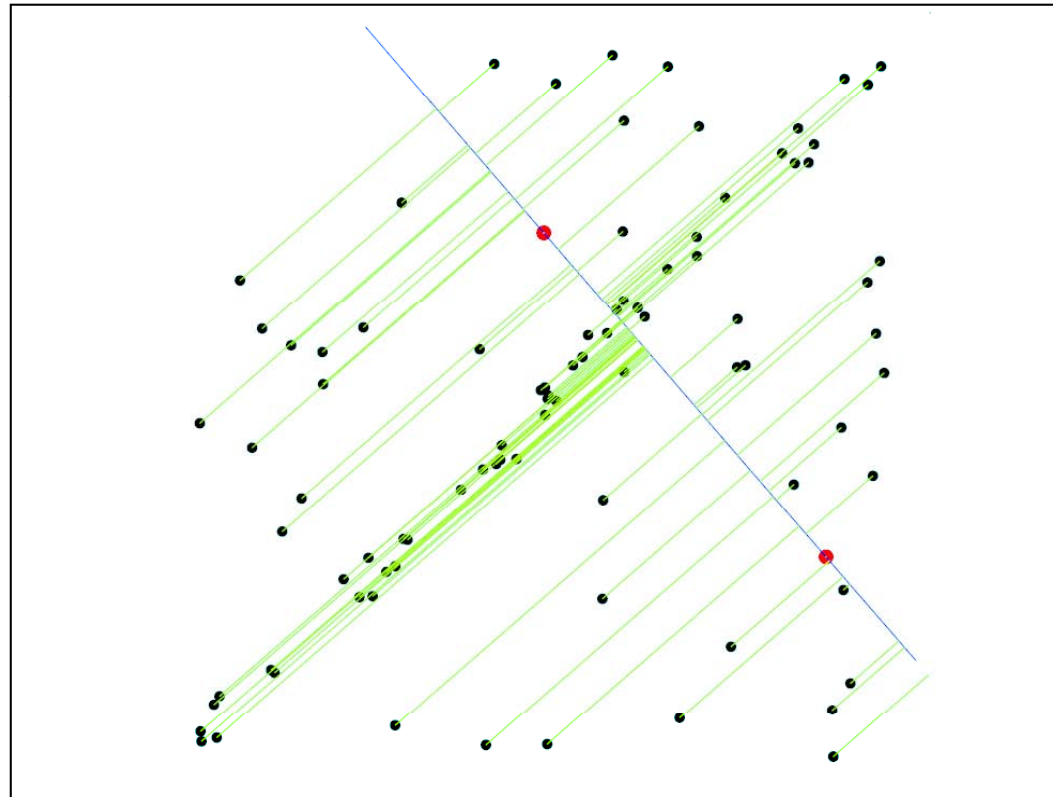
1. Randomly select minimal subset of points

RANSAC for line fitting example



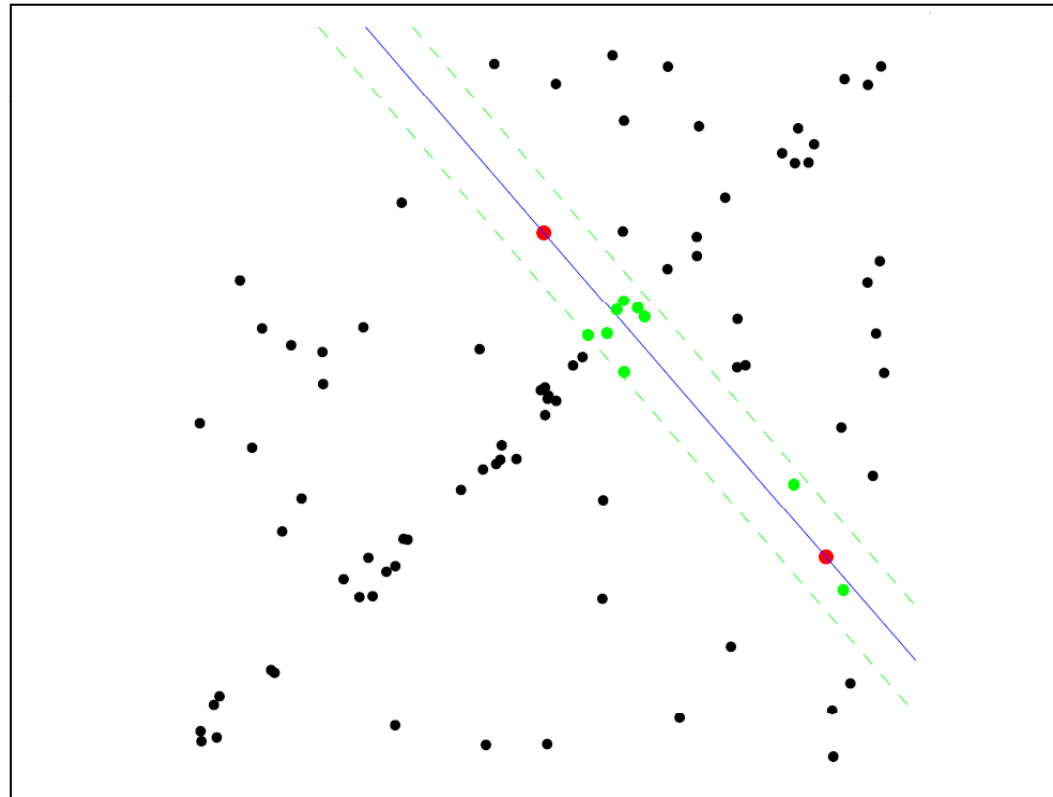
1. Randomly select minimal subset of points
2. Hypothesize a model

RANSAC for line fitting example



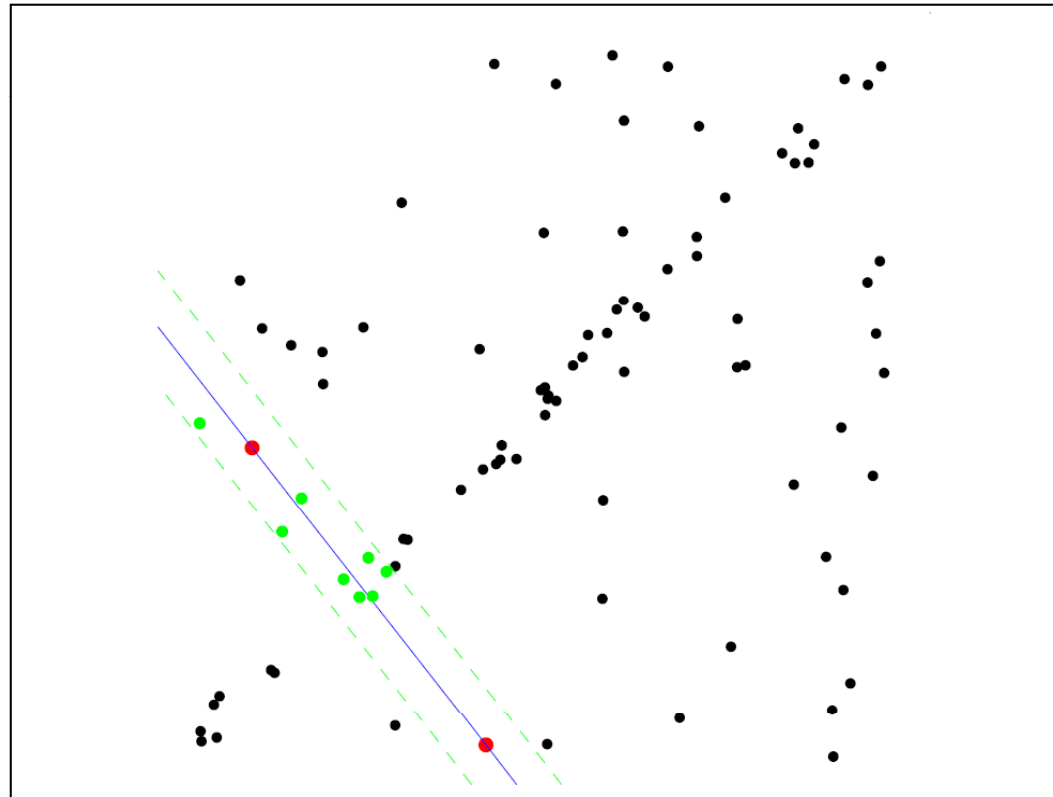
1. Randomly select minimal subset of points
2. Hypothesize a model
3. Compute error function

RANSAC for line fitting example



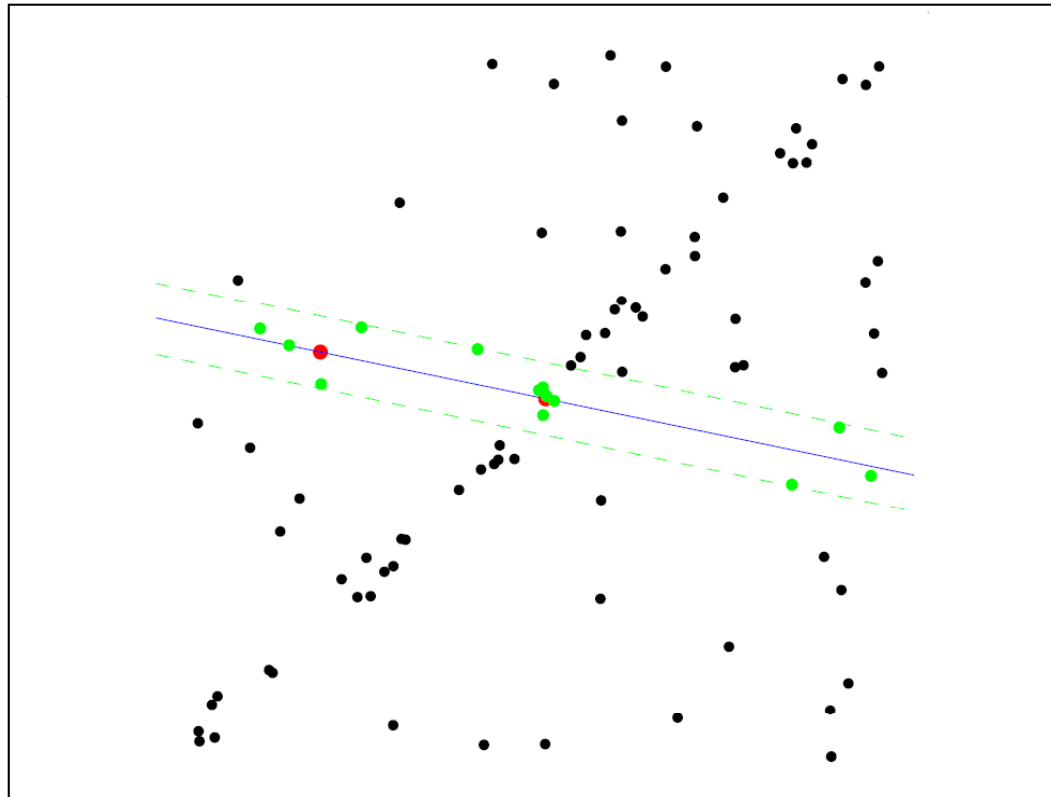
1. Randomly select minimal subset of points
2. Hypothesize a model
3. Compute error function
4. Select points consistent with model

RANSAC for line fitting example



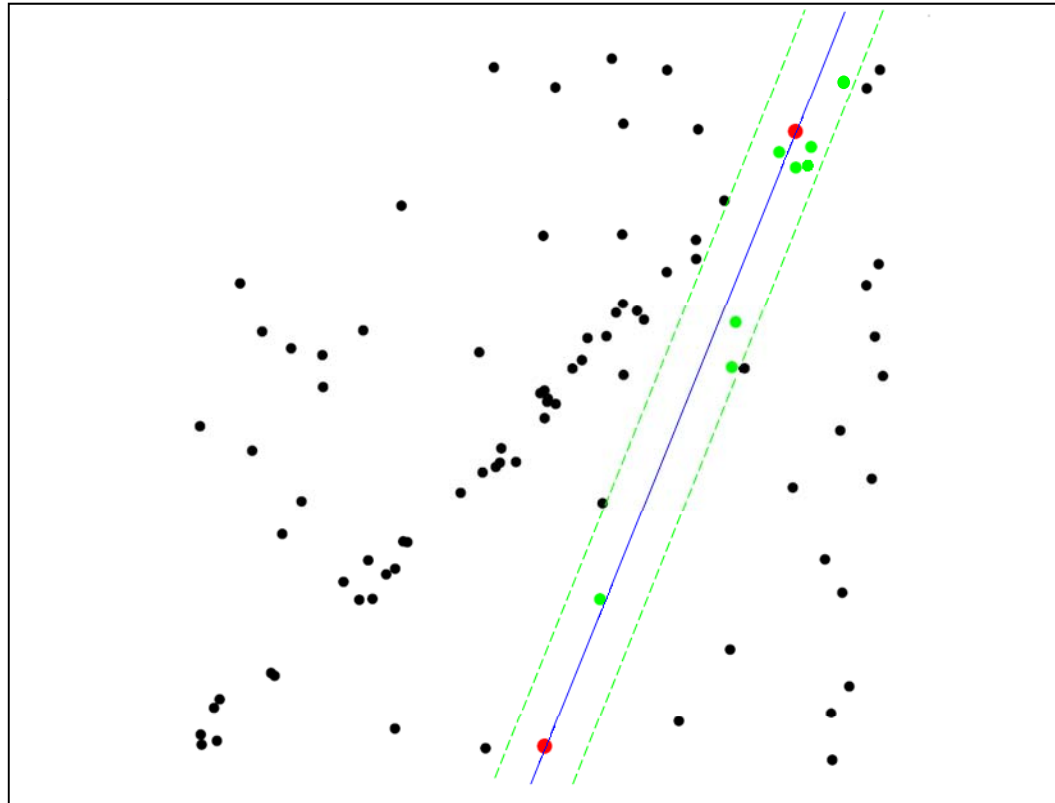
1. Randomly select minimal subset of points
2. Hypothesize a model
3. Compute error function
4. Select points consistent with model
5. Repeat *hypothesize-and-verify* loop

RANSAC for line fitting example



1. Randomly select minimal subset of points
2. Hypothesize a model
3. Compute error function
4. Select points consistent with model
5. Repeat *hypothesize-and-verify* loop

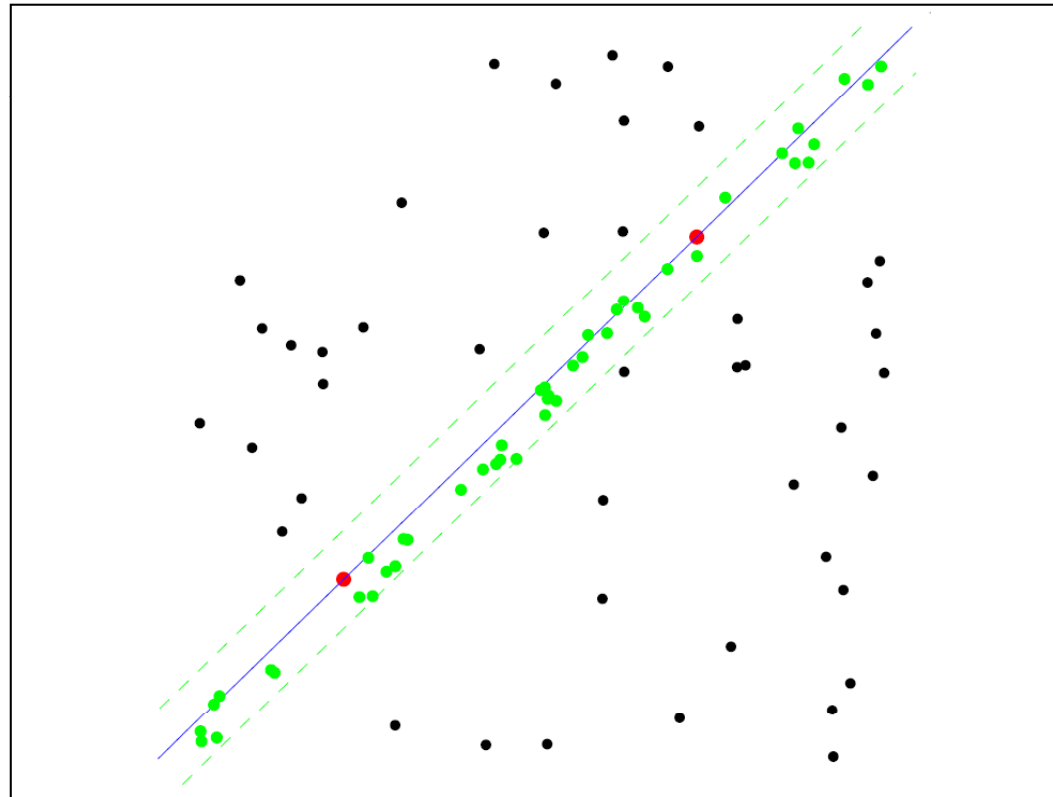
RANSAC for line fitting example



1. Randomly select minimal subset of points
2. Hypothesize a model
3. Compute error function
4. Select points consistent with model
5. Repeat *hypothesize-and-verify* loop

RANSAC for line fitting example

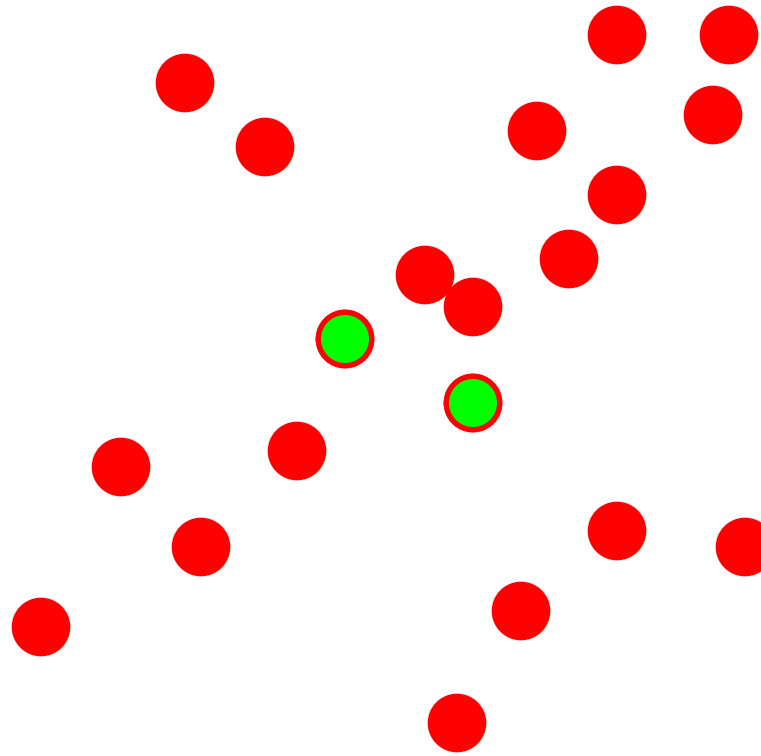
The best inlier structure



1. Randomly select minimal subset of points
2. Hypothesize a model
3. Compute error function
4. Select points consistent with model
5. Repeat *hypothesize-and-verify* loop

RANSAC

RANdom SAmple Consensus



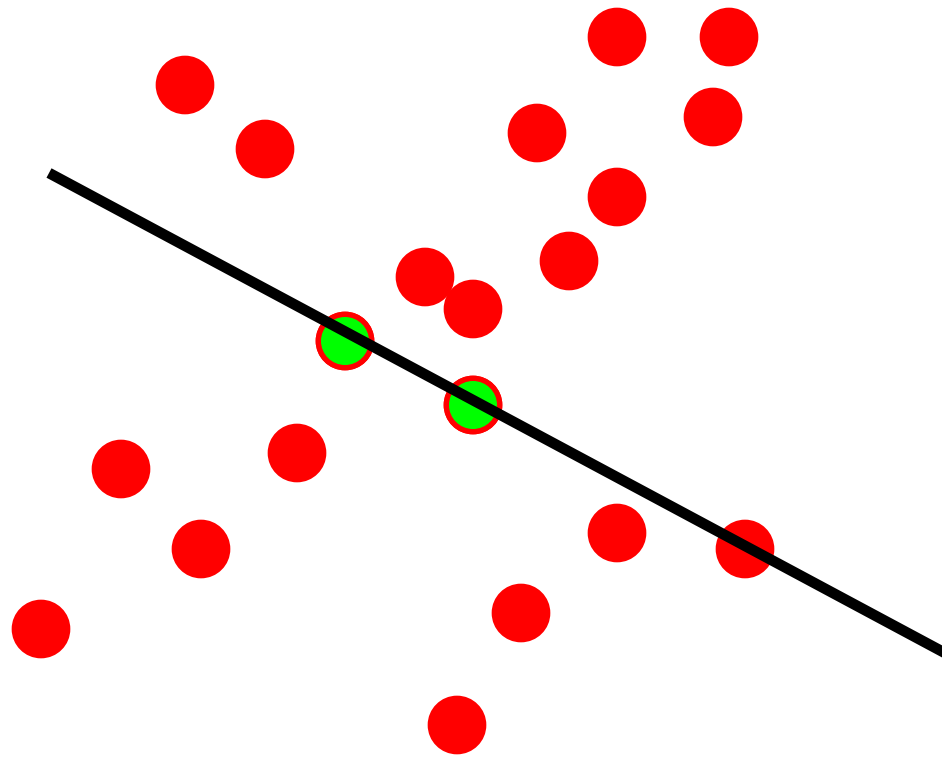
Sample set = set of points in 2D

Algorithm:

1. Select random sample of minimum required size to fit model
2. Compute a putative model from sample set
3. Compute the set of inliers to this model from whole data set

Repeat 1-3 until model with the most inliers over all samples is found

RANSAC



Sample set = set of points in 2D

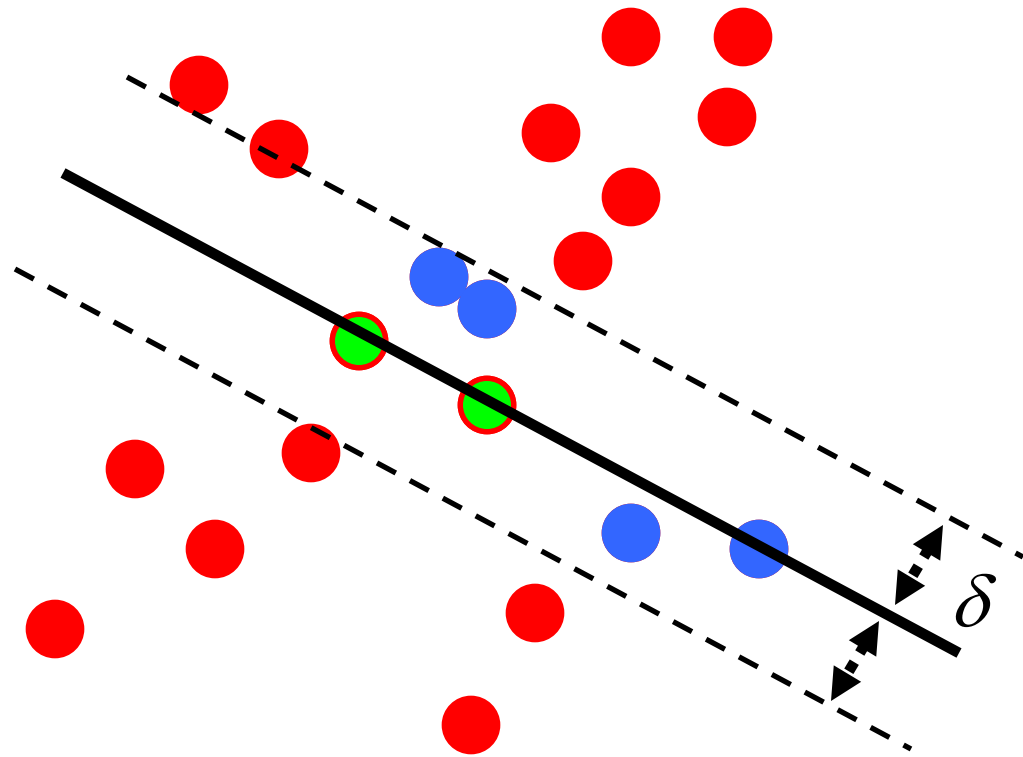
Algorithm:

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RANSAC

standard deviation of the inlier noise has to be given



Sample set = set of points in 2D

$$|\mathcal{O}| = 6$$

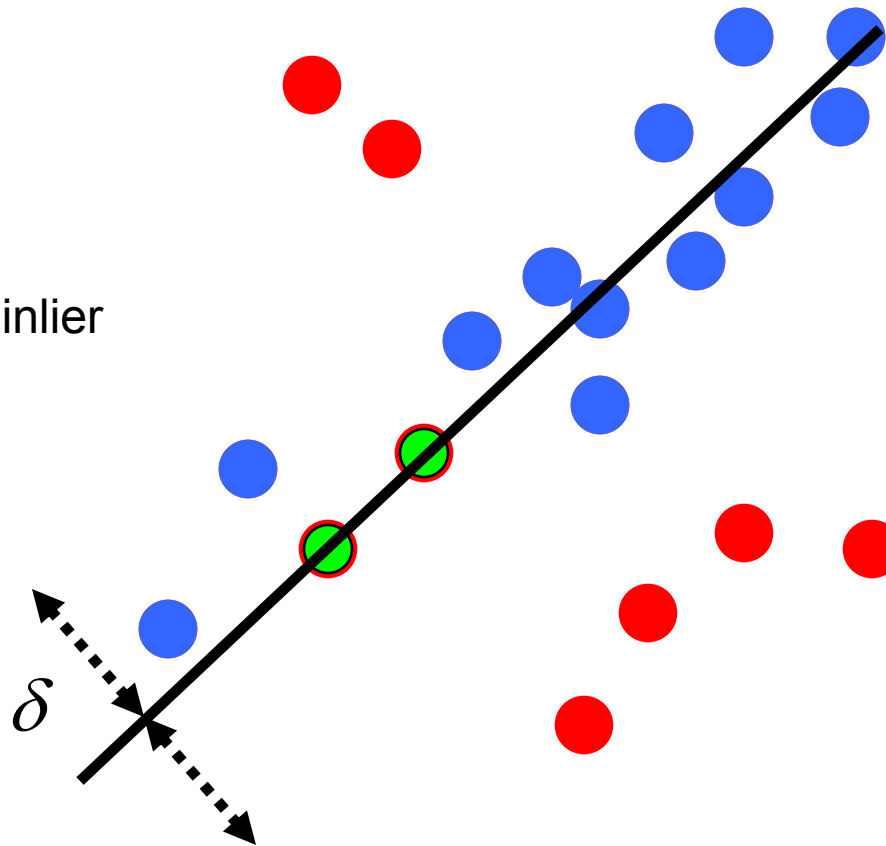
Algorithm:

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RANSAC

standard deviation of the inlier
noise has to be given

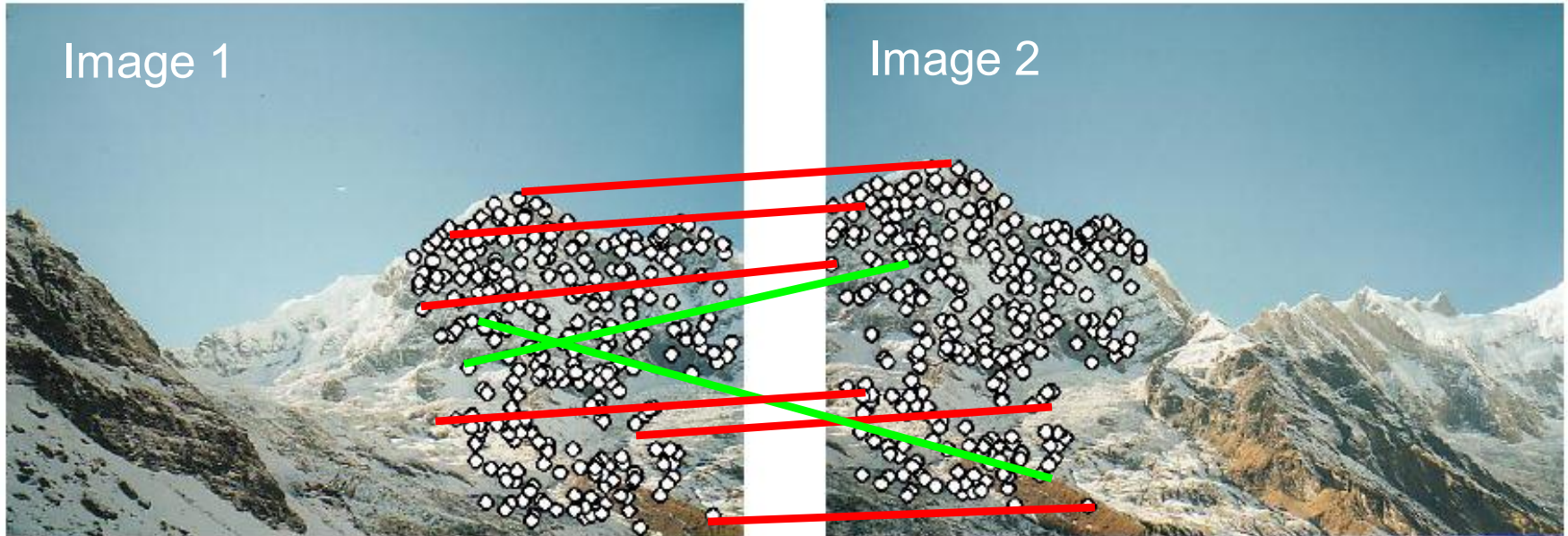


$$|O| = 14$$

Algorithm:

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 2. Compute a putative model from sample set
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- Repeat 1-3 until model with the most inliers over all samples is found

An example:



Matches:

Red: good matches

Green: bad matches

- By RANSAC fit a homography (later...) mapping features from image 1 to 2.
- Bad matches will be labeled as outliers (hence rejected).

Fitting helps matching.



this is a robust fit

RANSAC conclusions

a better robust estimator
exist already

Good

- Robust to outliers.
- The number of hypothesis N is taken sufficiently large (hundreds to thousands) that RANSAC gives very similar results every time.

Bad

- Computational time grows quickly with fraction of outliers and number of parameters.
- Not good for getting multiple inlier structures.

Common applications

- Computing a homography (e.g., image stitching)
- Estimating fundamental matrix (relating two views)