

Robotics

Introduction of Robotics

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- •What is a robot?
- History

What is a robot?



- The word *robot* was introduced in 1920
 - By the Czech writer Karel Čapek in his play R.U.R. (Rossum's Universal Robots)
 - "robota" in Slavic languages means "work", "labor"
 - A story of artificial people called robots



A scene from R.U.R.

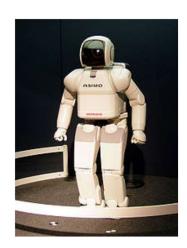


What is a robot? [cont'd]

- A mechanical device that can perform tasks (semi) automatically
 - Not necessarily a humanoid in appearance
 - Some robots require human guidance or remote control
 - Usually an electro-mechanical machine



Teakwon V



ASIMO



Industrial robot



What is a robot? [cont'd]

- No one definition of robot satisfies everyone
- Examples
 - Mechanical device able to perform preset motions
 - Remotely operated vehicle
 - Self-controlled car which could sense its environment and make driving decisions
 - Mechanical humanoid
 - Sentiment robot





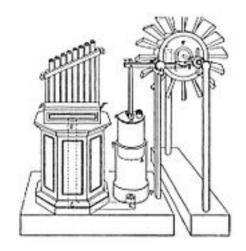


History

- Machinery for repetitive functions
 - Lifting water and grinding grain
- Hero of Alexandria (1st century AD)
 - First recorded steam engine
 - Wind-powered organ first instance of wind powering a machine in human history



Hero's engine (aeolipile)



Wind-powered organ



Al-Jazari (12th century AD)

- The Book of Knowledge of Ingenious Mechanical Devices
- Automaton (self-operating machine) a boat with four automatic musicians that floated on
 a lake to entertain guests at royal drinking parties





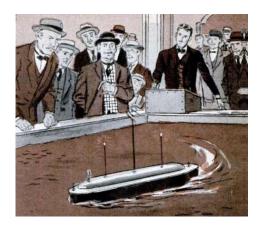
- Leonardo's robot (1495)
 - Humanoid automaton designed by Leonardo da Vinci
 - Not known whether he actually built it
 - Design notes were discovered in the 1950s
 - Able to make several human-like motions



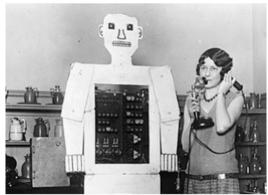
Model of **Leonardo's robot**



- Nikola Tesla (1898)
 - A radio-controlled boat
 - o Tesla VS Edison

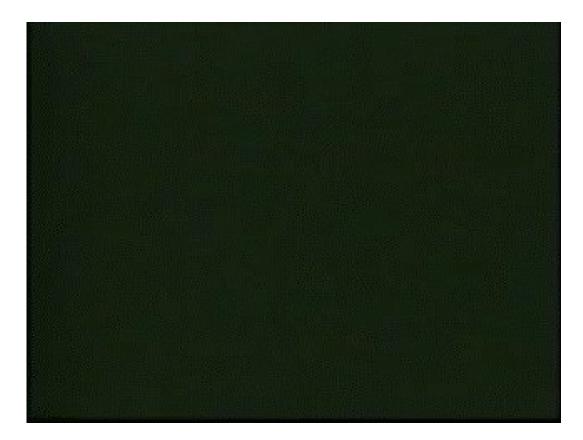


- **Televox** (1926)
 - Considered as first robot put to <u>useful work for consumer</u>
 - Connected to various devices via phone lines and allows users to turn equipment off and on using voice commands





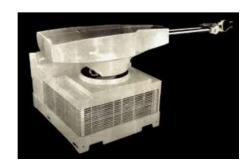
- William Grey Walter (1948)
 - First electronic *autonomous robots* recognizing environments
 - Tasks in unknown environments without human guidance
 - Grey Walter's Tortoise





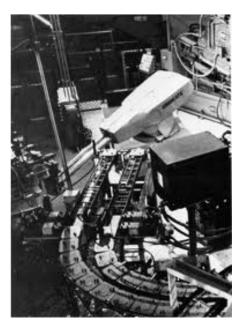
● George Devol (1954)

- First patent about digital and programmable robot
- Tasks can be programmable general-purpose robot which can do multiple tasks



Joseph Engelberger (1961)

Unimate: First industrial robot which worked on General Motors assembly line





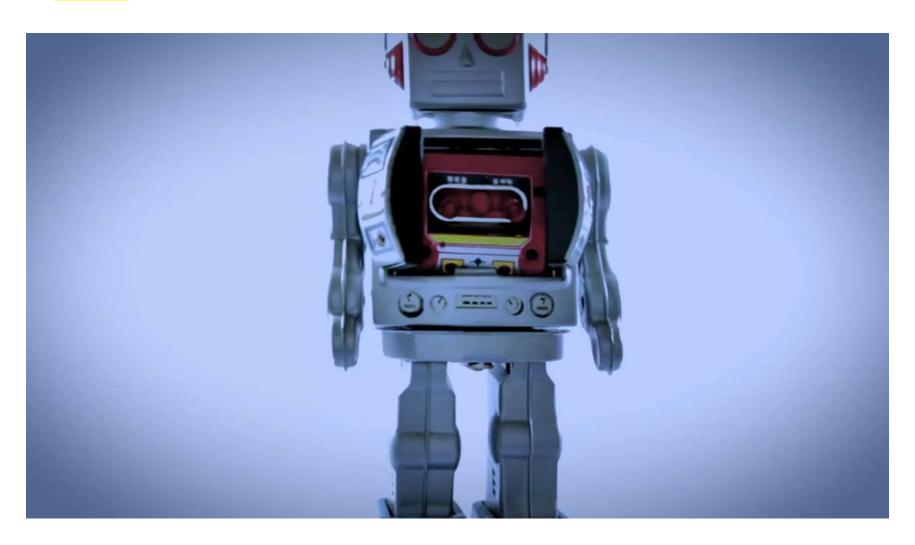
- **ASIMO** (2000~2018)
 - A humanoid robot created by Honda
 - o Designed as a helper to people : 130cm and 54kg, operate in real-world environments





State of the arts

● Pepper - SoftBank





State of the arts [cont'd]

Ongoing robot technology to create the IRON-MAN!!!!(3m)





State of the arts [cont'd]

• Jibo - MIT

