

Lecture 19: Maximum Principles & Laplace's Eqn.

The Laplace Eqn

- Any time-independent solution to the heat- or wave eqn. must have $-\Delta u = 0$. This is the Laplace equation. It usually has some B.C. $u|_{\partial D} = f$
- Functions satisfying the Laplace Eqn. are called harmonic. We will see that they have many nice properties.
- The Laplace Eqn. commonly arises in physics. A conservative v. field may be represented by a gradient $v = \nabla \phi$. If the vector field is solenoidal, $\nabla \cdot v = 0$ or $\Delta \phi = 0$. Similar considerations arise in electrostatics.

- We will focus on $U = D \subseteq \mathbb{R}^2$. Given $g \in C^0(\partial D)$, we solve
$$\begin{cases} \Delta u = 0 \\ u|_{\partial D} = g \end{cases}$$

- In the separation of variables in polar coord, we found the harmonic family

$$\phi_k(r, \theta) = r^{|k|} e^{ik\theta} \quad \text{for } k \in \mathbb{Z}$$

By identifying $\partial D \leftrightarrow \mathbb{T}$ by $\begin{array}{ccc} \partial D & \xrightarrow{\pi} & \mathbb{T} \\ \text{circle} & \rightarrow & [0, 2\pi) \end{array}$ angles, we may write $g = g(\theta) \Leftrightarrow$
$$g(\theta) = \sum_{k \in \mathbb{Z}} c_k[g] e^{ik\theta}$$

Since $e^{ik\theta} = \phi_k(1, \theta)$, we hope to construct a solution

$$u(r, \theta) = \sum_{k \in \mathbb{Z}} c_k[g] \phi_k(r, \theta)$$

For $g \in C^0$, $\{c_k[g]\}$ is odd and $|\phi_k(r, \theta)| = r^{|k|}$ has
$$\sum_{k \in \mathbb{Z}} r^{|k|} < \infty \quad \text{for } r < 1$$

In fact, for $\{r \leq R\}$ and $R < 1$, convergence is uniform.

• Let's try to clean this up.

$$u(r, \theta) = \sum_{k \in \mathbb{Z}} \frac{1}{2\pi} \int_0^{2\pi} r^{|k|} e^{ik(\theta-\eta)} g(\eta) d\eta$$

as convergence is uniform in θ for $\{r \leq R\}$,

$$u(r, \theta) = \frac{1}{2\pi} \int_0^{2\pi} \sum_{k \in \mathbb{Z}} r^{|k|} e^{ik(\theta-\eta)} g(\eta) d\eta$$

$$= \frac{1}{2\pi} \int_0^{2\pi} P_r(\theta-\eta) g(\eta) d\eta$$

for $P_r(\theta) = \sum_{k \in \mathbb{Z}} r^{|k|} e^{ik\theta}$

the Poisson Kernel

We can deduce directly $\frac{1}{2\pi} \int_0^{2\pi} P_r(\theta) d\theta = 1$

and $P_r(\theta) = 1 + \sum_{k=1}^{\infty} (re^{i\theta})^k + \sum_{k=1}^{\infty} (re^{-i\theta})^k$

$$= 1 + \frac{re^{i\theta}}{1-re^{i\theta}} + \frac{re^{-i\theta}}{1-re^{-i\theta}}$$

$$= \frac{1-r^2}{1-2r\cos(\theta)+r^2}$$

•) As $r \rightarrow 1^-$, $P_r(\theta)$ concentrates mass at 0, so we expect $u(r, \theta) \rightarrow g(\theta)$ as $r \rightarrow 1^-$

Thm 9.1 For $g \in C^0(\partial D)$, $\begin{cases} \Delta u = 0 & \text{in } D \\ u|_{\partial D} = g \end{cases}$ admits

a classical solution $u \in C^\infty(D) \cap C^0(\bar{D})$ given by

$$u(r, \theta) = \frac{1}{2\pi} \int_0^{2\pi} P_r(\theta-\eta) g(\eta) d\eta$$

[Pf] Since $P_r(\theta)$ is smooth and $\Delta P_r(\theta) = 0$, $u(r, \theta)$ is

smooth and satisfies $\Delta u(r, \theta) = 0$ as well. we check the boundary condition.

$$\lim_{r \rightarrow 1^-} u(r, \theta) = g(\theta)$$

•) We write

$$u(r, \theta) - g(\theta) = \frac{1}{2\pi} \int_{-\pi}^{\pi} P_r(\eta) [g(\theta - \eta) - g(\theta)] d\eta, \quad \text{Pick } \varepsilon > 0$$

By continuity, there exists $\delta > 0$ s.t. $|g(\theta - \eta) - g(\theta)| < \varepsilon$ for $|\eta| < \delta$.

For $|\eta| \geq \delta$, $\max_{\delta \leq |\eta| \leq \pi} P_r(\eta) = P_r(\delta)$ so

$$|u(r, \theta) - g(\theta)| \leq \frac{1}{2\pi} \left[\int_{-\delta}^{\delta} P_r(\eta) \cdot \varepsilon d\eta + \int_{\delta < |\eta| < \pi} P_r(\delta) |g(\theta - \eta) - g(\theta)| d\eta \right]$$

$$\leq \frac{1}{2\pi} \left[\varepsilon \cdot 2\pi + 2\pi \|g\|_{\infty} \int_{\delta < |\eta| < \pi} P_r(\delta) d\eta \right]$$

$$\leq \frac{\varepsilon}{2\pi} + 2\pi \|g\|_{\infty} P_r(\delta)$$

$$\leq \frac{1}{2\pi} \left[\varepsilon \cdot 2\pi + 2\pi \|g\|_{\infty} \int_{\delta < |\eta| < \pi} P_r(\delta) d\eta \right]$$

$$\leq \varepsilon + 2\pi \|g\|_{\infty} P_r(\delta)$$

Since $\lim_{r \rightarrow 1^-} P_r(\delta) = 0$, for $R < 1$ and $R < r < 1$,

$$2\pi \|g\|_{\infty} P_r(\delta) < \varepsilon$$

so $|u(r, \theta) - g(\theta)| \leq 2\varepsilon$ for $R < r < 1$. \square

Hence, $\lim_{r \rightarrow 1^-} |u(r, \theta) - g(\theta)| = 0$.

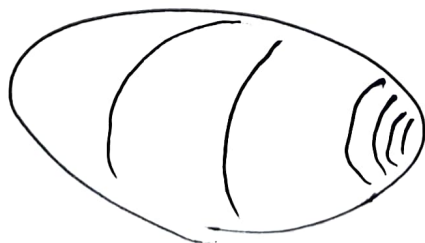
ex.) $g(\theta) = \begin{cases} 1 - |\theta|/a & |\theta| \leq a \\ 0 & a < |\theta| < \pi \end{cases} \quad \text{for } a \in (0, \pi)$



"Hot spot on a point of a plate"

gives

$$u(r, \theta) = \frac{a}{2\pi} + \frac{2}{a\pi} \sum_{k=1}^{\infty} \frac{1 - \cos(ka)}{k^2} \cos(k\theta)$$



Increasing height of u

Mean Value Formula

o) Setting $r=0$, ~~we~~ $u(0, \theta) = \frac{1}{2\pi} \int_0^{2\pi} g(\eta) d\eta$
 because $P_0(\theta) = 1$. This roughly says that the center point is the average of the edge points.

o) Let A_n denote the volume of the unit sphere in \mathbb{R}^n .

Notice $\text{Vol} [\partial B(x_0; r)] = A_n r^{n-1}$ ($n-1$ -dim. volume)

$\text{Vol} [B(x_0; r)] = \frac{A_n}{n} r^n$ (n -dim. volume)

These will be important to averaging as above. Further, we introduce

$$G_R(x) = \begin{cases} \frac{1}{2\pi} \ln(r/R) & n=2 \\ \frac{1}{(n-2)A_n} \left[\frac{1}{R^{n-2}} - \frac{1}{r^{n-2}} \right] & n \geq 3 \end{cases}$$

the unique solution of

$$\frac{\partial}{\partial r} G_R = A_n \frac{1}{r^{n-1}} \quad G_R|_{r=R} = 0$$

o) Notice also $G_R(x)$ is integrable (radial volume element is $A_n r^{n-1} dr$)

Thm 9.3 Assume $u \in C^2(\Omega)$ on a domain $\Omega \subset \mathbb{R}^n$ with $n \geq 2$.
 For $R > 0$ such that $\overline{B(x_0, R)} \subseteq \Omega$

$$u(x_0) = \frac{1}{A_n R^{n-1}} \int_{\partial B(x_0, R)} u(x) ds + \int_{B(x_0, R)} G_R(x-x_0) \Delta u(x) dx$$

[Pf] By a change of variables, consider $x_0 = 0$. Recall ~~the~~ Δ has radial component $\frac{1}{r^{n-1}} \frac{\partial}{\partial r} \left(r^{n-1} \frac{\partial}{\partial r} \right)$ such that

$\Delta G_R(x) = 0$ for $x \neq 0$. Then, we consider $\varepsilon < r < R$ for some $\varepsilon > 0$ and apply Green's Identity,

$$\begin{aligned} \int_{\{\varepsilon < r < R\}} G_R \Delta u dx &= \int_{\partial B(0, R)} (G_R \frac{\partial u}{\partial \nu} - u \frac{\partial G_R}{\partial \nu}) dS \\ &\quad - \int_{\partial B(0, \varepsilon)} (G_R \frac{\partial u}{\partial \nu} - u \frac{\partial G_R}{\partial \nu}) dS \end{aligned}$$

- Since u & G_R are integrable on $B(0; R)$ ~~and $\partial B(0; R)$~~
are ~~continuous~~,

$$\lim_{\epsilon \rightarrow 0} \int_{\{\epsilon < r < R\}} G_R \Delta u \, dx = \int_{B(0, R)} G_R \Delta u \, dx$$

Thus, we treat $\int_{\partial B(0, R)} G_R \frac{\partial u}{\partial r} - u \frac{\partial G_R}{\partial r} \, dS$ (A)
and the integral over $\partial B(0, \epsilon)$.

$$\text{First, (A)} = \int_{\partial B(0, R)} 0 \cdot \frac{\partial u}{\partial r} - u \cdot \frac{1}{A_n R^{n-1}} \, dS = -\frac{1}{A_n R^{n-1}} \int_{\partial B(0, R)} u \, dS$$

and second,

$$\begin{aligned} & \int_{\partial B(0, \epsilon)} G_R \frac{\partial u}{\partial r} - u \frac{\partial G_R}{\partial r} \, dS \\ &= G_R(\epsilon) \int_{\partial B(0, \epsilon)} \frac{\partial u}{\partial r} \, dS + \frac{1}{A_n \epsilon^{n-1}} \int_{\partial B(0, \epsilon)} u \, dS \end{aligned} \quad (B)$$

Notice that $\frac{\partial u}{\partial r}$ & u are well on $B(0, R)$, so

$$| (B) | \leq G_R(\epsilon) A_n \epsilon^{n-1} + \frac{1}{A_n \epsilon^{n-1}} \int_{\partial B(0, \epsilon)} u \, dS$$

and $G_R(\epsilon) A_n \epsilon^{n-1} \rightarrow 0$ as $\epsilon \rightarrow 0$.

By continuity, $\frac{1}{A_n \epsilon^{n-1}} \int_{\partial B(0, \epsilon)} u \, dS \rightarrow u(0)$ as $\epsilon \rightarrow 0$.

$$\text{Hence, } \int_{B(0, R)} G_R \Delta u \, dx = u(0) - \frac{1}{A_n R^{n-1}} \int_{\partial B(0, R)} u \, dS. \quad \square$$

- While the above formula may look quite odd,

it simplifies to

$$u(x_0) = \frac{1}{A_n R^{n-1}} \int_{\partial B(x, R)} u(x) \, dS$$

when u is harmonic. Thus, it immediately generalizes the circle formula. We may actually squeeze a stronger result out of this.

Corollary 9.4 Suppose $\Omega \subset \mathbb{R}^n$ for $n \geq 2$. For $u \in C^2(\Omega)$, the following are equivalent. $\Rightarrow \Omega$ open

(A) $\Delta u = 0$ on Ω

(B) For $\overline{B(x_0, R)} \subset \Omega$, $u(x_0) = \frac{1}{A_n R^{n-1}} \int_{\partial B(x_0, R)} u dS$

(C) For $\overline{B(x_0, R)} \subset \Omega$, $u(x_0) = \frac{n}{A_n R^n} \int_{B(x_0, R)} u dx$

[Pf] $A \Rightarrow B$ as noted above

For $B \Rightarrow C$, recall that

$$\begin{aligned} \int_{B(x_0, R)} u dx &= \int_0^R \int_{\partial B(x_0, r)} u dS dr \\ &= \int_0^R (A_n R^{n-1}) u(x_0) dr = \frac{A_n R^n}{n} u(x_0) \end{aligned}$$

as desired. The reverse $C \Rightarrow B$ follows similarly by differentiation.

For $B \Rightarrow A$, the Mean Value Formula gives $\int_{B(x_0, R)} G_R(x-x_0) \Delta u(x) dx = 0$ whenever $\overline{B(x_0, R)} \subset \Omega$

Without loss of generality, assume that $\Delta u(x_0) < 0$. Then, $\exists \varepsilon > 0$ and some ball $B(x_0, \delta)$ so

$\Delta u(x) \leq -\varepsilon < 0$ on $B(x_0, \delta)$ by continuity.

Since G_R is strictly negative & decreasing as $r \rightarrow 0$,

$$\int_{B(x_0, \delta)} G_R(x-x_0) \Delta u(x) dx > -\varepsilon G_R(r=\delta) > 0,$$

a contradiction. We may argue similarly if $\Delta u(x_0) > 0$. \square