

## Lecture 26: Fourier Transform Teaser

- In a "normal" vector space like  $\mathbb{R}^n$ , we come up with tricks like diagonalization to simplify calculations. How do you diagonalize a partial differential operator?

→ We focus on functions, which we normally consider pointwise like  $\{f(y)\}_{y \in \mathbb{R}^n}$ . We can think of this as acting under the "basis"  $\{\delta(x-y)\}_{y \in \mathbb{R}^n}$  in the sense

that  $f(x) = \int f(y) \delta(x-y) dy$  (for  $f \in C^0(\mathbb{R}^n)$ ).

or "f's coefficient at x is  $\langle f, \delta(x-\cdot) \rangle$ "

So that  $\{\delta(x-y)\}$  uniquely determines f via its coefficients ( $\delta(x-y)$  is "linearly independent")

→ We want a basis in which differentiation looks diagonal, so we might pick

$$\{e^{i\xi \cdot x}\}_{\xi \in \mathbb{R}^n}$$

because  $\partial_j e^{i\xi \cdot x} = i\xi_j e^{i\xi \cdot x}$

but, is this still a "basis"?

Remarkably, yes! Given a function f on  $\mathbb{R}^n$  ( $f \in L^2$ ), we can write f uniquely in the form

$$f(x) = \int a(\xi) e^{i\xi \cdot x} d\xi$$

- The Fourier transform  $\mathcal{F}$  is the "change-of-basis"  $f \mapsto a(\xi)$

- Let us try to find the form of  $F$ . We expect from linear algebra  $\tilde{F} = A\tilde{f}$  for a matrix  $A$ , vector  $b$ ,  
So here we try

$$F[f](\xi) \propto \int f(y) m(y, \xi) dy$$

to match the above processes. Then,

$$\delta_0(x-y) \stackrel{""}{=} \int m(y, \xi) e^{i\xi \cdot x} d\xi$$

- By translation symmetry, we expect  $\int m(y, \xi) e^{i\xi \cdot x} dx = \delta_0(x-y) = \int m(0, \xi) e^{i\xi \cdot (x-y)} d\xi$

So that if we believe  $\{e^{i\xi \cdot x}\}$  forms a basis,  
 $m(0, \xi) e^{-i\xi \cdot y} = m(y, \xi)$

- Next,  $\delta(x)$  has the property  $x^j \delta(x) = 0$ , while

$$0 = x^j \delta(x) = \int m(0, \xi) x^j e^{i\xi \cdot x} d\xi =$$

$$\int m(0, \xi) \frac{1}{i} \partial_{\xi_j} e^{i\xi \cdot x} dx$$

$$= i \int \partial_{\xi_j} (m(0, \xi)) e^{i\xi \cdot x} dx$$

So  $\partial_{\xi_j} m(0, \xi)$  ~~is~~ is a nonzero constant, or

$$\delta(x) = c \int e^{i\xi \cdot x} dx$$

$$\text{and } m(y, \xi) \propto e^{-i\xi \cdot y}$$

Thus, we ~~can~~ see

$$F[f](\xi) \propto \int f(y) e^{-i\xi \cdot y} dy$$

and claim the constant of proportionality is  $c = \frac{1}{(2\pi)^n}$ .

• Approaching via approximation

First,  $\delta(x) = \delta(x_1) \dots \delta(x_n)$ , so

$$\int e^{i x \cdot \xi} d\xi = \prod_{i=1}^n \int e^{i \xi_i x_i} d\xi_i$$

and  $C = (C_1)^n$ . We consider the 1D case

To make sense of  $\int_{\mathbb{R}} e^{i \xi x} dx$ , we "temper" by multiplying by  $e^{-\epsilon |\xi|}$ , integrate, and take  $\epsilon \rightarrow 0$ :

$$\lim_{\epsilon \rightarrow 0^+} \int_{\mathbb{R}} e^{i \xi x - \epsilon |\xi|} d\xi$$
$$= \lim_{\epsilon \rightarrow 0^+} \int_{-\infty}^0 e^{i \xi (x - i\epsilon)} d\xi + \int_0^{\infty} e^{i \xi (x + i\epsilon)} d\xi$$

$$= \lim_{\epsilon \rightarrow 0^+} \left[ i \frac{1}{(x - i\epsilon)} + i \frac{1}{(x + i\epsilon)} \right]$$

$$= \lim_{\epsilon \rightarrow 0} \frac{2\epsilon}{x^2 + \epsilon^2} = 2 \left( \int \frac{dt}{1+t^2} \right) \delta_0 = 2\pi \delta_0$$

by our distributions  
yesterday

$$\text{and so } C_1 = \frac{1}{2\pi}, \quad C = \left(\frac{1}{2\pi}\right)^n.$$

- In general, we define

$$\mathcal{F}[f](\xi) = \hat{f}(\xi) = \int_{\mathbb{R}^n} f(y) e^{-i\xi \cdot y} dy$$

for  $f \in C_c^\infty(\mathbb{R}^n; \mathbb{C})$

in fact,

$$f(x) = c \mathcal{F}^*(\hat{f})(x) = c \int_{\mathbb{R}^n} \hat{f}(\xi) e^{i\xi \cdot x} d\xi$$

$$\text{for } c = \frac{1}{(2\pi)^n}$$

- The Fourier transform has many useful properties, but foremost to PDE's is

$$\mathcal{F}[\partial_j f](\xi) = i\xi_j \mathcal{F}[f](\xi)$$

$$\mathcal{F}[x_j f](\xi) = i\partial_{\xi_j} \mathcal{F}[f](\xi)$$

- This allows us to "mess with" PDE's. Consider

$$\begin{cases} (\partial_t - \Delta)u = 0 \\ u(0, x) = g \end{cases}$$

if we take the Fourier transform only in space,

this becomes

$$\begin{cases} \partial_t \hat{u}(t, \xi) + |\xi|^2 \hat{u}(t, \xi) = 0 \\ \hat{u}(0, \xi) = \hat{g}(\xi) \end{cases}$$

$$\text{with solution } \hat{u}(t, \xi) = e^{-t|\xi|^2} \hat{g}(\xi)$$

So solving the heat equation simply means transforming back. Another property of the transform is

$$\mathcal{F}[f * g] = \mathcal{F}[f] \mathcal{F}[g], \text{ so}$$

$$\mathcal{F}^{-1}[e^{-t|\xi|^2} \hat{g}(\xi)] = \mathcal{F}^{-1}[e^{-t|\xi|^2}] * \mathcal{F}^{-1}[\hat{g}]$$

$$= (4\pi t)^{-n/2} e^{-|x|^2/4t} * g(x) !$$