

Lecture 21: Weak Solutions

- Roughly speaking, weak solutions are non-differentiable solutions that "satisfy" the PDE in an appropriate sense
- They arise due to perhaps non-differentiable initial data where a concept of a solution may still be important.

Test Functions

- We call $C_c^\infty(U)$ the space of test functions on U , with the idea that we "test against them".
- Indeed, let $u \in C^0(U)$. Then, if $\int_U u \cdot \varphi dx = 0$ for all $\varphi \in C_c^\infty(U)$, we must have $u = 0$.
- [PF] Assume for contradiction $u(x_0) > 0$. Then, by continuity, there exists some $B(x_0, \delta)$ on which $u(y) > \frac{1}{2}u(x_0) > 0$. Let $\varphi(x)$ be a smooth positive bump supported in $B(x_0, \delta)$ and $\varphi(x_0) = 1$. Then, $\int_U u \varphi dx > 0$. \square

In concept, C_c^∞ lets us "probe" functions.

- Further, if $u \in C^1(\mathbb{R})$, we may "detect" the derivative via $\varphi \in C_c^\infty$: For all $\varphi \in C_c^\infty(U)$ (and $U \subseteq \mathbb{R}$).

$$\int_U u' \varphi dx = \int_U u (-\varphi') dx$$

where the RHS "works" even if $u \notin C^1$.

- We use this concept to define a weak derivative.
 $u' = f$ if $\int_U -u \varphi' dx = \int_U f \varphi dx \quad \forall \varphi \in C_c^\infty(U)$.

- With that in mind, we consider the most general ambient space where these ideas make sense:

$$L^1_{loc}(U) = \{f: U \rightarrow \mathbb{C} ; f|_K \in L^1(K) \text{ for all compact } K \subset U\}$$

Lemma: 10.1 If $f \in L^1_{loc}(U)$ satisfies $\int_U f \varphi dx = 0$ for all $\varphi \in C_c^\infty(U)$, then $f \equiv 0$.

[Pf] Consider any $K \subseteq \Omega$ compact. Then, there exists some $\gamma > 0$ such that for all $0 < \varepsilon < \gamma$, the "bubble"

$B(K, \varepsilon) \subseteq \Omega$. We create a smooth φ_ε so $\varphi_\varepsilon \equiv 1$ on K and $\text{supp}(\varphi_\varepsilon) \subset B(K, \varepsilon)$. Then, $f \cdot \varphi_\varepsilon = f_\varepsilon \in L^2(\Omega)$. Pick $\{\varphi_K\} \subset C_c^\infty(\Omega)$ so $\varphi_K \rightarrow f_\varepsilon$ in L^2 . Notice that $\int f_\varepsilon \varphi_K dx = \int f \varphi_\varepsilon \varphi_K dx = 0$, so $\|f_\varepsilon\|_2 = 0$. Hence, $f_\varepsilon \equiv 0$ ($f_\varepsilon = 0$ a.e.).

We then must have $f \equiv 0$. □

ex.) In \mathbb{R} , consider $g(x) = \begin{cases} 0 & x < 0 \\ x & x \in [0, 1] \\ 1 & x > 1 \end{cases}$. We expect $g'(x)$ to look like $f(x) = \begin{cases} 0 & x \notin [0, 1] \\ 1 & x \in (0, 1) \end{cases}$.

In terms of weak derivatives,

$$\begin{aligned} \int_{-\infty}^{\infty} g \varphi' dx &= \int_{-\infty}^{\infty} \varphi' dx + \int_0^1 x \varphi' dx \\ &= -\varphi(1) + [x \varphi]_0^1 - \int_0^1 \varphi dx \\ &= -\int_0^1 \varphi dx = -\int_{\mathbb{R}} f \varphi dx \end{aligned}$$

So $g' = f$ weakly.

ex.) For $t \in \mathbb{R}$, define $w \in L^1_{loc}(U)$ by $w(t) = \begin{cases} w_-(t) & t < 0 \\ w_+(t) & t \geq 0 \end{cases}$ for $w_-, w_+ \in C^1(\mathbb{R})$.

$$\begin{aligned} \text{for } \varphi \in C_c^\infty(\mathbb{R}), \quad - \int_{-\infty}^{\infty} w(t) \varphi'(t) dt &= \int_{-\infty}^0 -w_- \varphi' dt + \int_0^{\infty} -w_+ \varphi' dt \\ &= [w_+(0) - w_-(0)] + \int_{-\infty}^0 w_+' \varphi dt + \int_{-\infty}^0 w_-' \varphi dt \end{aligned}$$

So if $w_+(0) = w_-(0)$, $w'(t) = \begin{cases} w_-'(t) & t < 0 \\ w_+'(t) & t > 0 \end{cases}$ weakly.

ex.) Consider $H(t) = \begin{cases} 0 & t < 0 \\ 1 & t > 0 \end{cases}$. For $\varphi \in C_c^\infty(\mathbb{R})$,

$$\int_{\mathbb{R}} -H(t) \varphi'(t) dt = \int_{\mathbb{R}} -\varphi'(t) dt = \varphi(0)$$

So we consider $H'(t)$ to be the "point mass" or evaluation $\delta_0(x)$ so $\int \delta_0(x) \varphi(x) dx = \varphi(0)$.

• Multi-Indices:

- we introduce a notation to simplify writing partials.

For each multi-index $\alpha = (\alpha_1, \alpha_2, \dots, \alpha_n)$ with

$\alpha_j \in \mathbb{N}_0$, we denote

$$D^\alpha = \frac{\partial^{\alpha_1}}{\partial x_1^{\alpha_1}} \cdots \frac{\partial^{\alpha_n}}{\partial x_n^{\alpha_n}}$$

with order $|\alpha| = \alpha_1 + \dots + \alpha_n$

e.g. if $u, \varphi \in C_c^\infty(\Omega)$,
$$\int_{\Omega} (D^\alpha u) \varphi dx = (-1)^{|\alpha|} \int_{\Omega} u D^\alpha \varphi dx.$$

Th^m 10.4 If $u \in C^m(U)$, then u is weakly differentiable to order m and the weak and classical derivatives coincide.

Conversely, if $u \in L^1_{loc}(U)$ has ~~class~~ weak derivatives $D^\alpha u$ for $|\alpha| \leq m$ and each $D^\alpha u$ is continuous (or equivalent to a continuous function), then u is equivalent to a $C^m(U)$ function.

[Pr] The first direction is integration-by-parts & lemma 10.1. The second direction relies on appropriate convergences we haven't built up analysis for (e.g. mollification). \square

Weak Solutions of Continuity Equations

1) Consider $\frac{\partial u}{\partial t} + \frac{\partial q}{\partial x} = 0$ $u|_{t=0} = g$ for $u(t, x)$, with flux $q(t, x)$ as we derived for the method-of-characteristics.

Suppose u is a classical solution & q is differentiable.

Let $\varphi \in C_c^\infty([0, \infty) \times \mathbb{R})$. Then,

$$\int_0^\infty \frac{\partial u}{\partial t} \varphi dt = -u\varphi|_{t=0} - \int_0^\infty u \frac{\partial \varphi}{\partial t} dt$$

$$\text{but } \int_0^\infty \frac{\partial q}{\partial x} \varphi dt = - \int_0^\infty q \frac{\partial \varphi}{\partial x} dx$$

Such that

$$\int_0^\infty \int_{-\infty}^\infty \left[\frac{\partial u}{\partial t} + \frac{\partial q}{\partial x} \right] \varphi dx dt = - \int_0^\infty \int_{-\infty}^\infty u \frac{\partial \varphi}{\partial t} + q \frac{\partial \varphi}{\partial x} dx dt - \int_{-\infty}^\infty u \varphi|_{t=0} dx$$

2) If u is a classical solution,

$$\int_0^\infty \int_{-\infty}^\infty u \frac{\partial \varphi}{\partial t} + q \frac{\partial \varphi}{\partial x} dx dt + \int_{-\infty}^\infty g \varphi|_{t=0} dx = 0 \quad (A)$$

for all $\varphi \in C_c^\infty([0, \infty) \times \mathbb{R})$. For g, q locally integrable, we define $u(t, x)$ to be a weak solution to

$$\begin{cases} \frac{\partial u}{\partial t} + \frac{\partial q}{\partial x} = 0 \\ u|_{t=0} = g \end{cases} \text{ if (A) holds for all } \varphi \in C_c^\infty.$$

ex.) Consider $q(t, x) = c \cdot u(t, x)$ ($c \in \mathbb{R}$). By the method of characteristics, $u(t, x) = g(x - ct)$.

If $g \in L^1_{loc}(\mathbb{R})$, this defines a weak solution:

$$\int_0^\infty \int_{-\infty}^\infty g(x - ct) \left[\frac{\partial \varphi}{\partial t}(t, x) - c \frac{\partial \varphi}{\partial x}(t, x) \right] dx dt$$

for $\tau = t$, $y = x - ct$ is

$$\int_0^\infty \int_{-\infty}^\infty g(y) \frac{\partial \tilde{\varphi}}{\partial \tau}(\tau, y) dy d\tau$$

$$\text{for } \tilde{\varphi}(\tau, y) = \varphi(\tau, y + c\tau).$$

$$= \int_{-\infty}^\infty g(y) (-\tilde{\varphi}(0, y)) dy$$

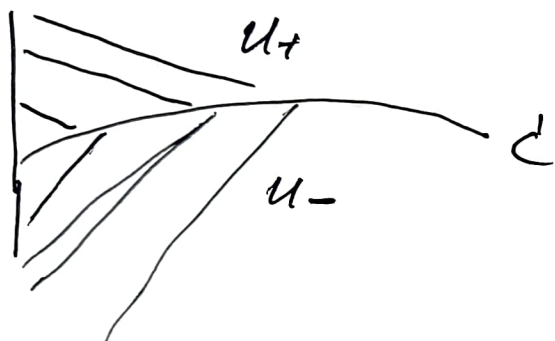
$$= \int_{-\infty}^\infty -g(y) \varphi(0, y) dy \quad \text{as desired.}$$

Rmk: Previously, we noted that jump discontinuities are a bit beyond Standard weak derivatives here. The above works because we see regularity along characteristics.

• Let us consider another equation $\frac{\partial u}{\partial t} - \frac{\partial}{\partial x} q(u) = 0$ (B)

for $q: \mathbb{R} \rightarrow \mathbb{R}$ smooth. The characteristics are straight lines whose slope depends on initial conditions.

- In such cases, we saw shocks form as characteristics crossed. One possible way to resolve this is to draw a shock curve ζ and patch classical solutions above and below the line, then give some "jump condition"



Thm 10.6 Rankine-Hugoniot Condition

Let ζ be characterized by $x = G(t)$ with $G \in C^1([0, \infty))$.

Suppose u is a weak solution of (B) given by

$$u(t, x) = \begin{cases} u_-(t, x) & x < G(t) \\ u_+(t, x) & x > G(t) \end{cases}$$

where u_+, u_- are classical solutions. Then, along ζ ,

$$q(u_+) - q(u_-) = (u_+ - u_-) G'$$

[Pf] Consider $\varphi \in C_c^\infty((0, \infty) \times \mathbb{R})$ so that by the weak solution defn, (b/c ζ open $(0, \infty) \times \mathbb{R}$)

$$\int_0^\infty \int_{-\infty}^\infty \left[u \frac{\partial \varphi}{\partial t} + q(u) \frac{\partial \varphi}{\partial x} \right] dx dt = 0$$

By our assumptions, this is

$$\begin{aligned} & \int_0^\infty \int_{-\infty}^{G(t)} q(u_-) \frac{\partial \varphi}{\partial x} dx dt + \int_0^\infty \int_{G(t)}^\infty q(u_+) \frac{\partial \varphi}{\partial x} dx dt + \int_0^\infty \int_{-\infty}^{G(t)} u_- \frac{\partial \varphi}{\partial t} dx dt \\ & + \int_0^\infty \int_{G(t)}^\infty u_+ \frac{\partial \varphi}{\partial t} dx dt \end{aligned}$$

1) Set $A_1 = \{(t, x) \in (0, \infty) \times \mathbb{R} : x < G(t)\}$.

Let $F = \langle u, q(u) \rangle$ and the above has term

$$\begin{aligned} \iint_{A_1} F \cdot \nabla_{t,x} \varphi \, dx \, dt &= - \iint_{A_1} \varphi \operatorname{div}(F) \, dx \, dt \\ &\quad + \int_{\partial A_1} \varphi \eta \cdot F \, ds \\ &= - \iint_{A_1} \varphi \left[\frac{\partial u}{\partial t} - \frac{\partial}{\partial x} q(u) \right] \, dx \, dt \\ &\quad + \int_0^\infty \varphi \langle u, q(u) \rangle \cdot \langle -G'(t), 1 \rangle \, dt \rightarrow 0 \text{ by assumption} \\ &= - \iint_{A_1} \varphi \left[\frac{\partial u}{\partial t} - \frac{\partial}{\partial x} q(u) \right] \, dx \, dt \\ &\quad + \int_0^\infty q(u_-) \varphi - \varphi u_- G' \Big|_{x=G(t)} \, dt \end{aligned}$$

Repeating on $A_2 = \{(t, x) \in (0, \infty) \times \mathbb{R} : x > G(t)\}$ gives

$$\iint_{A_2} u \frac{\partial \varphi}{\partial t} + q(u) \frac{\partial \varphi}{\partial x} \, dx \, dt = \int_0^\infty \left[(u_+ - u_-) \varphi G' - (q(u_+) - q(u_-)) \varphi \right]_{x=G(t)} \, dt$$

$$\text{Such that } \int_0^\infty \varphi \left[(u_+ - u_-) G' - (q(u_+) - q(u_-)) \right]_{x=G(t)} \, dt = 0$$

for all such φ , or

$$(u_+ - u_-) G' - (q(u_+) - q(u_-)) = 0, \quad \text{on } x = G(t). \quad \square$$

ex.) Consider the traffic equation $\frac{\partial u}{\partial t} + (1-2u) \frac{\partial u}{\partial x} = 0$

$$\begin{aligned} (q(u) = u - u^2) \text{ with} \\ u(t, x) = \begin{cases} a & x < 0 \\ b & x > 0 \end{cases} \end{aligned}$$

Characteristics are

$$x(t) = \begin{cases} x_0 + (1-2a)t & x_0 < 0 \\ x_0 + (1-2b)t & x_0 > 0 \end{cases}$$

If $a < b$, these give a shock

The solutions above & below the shock lines are constant:

$$u_- = a, \quad u_+ = b.$$

Thus, the R-H condition is $(b-b^2) - (a-a^2) = (b-a)G'$

$$\text{So } G' = (1-b-a)$$

or

$$u(t, x) = \begin{cases} a & x < (1-b-a)t \\ b & x > (1-b-a)t \end{cases}$$

(Shock starts at origin)

