## ECM1416 Forumlas

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1.	1 Vecto	rs			
1.1	.1 Vecto	r Norm			
		$  v   = \sqrt{\sum v_i^2}$		(	1)
1.1	.2 Inner	Product			
		$u \cdot v =  u  v \cos(\theta)$		(:	2)
		$u \cdot v = u^T \cdot v = \sum_{i=1}^n u_i v_i$		(;	3)
1.1	3 Rotat	ing Vector			
		$v' = \begin{bmatrix} v_x \cos(\theta) - v_y \sin(\theta) \\ v_x \sin(\theta) + v_y \cos(\theta) \end{bmatrix}$		(4	4)
1.:	2 Matra	acies			
1.2	2.1 Matri	ix Product $(A = (m \times n), B = (n \times p))$			
		$A \cdot B = \begin{bmatrix} \sum_{i=1}^{n} a_{1i} b_{i1} & \cdots & \sum_{i=1}^{n} a_{1i} b_{ip} \\ \vdots & \ddots & \vdots \\ \sum_{i=1}^{n} a_{ni} b_{i1} & \cdots & \sum_{i=1}^{n} a_{ni} b_{ip} \end{bmatrix}$		(	5)

# 1.2.2 Rotation Matrix

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$
 (6)

(5)

#### 1.2.3 Scale Matrix

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \lambda_1 x \\ \lambda_2 y \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$
 (7)

#### 1.2.4 Shear Matrix

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} x \\ \mu x + y \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ \mu & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$
 (9)

#### 1.2.5 Transpose Properties

$$(A+B)^T = A^T + B^T (10)$$

$$(AB)^T = A^T B^T (11)$$

#### 1.2.6 Identity Matrix

$$v = I_n v, \forall v \in \mathbb{R}^n \tag{12}$$

#### 1.2.7 Determinant of a $2 \times 2$ Matrix

$$\det\begin{pmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \end{pmatrix} = ad - bc \tag{13}$$

#### 1.2.8 Determinant of a $n \times n$ Matrix

$$\det(A) = \sum_{k=1}^{n} (-1)^{i+k} a_{ik} M_{ik} = \sum_{k=1}^{n} (-1)^{j+k} a_{kj} M_{kj}$$
(14)

#### 1.2.9 Inverse of a $2 \times 2$ Matrix

$$A^{-}1 = \begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{\det(A)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$
 (15)

#### 1.2.10 Inverse of a $n \times n$ Matrix

$$A^{-}1 = \frac{1}{\det(A)}C^{T} = \frac{1}{\det(A)} \begin{bmatrix} C_{11} & C_{21} & \cdots & C_{n1} \\ C_{21} & C_{22} & \cdots & C_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ C_{1n} & C_{2n} & \cdots & C_{nn} \end{bmatrix}$$
(16)

$$C_{ij} = (-1)^{i+j} M_{ij} (17)$$

#### 1.2.11 Properties of an Inverse

$$(A^{-1})^{-1} = A (18)$$

$$(A^T)^{-1} = (A^{-1})^T (19)$$

$$(AB)^{-1} = B^{-1}A^{-1} (20)$$

$$(kA)^{-1} = k^{-1}A^{-1} (21)$$

#### 1.2.12 Solving a System of Linear Equations

$$Ax = b (22)$$

$$x = A^{-1}b \tag{23}$$

### 2 Differentation

#### 2.1 Matrix Calculus

#### 2.1.1 Gradient

$$\nabla f = \begin{bmatrix} f_{x_1} \\ f_{x_2} \\ \vdots \\ f_{x_n} \end{bmatrix} \tag{24}$$

#### 2.1.2 Hessian

$$H_{f} = \begin{bmatrix} f_{x_{1}x_{1}} & f_{x_{1}x_{2}} & \cdots & f_{x_{1}x_{n}} \\ f_{x_{2}x_{1}} & f_{x_{2}x_{2}} & \cdots & f_{x_{2}x_{n}} \\ \vdots & \vdots & \ddots & \vdots \\ f_{x_{m}x_{1}} & f_{x_{m}x_{2}} & \cdots & f_{x_{m}x_{m}} \end{bmatrix}$$

$$(25)$$

#### 2.1.3 Jacobian

$$D_{f} = \begin{bmatrix} \nabla f_{1} \\ \nabla f_{2} \\ \vdots \\ \nabla f_{n} \end{bmatrix} = \begin{bmatrix} f_{1x_{1}} & f_{1x_{2}} & \dots & f_{1x_{n}} \\ f_{2x_{1}} & f_{2x_{2}} & \dots & f_{2x_{n}} \\ \vdots & \vdots & \ddots & \vdots \\ f_{nx_{1}} & f_{nx_{2}} & \dots & f_{nx_{n}} \end{bmatrix}$$
(26)

#### 2.2 Taylor Expantion

$$f(x) \approx \sum_{i=0}^{n} \frac{f^{i}(a)(x-a)^{i}}{i!}$$
 (27)

## 2.3 Maclorian Expantion (a = 0)

**2.3.1**  $\sin(x)$ 

$$\sin(x) \approx \sum_{k=0}^{n} \frac{(-1)^k x^{2k+1}}{(2k+1)!}$$
 (28)

**2.3.2**  $\cos(x)$ 

$$\cos(x) \approx \sum_{k=0}^{n} \frac{(-1)^k x^{2k}}{(2k)!}$$
 (29)

**2.3.3**  $e^x$ 

$$e^x \approx \sum_{k=0}^n \frac{x^k}{k!} \tag{30}$$

**2.3.4**  $\ln|1+x|$ 

$$\ln|1+x| \approx \sum_{k=0}^{n} (-1)^k \frac{x^{k+1}}{k+1} \tag{31}$$

**2.3.5**  $c(\frac{1}{1-x})$ 

$$c(\frac{1}{1-x}) \approx c \sum_{k=0}^{n} x^k \tag{32}$$

## 2.4 Solving ODEs

#### 2.4.1 Intergrating Factor

$$\frac{dy}{dx} + P(x)y = Q(x) \tag{33}$$

$$I.F = e^{\int P(x)dx} \tag{34}$$

$$\frac{d}{dx}(e^{\int P(x)dx}y) = Q(x)e^{\int P(x)dx} \tag{35}$$

$$y = \frac{\int Q(x)e^{\int P(x)dx}dx}{e^{\int P(x)dx}}$$
 (36)

#### 2.4.2 Separation of Variables

$$\frac{dy}{dx} = g(x)h(y) \tag{37}$$

$$\frac{dy}{dx} = g(x)h(y)$$

$$\frac{dy}{dx} \frac{1}{h(y)} = g(x)$$
(38)

$$\int \frac{1}{h(y)} dy = \int g(x) dx \tag{39}$$

#### 2.4.3 Eulers Method

$$y_{n+1} = y_n + hf(x_n, y+n)$$
 (40)

$$x_{n+1} = x_n + h \tag{41}$$

## **Probability**

#### 3.0.1 Given That

$$P(A|B) = \frac{P(A \cap B)}{P(B)} \tag{42}$$

#### 3.0.2 Independence

$$P(A \cap B) = P(A)P(B) \tag{43}$$

#### 3.0.3 Law of Total Probability

$$P(A) = \sum_{n} P(A \cap B_n) = \sum_{n} P(A|B_n)P(B_n) = \sum_{n} P(B_n|A)P(A)$$
 (44)

#### 3.0.4 Bayes Theorm

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)} \tag{45}$$

#### **Markov Chains** 4