ETHAN LEW

https://eth0lew.com

TECHNICAL SKILLS

Research Experience **Programming** Libraries/Frameworks Formal Verification, Cyber-physical Systems, Data-driven Controls

Python, R, Rust, C/C++, LATEX, Bash

PyTorch, Tensorflow, Apache Spark, Gurobi, ONNX

WORK EXPERIENCE

Galois, Inc., 421 SW 6th Ave, Portland, OR 97204

2019-Present

Research Engineer

- · Excelled in developing research methodologies, writing sophisticated software prototypes, and exceeding project deliverables.
- · Contributed significant research and engineering to high-profile DARPA programs at the company: SSITH (2019-2021), Assured Autonomy (2019-2022), SDCPS (2021-2023), and Space-BACN (2022-Present).
- · Demonstrated expertise in system analysis and auditing, particularly in relation to the US Census Bureau's Disclosure Avoidance System (2021-Present).

Johns Hopkins APL, 11100 Johns Hopkins Rd, Laurel, MD 20723

2019

Electrical Engineering Intern

· Research Projects: troposcatter communication system feasibility, FDTD solver for bodies of revolution, and methods and benchmarks for an adaptive radar resource manager (RRM).

Summit Wireless Technologies, 20575 Von Neumann Dr., Beaverton, OR 97006 2018-2019 Electrical Engineering Intern

Contributed engineering across several teams including the development of a RF power meter, a Linux wireless driver, and the wireless audio stack core.

Portland State University, 1825 SW Broadway, Portland, OR 97201

2017

- Climate Research Intern
- · Research Project: Sensitivity of Global Methane Bayesian Inversion to Surface Observation Data Sets and Chemical-Transport Model Resolution.
- · Presented project at the Center for Climate and Aerosol Research (CCAR) symposium, Council on Undergraduate Research (CUR) symposium, and the American Geophysical Union (AGU) Fall Meeting.

EDUCATION

Portland State University, OR

June 2016 - June 2019

BS Electrical Engineering Summa Cum Laude

Portland Community College, OR

March 2015 - June 2017

Transfer Program

GPA: 4.00

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PROGRAM COMMITTEES

26th ACM International Conference on Hybrid Systems: Computation and Control 2021 Repeatability Evaluation Program Committee HSCC 2023

25th ACM International Conference on Hybrid Systems: Computation and Control 2021 Repeatability Evaluation Program Committee HSCC 2022

ADHS 2021

24th ACM International Conference on Hybrid Systems: Computation and Control 2021
Repeatability Evaluation Program Committee

HSCC 2021

PUBLICATIONS

Davis, E., Dey, S., Karvonen, A., Lew, E., Quick, D., Shyamshankar, P., Hille, T., and Lebeau, M. (2023). Leveraging manifold learning and relationship equity management for symbiotic explainable artificial intelligence. In *International Conference on Applied Human Factors and Ergonomics*, pages 490–510. AHFE International

Bak, S., Bogomolov, S., Hencey, B., Kochdumper, N., Lew, E., and Potomkin, K. (2022). Reachability of koopman linearized systems using random fourier feature observables and polynomial zonotope refinement. In *International Conference on Computer Aided Verification*, pages 490–510. Springer

AWARDS

Generalized RAcing Intelligence Competition (GRAIC) 1st Place Head-to-Head Category	$\begin{array}{c} 2022 \\ CPS\text{-}IoT \ Week \end{array}$
Electrical and Computer Engineering Capstone Poster Competition Best Overall Project	$\begin{array}{c} 2019 \\ PSU\ ECE \end{array}$
Intel Compute Stick Challenge 1st Place	$2016\\Intel$

PROJECTS

AutoKoopman: A Toolbox for Automated System Identification via Koopman Operator Linearization 2022-Present

· AutoKoopman is a python library for the use of Koopman operator methods for data-driven dynamical systems analysis and control. The library has convenient functions to learn systems using a few lines of code. It has a variety of linearization methods under shared class interfaces. These methods are pluggable into hyperparameter optimizers which can automate the process of model optimization.

Control System Analysis Framework (CSAF)

2019-Present

· CSAF is a framework to minimize the effort required to evaluate, implement, and verify controller design (classical and learning enabled) with respect to the system dynamics.

BESSPIN Automotive Demonstrator

2020-2021

• The BESSPIN CyberPhysical Demonstrator was developed under the DARPA SSITH Program. The demonstrator is intended to showcase the use of the SSITH secure hardware technology in a passenger vehicle. Visitors will experience driving a vehicle as it is being hacked, and the process of hacking an unprotected and a SSITH protected car.