

Question 1.

Let  $A = \begin{pmatrix} 1 & 0 & -1 & 1 \\ 1 & 1 & 1 & 0 \\ 2 & 1 & 0 & 1 \end{pmatrix}$ . Use row and column operations on  $A$  to obtain a matrix  $B$  of the form in Theorem 53. Use that work to find invertible matrices  $P, Q$  so that  $B = PAQ$ .

*Proof.* We perform the following row and column operations:

$$A = \begin{pmatrix} 1 & 0 & -1 & 1 \\ 1 & 1 & 1 & 0 \\ 2 & 1 & 0 & 1 \end{pmatrix} \xrightarrow[r_3 \rightarrow r_3 - 2r_1]{r_2 \rightarrow r_2 - r_1} \begin{pmatrix} 1 & 0 & -1 & 1 \\ 0 & 1 & 2 & -1 \\ 0 & 1 & 2 & -1 \end{pmatrix} \xrightarrow{r_3 \rightarrow r_3 - r_2} \begin{pmatrix} 1 & 0 & -1 & 1 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow[c_4 \rightarrow c_4 - c_1 + c_2]{c_3 \rightarrow c_3 + c_1 - 2c_2} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Define this matrix we obtained as  $B$ . We will perform the same row and column operations above on  $I_3$  and  $I_4$ , respectively in order to define  $P$  and  $Q$ . We have that

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow[r_3 \rightarrow r_3 - 2r_1]{r_2 \rightarrow r_2 - r_1} \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -2 & 0 & 1 \end{pmatrix}$$

$$\xrightarrow{r_3 \rightarrow r_3 - r_2} \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -1 & -1 & 1 \end{pmatrix}$$

and

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \xrightarrow[c_4 \rightarrow c_4 - c_1 + c_2]{c_3 \rightarrow c_3 + c_1 - 2c_2} \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & -2 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Let  $P = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -1 & -1 & 1 \end{pmatrix}$ ,  $Q = \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & -2 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$ . We see that

$$PAQ = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -1 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 & 1 \\ 1 & 1 & 1 & 0 \\ 2 & 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & -2 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & -1 & 1 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & -2 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\begin{aligned}
&= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \\
&= B
\end{aligned}$$

as required. □

### Question 2.

Let  $A = \begin{pmatrix} 1 & -2 & -4 \\ 1 & 1 & -1 \\ 1 & 0 & -1 \end{pmatrix}$ .

- (a) Verify that  $A$  is invertible, by row-reducing the augmented matrix  $(A|I_3)$ .
- (b) Use (a) to find  $A^{-1}$ .
- (c) Express  $A$  as a product of elementary matrices.

*Proof.*

(a): We see that

$$\begin{aligned}
(A|I_3) &= \left( \begin{array}{ccc|ccc} 1 & -2 & -4 & 1 & 0 & 0 \\ 1 & 1 & -1 & 0 & 1 & 0 \\ 1 & 0 & -1 & 0 & 0 & 1 \end{array} \right) \xrightarrow{r_2 \rightarrow r_2 - r_1, r_3 \rightarrow r_3 - r_1} \left( \begin{array}{ccc|ccc} 1 & -2 & -4 & 1 & 0 & 0 \\ 0 & 3 & 3 & -1 & 1 & 0 \\ 0 & 2 & 3 & -1 & 0 & 1 \end{array} \right) \\
&\xrightarrow{r_1 \rightarrow r_1 + r_3, r_2 \rightarrow r_2 - r_3} \left( \begin{array}{ccc|ccc} 1 & 0 & -1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 & -1 \\ 0 & 2 & 3 & -1 & 0 & 1 \end{array} \right) \xrightarrow{r_3 \rightarrow r_3 - 2r_2} \left( \begin{array}{ccc|ccc} 1 & 0 & -1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 & -1 \\ 0 & 0 & 3 & -1 & -2 & 3 \end{array} \right) \\
&\xrightarrow{r_1 \rightarrow r_1 + \frac{1}{3}r_3} \left( \begin{array}{ccc|ccc} 1 & 0 & 0 & -\frac{1}{3} & -\frac{2}{3} & 2 \\ 0 & 1 & 0 & 0 & 1 & -1 \\ 0 & 0 & 3 & -1 & -2 & 3 \end{array} \right) \xrightarrow{r_3 \rightarrow \frac{1}{3}r_3} \left( \begin{array}{ccc|ccc} 1 & 0 & 0 & -\frac{1}{3} & -\frac{2}{3} & 2 \\ 0 & 1 & 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & -\frac{1}{3} & -\frac{2}{3} & 1 \end{array} \right)
\end{aligned}$$

Since  $A$  can be row reduced into the identity matrix,  $A$  is invertible.

(b):

By our row reductions above, we know that  $A^{-1} = \begin{pmatrix} -\frac{1}{3} & -\frac{2}{3} & 2 \\ 0 & 1 & -1 \\ -\frac{1}{3} & -\frac{2}{3} & 1 \end{pmatrix}$ .

(c):

To express  $A$  as a product of elementary matrices, we can apply the opposite row operations to the identity matrix in reverse order. That is,

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & -\frac{1}{3} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

□

## Question 3.

Find the explicit formula for the linear transformation  $T : \mathbb{Q}^4 \rightarrow \mathbb{Q}^3$  which satisfies:

$$T \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \quad T \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \quad T \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}, \quad T \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

*Proof.* Notice that

$$\beta = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \right\}$$

is a basis for  $\mathbb{Q}^4$ . We attempt to find the general form for a vector  $(x, y, z, w) \in \mathbb{Q}^4$  in terms of these vectors. By inspection, we see that

$$\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = (x - 2y + z) \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + (y - z) \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + (z - w) \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix} + w \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

Thus

$$\begin{aligned} T \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} &= (x - 2y + z) T \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + (y - z) T \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + (z - w) T \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix} + w T \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \\ &= (x - 2y + z) \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + (y - z) \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} + (z - w) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} + w \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} x - 2y + z \\ 2x - 3y + z \\ 3x - 5y + 3z - w \end{pmatrix} \end{aligned}$$

□

## Question 4.

Let  $\mathbb{F} = \mathbb{Q}$  and  $V = \mathcal{M}_{2 \times 2}(\mathbb{F})$ . Consider the linear map  $T : \mathcal{M}_{2 \times 2}(\mathbb{F}) \rightarrow \mathcal{M}_{2 \times 2}(\mathbb{F})$  given by  $T(A) = A^T$ . Set  $\beta = \{E_{11}, E_{12}, E_{21}, E_{22}\}$  and  $\gamma = \{E_{11}, E_{22}, E_{12} + E_{21}, E_{12} - E_{21}\}$ .





### Question 5.

Let  $T : \mathcal{M}_{n \times n}(\mathbb{F}) \rightarrow \mathcal{M}_{n \times n}(\mathbb{F})$  be the linear map given by  $T(A) = A + A^T$ .

(a) Find  $N(T)$  and  $\dim N(T)$ .

We claim that  $N(T)$  is the set of all skew symmetric matrices with zeroes on the diagonal, which has dimension  $\frac{1}{2}n(n-1)$ .

Set  $T(A) = A + A^T = 0$ . We have that  $A_{ij} + A_{ji} = 0$  for each  $0 < i, j \leq n$ . In particular, we have that  $A_{ii} = 0$  if  $i = j$  and  $A_{ij} = -A_{ji}$  otherwise. But this describes exactly all skew symmetric matrices with zeroes on the diagonal. The basis for this set is

$$\beta = \{E_{ij} - E_{ji} : 0 < i < j \leq n\}$$

and there are  $\frac{1}{2}n(n-1)$  vectors in this set, so  $\dim N(T) = \frac{1}{2}n(n-1)$ .

(b) What is  $\text{im}(T)$ ?

We claim that  $\text{im}(T)$  is the set of all symmetric matrices  $S_n$ . We see that

$$(A + A^t)_{ij} = A_{ij} + A_{ij}^t = A_{ij} + A_{ji} = A_{ji} + A_{ji}^t = (A + A^t)_{ji}$$

so  $\text{im}(T) \subseteq S_n$ . To show set equality, suppose that  $B$  is a symmetric matrix. Let  $A = \frac{1}{2}B$  then

$$T(A) = \frac{1}{2}T(B) = \frac{1}{2}(B + B^t) = B$$

Thus  $\text{im}(T) = S_n$  and has basis

$$\gamma = \{E_{ij} : 0 < i \leq j \leq n\}.$$

and is dimension  $\frac{1}{2}n(n+1)$ .

(c) Is  $\mathcal{M}_{n \times n}(\mathbb{F}) = \text{im}(T) \oplus N(T)$ ?

Yes.

To show this, notice that  $\beta \cap \gamma = \emptyset$ , so  $\text{im}(T) \oplus N(T)$  has basis  $\alpha = \beta \cup \gamma$ . But notice that  $|\alpha| = \frac{1}{2}n(n-1) + \frac{1}{2}n(n+1) = n^2$ , which is the dimension of  $\mathcal{M}_n(\mathbb{F})$ . Therefore  $\alpha$  is actually a basis for  $\mathcal{M}_n(\mathbb{F})$  and thus  $\mathcal{M}_n(\mathbb{F}) = \text{im}(T) \oplus N(T)$ .

### Question 6.

Let  $V, W$  be vector spaces over a field  $\mathbb{F}$  and  $T : V \rightarrow W$  a linear map. Prove that  $T$  is injective if and only if  $N(T) = \{0_V\}$ . (Make no assumption here about  $\dim V, \dim W$ .)

*Proof.* Suppose that  $T$  is injective. Let  $T(x) = 0$ , for some  $x \in V$ . Recall that  $T(0) = 0$  for any linear map. Therefore by injectivity  $x = 0$ , so  $N(T) = \{0\}$ .

Conversely, suppose that  $N(T) = \{0\}$ . Let  $x, y \in V$  such that  $T(x) = T(y)$ . By linearity, we have that  $T(x - y) = 0$ , but this implies that  $x - y = 0$ , so  $x = y$  and  $T$  is injective.

□

### Question 7.

Let  $V, W$  be vector spaces over a field  $\mathbb{F}$ , and  $T : V \rightarrow W$  a linear map. Find a condition on  $T$  which is equivalent to " $T(S)$  spans  $W$  for any spanning set  $S \subseteq V$  of  $V$ ".  
(Hint: Write down the definition of  $T(S)$  is spanning to get started.)

*Proof.* We claim that this statement is equivalent to saying that  $T$  is surjective. Suppose that for any set  $S \subseteq V$  that spans  $V$ ,  $T(S)$  spans  $W$ . We prove that  $T$  is surjective. Let  $w \in W$ . We can write  $w$  as a linear combination of some number of vectors in  $T(S)$ . That is, for some  $k \in \mathbb{N}$  and  $s_i \in S$ ,  $c_i \in \mathbb{F}$ ,  $i \in \{1, \dots, k\}$ ,

$$w = \sum_{i=1}^k c_i T(s_i) = T \left( \sum_{i=1}^k c_i s_i \right)$$

so  $T$  is surjective.

Conversely, suppose that  $T$  is surjective. Let  $S$  be a spanning set of  $V$ . We will show that  $T(S)$  spans  $W$ . Let  $w \in W$ . By surjectivity, there exists  $v \in V$  so that  $T(v) = w$ . We can rewrite

$$v = \sum_{i=1}^k c_i s_i$$

for some number of vectors  $s_i \in S$  and  $c_i \in \mathbb{F}$ . Then

$$T \left( \sum_{i=1}^k c_i s_i \right) = w \implies \sum_{i=1}^k c_i T(s_i) = w$$

Notice that  $T(s_i) \in T(S)$ , from which it follows that  $T(S)$  spans  $W$ , and the proof is complete. □

### Question 8.

Let  $P \in \mathcal{M}_{n \times n}(\mathbb{F})$ . Prove the following three conditions are equivalent.

- (a)  $P$  is invertible.
- (b) There exists bases  $\beta, \gamma$  of  $\mathbb{F}^n$  so that  $P = [I_{\mathbb{F}^n}]_{\beta}^{\gamma}$ .
- (c) For any  $n$ -dimensional vector space  $V$  over  $\mathbb{F}$ , there exists bases  $\beta, \gamma$  of  $V$  so that  $P = [I_V]_{\beta}^{\gamma}$ .

*Proof.* Suppose (a). We prove (b) and (c) at the same time.





### Question 9.

Consider the relation  $\equiv$  on  $\mathcal{M}_{m \times n}(\mathbb{F})$  defined by  $A \equiv B$  if  $A \rightarrow B$  using a combination of row and/or column operations.

- (a) Prove that  $\equiv$  is an equivalence relation on  $\mathcal{M}_{m \times n}(\mathbb{F})$ .
- (b) Find a condition on  $A, B$  which is equivalent to  $A \equiv B$ . (Hint: Theorem 53.)
- (c) Classify the equivalence classes for this relation, and prove that there are exactly  $1 + \min\{n, m\}$  such classes.

*Proof.*

(a):

We show reflexivity, symmetry, and transitivity in that order.

Reflexivity: Since  $IA = A$ , and  $I$  is considered a row operation,  $A \equiv A$ .

Symmetry: Suppose that  $A \equiv B$  then for some invertible matrices  $P, Q$  we have that  $PAQ = B$ . But at the same time this means that  $P^{-1}BQ^{-1} = A$  so  $B \equiv A$ .

Transitivity: Suppose that  $A \equiv B$  and  $B \equiv C$ . Then for invertible matrices  $P, Q, R, S$ ,  $PAQ = B$  and  $RBS = C$ , so  $(RP)A(QS) = R(PAQ)S = RBS = C$ . Since  $RP, QS$  are also invertible, we have that  $A \equiv C$ .

(b):

We claim that an equivalent condition is  $\text{rank}A = \text{rank}B$ . Suppose that  $A \equiv B$ . Then  $PAQ = B$  for some invertible matrices  $P, Q$ , but it is known that rank is preserved by multiplication with invertible matrices, so  $\text{rank}A = \text{rank}PAQ = \text{rank}B$ .

Conversely, suppose that  $r := \text{rank}A = \text{rank}B$ . By Theorem 53, there exist row/column operations so that

$$A, B \rightarrow \left( \begin{array}{c|c} I_r & 0 \\ \hline 0 & 0 \end{array} \right).$$

We denote this matrix by  $J_r$ . that is, for invertible matrices  $P, Q, R, S$ ,  $PAQ = I' = RBS$ . It follows that  $R^{-1}PAQS^{-1} = B$ , so  $A \equiv B$  as desired.

(c):

We can classify the equivalence classes by matrix rank. That is, each equivalence class is of the form

$$[J_r] = \{A \in \mathcal{M}_{m \times n}(\mathbb{F}) : \text{rank}A = r\}.$$

The possible ranks of  $m \times n$  matrices range from 0 to  $\min\{n, m\}$ , so there are  $\min\{n, m\} + 1$  different values of  $r$ . We will verify that these equivalence classes are exhaustive and disjoint. Every  $m \times n$  matrix must have a rank, so it belongs to at least one of the classes, but at the same time, a matrix can possibly only have one rank, so it necessarily belongs to exactly one equivalence class.

□

### Question 10.

Let  $V, W$  be finite dimensional vector spaces over  $\mathbb{F}$ , and  $T : V \rightarrow W$  a linear map with  $\text{rank} T = 2$ . Set  $n = \dim V$ ,  $m = \dim W$ . Let  $\mathbf{x}_1, \mathbf{x}_2 \in \mathbb{F}^n$  be two non-parallel vectors. Prove there exists bases  $\beta, \gamma$  of  $V, W$  respectively, so that  $[T]_{\beta}^{\gamma} = (\mathbf{x}_1 \ \mathbf{x}_2 \ 0 \ \cdots \ 0)$ . (Hint: use problems 7,8.)

*Proof.* Define

$$A = (\mathbf{x}_1 \ \mathbf{x}_2 \ 0 \ \cdots \ 0)$$

$\text{rank } A = 2$  because there are 2 linearly independent rows. Fix two arbitrary bases  $\beta', \gamma'$  and consider  $[T]_{\beta'}^{\gamma'}$ , which is rank 2 by assumption. By question 9, we can perform a sequence of row and column operations to turn  $[T]_{\beta'}^{\gamma'}$  into  $A$ . In particular, for invertible matrices  $P \in \mathcal{M}_m(\mathbb{F}), Q \in \mathcal{M}_n(\mathbb{F})$ ,

$$P[T]_{\beta'}^{\gamma'}Q = A$$

Using question 8, and noting that the choice of  $\beta$  was arbitrary in its proof, we can say that  $P = [I_W]_{\gamma'}^{\gamma}$  and  $Q^{-1} = [I_V]_{\beta'}^{\beta}$  for some basis  $\gamma$  of  $W$  and  $\beta$  of  $V$ . Thus we have that

$$A = P[T]_{\beta'}^{\gamma'}Q = [I_W]_{\gamma'}^{\gamma}[T]_{\beta'}^{\gamma'}[I_V]_{\beta}^{\beta'} = [T]_{\beta}^{\gamma}$$

which is what we wanted. □

### Question 11.

Let  $T : V \rightarrow V$  be linear. We say that a subspace  $W \subseteq V$  is “ $T$ -invariant” if  $T(W) \subseteq W$ . For example, if  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  is counter-clockwise rotation around the  $z$ -axis by angle  $\theta$ , then  $P_{xy} = \{(x, y, 0) \in \mathbb{R}^3\}$  is  $T$ -invariant, as is  $L_z$  (the  $z$ -axis).

- Verify the claims made above, by showing that  $P_{xy}$  and  $L_z$  are  $T$ -invariant.
- Show that  $\mathbb{R}^3 = P_{xy} \oplus L_z$  by finding a basis  $\beta = \beta_1 \cup \beta_2$  for  $\mathbb{R}^3$  so that  $\beta_1$  is a basis for  $P_{xy}$  and  $\beta_2$  is a basis for  $L_z$ .
- Using your basis  $\beta$  from (b), find  $[T]_{\beta}$ .

*Proof.*

(a):

We begin by finding an expression for  $T$ . Notice that

$$\begin{aligned} T(e_1) &= (\cos \theta, \sin \theta, 0) \\ T(e_2) &= (-\sin \theta, \cos \theta, 0) \\ T(e_3) &= (0, 0, 1) \end{aligned}$$

In the case of  $e_1, e_2$ , the projection onto the  $xy$ -plan lies on the unit circle, and thus each vector is rotated  $\theta$  and  $\theta + \frac{\pi}{2}$  radians respectively (relative to the point  $(0, 1)$ ). Then we have that

$$\begin{aligned} T(x, y, z) &= x(\cos \theta, \sin \theta, 0) + y(-\sin \theta, \cos \theta, 0) + z(0, 0, 1) \\ &= (x \cos \theta - y \sin \theta, x \sin \theta + y \cos \theta, z) \end{aligned}$$

Now, let  $(x, y, 0) \in P_{xy}$ . Then

$$T(x, y, 0) = (x \cos \theta - y \sin \theta, x \sin \theta + y \cos \theta, 0) \in P_{xy}$$

Additionally, let  $(0, 0, z) \in L_z$ . Then

$$T(0, 0, z) = (0, 0, z) \in L_z$$

Thus  $P_{xy}$  and  $L_z$  are  $T$ -invariant subspaces.

(b):

Let  $\beta_1 = \{e_1, e_2\}, \beta_2 = \{e_3\}$ . It is clear that  $\beta_1$  is a basis for the  $xy$ -plane and  $\beta_2$  is a basis for the  $z$ -axis. Then  $\beta = \{e_1, e_2, e_3\}$  is the standard ordered basis for  $\mathbb{R}^3$ , which was what we wanted to show.

(c):

We have already found all we need from the previous parts:

$$[T]_\beta = ([T(e_1)]_\beta \quad [T(e_2)]_\beta \quad [T(e_3)]_\beta) = \begin{pmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

□

## Question 12.

Let  $V$  be a finite dimensional vector space over  $\mathbb{F}$ ,  $T \in \mathcal{L}(V)$ , and  $W_1 \subseteq V$  a  $T$ -invariant subspace with basis  $\beta_1$ . Set  $k = \dim W_1$ .

We will generalize what we saw in #11c.

(a) Extend  $\beta_1$  to a basis  $\beta$  of  $V$ . Show that  $[T]_\beta = \left( \begin{array}{c|c} A & C \\ \hline O_{n-k,k} & B \end{array} \right)$ , where  $A$  is  $k \times k$ ,  $B$  is  $(n - k) \times (n - k)$ , and  $C$  is  $k \times (n - k)$ .

(b) Suppose that  $W_2$  is a subspace so that  $V = W_1 \oplus W_2$ . Let  $\beta = \beta_1 \cup \beta_2$ , where  $\beta_2$  is any basis for  $W_2$ .

Prove that if  $W_2$  is  $T$ -invariant, then  $[T]_\beta = \left( \begin{array}{c|c} A & O_{k,n-k} \\ \hline O_{n-k,k} & B \end{array} \right)$  is block diagonal.

(c) Is the converse of (b) true or false? Justify your answer.

*Proof.*

(a):

Let  $n = \dim V$ . Let  $\beta_1 = \{v_1, \dots, v_k\}$  be a basis for  $W_1$ . Let  $\beta = \{v_1, \dots, v_k, v_{k+1}, \dots, v_n\}$  be the basis obtained from extending  $\beta_1$ . To show that  $[T]_\beta = \left( \begin{array}{c|c} A & C \\ \hline O_{n-k,k} & B \end{array} \right)$ , we are unconcerned about the matrices on the right hand side, so we only focus on the left side of the matrix. Consider the  $i$ th column of  $[T]_\beta$ , where  $1 \leq i \leq k$ . This is equal to  $[T(v_i)]_\beta$ . Since  $W_1$  is  $T$ -invariant,  $T(v_i) \in W_1$ , so it can be expressed as a linear combination of exclusively vectors in  $\beta_1$ . Thus

$$[T(v_i)]_\beta = \begin{pmatrix} a_{1i} \\ \vdots \\ a_{ki} \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

where  $a_{ji} \in \mathbb{F}$  and the bottom  $n - k$  entries are 0. Since this is true for all columns 1 to  $k$ , the statement is proven.

(b):

Now take  $W_2$  to be a  $T$ -invariant subspace so that  $V = W_1 \oplus W_2$ . Let  $\beta = \beta_1 \cup \beta_2$ , where  $\beta_1, \beta_2$  are bases for  $W_1, W_2$  respectively. To show that  $\left( \begin{array}{c|c} A & O_{k,n-k} \\ \hline O_{n-k,k} & B \end{array} \right)$ , it suffices to show the right sides are equivalent, as we have proved the left side in the previous part. The argument is very similar to before, so we will be brief. For each  $T(v_i)$ , where  $v_i \in W_2$ , the representation as a linear combination does not use any vectors from  $W_1$ , so the first  $k$  entries of  $[T(v_i)]_\beta$  are guaranteed to be 0 as required.

(c):

The converse is true. Suppose that  $[T]_\beta = \left( \begin{array}{c|c} A & O_{k,n-k} \\ \hline O_{n-k,k} & B \end{array} \right)$  is block diagonal. Let  $v \in W_2$ . Write  $v = \sum_{i=k+1}^n a_i v_i$  as a linear combination of vectors in  $\beta_2$ . It follows that

$$T(v) = \sum_{i=k+1}^n a_i T(v_i) = \sum_{i=k+1}^n a_i \sum_{j=k+1}^n b_{ij} v_j \in W_2$$

thus verifying that  $W_2$  is  $T$ -invariant. □

### Question 13.

Determine if the statements below are true or false. If true, give a proof. If false, explain why, and/or provide a counterexample.

(a) Let  $\beta = \{e_1, \dots, e_n\}$  be the standard basis for  $\mathbb{F}^n$ , and  $\gamma = \{v_1, \dots, v_n\}$  a basis for

