

Linear Programming And The Simplex Algorithm

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What Is Linear Programming?

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- Linear programming is an optimization technique where we assign values to variables constrained by linear relationships.
- Linear programming problems often appear in applications such as operations research and finance.
- Problems will often come in the flavor of finding the best way to allocate resource under certain constraints.

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- You have the following resource budget:

	Corn	Soybeans	Available
Fertilizer/herbicide	9 gal/acre	3 gal/acre	40500 gal
Harvesting labor	$\frac{3}{4}$ hr/acre	1 hr/acre	5250 hr
Profit	240 \$/acre	160 \$/acre	

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- **How do you optimally plant corn and soybeans to maximize profit?**

Example (cont.)

We can write this optimization problem as

$$\begin{array}{llll} \max & 240x_1 + 160x_2 & & \text{(Profit function)} \\ \text{s.t.} & 9x_1 + 3x_2 \leq 40500 & & \text{(Fertilizer/herbicide constraint)} \\ & \frac{3}{4}x_1 + x_2 \leq 5250 & & \text{(Labor constraint)} \\ & x_1 + x_2 \leq 6000 & & \text{(Land constraint)} \\ & x_1, x_2 \geq 0 & & \text{(Non-negativity constraint)} \end{array}$$

where your job is to find the best possible assignment of x_1 and x_2 which represent the amount of corn and soybeans you plant, respectively.

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where A is an $m \times n$ matrix, x and c are n dimensional column vectors, and b is an m dimensional column vector.

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Remark

Let b and b' are m dimensional vectors. By $b \leq b'$, we mean that for all $i = 1, 2, \dots, m$

$$b_i \leq b'_i$$

Formalism Made Concrete

Original linear program:

$$\begin{array}{ll}\max & 240x_1 + 160x_2 \\ \text{s.t.} & 9x_1 + 3x_2 \leq 40500 \\ & \frac{3}{4}x_1 + x_2 \leq 5250 \\ & x_1 + x_2 \leq 6000 \\ & x_1, x_2 \geq 0\end{array}$$

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Standard form:

$$\max \quad \overbrace{\begin{bmatrix} 240 \\ 160 \end{bmatrix}}^{c^T} \overbrace{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}}^x$$

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 - Feasible ... optimal solution has finite objective value
 - Infeasible ... no solutions
 - Unbounded ... the objective value can be made infinite

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Is Standard Form Too Restrictive?

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- What if we want to *minimize* the objective function?
- What if we want variables to be *unbounded*?
- What if we want variables to *lie in an interval*?
- What if we want constraints to use \geq or $=$?
- **All of these situations can be reformulated into a standard form equivalent!**

Example

Consider

$$x_1 + x_2 \leq 6000$$

Slack Form Intuition

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$$x_1 + x_2 \leq 6000$$

then

$$0 \leq \underbrace{6000 - x_1 - x_2}_s$$

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$$0 \leq \underbrace{6000 - x_1 - x_2}_s$$

where s is the “slack” we have in increasing $x_1 + x_2$ until the constraint is violated.

Slack Form

From the standard form we can construct the slack form:

$$\begin{array}{ll}\max & c^T x \\ \text{s.t.} & s = b - Ax \\ & x, s \geq 0\end{array}$$

where s holds the “slack” variables which are added.

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- *Note: As you solve a linear program, the nonbasic and basic variables will change.*

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- *Note: Only nonbasic variables appear in the objective function*
- *Note: As you solve a linear program, the nonbasic and basic variables will change.*
- *Note: Slack form makes solving linear programs easier.*

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Interesting Theoretical Remarks

- The ability to solve linear programs in polynomial time means we have algorithms to solve problems reduced to linear programs quickly!

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Interesting Theoretical Remarks

- The ability to solve linear programs in polynomial time means we have algorithms to solve problems reduced to linear programs quickly!
- Restricting the variables to integers makes solving linear programs **NP-Hard**! (*3-CNF-SAT can be reduced to determining if an integer linear program is feasible*)

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- Third Constraint: x_1 can be at most $6000/1 = 6000$
- Leaving Variable: s_1

Simplex Example (cont.)

Increasing x_1 as much as possible means $s_1 = 0$ (there is no more “slack”), and we can turn s_1 nonbasic and x_1 basic:

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We now substitute all occurrences of x_1 to get

$$\begin{array}{ll}\max & -\frac{80}{3}s_1 + 80x_2 + 1080000 \\ \text{s.t.} & x_1 = 4500 - \frac{1}{9}s_1 - \frac{1}{3}x_2 \\ & s_2 = 1875 + \frac{1}{12}s_1 - \frac{3}{4}x_2 \\ & s_3 = 1500 + \frac{1}{9}s_1 - \frac{2}{3}x_2 \\ & x_1, x_2, s_1, s_2, s_3 \geq 0\end{array}$$

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We now repeat this process ...

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- Basic Solution: $(x_1, x_2, s_1, s_2, s_3) = (4500, 0, 0, 1875, 1500)$

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- Entering Variable: x_2

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Simplex Example (cont.)

$$\begin{array}{ll}\max & -\frac{80}{3}s_1 + 80x_2 + 1080000 \\ \text{s.t.} & x_1 = 4500 - \frac{1}{9}s_1 - \frac{1}{3}x_2 \\ & s_2 = 1875 + \frac{1}{12}s_1 - \frac{3}{4}x_2 \\ & s_3 = 1500 + \frac{1}{9}s_1 - \frac{2}{3}x_2 \\ & x_1, x_2, s_1, s_2, s_3 \geq 0\end{array}$$

- Basic Solution: $(x_1, x_2, s_1, s_2, s_3) = (4500, 0, 0, 1875, 1500)$
- Basic Solution Value: 1080000
- Entering Variable: x_2
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After pivoting we get ...

Simplex Example (cont.)

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- Basic Solution Value: 1260000
- We stop now because we cannot increase the objective function anymore.
- It turns out that this is the optimal solution!
- We should plant $x_1 = 3750$ acres of corn and $x_2 = 2250$ acres of soybeans yielding a profit of \$1,260,000.

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5. Go back to Step 2 and if an entering variable cannot be found, stop.
6. The basic solution is optimal so return it.

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Our Implementation Goals

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- Abstract away technical details of doing tedious transformations
- Use type-system to force users to use interface correctly
- Create test cases to validate our implementation

Our Implementation Usage Example

Creating a linear program:

```
LinearProgram p = new LinearProgram();  
Variable corn = p.registerNonnegativeVariable("corn");  
Variable soybeans = p.registerNonnegativeVariable("soybeans");
```

Our Implementation Usage Example

Adding constraints:

```
p.addConstraint(new Constraint(  
    new ArrayList<>(Arrays.asList(corn, soybeans)),  
    new ArrayList<>(Arrays.asList(9.0, 3.0)),  
    Relation.LEQ,  
    40500  
));  
p.addConstraint(new Constraint(  
    new ArrayList<>(Arrays.asList(corn, soybeans)),  
    new ArrayList<>(Arrays.asList(3.0/4.0, 1.0)),  
    Relation.LEQ,  
    5250  
));  
p.addConstraint(new Constraint(  
    new ArrayList<>(Arrays.asList(corn, soybeans)),  
    new ArrayList<>(Arrays.asList(1.0, 1.0)),  
    Relation.LEQ,  
    6000  
));
```

Our Implementation Usage Example

Adding objective function:

```
p.setObjective(new ObjectiveFunction(  
    ObjectiveGoal.MAXIMIZE,  
    new ArrayList<>(Arrays.asList(corn, soybeans)),  
    new ArrayList<>(Arrays.asList(240.0, 160.0))  
));
```

Our Implementation Usage Example

Getting the solution:

```
System.out.println("Optimal profit: " + p.getObjectiveValue());  
System.out.println("Corn: " + p.evaluateVariable(corn));  
System.out.println("Soybeans: " + p.evaluateVariable(soybeans));
```


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4. Convert the answer found for \mathcal{L}' back into an answer in \mathcal{L}

- Used exercises from a textbook¹ and checked with the answers in the back of the book

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- Used problems from the section on solving systems of difference constraints in CLRS
- Recasted example maximum flow problems in CLRS into linear programs
- Created stress tester that randomly generates maximum flow problems and validated solution with Max-Flow Min-Cut Theorem

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- Maximize total flow out of the source s : $\sum_{v \in V} f_{sv} - f_{vs}$
- All constraints and the objective function are linear relationships on the variables which means finding a maximum flow is reduced to solving a linear program!

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- Generate large randomized flow network parameterized by n and k (Figure 1)

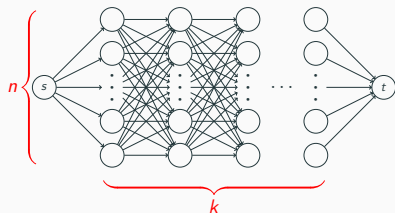


Figure 1: Stress test network architecture

Stress Testing Our Implementation

- Large linear programs may expose implementation issues
- How do we generate large linear programs and also validate the answer?
- Generate large randomized flow network parameterized by n and k (Figure 1)
- Max-Flow Min-Cut Theorem says that validating a maximum flow amounts to finding the non-existence of an augmenting path!

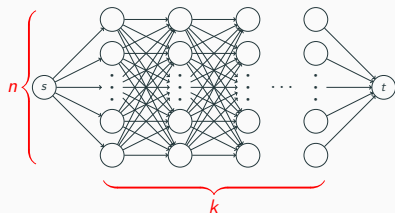


Figure 1: Stress test network architecture

Thanks!

Thanks for listening!

- Implementation Code: <https://github.com/EthanTheMaster/LinearProgrammingSimplexAlgorithm>