



CAL POLY

EE 367 Final Lab

Design and Analysis of a DTMF Decoding System

Report by:

Ethan Vosburg (evosburg@calpoly.edu)

Isaac Lake (ilake@calpoly.edu)

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1 Documentation

Summary of our results: We prepared to implement all of our filters to complete the project when we realized we could skip that step and just run peak detectors. Our final ISI error was 7.1%. Because of our solution, we solved the need for filters thus we required 0 bits for them.

1. High-Level block diagram

Our solution to the project reads the sample creates a buffer, takes the DFT of that buffer, and uses peak detectors to find the peak on the upper and lower half of the frequency chart, sends those peaks into a simple logic brick that will find and output the corresponding symbol.

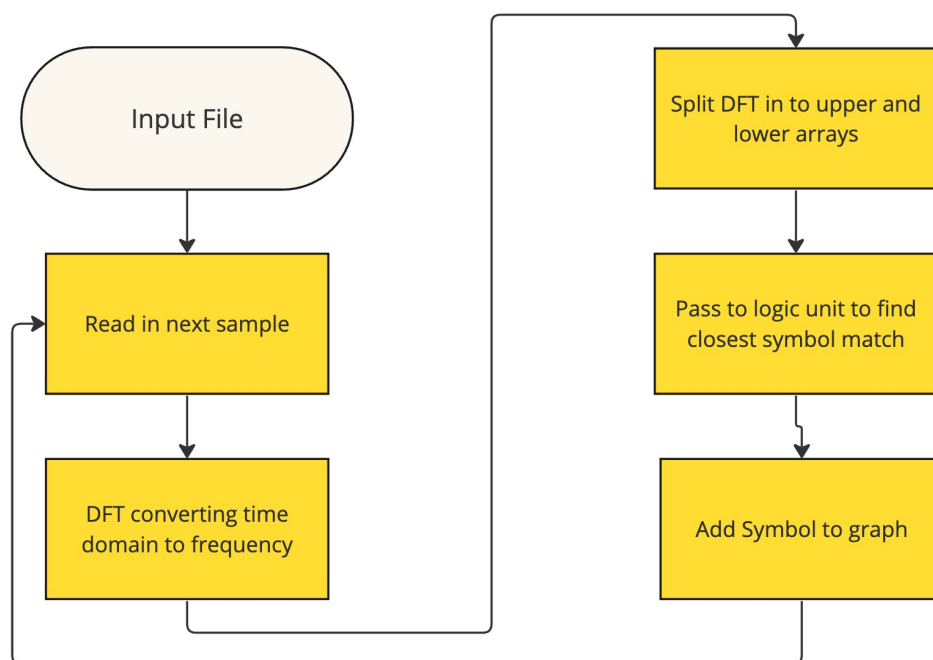


Figure 1: High-level block diagram

2. Python source code used to implement your system.

Listing 1: Python DTMF

```

1  #!/usr/bin/python
2
3  import sys
4  import time
5
6  import base64
7  import random as random
8
9  import datetime
10 import time
11 import math
12
13 import matplotlib.pyplot as plt
14 import numpy as np
15
16 from cpe367_wav import cpe367_wav
17 from cpe367_sig_analyzer import cpe367_sig_analyzer
18
19 from my_fifo import my_fifo
20 from tqdm import tqdm
21 from LogicUnit import LogicUnit
22
23
24 #####
25 #####
26 # define routine for detecting DTMF tones
27 def process_wav(fpath_sig_in):
28
29
30     #####
31     # define list of signals to be displayed by and analyzer
32     # note that the signal analyzer already includes: 'symbol_val', 'symbol_det', 'error'
33     more_sig_list = ['sig_1', 'sig_2']
34
35     # sample rate is 4kHz
36     fs = 4000
37     # 30 is best
38     fifoSize = 30
39     multiRatio = fs // fifoSize
40
41     # Create fifo
42     buffer = my_fifo(fifoSize)
43
44     # instantiate signal analyzer and load data
45     s2 = cpe367_sig_analyzer(more_sig_list, fs)
46     s2.load(fpath_sig_in)
47     s2.print_desc()
48
49     #####
50     # students: setup filters
51
52     # process input
53     xin = 0
54     for n_curr in tqdm(range(s2.get_len()), desc="Processing..."):
55
56         # read next input sample from the signal analyzer
57         xin = s2.get('xin', n_curr)
58
59         buffer.update(xin)
60         magnitudeArray = []
61
62         for i in range(buffer.get_size()):
63             magnitudeArray.append(buffer.get(i))
64
65         dftList = dft(magnitudeArray)

```

```

66     lowerMax = np.argmax(dftList[:len(dftList)//2])
67     upperMax = np.argmax(dftList[len(dftList)//2:] + len(dftList)//2
68     # print(buffer.get_size())
69     # print(len(dftList))
70     # print(dftList)
71
72     symbol_val_det = LogicUnit(lowerMax * multiRatio, upperMax * multiRatio).symbol()
73
74     # save intermediate signals as needed, for plotting
75     # add signals, as desired!
76     s2.set('sig_1',n_curr,xin)
77     s2.set('sig_2',n_curr,2 * xin)
78
79     # save detected symbol
80     s2.set('symbol_det',n_curr,symbol_val_det)
81
82     # get correct symbol (provided within the signal analyzer)
83     symbol_val = s2.get('symbol_val',n_curr)
84
85     # compare detected signal to correct signal
86     symbol_val_err = 0
87     if symbol_val != symbol_val_det: symbol_val_err = 1
88
89     # save error signal
90     s2.set('error',n_curr,symbol_val_err)
91
92
93     # display mean of error signal
94     err_mean = s2.get_mean('error')
95     print('mean error = '+str( round(100 * err_mean,1) )+'%')
96
97     # define which signals should be plotted
98     plot_sig_list = ['sig_1','sig_2','symbol_val','symbol_det','error']
99
100    # plot results
101    s2.plot(plot_sig_list)
102
103    return True
104
105    #####
106    #####
107    # define DFT function
108    def dft(sampleValues):
109        # Initialize variables
110        dftList = []
111        n = 0
112
113        for sample in range(len(sampleValues)//2):
114            # Initialize resetting variables
115            dftCalcArray = []
116            imag = 0
117            real = 0
118
119            # Perform DFT calculation
120            for k in range(len(sampleValues) - 1):
121                imag += sampleValues[k] * np.sin(-2 * math.pi * k * n / len(sampleValues))
122                real += sampleValues[k] * np.cos(-2 * math.pi * k * n / len(sampleValues))
123            dftList.append(np.sqrt(imag**2 + real**2) / (len(sampleValues)//2))
124            # print(f"Sample {sample}: {dftList[sample]} and {sampleValues[sample]}")
125            n+=1
126
127        return dftList
128
129
130
131
132    #####
133    #####
134    # define main program
135    def main():

```

```
136
137 # check python version!
138 major_version = int(sys.version[0])
139 if major_version < 3:
140     print('Sorry! must be run using python3.')
141     print('Current version: ')
142     print(sys.version)
143     return False
144
145 # assign file name
146 fpath_sig_in = 'Final Lab/source/input/DTMF Signals Slow.txt'
147 # fpath_sig_in = 'Final Lab/source/input/DTMF Signals Fast.txt'
148
149
150 # let's do it!
151 return process_wav(fpath_sig_in)
152
153
154
155
156 #####
157 #####
158 # call main function
159 if __name__ == '__main__':
160
161     main()
162     quit()
```

Listing 2: Logic Unit for Getting Symbols from Frequency

```
1 import numpy as np
2
3 class LogicUnit:
4
5     def __init__(self, lowerMax, upperMax):
6         self.lowerMax = lowerMax
7         self.upperMax = upperMax
8
9     def symbol(self):
10         lowerArray = [697, 770, 852, 941]
11         self.lowerDiffs = np.abs(lowerArray - self.lowerMax)
12         upperArray = [1209, 1336, 1477, 1633]
13         self.upperDiffs = np.abs(upperArray - self.upperMax)
14
15         two_d_array = [
16             [1, 2, 3, 'a'],
17             [4, 5, 6, 'b'],
18             [7, 8, 9, 'c'],
19             ['*', 0, '#', 'd']
20         ]
21         return two_d_array[np.argmin(self.lowerDiffs)][np.argmin(self.upperDiffs)]
```

3. Generated Analysis Data

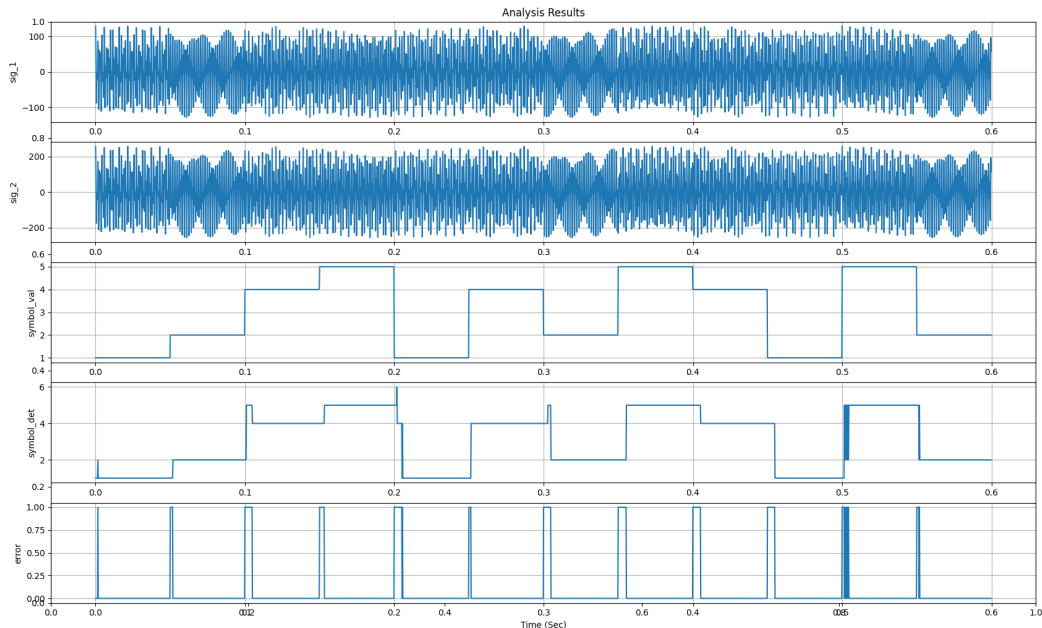


Figure 2: Analysis Results

4. Filters (While we did not end up using them these are the filters we made)

Listing 3: 697HZ BP

```

1 function y = BP697(x)
2 %DOFILTER Filters input x and returns output y.
3
4 % MATLAB Code
5 % Generated by MATLAB(R) 23.2 and DSP System Toolbox 23.2.
6 % Generated on: 05-Mar-2024 13:08:57
7
8 %#codegen
9
10 % To generate C/C++ code from this function use the codegen command.
11 % Type 'help codegen' for more information.
12
13 persistent Hd;
14
15 if isempty(Hd)
16     % The following code was used to design the filter coefficients:
17     %
18     % Fstop1 = 620;    % First Stopband Frequency
19     % Fpass1 = 680;    % First Passband Frequency
20     % Fpass2 = 710;    % Second Passband Frequency
21     % Fstop2 = 780;    % Second Stopband Frequency
22     % Astop1 = 6;      % First Stopband Attenuation (dB)
23     % Apass = 1;       % Passband Ripple (dB)
24     % Astop2 = 6;      % Second Stopband Attenuation (dB)
25     % Fs = 4000;       % Sampling Frequency
26     %
27     % h = fdesign.bandpass('fst1,fp1,fp2,fst2,ast1,ap,ast2', Fstop1, Fpass1, ...
28     %                     Fpass2, Fstop2, Astop1, Apass, Astop2, Fs);
29

```

```

30      %
31      % Hd = design(h, 'butter', ...
32      %      'MatchExactly', 'passband', ...
33      %      'SystemObject', true,...
34      %      UseLegacyBiquadFilter=true);
35
36      Hd = dsp.BiquadFilter( ...
37      'Structure', 'Direct form II', ...
38      'SOSMatrix', [1 0 -1 1 -0.881385021996587 0.911473662795519], ...
39      'ScaleValues', [0.0442631686022406; 1]);
40  end
41
42  s = double(x);
43  y = step(Hd,s);

```

Listing 4: 770HZ BP

```

1  function y = BP770(x)
2  %DOFILTER Filters input x and returns output y.
3
4  % MATLAB Code
5  % Generated by MATLAB(R) 23.2 and DSP System Toolbox 23.2.
6  % Generated on: 05-Mar-2024 13:07:06
7
8  %#codegen
9
10 % To generate C/C++ code from this function use the codegen command.
11 % Type 'help codegen' for more information.
12
13 persistent Hd;
14
15 if isempty(Hd)
16
17     % The following code was used to design the filter coefficients:
18     %
19     % Fstop1 = 700;    % First Stopband Frequency
20     % Fpass1 = 750;    % First Passband Frequency
21     % Fpass2 = 790;    % Second Passband Frequency
22     % Fstop2 = 840;    % Second Stopband Frequency
23     % Astop1 = 6;      % First Stopband Attenuation (dB)
24     % Apass = 1;       % Passband Ripple (dB)
25     % Astop2 = 6;      % Second Stopband Attenuation (dB)
26     % Fs = 4000;      % Sampling Frequency
27     %
28     % h = fdesign.bandpass('fst1,fp1,fp2,fst2,ast1,ap,ast2', Fstop1, Fpass1, ...
29     %                     Fpass2, Fstop2, Astop1, Apass, Astop2, Fs);
30     %
31     % Hd = design(h, 'butter', ...
32     %      'MatchExactly', 'passband', ...
33     %      'SystemObject', true,...
34     %      UseLegacyBiquadFilter=true);
35
36     Hd = dsp.BiquadFilter( ...
37     'Structure', 'Direct form II', ...
38     'SOSMatrix', [1 0 -1 1 -0.666157014109844 0.883665323160146], ...
39     'ScaleValues', [0.0581673384199269; 1]);
40 end
41
42 s = double(x);
43 y = step(Hd,s);

```

Listing 5: 852HZ BP

```

1  function y = BP852(x)
2  %DOFILTER Filters input x and returns output y.
3

```



```

4 % MATLAB Code
5 % Generated by MATLAB(R) 23.2 and DSP System Toolbox 23.2.
6 % Generated on: 05-Mar-2024 13:10:47
7
8 %#codegen
9
10 % To generate C/C++ code from this function use the codegen command.
11 % Type 'help codegen' for more information.
12
13 persistent Hd;
14
15 if isempty(Hd)
16     % The following code was used to design the filter coefficients:
17     %
18     % Fstop1 = 790; % First Stopband Frequency
19     % Fpass1 = 840; % First Passband Frequency
20     % Fpass2 = 870; % Second Passband Frequency
21     % Fstop2 = 920; % Second Stopband Frequency
22     % Astop1 = 6; % First Stopband Attenuation (dB)
23     % Apass = 1; % Passband Ripple (dB)
24     % Astop2 = 6; % Second Stopband Attenuation (dB)
25     % Fs = 4000; % Sampling Frequency
26     %
27     % h = fdesign.bandpass('fst1,fp1,fp2,fst2,ast1,ap,ast2', Fstop1, Fpass1, ...
28     %                     Fpass2, Fstop2, Astop1, Apass, Astop2, Fs);
29     %
30     % Hd = design(h, 'butter', ...
31     %             'MatchExactly', 'passband', ...
32     %             'SystemObject', true,...
33     %             'UseLegacyBiquadFilter=true');
34
35     Hd = dsp.BiquadFilter( ...
36         'Structure', 'Direct form II', ...
37         'SOSMatrix', [1 0 -1 1 -0.431733010683812 0.911473662795518], ...
38         'ScaleValues', [0.044263168602241; 1]);
39
40 end
41
42 s = double(x);
43 y = step(Hd,s);

```

Listing 6: 941HZ BP

```

1 function y = BP941(x)
2 %DOFILTER Filters input x and returns output y.
3
4 % MATLAB Code
5 % Generated by MATLAB(R) 23.2 and DSP System Toolbox 23.2.
6 % Generated on: 05-Mar-2024 13:11:50
7
8 %#codegen
9
10 % To generate C/C++ code from this function use the codegen command.
11 % Type 'help codegen' for more information.
12
13 persistent Hd;
14
15 if isempty(Hd)
16     % The following code was used to design the filter coefficients:
17     %
18     % Fstop1 = 870; % First Stopband Frequency
19     % Fpass1 = 920; % First Passband Frequency
20     % Fpass2 = 960; % Second Passband Frequency
21     % Fstop2 = 1010; % Second Stopband Frequency
22     % Astop1 = 6; % First Stopband Attenuation (dB)
23     % Apass = 1; % Passband Ripple (dB)
24     % Astop2 = 6; % Second Stopband Attenuation (dB)
25

```

```

26 % Fs      = 4000; % Sampling Frequency
27 %
28 % h = fdesign.bandpass('fst1,fp1,fp2,fst2,ast1,ap,ast2', Fstop1, Fpass1, ...
29 %                      Fpass2, Fstop2, Astop1, Apass, Astop2, Fs);
30 %
31 % Hd = design(h, 'butter', ...
32 %             'MatchExactly', 'passband', ...
33 %             'SystemObject', true,...
34 %             UseLegacyBiquadFilter=true);
35
36 Hd = dsp.BiquadFilter( ...
37     'Structure', 'Direct form II', ...
38     'SOSMatrix', [1 0 -1 1 -0.17735608093889 0.883665323160146], ...
39     'ScaleValues', [0.058167338419927; 1]);
40 end
41
42 s = double(x);
43 y = step(Hd,s);

```

Listing 7: 1209HZ BP

```

1 function y = BP1209(x)
2 %DOFILTER Filters input x and returns output y.
3
4 % MATLAB Code
5 % Generated by MATLAB(R) 23.2 and DSP System Toolbox 23.2.
6 % Generated on: 05-Mar-2024 13:13:13
7
8 %#codegen
9
10 % To generate C/C++ code from this function use the codegen command.
11 % Type 'help codegen' for more information.
12
13 persistent Hd;
14
15 if isempty(Hd)
16
17     % The following code was used to design the filter coefficients:
18     %
19     % Fstop1 = 1140; % First Stopband Frequency
20     % Fpass1 = 1190; % First Passband Frequency
21     % Fpass2 = 1230; % Second Passband Frequency
22     % Fstop2 = 1280; % Second Stopband Frequency
23     % Astop1 = 6; % First Stopband Attenuation (dB)
24     % Apass = 1; % Passband Ripple (dB)
25     % Astop2 = 6; % Second Stopband Attenuation (dB)
26     % Fs      = 4000; % Sampling Frequency
27     %
28     % h = fdesign.bandpass('fst1,fp1,fp2,fst2,ast1,ap,ast2', Fstop1, Fpass1, ...
29     %                      Fpass2, Fstop2, Astop1, Apass, Astop2, Fs);
30     %
31     % Hd = design(h, 'butter', ...
32     %             'MatchExactly', 'passband', ...
33     %             'SystemObject', true,...
34     %             UseLegacyBiquadFilter=true);
35
36     Hd = dsp.BiquadFilter( ...
37         'Structure', 'Direct form II', ...
38         'SOSMatrix', [1 0 -1 1 0.610453230045989 0.883665323160146], ...
39         'ScaleValues', [0.058167338419927; 1]);
40 end
41
42 s = double(x);
43 y = step(Hd,s);

```

Listing 8: 1336HZ BP

```
1 function y = BP1336(x)
2 %DOFILTER Filters input x and returns output y.
3
4 % MATLAB Code
5 % Generated by MATLAB(R) 23.2 and DSP System Toolbox 23.2.
6 % Generated on: 05-Mar-2024 13:14:08
7
8 %#codegen
9
10 % To generate C/C++ code from this function use the codegen command.
11 % Type 'help codegen' for more information.
12
13 persistent Hd;
14
15 if isempty(Hd)
16
17     % The following code was used to design the filter coefficients:
18     %
19     % Fstop1 = 1270; % First Stopband Frequency
20     % Fpass1 = 1320; % First Passband Frequency
21     % Fpass2 = 1360; % Second Passband Frequency
22     % Fstop2 = 1410; % Second Stopband Frequency
23     % Astop1 = 6; % First Stopband Attenuation (dB)
24     % Apass = 1; % Passband Ripple (dB)
25     % Astop2 = 6; % Second Stopband Attenuation (dB)
26     % Fs = 4000; % Sampling Frequency
27     %
28     % h = fdesign.bandpass('fst1,fp1,fp2,fst2,ast1,ap,ast2', Fstop1, Fpass1, ...
29     %                     Fpass2, Fstop2, Astop1, Apass, Astop2, Fs);
30     %
31     % Hd = design(h, 'butter', ...
32     %             'MatchExactly', 'passband', ...
33     %             'SystemObject', true,...
34     %             'UseLegacyBiquadFilter=true');
35
36     Hd = dsp.BiquadFilter( ...
37         'Structure', 'Direct form II', ...
38         'SOSMatrix', [1 0 -1 1 0.959337037818403 0.883665323160145], ...
39         'ScaleValues', [0.0581673384199272; 1]);
40 end
41
42 s = double(x);
43 y = step(Hd,s);
```

Listing 9: 1477HZ BP

```
1 function y = BP1477(x)
2 %DOFILTER Filters input x and returns output y.
3
4 % MATLAB Code
5 % Generated by MATLAB(R) 23.2 and DSP System Toolbox 23.2.
6 % Generated on: 05-Mar-2024 13:17:30
7
8 %#codegen
9
10 % To generate C/C++ code from this function use the codegen command.
11 % Type 'help codegen' for more information.
12
13 persistent Hd;
14
15 if isempty(Hd)
16
17     % The following code was used to design the filter coefficients:
18     %
19     % Fstop1 = 1390; % First Stopband Frequency
20     % Fpass1 = 1450; % First Passband Frequency
21     % Fpass2 = 1490; % Second Passband Frequency
```

```

22 % Fstop2 = 1540; % Second Stopband Frequency
23 % Astop1 = 6; % First Stopband Attenuation (dB)
24 % Apass = 1; % Passband Ripple (dB)
25 % Astop2 = 6; % Second Stopband Attenuation (dB)
26 % Fs = 4000; % Sampling Frequency
27 %
28 % h = fdesign.bandpass('fst1,fp1,fp2,fst2,ast1,ap,ast2', Fstop1, Fpass1, ...
29 % Fpass2, Fstop2, Astop1, Apass, Astop2, Fs);
30 %
31 % Hd = design(h, 'butter', ...
32 % 'MatchExactly', 'passband', ...
33 % 'SystemObject', true,...
34 % UseLegacyBiquadFilter=true);
35
36 Hd = dsp.BiquadFilter( ...
37 'Structure', 'Direct form II', ...
38 'SOSMatrix', [1 0 -1 1 1.2683561909662 0.883665323160146], ...
39 'ScaleValues', [0.058167338419927; 1]);
40 end
41
42 s = double(x);
43 y = step(Hd,s);

```

Listing 10: 1633HZ BP

```

1 function y = BP1633(x)
2 %DOFILTER Filters input x and returns output y.
3
4 % MATLAB Code
5 % Generated by MATLAB(R) 23.2 and DSP System Toolbox 23.2.
6 % Generated on: 05-Mar-2024 13:18:44
7
8 %#codegen
9
10 % To generate C/C++ code from this function use the codegen command.
11 % Type 'help codegen' for more information.
12
13 persistent Hd;
14
15 if isempty(Hd)
16
17     % The following code was used to design the filter coefficients:
18     %
19     % Fstop1 = 1560; % First Stopband Frequency
20     % Fpass1 = 1620; % First Passband Frequency
21     % Fpass2 = 1660; % Second Passband Frequency
22     % Fstop2 = 1710; % Second Stopband Frequency
23     % Astop1 = 6; % First Stopband Attenuation (dB)
24     % Apass = 1; % Passband Ripple (dB)
25     % Astop2 = 6; % Second Stopband Attenuation (dB)
26     % Fs = 4000; % Sampling Frequency
27     %
28     % h = fdesign.bandpass('fst1,fp1,fp2,fst2,ast1,ap,ast2', Fstop1, Fpass1, ...
29     % Fpass2, Fstop2, Astop1, Apass, Astop2, Fs);
30     %
31     % Hd = design(h, 'butter', ...
32     % 'MatchExactly', 'passband', ...
33     % 'SystemObject', true,...
34     % UseLegacyBiquadFilter=true);
35
36     Hd = dsp.BiquadFilter( ...
37     'Structure', 'Direct form II', ...
38     'SOSMatrix', [1 0 -1 1 1.59121640388426 0.883665323160147], ...
39     'ScaleValues', [0.0581673384199265; 1]);
40 end
41
42 s = double(x);
43 y = step(Hd,s);

```

2 Additional Question

Answers elaborating on our project.

1. Describe how your system design evolved throughout the project. Were there any significant changes to your approach?

Originally we were following the advice of filtering for each frequency and then detecting the peak but eventually, we realized we could accomplish the same result with only peak detectors thus we pivoted our solution halfway through. This was also simpler to implement and allowed use to leverage the matrix operations available in numpy.

2. How would you modify your system design to provide a separate output signal indicating that no symbol is present?

We could very easily put a check that if the peaks detected weren't high enough we send in a unique fail value to our logic unit that would be able to check against a threshold that we set and then from there fail if a symbols is not found or bad.

3. How might your system be improved, in terms of: ISI performance, computational requirements, or numerical representation?

This can always be optimized by finding the perfect buffer size amount, shifting from 36 to 30 counts brought our error down to 7.1% from 15%. Changing the signal chain of the DFT would also help with the processing accuracy that we saw. Because we know the specific data that we are working with, we would also be able to tailor the solution more closely to our goal.

4. What are the benefits of using the dual tones of the DTMF standard?

The benefits are that we only need $2\sqrt{(\# \text{ of symbols})}$ to represent symbols, in our case, we only need to look at 6 frequencies as opposed to 9 individual frequencies, additionally we know where the frequencies we are looking for are and can ignore much of the noise with some clever peak detection.

5. Could a square wave be used? What are the pros and cons of using a square wave to generate the various DTMF signals?

A square wave could be used instead of a sin wave to implement the DTMF however, there might be some problems with combining the square waves as they would sum differently than when using sin waves.