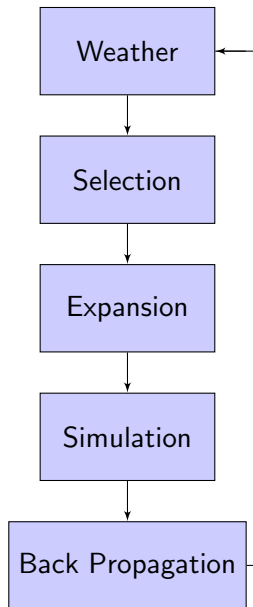


MCTS for CTP

Joe De Oliveira

June 2020

Monte Carlo Tree Search for CTP : 5 steps

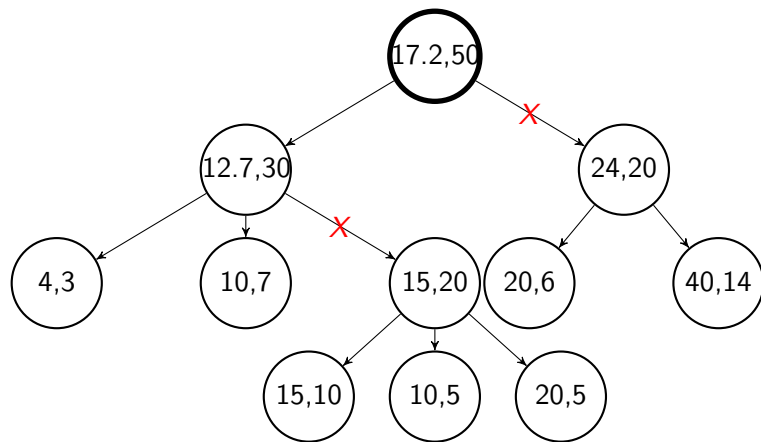


Monte Carlo Tree Search for CTP : selection

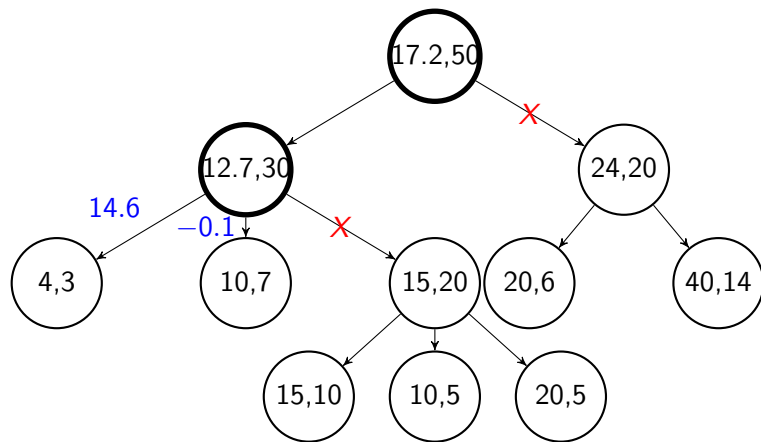
- new formula for exploration VS exploitation

$$B\sqrt{\frac{\ln(n)}{ni}} - cost(j, i) - si$$

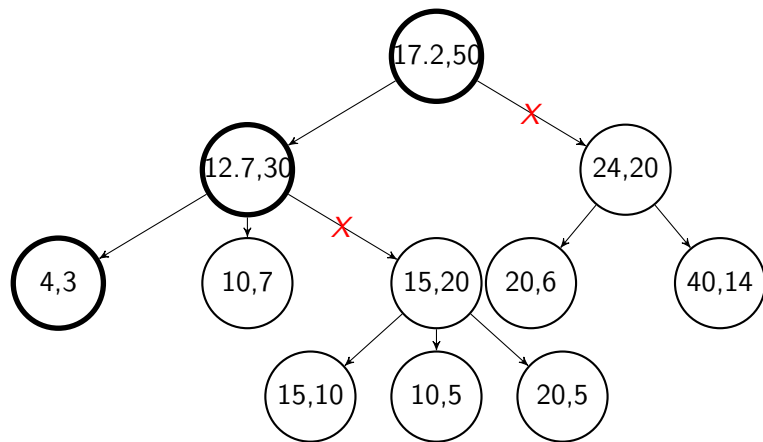
Monte Carlo Tree Search for CTP : selection



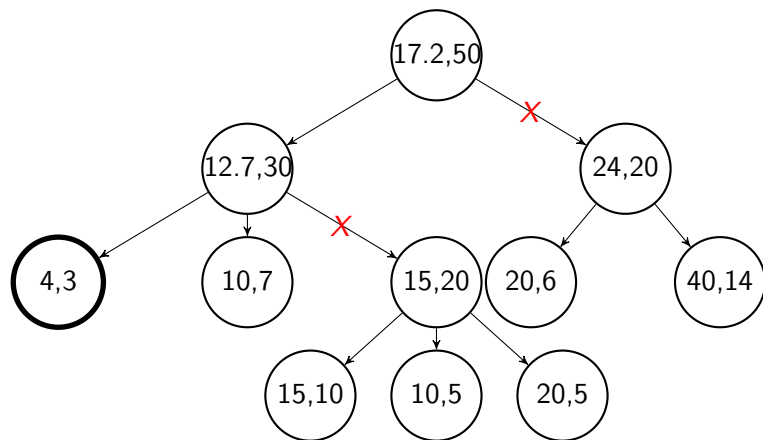
Monte Carlo Tree Search for CTP : selection



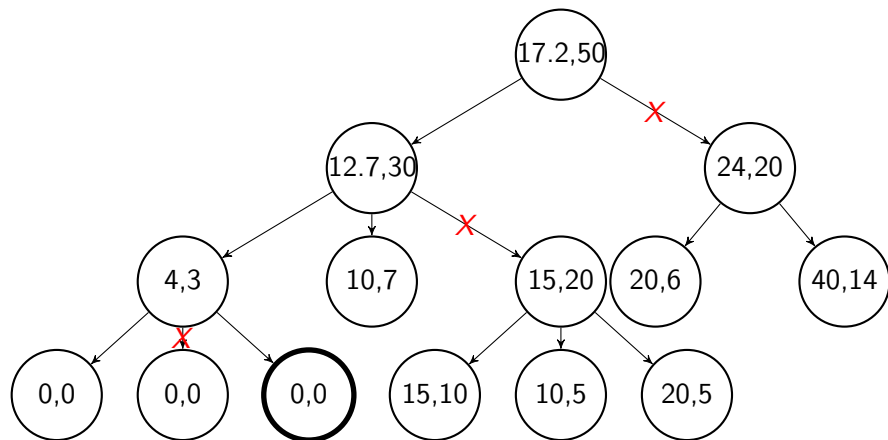
Monte Carlo Tree Search for CTP : selection



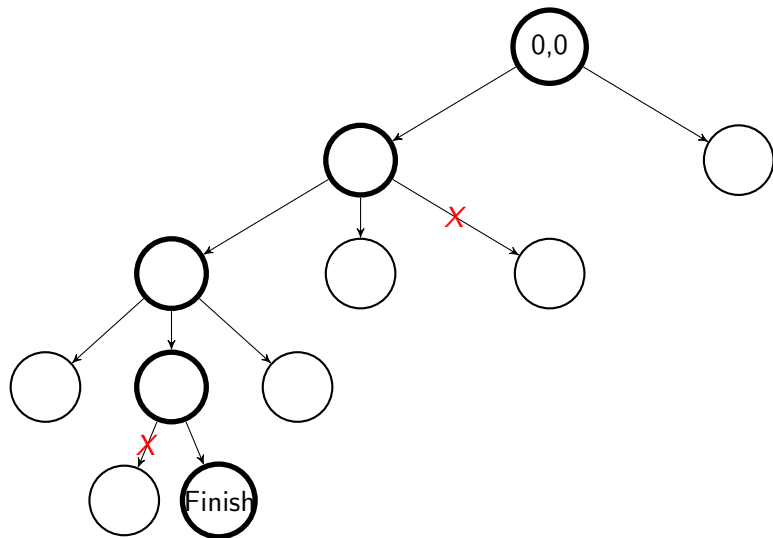
Monte Carlo Tree Search for CTP : expansion



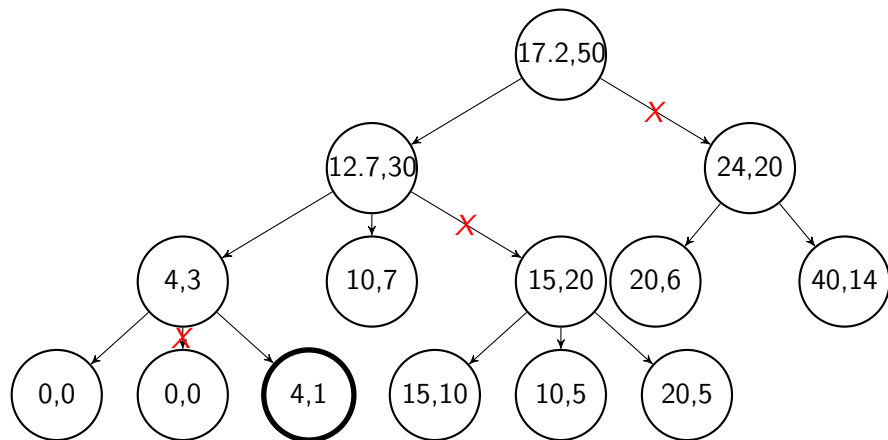
Monte Carlo Tree Search for CTP : expansion



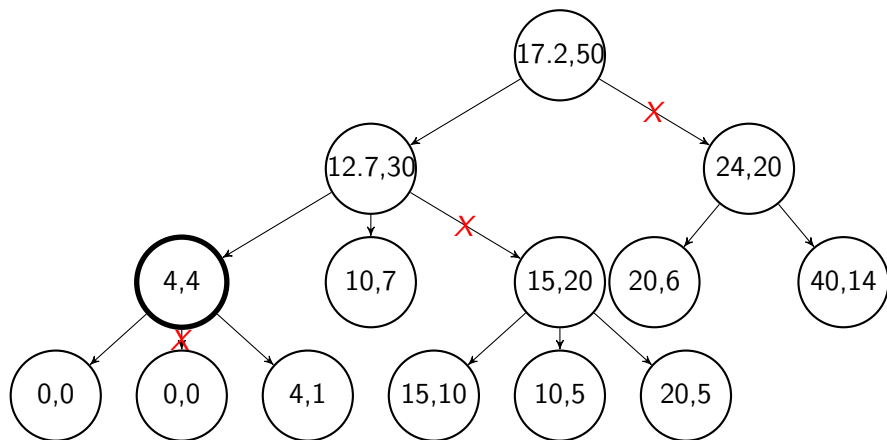
Monte Carlo Tree Search for CTP : simulation



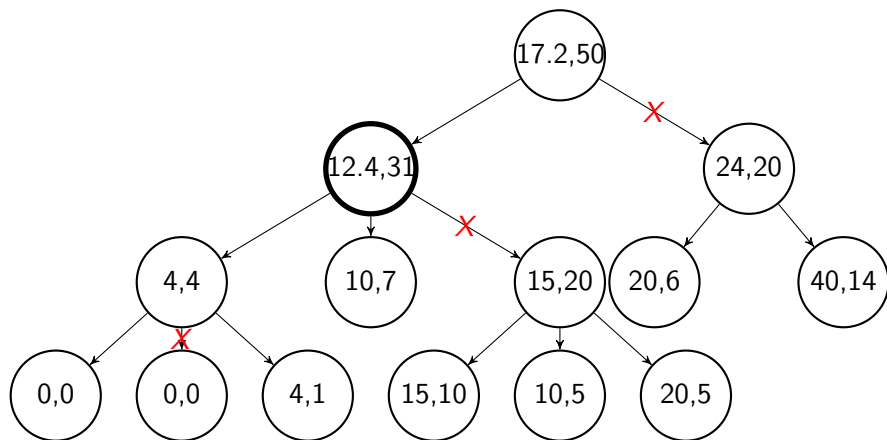
Monte Carlo Tree Search for CTP : back propagation



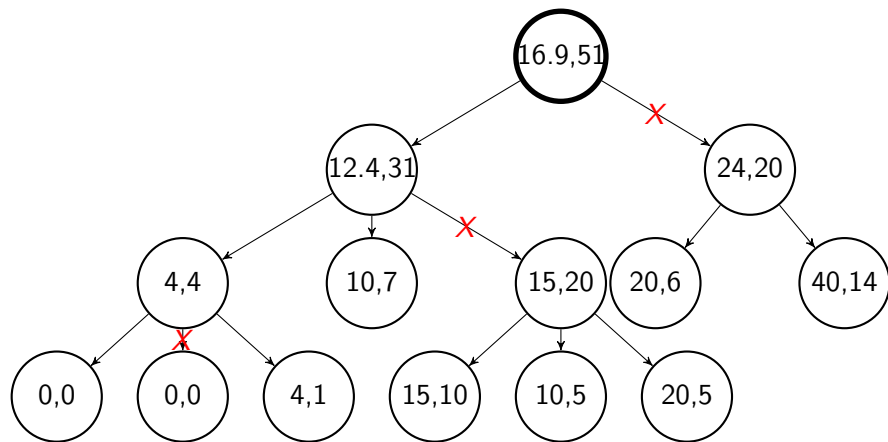
Monte Carlo Tree Search for CTP : back propagation



Monte Carlo Tree Search for CTP : back propagation



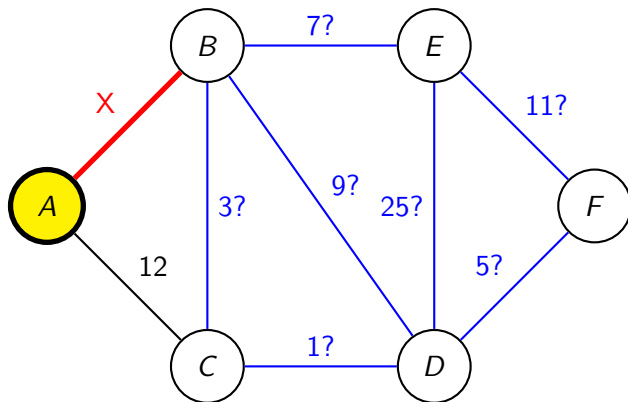
Monte Carlo Tree Search for CTP : back propagation



Monte Carlo Tree Search for CTP : optimistic

- this is the "blind" method, whom don't work very well
- we can use the "optimistic" method

Monte Carlo Tree Search for CTP : belief state

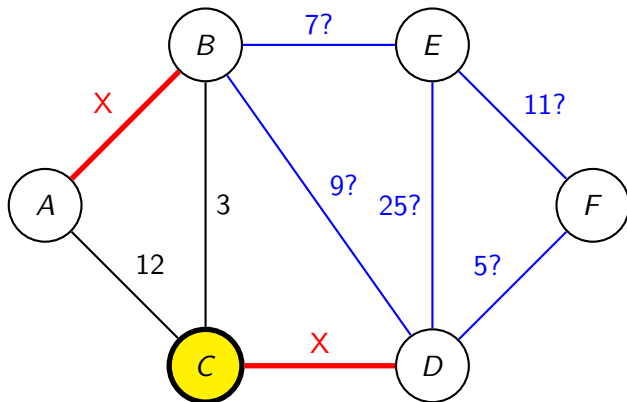


open : [A,C]

closed: [A,B]

unknown: [B,C] , [B,D] , [B,E] , [C,D] , [D,E] , [D,F] , [E,F]

Monte Carlo Tree Search for CTP : belief state

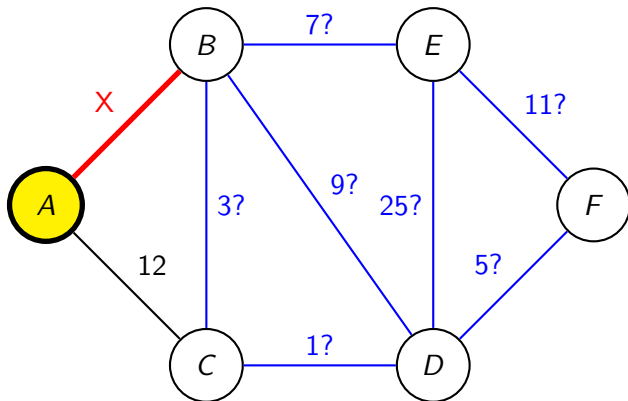


open : [A,C] , [B,C]

closed: [A,B] , [C,D]

unknown: [B,D] , [B,E] , [D,E] , [D,F] , [E,F]

Monte Carlo Tree Search for CTP : optimistic

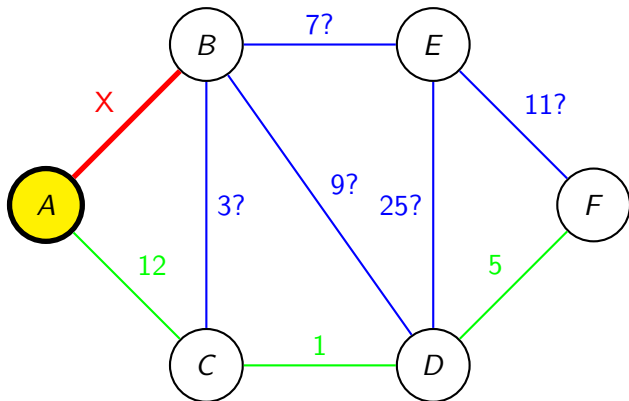


open : [A,C]

closed: [A,B]

unknown: [B,C] , [B,D] , [B,E] , [C,D] , [D,E] , [D,F] , [E,F]

Monte Carlo Tree Search for CTP : optimistic



open : [A,C]

closed: [A,B]

unknown: [B,C] , [B,D] , [B,E] , [C,D] , [D,E] , [D,F] , [E,F]

Monte Carlo Tree Search for CTP : optimistic MCTS

we use optimistic to get an headstart
on the estimated value of a node

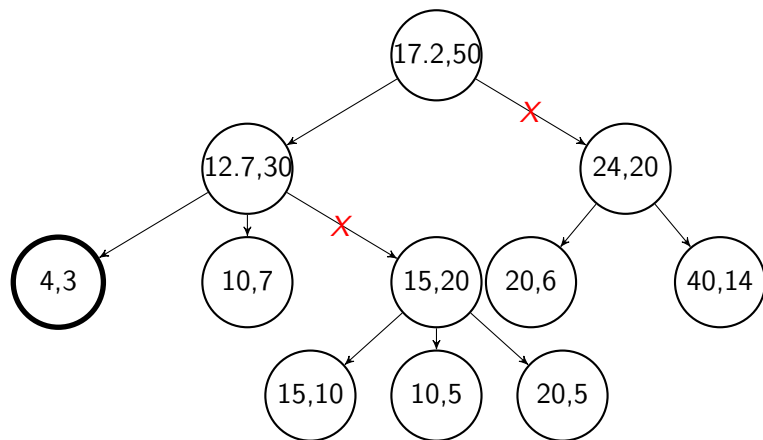
Monte Carlo Tree Search for CTP : selection optimistic

- modified formula for exploration VS exploitation

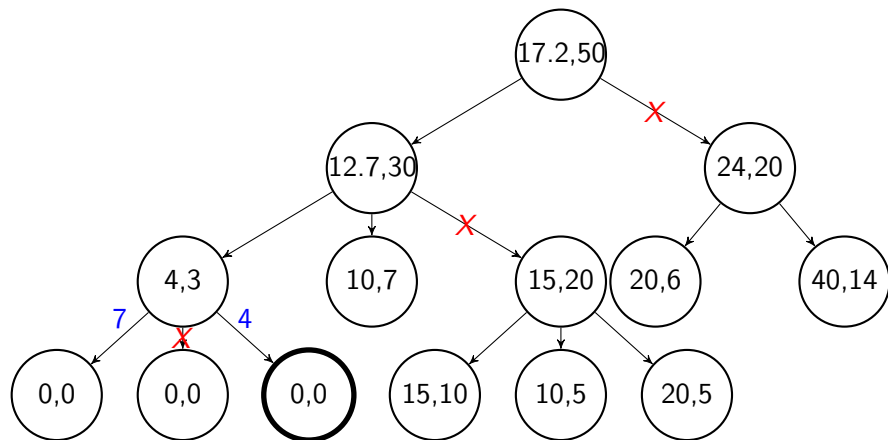
$$B' \sqrt{\frac{\ln(n+M)}{ni+M}} - cost(j,i) - si'$$

$$B' = \frac{(B * n) + (optimistic(beliefState(root)) * M)}{n + M}$$

Monte Carlo Tree Search for CTP : expansion



Monte Carlo Tree Search for CTP : expansion



Monte Carlo Tree Search for CTP : selection optimistic

Simulation and back propagation are identical
to the blind version