

* Recall | a field $(k, +, \times)$ = set with two operations, $(k, +)$ abelian group with identity 0, $(k^* = k - \{0\}, \times)$ abelian group with identity 1, distributive law.

* Given a field k , we always have a ring homomorphism $\varphi: \mathbb{Z} \rightarrow k$
 (this determines φ , since 1 generates \mathbb{Z}) $\hookrightarrow \varphi(a+b) = \varphi(a) + \varphi(b), \varphi(ab) = \varphi(a)\varphi(b)$
 $1 \mapsto 1_k$

Is this injective? For most fields we'll consider (eg. $\mathbb{Q}, \mathbb{R}, \mathbb{C}, \mathbb{R}(x), \mathbb{R}((x)), \dots$), it is.

If so, say k has characteristic zero. Otherwise:

Prop: $\ker(\varphi: \mathbb{Z} \rightarrow k) = \mathbb{Z}_p$ for some prime p .

Pf: $\ker(\varphi)$ is a subgroup of \mathbb{Z} , hence of the form $\mathbb{Z}n$. If n is not prime, write $n = ab$ for $1 < a, b < n$. Then $\varphi(n) = \varphi(ab) = \varphi(a)\varphi(b) = 0 \in k$, but this implies $\varphi(a) = 0$ or $\varphi(b) = 0$ (if $\varphi(a) \neq 0$, multiply by $\varphi(a)^{-1}$ to get $\varphi(b) = 0$). Since by assumption n is the smallest positive integer st. $\varphi(n) = 0$, this is a contradiction. \square

Def: Say k has characteristic p if $\ker(\varphi) = \mathbb{Z}_p$. (This means $p \cdot 1_k = \underbrace{1 + \dots + 1}_{p \text{ times}} = 0$!)

So far our only example of such a field is \mathbb{Z}/p , but there are more.

Theorem: For all $n \geq 1$ and prime p , there exists a unique field with p^n elements (up to isomorphism), and these are all the finite fields.

(There are also infinite fields of characteristic p , for example $\mathbb{Z}/p((x))$!).

Def: A vector space over k is a set V with two operations:

- (1) addition $+: V \times V \rightarrow V$ making V an abelian group with identity $0 \in V$.
- (2) scalar multiplication $\times: k \times V \rightarrow V$ associative $(ab)v = a(bv)$; $1v = v, 0v = 0$;
 distributive $a(v+v') = av + av', (a+b)v = av + bv$

Def: A subspace of a vector space is a nonempty subset $W \subset V$ that is preserved by addition and scalar multiplication: $W+W \subset W, k \cdot W \subset W$.
 (so W is also a vector space!) \uparrow in fact $=W \uparrow \hookrightarrow$ this implies $0 \in W$.

- Examples:
- $\{0\}$ is a vector space
 - $k^n = \{(a_1, \dots, a_n) \mid a_i \in k\}$ with componentwise addition / scalar mult.
 - $k^\infty = \{(a_i)_{i \in \mathbb{N}} \mid a_i \in k\}$ (sequences in k) $\supset \{\text{sequences which are eventually zero}\}$
 (\Leftrightarrow polynomials $k[x]$, power series $k[[x]]$)
 - given any set $S, k^S = \{\text{maps } f: S \rightarrow k\}$
 - $\{\text{functions } f: \mathbb{R} \rightarrow \mathbb{R}\} \supset \{\text{continuous functions}\} \supset \{\text{differentiable functions}\}$.

Span, linear independence, basis: Let V be a vector space / k . ②

Def: Given $v_1, \dots, v_n \in V$, the span of v_1, \dots, v_n is the smallest subspace of V which contains v_1, \dots, v_n . Concretely, $\text{span}(v_1, \dots, v_n) = \{a_1 v_1 + \dots + a_n v_n \mid a_i \in k\}$

Def: say v_1, \dots, v_n span V if $\text{span}(v_1, \dots, v_n) = V$.

Def: We say $v_1, \dots, v_n \in V$ are linearly independent if $a_1 v_1 + \dots + a_n v_n = 0 \Rightarrow a_1 = a_2 = \dots = a_n = 0$.

Equivalently, given $v_1, \dots, v_n \in V$, we have a linear map $\phi: k^n \rightarrow V$
 $(a_1, \dots, a_n) \mapsto \sum a_i v_i$
 v_1, \dots, v_n are linearly indep $\Leftrightarrow \phi$ injective
 v_1, \dots, v_n span $V \Leftrightarrow \phi$ surjective.

Def: (v_1, \dots, v_n) are a basis of V if they are linearly independent and span V .

Then any element of V can be expressed uniquely as $\sum a_i v_i$ for some $a_i \in k$.

Ex: $(1, 0)$ and $(0, 1)$ are a basis of k^2 . So are $(1, 1)$ and $(1, -1)$ for most fields k .
(what if $\text{char}(k) = 2$?)

* We will see soon: if V has a basis with n elements, then every basis of V has n elements. We say the dimension of V is $\dim(V) = n$.

One can also consider infinite-dimensional vector spaces: for $S \subset V$ any subset,

Def: $\text{span}(S)$ = smallest subspace of V containing S
 $= \{a_1 v_1 + \dots + a_k v_k \mid k \in \mathbb{N}, a_i \in k, v_i \in S\}$
(all finite linear combinations of elements of S)

- The elements of S are linearly independent if there are no finite linear relations:
 $a_1 v_1 + \dots + a_k v_k = 0 \quad (a_i \in k, v_i \in S) \Rightarrow a_1 = \dots = a_k = 0$.
- S is a basis of V if its elements are linearly indep and span V .

Example: $\{1, x, x^2, x^3, \dots\}$ is a basis of $k[x]$.
• does $k[[x]]$ have a basis? what is it?

Linear maps:

Def: Let V, W be vector spaces / k . A homomorphism of vector spaces, or linear map, $\varphi: V \rightarrow W$, is any map that is compatible with the operations:
 $\varphi(u+v) = \varphi(u) + \varphi(v), \quad \varphi(\lambda v) = \lambda \varphi(v) \quad \forall \lambda \in k, \forall u, v \in V$.

Prop: || The set of linear maps $V \rightarrow W$ is itself a vector space/ k , denoted $\text{Hom}(V, W)$. (3)

Proof: Given $\varphi, \psi \in \text{Hom}(V, W)$, define $\varphi + \psi$ by $(\varphi + \psi)(v) = \varphi(v) + \psi(v)$. $\forall v \in V$
 $\lambda \in k$ by $(\lambda \varphi)(v) = \lambda \cdot \varphi(v)$

One can check that $\varphi + \psi$ and $\lambda \varphi$ defined in this way are linear maps
(rather boring, but worth checking if you're not sure!) (so we do have operations $+$, \cdot on $\text{Hom}(V, W)$)
 \bullet these operations on $\text{Hom}(V, W)$ satisfy the axioms of a vector space. \square

\bullet We'll soon see: if $\dim(V) = n$ and $\dim(W) = m$ then $\dim(\text{Hom}(V, W)) = mn$.
(in bases for V and W , linear maps become $m \times n$ matrices!)

\star How does the choice of the field k matter when discussing vector spaces?

Given a subfield $k' \subset k$ (eg. $\mathbb{R} \subset \mathbb{C}$ or $\mathbb{Q} \subset \mathbb{R}$), a vector space over k can also be viewed as a vector space over k' , by "restriction of scalars".

(namely, only look at scalar multiplication restricted to domain $k' \times V \subset k \times V$).

In particular, k itself is a vector space over k' !

Ex: \mathbb{C} is a vector space over itself (of dim. 1, $\{1\}$ is a basis)

It is also a vector space over \mathbb{R} (of dim. 2, with basis $\{1, i\}$)

If V, W are \mathbb{C} -vector spaces hence also \mathbb{R} -vector spaces,

any \mathbb{C} -linear map is also \mathbb{R} -linear, but the converse isn't true: $\text{Hom}_{\mathbb{C}}(V, W) \subsetneq \text{Hom}_{\mathbb{R}}(V, W)$

For example, complex conjugation $\mathbb{C} \rightarrow \mathbb{C}$

$$z = a + bi \mapsto \bar{z} = a - bi$$

is \mathbb{R} -linear: $\begin{cases} \overline{z_1 + z_2} = \bar{z}_1 + \bar{z}_2 \\ \overline{a z} = a \bar{z} \quad \forall a \in \mathbb{R} \end{cases}$

So: the choice of field k matters.

but not \mathbb{C} -linear ($i \bar{z} \neq \bar{i z}$).

Bases and dimension:

\star Say V is finite-dimensional if there is a finite subset $\{v_1, \dots, v_m\}$ which spans V ,
ie. all elts of V are linear combinations $\sum a_i v_i$.

\star Lemma: || if $\{v_1, \dots, v_m\}$ spans V , then a subset of $\{v_1, \dots, v_m\}$ is a basis.

Proof: If the $\{v_i\}$ are linearly independent, they form a basis.

Otherwise, there is some linear relation $\sum a_i v_i = 0$, a_i not all zero.

This can be solved for $v_i =$ a linear combination of the others if $a_i \neq 0$.

\rightarrow remove v_i , $\{v_j / j \neq i\}$ still spans V .

Continue removing elements until the remaining ones are linearly indep. \square

\star Thus, every finite-dimensional vector space has a basis.

* Lemma: \parallel If $\{v_1, \dots, v_m\}$ are linearly indept., there exists a basis of V which contains $\{v_1, \dots, v_m\}$ (4)

Proof: Let $\{w_1, \dots, w_r\}$ be a spanning set for V . by induction we enlarge $\{v_1, \dots, v_m\}$ to a basis of $W_j = \text{span}(\{v_1, \dots, v_m, w_1, \dots, w_j\}) \subset V$ for each $j = 0, \dots, r$.
For $j=0$: $\{v_1, \dots, v_m\}$ basis of W_0 .

Assuming $\{v_1, \dots, v_m, w_1, \dots, w_{j-1}\}$ is a basis of $W_{j-1} = \text{span}(\{v_1, \dots, v_m, w_1, \dots, w_{j-1}\})$,
if $w_j \in W_{j-1}$ then we already have a basis of $W_j = W_{j-1}$.

otherwise, $\{v_1, \dots, v_m, w_1, \dots, w_{j-1}, w_j\}$ are linearly indept. (why?) and span W_j .

This ends with a basis of $W_r = V$ (since $\{w_1, \dots, w_r\}$ span).

* Theorem: \parallel If $\{v_1, \dots, v_m\}$ and $\{w_1, \dots, w_n\}$ are bases of V , then $m=n$. (same # elements).

Proof: • We claim $\exists j \in \{1, \dots, n\}$ st. $\{v_1, \dots, v_{m-1}, w_j\}$ is a basis.

Indeed, $\{v_1, \dots, v_{m-1}\}$ are linearly independent, but don't span V
(else $v_m \in \text{span}\{v_1, \dots, v_{m-1}\}$ gives a linear relation $\sum_{i=1}^{m-1} a_i v_i - v_m = 0$).

So $\exists j$ st. $w_j \notin \text{span}\{v_1, \dots, v_{m-1}\}$ (else w_1, \dots, w_n can't span all V).

Now $\{v_1, \dots, v_{m-1}, w_j\}$ are linearly independent (why?),

but using all the v 's, can write $w_j = \sum_{i=1}^m a_i v_i$ (neces. $a_m \neq 0$)

So $v_m = \frac{1}{a_m} (w_j - \sum_{i=1}^{m-1} a_i v_i) \in \text{span}(\{v_1, \dots, v_{m-1}, w_j\})$

and this implies $\{v_1, \dots, v_{m-1}, w_j\}$ span V hence are a basis.

• Repeat this process to exchange one v for one w each time

(we don't use the same w twice since the new w we pick has to be independent of the rest of our basis)

We end up with only w 's & get an m -element subset of $\{w_1, \dots, w_n\}$ that is also a basis. Necessarily this is all of $\{w_1, \dots, w_n\}$, and $m=n$. \square

* Def: \parallel The dimension of V is the cardinality of any basis.

* Given a basis (v_1, \dots, v_n) of V , we get a linear map $\varphi: k^n \rightarrow V$
 $(a_1, \dots, a_n) \mapsto \sum a_i v_i$

Linear independence $\iff \varphi$ injective

spanning $V \iff \varphi$ surjective, so φ is an isomorphism!

Every finite-dim. vector space $/k$ is isomorphic to k^n for $n = \dim V$.

(+ basis gives a specific choice of such an isomorphism).

* Given basis (v_1, \dots, v_n) of V and (w_1, \dots, w_m) of W , we can represent a linear map $\varphi \in \text{Hom}(V, W)$ by an $m \times n$ matrix $A \in M_{m,n}$. This amounts to:

$$\begin{array}{ccc} V & \xrightarrow{\varphi} & W \\ \uparrow \cong \text{basis} & & \uparrow \cong \text{basis} \\ k^n & \xrightarrow{A} & k^m \end{array}$$

Write $A = (a_{ij})_{\substack{1 \leq i \leq m \text{ rows} \\ 1 \leq j \leq n \text{ columns}}} = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ a_{21} & & \\ \vdots & & \\ a_{m1} & \dots & a_{mn} \end{pmatrix} \quad (5)$

$A: k^n \rightarrow k^m$ by multiplication w/ column vectors $\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \mapsto A \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$

Notation: $A = \mathcal{M}(\varphi, (v), (w))$

* The entries of A are characterized by: $\varphi(v_j) = \sum_{i=1}^m a_{ij} w_i$.

I.e. the columns of A give the components of $\varphi(v_1), \dots, \varphi(v_n)$ in the basis $\{w_1, \dots, w_m\}$.

Representing any element $x \in V$ as $x = \sum_{i=1}^n x_i v_i \leftrightarrow$ column vector $X = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$
and similarly for $y = \varphi(x) \in W$, $y = \sum_{i=1}^m y_i w_i \leftrightarrow Y = \begin{pmatrix} y_1 \\ \vdots \\ y_m \end{pmatrix} = AX$.

* As a memory aid, the isom. $k^n \xrightarrow{\cong} V$ given by the basis can be written symbolically as multiplication of row & column vectors $(v_1 \dots v_n) \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \sum x_i v_i$.
 \triangle these aren't numbers!!

$$\varphi((v_1 \dots v_n) X) = (w_1 \dots w_m) AX.$$

* This construction gives an isomorphism between the vector spaces $\text{Hom}(V, W)$ and $\mathcal{M}_{m,n}$! In particular $\dim \text{Hom}(V, W) = \dim \mathcal{M}_{m,n} = mn$.
linear maps \leftrightarrow matrices

* How do things change if we choose different basis for V and/or W ?

If we change basis from $(v_1 \dots v_n)$ to $(v'_1 \dots v'_n)$, write $v'_j = \sum_{i=1}^n p_{ij} v_i$

and get an $n \times n$ matrix P whose j^{th} column gives the components of v'_j in the basis $(v_1 \dots v_n)$. Symbolically $(v'_1 \dots v'_n) = (v_1 \dots v_n) P$.

So: $(v'_1 \dots v'_n) X' = (v_1 \dots v_n) P X'$ i.e. the element of V described by a column vector X' in new basis is described by $X = P X'$ in old basis.

More conceptually: $P = \mathcal{M}(\text{id}_V, (v'), (v))$!

Do the same for W , but proceed in inverse direction, let $Q = \mathcal{M}(\text{id}_W, (w), (w'))$
i.e. $(w_1 \dots w_m) = (w'_1 \dots w'_m) Q$.

$$\begin{aligned} \text{Hence: } \varphi((v'_1 \dots v'_n) X') &= \varphi((v_1 \dots v_n) P X') = (w_1 \dots w_m) A P X' \\ &= (w'_1 \dots w'_m) Q A P X' \end{aligned}$$

$$\text{i.e. } \mathcal{M}(\varphi, (v'), (w')) = Q A P.$$

⑥

In particular, if $V=W$ and change basis, for $\varphi \in \text{Hom}(V, V)$,

$$\begin{aligned} A &= \mathcal{M}(\varphi, (v), (v)) \\ A' &= \mathcal{M}(\varphi, (v'), (v')) \end{aligned} \quad \text{are related by } A' = P^{-1}AP.$$

But... the whole point of linear algebra is to avoid all this and work with linear maps in a coordinate-free language as much as possible.

Next up: sums of subspaces, direct sums, dimension formulas.