Recall: . a metric space (X, d) = set with distance function d. XxX -> R 30 st.

- 1) d(p,q) = 0 iff p = q, 2) d(p,q) = d(q,p), 3) $d(p,r) \in d(p,q) + d(q,r)$
- · open balls Br(p)= {xEX/d(p,x)<r}. UCX is open iff VpEU 3r>0 st. Br(p) CU. $f: X \longrightarrow Y$ is continuous $\iff \forall p \in X \ \forall \epsilon > 0 \ \exists s > 0 \ st \ f(B_s(p)) = B_{\epsilon}(f(p))$ \$\this vill be the def or ordside of the netic case.

Recall: • a sequence $p_n \to p$ in (X,d) if $\forall \varepsilon > 0 \exists N \text{ st. } n \ge N \Rightarrow d(p_n,p) < \varepsilon$.

· Prop. if Pn -> p, men every open subset U > p contains pn for all but finitely many n. This will be the definition of limit orbide the metric case.

(Pf: $U \ni P$, $V \circ P \Leftrightarrow \exists E > 0 \text{ st-} B_{E}(P) \subset U$. So $\exists N \text{ st-} n \geqslant N \Rightarrow P_{n} \in B_{E}(P) \subset U$).

* We will now reformulate / generalize all this in the context of topological spaces, ie sets equipped with a topology which may or may not come from a metric.

Def: A topological space = a set X together with a collection $T \subset P(X)$, the open sets in X, such that $\bullet \not o \in T$, $X \in T$ • arbitrary unions of open sets are open

• finite intersections of open sets are open.

Why bother? One assure i many natural topologies do not come from a metric! Eg, in analysis:

· on the space of (bounded) functions fix -1/R, uniform conveyence topology $(f_h \rightarrow f \text{ iff sup } |f_h(x) - f(x)| \rightarrow 0)$ one from a netic $(d(f,g) = \sup_{x} |f(x) - g(x)|)$

but pointwise convergence (fn-) f iff $\forall x \in X$ $f_n(x) \rightarrow f(x)$) doesn't. ("product topology")

· Coo topology on smooth Runchions R-IR down't come from a metric either.

And on the other hand, a metric contains extraneous information for topology Eg. (\mathbb{R}^n, d) , (\mathbb{R}^n, d_0) , (\mathbb{R}^n, d_0) have the same open sets => same top.

 \underline{Def} . $f: X \rightarrow Y$ is continuous if $\forall U \subset Y$, $U \circ pen \Rightarrow f^{-1}(U) \subset X$ is open.

- a sequence $\{p_n\}$ in X converges to a <u>limit</u> $p(p_n \rightarrow p)$ if $\forall U \ni p$ open, $\exists N \in \mathbb{N}$ if $n \ge N \Rightarrow p_n \in U$.
- Exi . (X,d) metric space \Rightarrow $T = \{U \subset X \mid \forall_P \in U \exists E>0 \text{ st. } B_E(P) \subset U\}$ metric topology • disnete topology: T = P(X) (every subset is open and closed.) (eg. ~ would top. on ZCR). (this is in fact a metric topology: set $d(x,y)=1 \ \forall x \neq y$.)

These abstract det's imply basic facts about continuity, such as:

* Given two topologies T, T' on X, if TCT' we say T' is fine-, T is coarser.

The finest topology on X is the discrete one (all points are isolated), while

the coarsest is {\$p, X} ("one big clump").

• The finer topology T' has more open sets; it's easier for functions X-14 to be continuous wit T' than T (every function from a discrete set is continuous)

It's harder for sequences to converge in T' (eg. on a discrete set, convergent sequences much be constant after finitely many terms; while for T={\$\phi_{,}X\$} every sequence converges to every point of X, in patientar limit is n't unique!).

* Keeping track of all the open sets is combesome - in muliic space we started with open balls & got a characterization of open sets in terms of these. The analogous notion for a general topology is that of <u>basis</u>.

Def. Assume $B \subset P(X)$ is a collection of schedule of $X \text{ st} \cdot 1$ $\bigcup B = X$, $B \in B$ 2) if $B_1, B_2 \in B$ and $x \in B_1 \cap B_2$ then $\exists B' \in B \text{ st} \cdot x \in B \subset B_1 \cap B_2$.

Then we say B is a <u>basis</u> and <u>generates</u> the B, $\frac{3B'(x)}{x}$ topology T = arbitrary unions of elements of B.

Egwidely: UET (=> VXEU 3BEB st. xEBCU.

Check: (1) the two characterizations of T are equivalent, (2) T is a topology

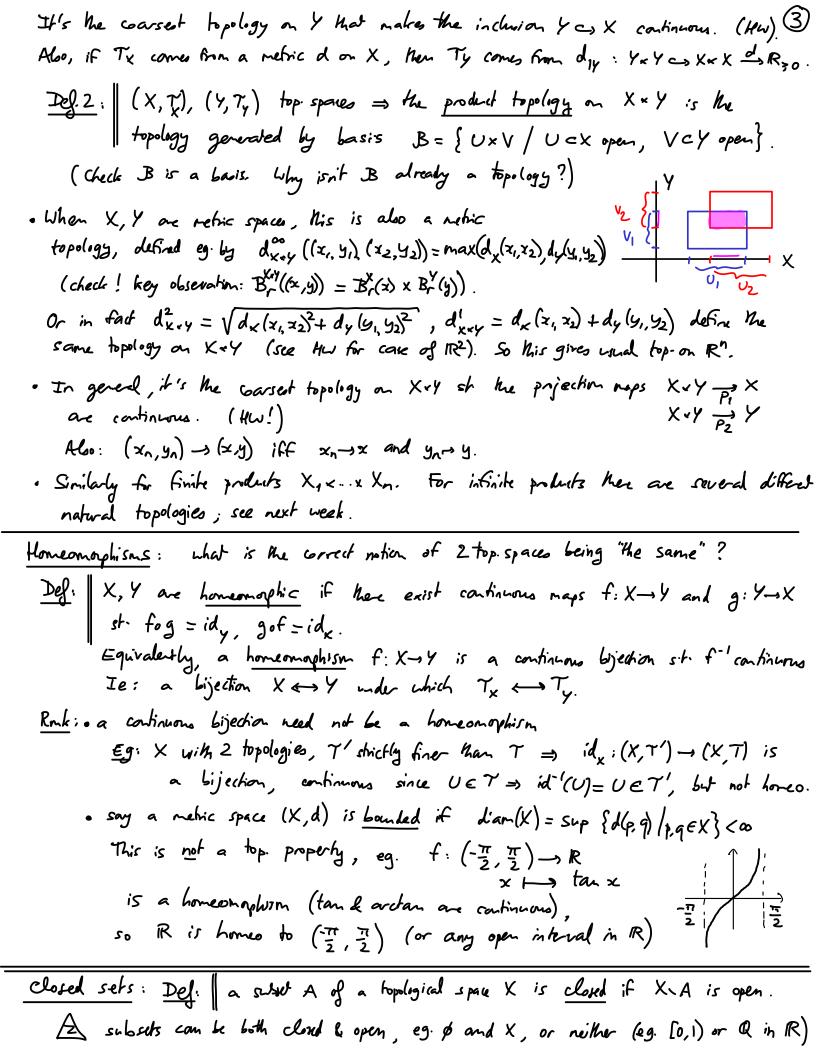
Rnh: Unlike bases in lin. alg., bases in topology can contain redundant into -a better analogy is with generating sets... eg. metric topology is generated by any of: all open sets; open balls $B_{r}(x)$, $x\in X$, r>0; open balls $B_{r}(x)$, $x\in X$; open balls $B_{r}(x)$, $y\in Y\subset X$ dense subset (every nonempty open interects Y) eg. $R\subset R$. So for example the usual topology on R or R^n actually admits a cumbable basis!

· Mahing new topological spaces; subspaces, products.

Def: (X, T) top space, Y = X any subset \Rightarrow the subspace topology on Y is $T_Y = \{U \cap Y \mid U \in T_X\}$. (Verify: this satisfies the axioms of a topology).

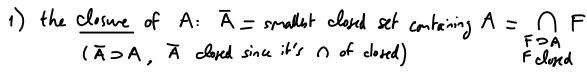
DIt's important when stating "U is open" to be clear: as a subset of what space?

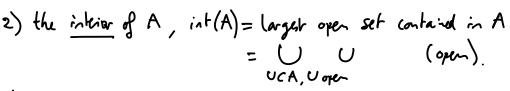
Eg. Y is always open as a subset of itself! $(0,1) \subset \mathbb{R} \subset \mathbb{R}^2$ is open in \mathbb{R} but not in \mathbb{R}^2 .



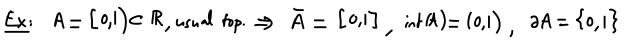
Axions of open sets imply: { . p, X are closed . a bitrary intersections of closed sets are closed . finite unions of closed sets are closed.

Del: AC X any subject => we define





3) the boundary of A is $\partial A = \overline{A} - int(A)$



 \underline{Rnh} ; A is closed iff $\overline{A} = A$, open iff int(A) = A.

• $\overline{X-A} = X-int(A)$, $int(X-A) = X-\overline{A}$. (*)

Def: Say UCX is a reighborhood of PEX if U is open and PEU.

Prop: (1) $p \in int(A)$ iff A contains a neighborhood of p.

(2) $p \in \overline{A}$ iff every neighborhood of p interects A non-himitably.

(check this! (1) follows from def is: p \in int(A) \in \frac{1}{2} \text{open of p \in VU \text{open, A nU \in \in \text{op}}.

Def: | sony A is dense if $\overline{A} = X$. (i.e. every nonempty open subset of X interects A non-hibialty). \underline{Ex} : \mathbb{Q} is dense in \mathbb{R} (for usual hypology).

Next time we'll see the relation between closure, limit points, limits of sequences and introduce the Hansdorff property.