We are given several pieces of information about four functions y_1, y_2, y_3 and f:

$$y_1''' + p(x)y_1'' + q(x)y_1' + r(x)y_1 = 0$$

$$y_2''' + p(x)y_2'' + q(x)y_2' + r(x)y_2 = 0$$

$$y_3''' + p(x)y_3'' + q(x)y_3' + r(x)y_3 = 0$$

$$y_1^2 + y_2^2 + y_3^2 = 1$$

$$y_1'^2 + y_2'^2 + y_3'^2 = f$$

My plan is simply to take these equations and differentiation some of them a few times so that I have enough equations that I can make some substitutions and so on to get an equation which has no y_i in it at all; that will be the final equation, from which I will read off the constants A and B.

The first three equations will allow us to get rid of any third derivatives of the y_i . There seems to be nothing to gain from differentiating these to learn about the higher derivatives of the y_i . I will differentiate the last equation only once because there seems to be no advantage to getting f'' into the picture. The middle equation I will differentiate three times only – by the third time I will be including $y_i'''(x)$ so I will be able to make use of the top equations, but there will be nothing additional learned by going further.

In other words, I will enlarge the original set of equations to get a larger set:

$$\begin{aligned} y_1''' + p(x)y_1'' + q(x)y_1' + r(x)y_1 &= 0 \\ y_2''' + p(x)y_2'' + q(x)y_2' + r(x)y_2 &= 0 \\ y_3''' + p(x)y_3'' + q(x)y_3' + r(x)y_3 &= 0 \\ y_1^2 + y_2^2 + y_3^2 &= 1 \\ y_1y_1' + y_2y_2' + y_3y_3' &= 0 \\ y_1y_1''' + (y_1')^2 + y_2y_2'' + (y_2')^2 + y_3y_3'' + (y_3')^2 &= 0 \\ y_1y_1''' + 3y_1'y_1'' + y_2y_2''' + 3y_2'y_2'' + y_3y_3''' + 3y_3'y_3'' &= 0 \\ y_1y_1''' + 3y_1'y_1'' + y_2y_2''' + 2y_2'y_2'' + 2y_3'y_3'' &= f' \end{aligned}$$

Calling these equations e_1 through e_9 , we simply compute

$$-y_1e_1 - y_2e_2 - y_3e_3 + r(x)e_4 + q(x)e_5 + p(x)e_6 + e_7 - p(x)e_8 - (3/2)e_9$$

a sum which makes the left side vanish and makes the right side equal r(x) - p(x)f(x) - (3/2)f'(x). Solving for f' gives

$$f'(x) + (2/3)p(x)f(x) = (2/3)r(x)$$

i.e. the solution is A = 2/3, B = 2/3.

I suppose you could simply assume the question-posers are correct when they assert that such constants A and B exist that are independent of the functions p, q, r and the y_i ; in that case, you can take any y_i you like whose squares sum to 1 (that is, any parameterization of a path on the unit sphere at the origin), compute the corresponding p, q, r as the solution to a system of three linear equations e_1, e_2, e_3 in three unknowns, compute

f as shown, and then the expression E = f'(x) + Ap(x)f(x) - Br(x); this should vanish identically for the right A and B. You could check that by evaluating E at any two points $x = x_1, x = x_2$ to obtain two linear equations to solve for the two unknowns A, B; or if E is a rational function you could pick two powers of x in the numerator and choose A, B to make their coefficients vanish. I actually carried this out using

$$y_1(x) = (x^4 + x^2 - 1)/s(x), \quad y_2(x) = 2x/s(x), \quad y_3(x) = 2x^2/s(x)$$

where $s(x) = x^4 + x^2 + 1$ (or more precisely, I knew the sequence of commands to type into my computer to find three functions whose squares sum to 1, and from there to compute p, q, r, then f, then f' + Apf - Br, and the numerator of the latter was a polynomial whose coefficients were linear combinations of A and B which all vanished precisely when A = B = 2/3.) But I doubt the problem-graders would be happy with a solution that does not establish that A, B are independent of the y_i that I chose!