

Homework 5 Writeup

Instructions

- Provide an overview about how your project functions.
- Describe any interesting decisions you made to write your algorithm.
- Show and discuss the results of your algorithm.
- Feel free to include code snippets, images, and equations.
- List any extra credit implementation and result (optional).
- Use as many pages as you need, but err on the short side.
- **Please make this document anonymous.**

Project Overview

This project is about training a convolutional neural network to perform scene classification. We train a head on a pre-trained model, and create and train a model from scratch.

Implementation Detail

Result

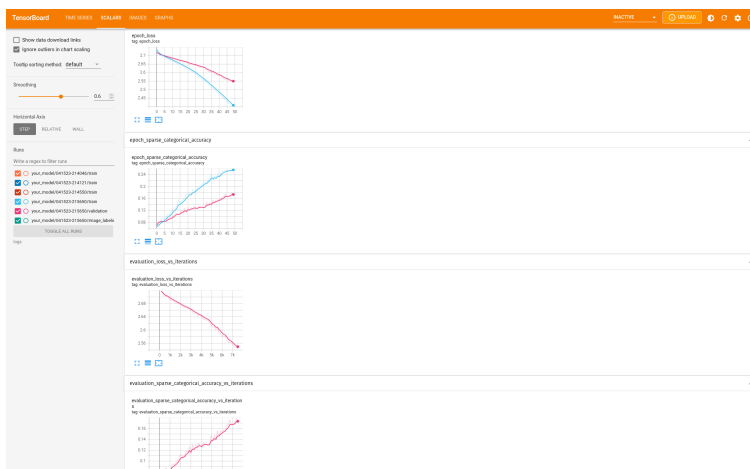


Figure 1: Task 1: Training the small model on CPU. Somehow this was very fast.

```

Dataset std shape: [224, 224, 3]
Dataset std top left pixel value: [0.2643, 0.2643, 0.2643]
Found 1500 images belonging to 15 classes.
Found 2985 images belonging to 15 classes.
2023-04-16 12:25:58.562188: W tensorflow/compiler/xla/stream_executor/platform/default/dso_loader.cc:64] Could not load dynamic library 'libcuda.so.1'; dLError: libcuda.so.1: cannot open shared object file: No such file or directory
2023-04-16 12:25:58.562126: W tensorflow/compiler/xla/stream_executor/cuda/cuda_driver.cc:265] failed call to cuInit: UNKNOWN ERROR (303)
2023-04-16 12:25:58.562138: I tensorflow/compiler/xla/stream_executor/cuda/cuda_diagnostics.cc:156] kernel driver does not appear to be running on this host (pop-os): /proc/driver/nvidia/version does not exist
2023-04-16 12:25:58.562289: I tensorflow/core/platform/cpu_feature_guard.cc:193] This TensorFlow binary is optimized with oneAPI Deep Neural Network Library (oneDNN) to use the following CPU instructions in performance-critical operations: AVX2 AVX512F AVX512_VNNI FMA
To enable them in other operations, rebuild TensorFlow with the appropriate compiler flags.
Model: "your_model"

Layer (type)                 Output Shape              Param #
-----
conv2d (Conv2D)              multiple                  2280
max_pooling2d (MaxPooling2D) multiple                  0
conv2d_1 (Conv2D)            multiple                  45060
max_pooling2d_1 (MaxPooling2D) multiple                  0
dropout (Dropout)            multiple                  0
conv2d_2 (Conv2D)            multiple                  135090
max_pooling2d_2 (MaxPooling2D) multiple                  0
flatten (Flatten)            multiple                  0
dense (Dense)                 multiple                  10584150
dropout_1 (Dropout)          multiple                  0
dense_1 (Dense)              multiple                  11325
dropout_2 (Dropout)          multiple                  0
dense_2 (Dense)              multiple                  1140

Total params: 10,779,045
Trainable params: 10,779,045
Non-trainable params: 0

Done setting up image labeling logger.
<keras.preprocessing.image.DirectoryIterator object at 0x7fd174ca46a0>
Epoch 1/100
CTraceback (most recent call last):
  File "/home/ethan/school/csi43/homework5_cnns-EtomicBomb/code/run.py", line 274, in <module>
    main()
  File "/home/ethan/school/csi43/homework5_cnns-EtomicBomb/code/run.py", line 268, in main
    train(model, datasets, checkpoint_path, logs_path, init_epoch)
  File "/home/ethan/school/csi43/homework5_cnns-EtomicBomb/code/run.py", line 167, in train
    model.fit(
  File "/home/ethan/.local/lib/python3.10/site-packages/keras/utils/traceback_utils.py", line 65, in error_handler
    return fn(*args, **kwargs)
  File "/home/ethan/.local/lib/python3.10/site-packages/keras/engine/training.py", line 1650, in fit
    tmp_logs = self.train_function(iterator)
  File "/home/ethan/.local/lib/python3.10/site-packages/tensorflow/python/util/traceback_utils.py", line 150, in error_handler

```

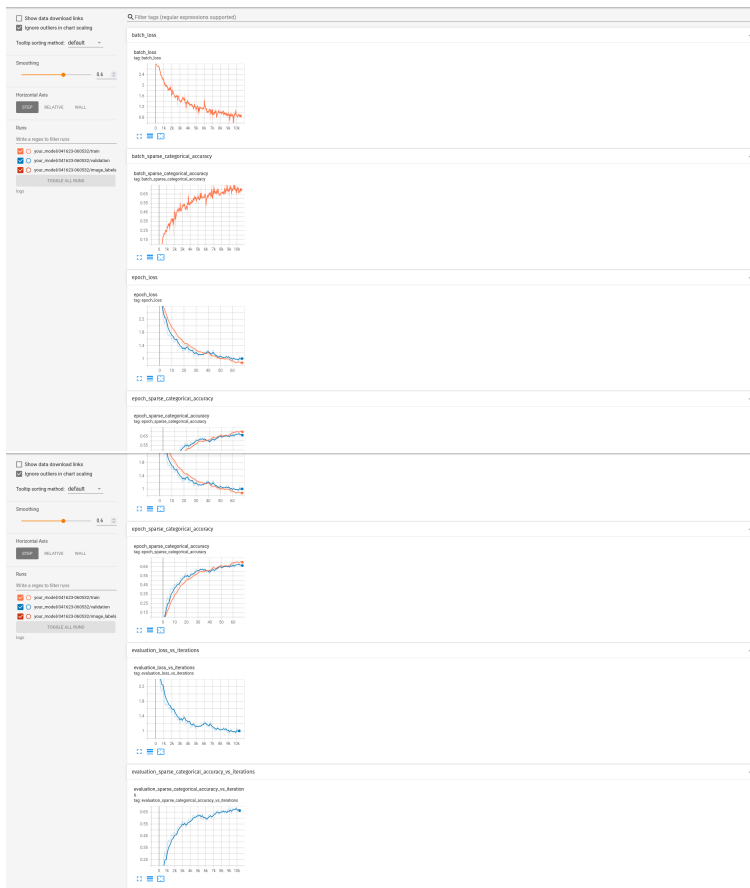


Figure 2: Progress training the complete model

With	Epochs	Sparse categorization accuracy
Base	3	0.2315
Standardization	3	0.1300
Data augmentation	3	0.1008
Regularization	56	0.6873

Table 1: Task 1 performance after adding each intermediate sophistication. I was able to train the network with full standardization, augmentation, and regularization on Colab. The intermediate networks were trained on my laptop (which only has a cpu – thus limited epochs). This is because I was not able to access Colab GPUs due to availability limits when I went back to do at the intermediate stages. I believe the decreasing accuracy as more sophistication was added is just because of random chance and high variation from few epochs. I noticed that before adding data augmentation (on my lost intermediate run, when I still could use Colab) the training accuracy was able to get to basically 100, while the test accuracy stayed low - maybe in the 20s or 30s. When I added augmentation, the accuracy in training and testing coincided.



Figure 3: Task 1: Progress training the intermediate models.

Type	Sparse categorization accuracy
Total	0.9106

Table 2: Task 3 performance

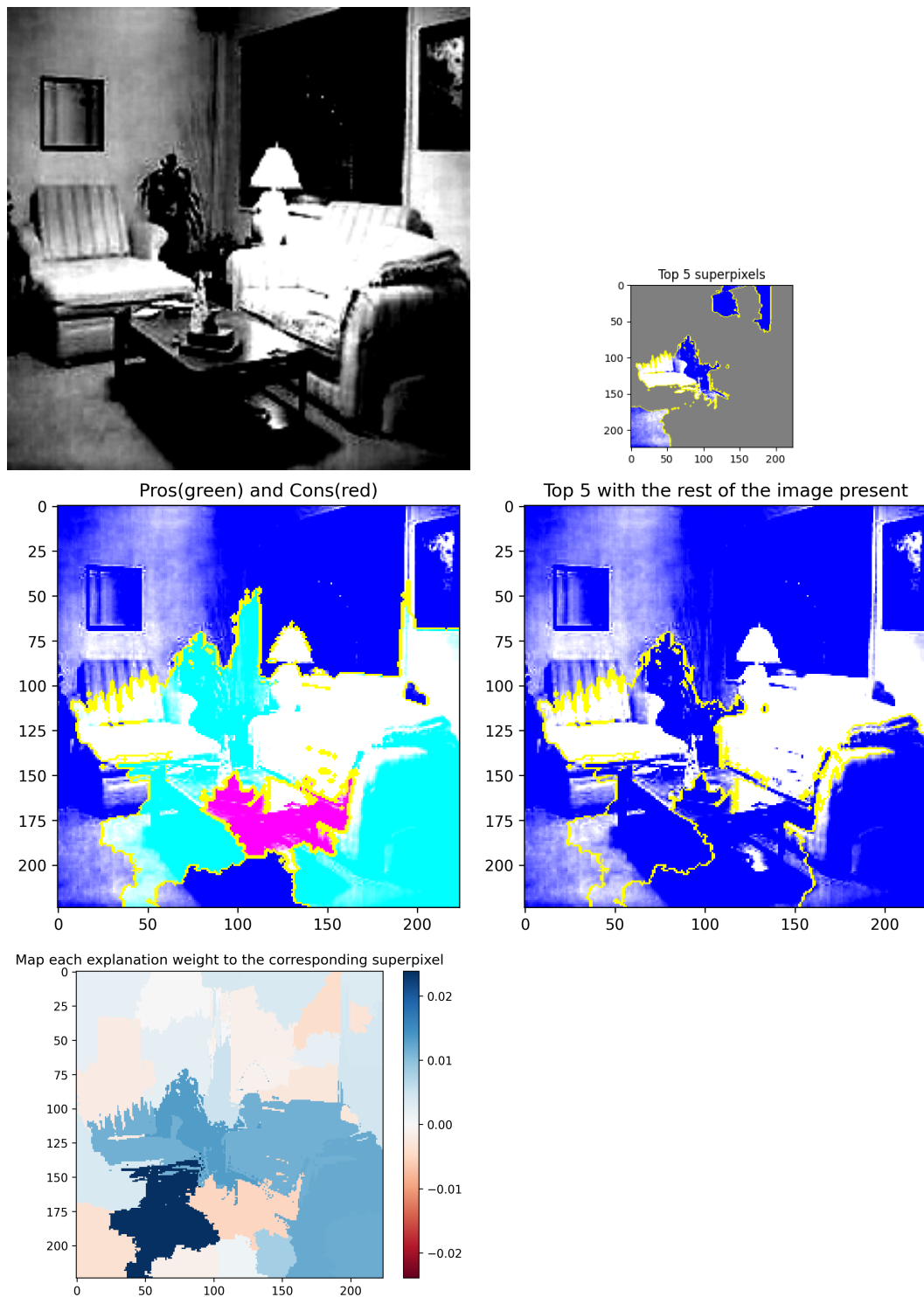


Figure 4: This is a bedroom, but was predicted as a living room. Curious. This model seemed to focus on the middle left of the image, especially the floor and part of the chair. It also seemed to attend to the window. These features – floors, chairs, and windows are all part of both bedrooms and living rooms. If it only attended to these features it's not surprising that it would get confused. I was not able to figure out whether it likes using the sky for its successful classifications.

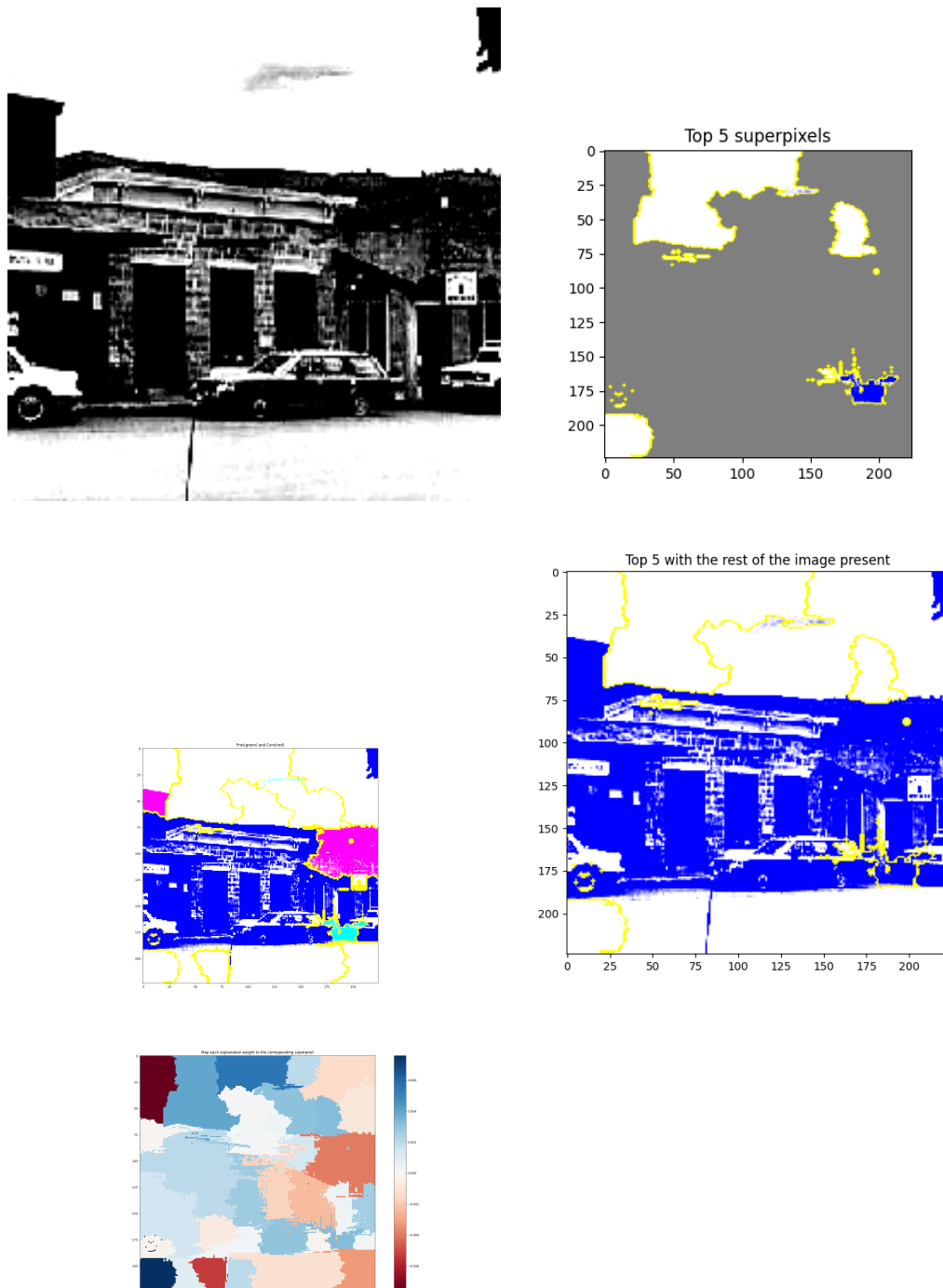


Figure 5: This is an inside city, but was predicted as a suburb. Curious. It seems like the model didn't really care about the architecture. Instead it focused on the sky and the front of a car, and part of the street. It would make sense that it would confuse an outdoor image of a suburb with a city if it was just looking at the sky.

```

Model: "vgg_base"
Layer (type) Output Shape Param #
-----
block1_conv1 (Conv2D) (None, 224, 224, 64) 1792
block1_conv2 (Conv2D) (None, 224, 224, 64) 36928
block1_pool (MaxPooling2D) (None, 112, 112, 64) 0
block2_conv1 (Conv2D) (None, 112, 112, 128) 73856
block2_conv2 (Conv2D) (None, 112, 112, 128) 147584
block2_pool (MaxPooling2D) (None, 56, 56, 128) 0
block3_conv1 (Conv2D) (None, 56, 56, 256) 295168
block3_conv2 (Conv2D) (None, 56, 56, 256) 590880
block3_conv3 (Conv2D) (None, 56, 56, 256) 590880
block3_pool (MaxPooling2D) (None, 28, 28, 256) 0
block4_conv1 (Conv2D) (None, 28, 28, 512) 1180160
block4_conv2 (Conv2D) (None, 28, 28, 512) 2359808
block4_conv3 (Conv2D) (None, 28, 28, 512) 2359808
block4_pool (MaxPooling2D) (None, 14, 14, 512) 0
block5_conv1 (Conv2D) (None, 14, 14, 512) 2359808
block5_conv2 (Conv2D) (None, 14, 14, 512) 2359808
block5_conv3 (Conv2D) (None, 14, 14, 512) 2359808
block5_pool (MaxPooling2D) (None, 7, 7, 512) 0
=====
Total params: 14,714,688
Trainable params: 0
Non-trainable params: 14,714,688
Model: "vgg_head"
Layer (type) Output Shape Param #
-----
flatten (Flatten) (None, 25088) 0
dense (Dense) (None, 400) 10035600
dropout (Dropout) (None, 400) 0
dense_1 (Dense) (None, 256) 102656
dense_2 (Dense) (None, 128) 32896
dropout_1 (Dropout) (None, 128) 0
dense_3 (Dense) (None, 15) 1935
=====
Total params: 10,173,087
Trainable params: 10,173,087
Non-trainable params: 0
Done setting up image labeling logger.
<keras.preprocessing.image.DirectoryIterator object at 0x7f0420506a0>

```

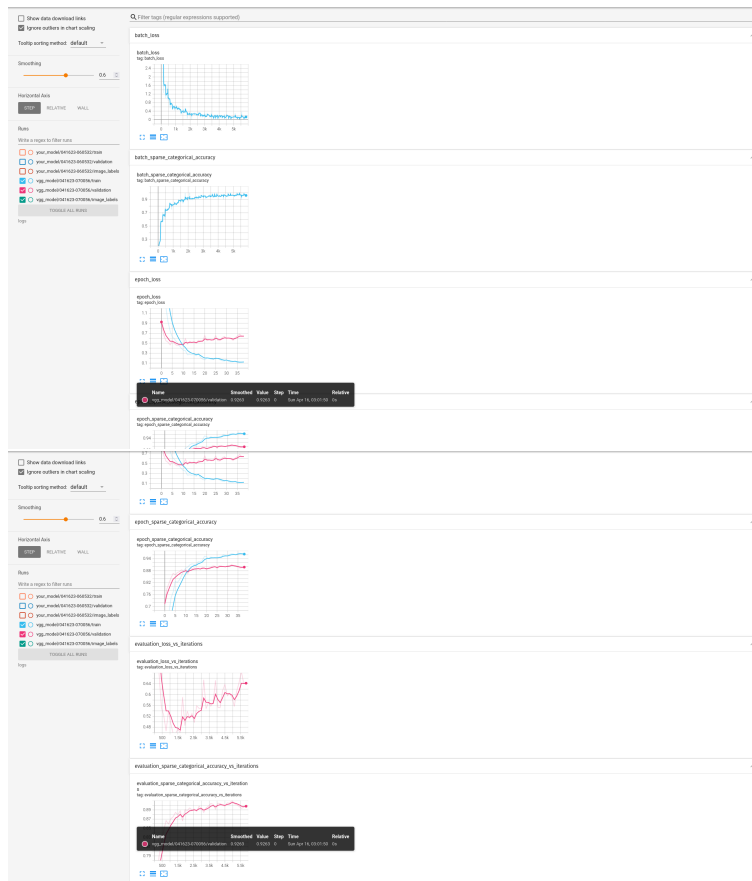


Figure 6: Task 3: Progress training head of the vgg model.