

/root/my_ros_ws/src
/rt2_assignment1/src
/position_service.cpp

```
graph TD; A["/root/my_ros_ws/src<br>/rt2_assignment1/src<br>/position_service.cpp"] --> B["ros/ros.h"]; A --> C["rt2_assignment1/RandomPosition.h"]
```

ros/ros.h

rt2_assignment1/RandomPosition.h