



Robotics

By C.S.G. Lee, K.S. Fu, R.C. Gonzalez

McGraw Hill Education, 2008. Softcover. Condition: New. First edition. This book is intended for the undergraduate students of Mechanical, Production and Industrial Engineering, Scientists and practicing engineers. It provides a comprehensive, well-organized, and up-to-date account of basic principles underlying the design, analysis and synthesis of robotic systems. Salient Features Presents analytical techniques and fundamental principles of robotics in a unified and coherent manner Numerous examples are worked out in the text to illustrate the discussion, and exercises of various types and complexity are included at the end of each chapter Table of contents: 1 Introduction 2 Robot Arms Kinematics 3 Robot Arm Dynamics 4 Planning of Manipulator Trajectories 5 Robot Arm Control 6 Sensing 7 Lower-Level Vision 8 Higher Level Vision 9 Robot Programming Languages 10 Robot Intelligence and Task Planning Appendixes Printed Pages: 594.



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