

# ex5\_sol

May 23, 2018

## 1 Exercise 5 - Convolutional Neural Networks and the MNIST dataset

This exercise is based on <https://github.com/leriomaggio/deep-learning-keras-tensorflow>

We want to solve the same multinomial classification problem as in last weeks exercise 4 using the MNIST dataset, but this time we want to use a convolutional neural network for it.

Before we start, we define a few useful functions, which we used in exercise 4:

```
In [1]: #####

import matplotlib.pyplot as plt
%matplotlib inline

def plot_history(network_history):
    plt.figure()
    plt.xlabel('Epochs')
    plt.ylabel('Loss')
    plt.plot(network_history.history['loss'])
    plt.plot(network_history.history['val_loss'])
    plt.legend(['Training', 'Validation'])

    plt.figure()
    plt.xlabel('Epochs')
    plt.ylabel('Accuracy')
    plt.plot(network_history.history['acc'])
    plt.plot(network_history.history['val_acc'])
    plt.legend(['Training', 'Validation'], loc='lower right')
    plt.show()

#####

import itertools
def plot_confusion_matrix(cm, classes,
                          normalize=False,
                          title='Confusion matrix',
                          cmap=plt.cm.Blues):
    """
    This function prints and plots the confusion matrix.
```

```

Normalization can be applied by setting `normalize=True`.
"""

plt.imshow(cm, interpolation='nearest', cmap=cmap)
plt.title(title)
plt.colorbar()
tick_marks = np.arange(len(classes))
plt.xticks(tick_marks, classes, rotation=45)
plt.yticks(tick_marks, classes)

if normalize:
    cm = cm.astype('float') / cm.sum(axis=1)[:, np.newaxis]

thresh = cm.max() / 2.
for i, j in itertools.product(range(cm.shape[0]), range(cm.shape[1])):
    plt.text(j, i, cm[i, j],
             horizontalalignment="center",
             color="white" if cm[i, j] > thresh else "black")

plt.tight_layout()
plt.ylabel('True label')
plt.xlabel('Predicted label')

#####
import matplotlib.cm as cm
def display_errors(errors_index,img_errors,pred_errors, obs_errors):
    """ This function shows 6 images with their predicted and real labels"""
    n = 0
    nrows = 2
    ncols = 3
    fig, ax = plt.subplots(nrows,ncols,sharex=True,sharey=True)
    for row in range(nrows):
        for col in range(ncols):
            error = errors_index[n]
            ax[row,col].imshow((img_errors[error]).reshape((28,28)), cmap=cm.Greys, interpl=nearest)
            ax[row,col].set_title("Predicted label :{}\nTrue label :{}".format(pred_errors[row,col],obs_errors[row,col]))
            n += 1

#####

```

## 1.1 Data Preparation

### 1.1.1 Very Important:

When dealing with images & convolutions, you need to handle the `image_data_format` properly, i.e. is the channel given first or last. The channel axis is an additional dimension of the input data used to access different views of the data, e.g. red/green/blue of a color image, left or right of a stereo sound file)

In [2]: `from keras import backend as K`

Using TensorFlow backend.

```
-----  
RuntimeError                                Traceback (most recent call last)  
  
RuntimeError: module compiled against API version 0xc but this version of numpy is 0xb
```

```
-----  
RuntimeError                                Traceback (most recent call last)  
  
RuntimeError: module compiled against API version 0xc but this version of numpy is 0xb
```

```
In [3]: img_rows, img_cols = 28, 28  
  
if K.image_data_format() == 'channels_first':  
    shape_ord = (1, img_rows, img_cols)  
else: # channel_last  
    shape_ord = (img_rows, img_cols, 1)
```

### 1.1.2 Task 1: Data preprocessing

- Load the mnist data of the keras datasets
- Scale the design matrix to values between 0 and 1
- Convert the design matrix to the expected (60000, 28, 28, 1) shape
- Convert the target vector to one-hot-vectors for the 10 classes
- Split the training data into 70% training and 30% validation data sets

### 1.1.3 Loading Data

```
In [4]: #Import the required libraries  
import numpy as np  
from keras.utils import np_utils  
  
np.random.seed(1338) # for reproducibility!!  
  
from keras.datasets import mnist  
  
(X_train, y_train), (X_test, y_test) = mnist.load_data()
```

### 1.1.4 Preprocess and Normalise Data

Convert the data to float, scale it with a MinMaxScaler and add the channel dimension

```
In [5]: X_train.shape
```

```
Out[5]: (60000, 28, 28)
```

```
In [6]: X_train = X_train.astype('float32')
```

```
X_test = X_test.astype('float32')
```

```
from sklearn.preprocessing import MinMaxScaler
```

```
scaler = MinMaxScaler(feature_range=(0, 1))
```

```
X_train = scaler.fit_transform(X_train.reshape(X_train.shape[0],img_rows*img_cols))
```

```
X_test = scaler.transform(X_test.reshape(X_test.shape[0],img_rows*img_cols))
```

```
X_train = X_train.reshape(X_train.shape[0],img_rows,img_cols)
```

```
X_test = X_test.reshape(X_test.shape[0],img_rows,img_cols)
```

```
In [7]: X_train.shape
```

```
Out[7]: (60000, 28, 28)
```

```
In [8]: X_train = X_train.reshape((X_train.shape[0],) + shape_ord)
```

```
X_test = X_test.reshape((X_test.shape[0],) + shape_ord)
```

```
In [9]: X_train.shape
```

```
Out[9]: (60000, 28, 28, 1)
```

### 1.1.5 Convert target vector

```
In [10]: from keras.utils import np_utils
```

```
num_classes = 10
```

```
Y_train = np_utils.to_categorical(y_train, num_classes)
```

```
Y_test = np_utils.to_categorical(y_test, num_classes)
```

```
Y_test[0]
```

```
Out[10]: array([ 0.,  0.,  0.,  0.,  0.,  0.,  0.,  1.,  0.,  0.], dtype=float32)
```

### 1.1.6 Split Training and Validation Data

```
In [11]: from sklearn.model_selection import train_test_split
```

```
X_train, X_val, Y_train, Y_val = train_test_split(X_train, Y_train, test_size=0.3, rand
```

## 1.2 A simple convolutional neural network

### Convolution2D

```
from keras.layers.convolutional import Conv2D
```

```
Conv2D(filters, kernel_size, strides=(1, 1), padding='valid',
```

```

data_format=None, dilation_rate=(1, 1), activation=None,
use_bias=True, kernel_initializer='glorot_uniform',
bias_initializer='zeros', kernel_regularizer=None,
bias_regularizer=None, activity_regularizer=None,
kernel_constraint=None, bias_constraint=None)

```

**Arguments:** filters: Integer, the dimensionality of the output space (i.e. the number output of filters in the convolution).

kernel\_size: An integer or tuple/list of 2 integers, specifying the width and height of the 2D convolution window. Can be a single integer to specify the same value for all spatial dimensions.

strides: An integer or tuple/list of 2 integers, specifying the strides of the convolution along the width and height. Can be a single integer to specify the same value for all spatial dimensions. Specifying any stride value != 1 is incompatible with specifying any dilation\_rate value != 1.

padding: one of "valid" or "same" (case-insensitive).

data\_format: A string, one of channels\_last (default) or channels\_first. The ordering of the dimensions in the inputs. channels\_last corresponds to inputs with shape (batch, height, width, channels) while channels\_first corresponds to inputs with shape (batch, channels, height, width). It defaults to the image\_data\_format value found in your Keras config file at ~/.keras/keras.json. If you never set it, then it will be "channels\_last".

dilation\_rate: an integer or tuple/list of 2 integers, specifying the dilation rate to use for dilated convolution. Can be a single integer to specify the same value for all spatial dimensions. Currently, specifying any dilation\_rate value != 1 is incompatible with specifying any stride value != 1.

activation: Activation function to use (see activations). If you don't specify anything, no activation is applied (ie. "linear" activation:  $a(x) = x$ ).

use\_bias: Boolean, whether the layer uses a bias vector.

kernel\_initializer: Initializer for the kernel weights matrix (see initializers).

bias\_initializer: Initializer for the bias vector (see initializers).

kernel\_regularizer: Regularizer function applied to the kernel weights matrix (see regularizer).

bias\_regularizer: Regularizer function applied to the bias vector (see regularizer).

activity\_regularizer: Regularizer function applied to the output of the layer (its "activation"). (see regularizer).

kernel\_constraint: Constraint function applied to the kernel matrix (see constraints).

bias\_constraint: Constraint function applied to the bias vector (see constraints).

```

In [12]: from keras.models import Sequential
         from keras.layers.core import Dense, Dropout, Activation, Flatten

         from keras.layers.convolutional import Conv2D
         from keras.layers.pooling import MaxPooling2D

```

### 1.2.1 Model Definition

```

In [13]: # -- Initializing the values for the convolution neural network

nb_epoch = 10 # kept very low! Please increase if you can use a GPU

batch_size = 256
# number of convolutional filters to use

```

```

nb_filters = 32
# size of pooling area for max pooling
nb_pool = 2
# convolution kernel size
nb_conv = 3

```

```
In [14]: model = Sequential()
```

```

model.add(Conv2D(nb_filters, kernel_size=(nb_conv, nb_conv), padding='valid', activation='relu',
                 input_shape=shape_ord)) # note: the very first layer must always
model.add(Flatten())
model.add(Dense(10, activation='softmax'))

model.compile(loss='categorical_crossentropy', optimizer='adam', metrics=['accuracy'])

model.summary()

```

```

-----
Layer (type)                 Output Shape          Param #
-----
conv2d_1 (Conv2D)            (None, 26, 26, 32)   320
-----
flatten_1 (Flatten)          (None, 21632)         0
-----
dense_1 (Dense)              (None, 10)            216330
=====
Total params: 216,650
Trainable params: 216,650
Non-trainable params: 0
-----

```

## 1.2.2 Training

```
In [15]: hist = model.fit(X_train, Y_train, batch_size=batch_size,
                          epochs=nb_epoch, verbose=1,
                          validation_data=(X_val, Y_val))
```

Train on 42000 samples, validate on 18000 samples

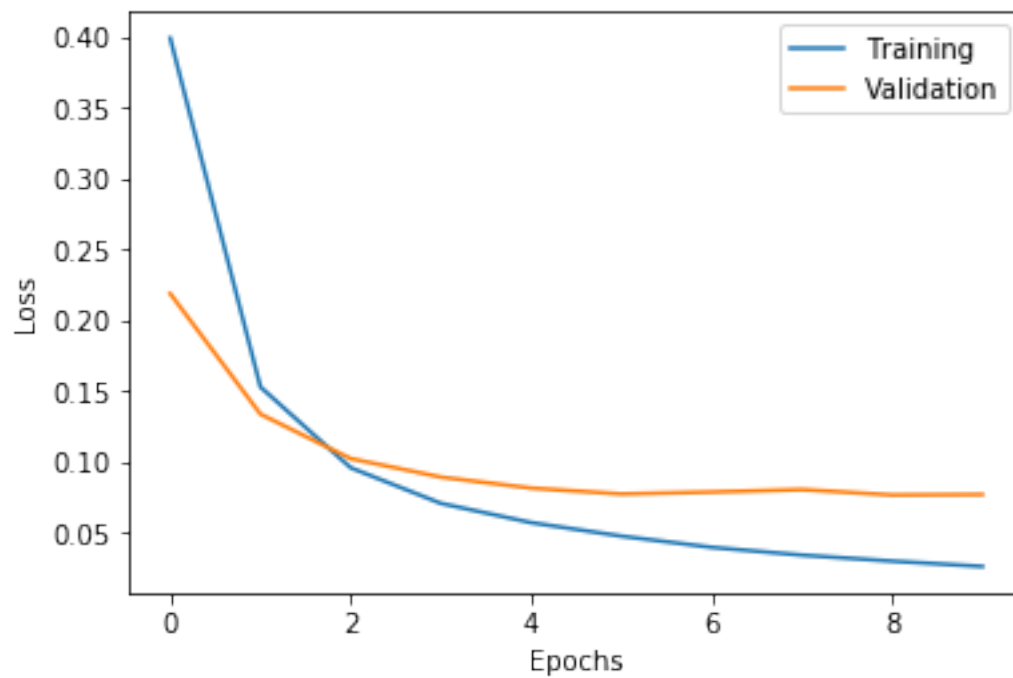
```

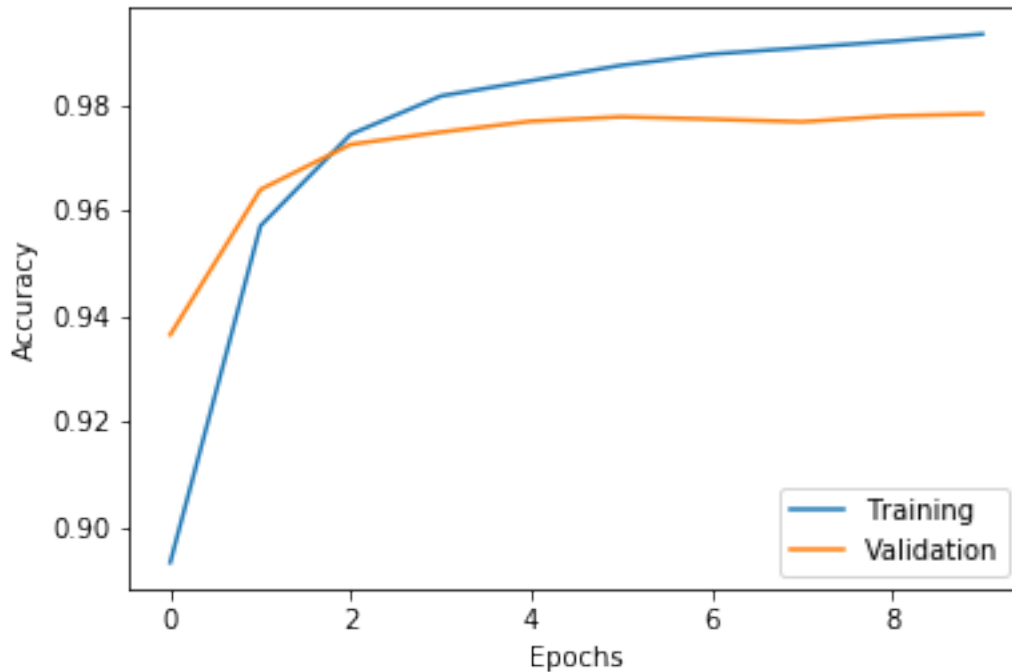
Epoch 1/10
42000/42000 [=====] - 12s 291us/step - loss: 0.3995 - acc: 0.8932 - val
Epoch 2/10
42000/42000 [=====] - 23s 552us/step - loss: 0.1529 - acc: 0.9570 - val
Epoch 3/10
42000/42000 [=====] - 19s 456us/step - loss: 0.0958 - acc: 0.9744 - val
Epoch 4/10
42000/42000 [=====] - 19s 444us/step - loss: 0.0706 - acc: 0.9816 - val
Epoch 5/10
42000/42000 [=====] - 19s 441us/step - loss: 0.0570 - acc: 0.9845 - val

```

```
Epoch 6/10
42000/42000 [=====] - 22s 516us/step - loss: 0.0474 - acc: 0.9874 - val
Epoch 7/10
42000/42000 [=====] - 23s 553us/step - loss: 0.0395 - acc: 0.9895 - val
Epoch 8/10
42000/42000 [=====] - 18s 433us/step - loss: 0.0340 - acc: 0.9907 - val
Epoch 9/10
42000/42000 [=====] - 21s 505us/step - loss: 0.0298 - acc: 0.9920 - val
Epoch 10/10
42000/42000 [=====] - 16s 372us/step - loss: 0.0260 - acc: 0.9933 - val
```

```
In [16]: plot_history(hist)
```





### 1.2.3 Task 2: Evaluating - Define an evaluate function, with the following properties:

- It takes X\_test and Y\_test as arguments
- It calculates the loss, the accuracy and the classification report
- It plots the probability of being a zero for true zeros (red) and non-zeros (blue)
- It computes and plots the confusion matrix
- It plots the image, the prediction and the true value for the top 6 errors
- It plots image and predictions for the first 15 examples

```
In [17]: from sklearn.metrics import confusion_matrix, classification_report

def evaluate(X_test, Y_test):

    ##Evaluate loss and metrics
    loss, accuracy = model.evaluate(X_test, Y_test, verbose=0)
    print('Test Loss:', loss)
    print('Test Accuracy:', accuracy)
    # Predict the values from the test dataset
    Y_pred = model.predict(X_test)
    # Convert predictions classes to one hot vectors
    Y_cls = np.argmax(Y_pred, axis = 1)
    # Convert validation observations to one hot vectors
    Y_true = np.argmax(Y_test, axis = 1)
    print 'Classification Report:\n', classification_report(Y_true,Y_cls)
```



```

## Plot 0 probability
label=0
Y_pred_prob = Y_pred[:,label]
plt.hist(Y_pred_prob[Y_true == label], alpha=0.5, color='red', bins=10, log = True)
plt.hist(Y_pred_prob[Y_true != label], alpha=0.5, color='blue', bins=10, log = True)
plt.legend(['digit == 0', 'digit != 0'], loc='upper right')
plt.xlabel('Probability of being 0')
plt.ylabel('Number of entries')
plt.show()

# compute the confusion matrix
confusion_mtx = confusion_matrix(Y_true, Y_cls)
# plot the confusion matrix
plt.figure(figsize=(8,8))
plot_confusion_matrix(confusion_mtx, classes = range(10))

#Plot largest errors
errors = (Y_cls - Y_true != 0)
Y_cls_errors = Y_cls[errors]
Y_pred_errors = Y_pred[errors]
Y_true_errors = Y_true[errors]
X_test_errors = X_test[errors]
# Probabilities of the wrong predicted numbers
Y_pred_errors_prob = np.max(Y_pred_errors,axis = 1)
# Predicted probabilities of the true values in the error set
true_prob_errors = np.diagonal(np.take(Y_pred_errors, Y_true_errors, axis=1))
# Difference between the probability of the predicted label and the true label
delta_pred_true_errors = Y_pred_errors_prob - true_prob_errors
# Sorted list of the delta prob errors
sorted_delta_errors = np.argsort(delta_pred_true_errors)
# Top 6 errors
most_important_errors = sorted_delta_errors[-6:]
# Show the top 6 errors
display_errors(most_important_errors, X_test_errors, Y_cls_errors, Y_true_errors)

##Plot predictions
slice = 15
predicted = model.predict(X_test[:slice]).argmax(-1)
plt.figure(figsize=(16,8))
for i in range(slice):
    plt.subplot(1, slice, i+1)
    plt.imshow(X_test[i].reshape(28,28), interpolation='nearest')
    plt.text(0, 0, predicted[i], color='black',
            bbox=dict(facecolor='white', alpha=1))
    plt.axis('off')

```

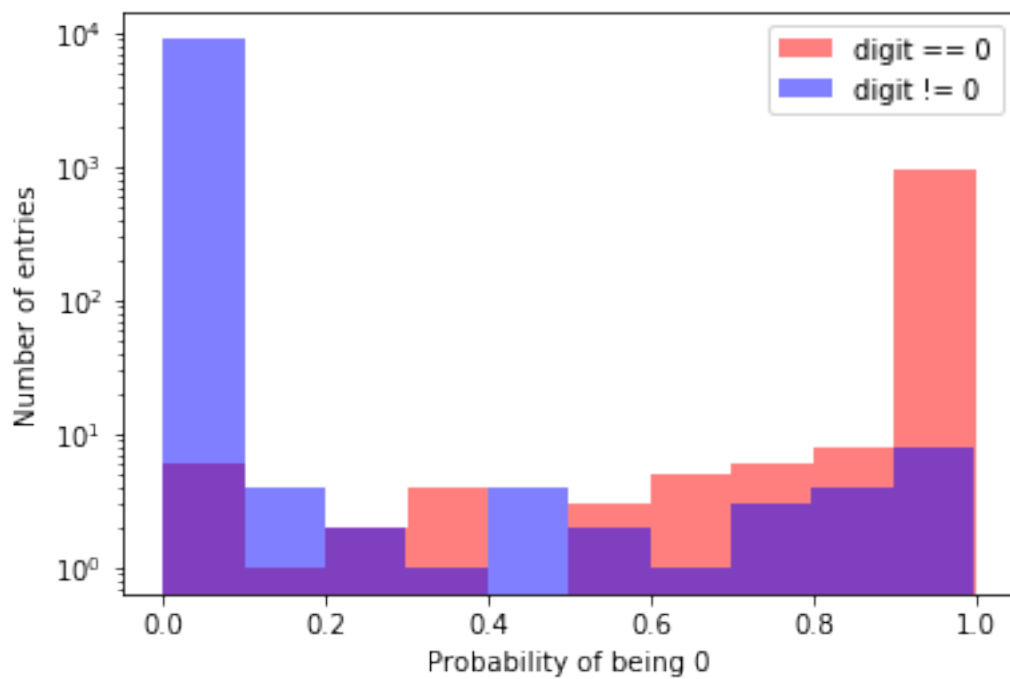
In [18]: evaluate(X\_test, Y\_test)

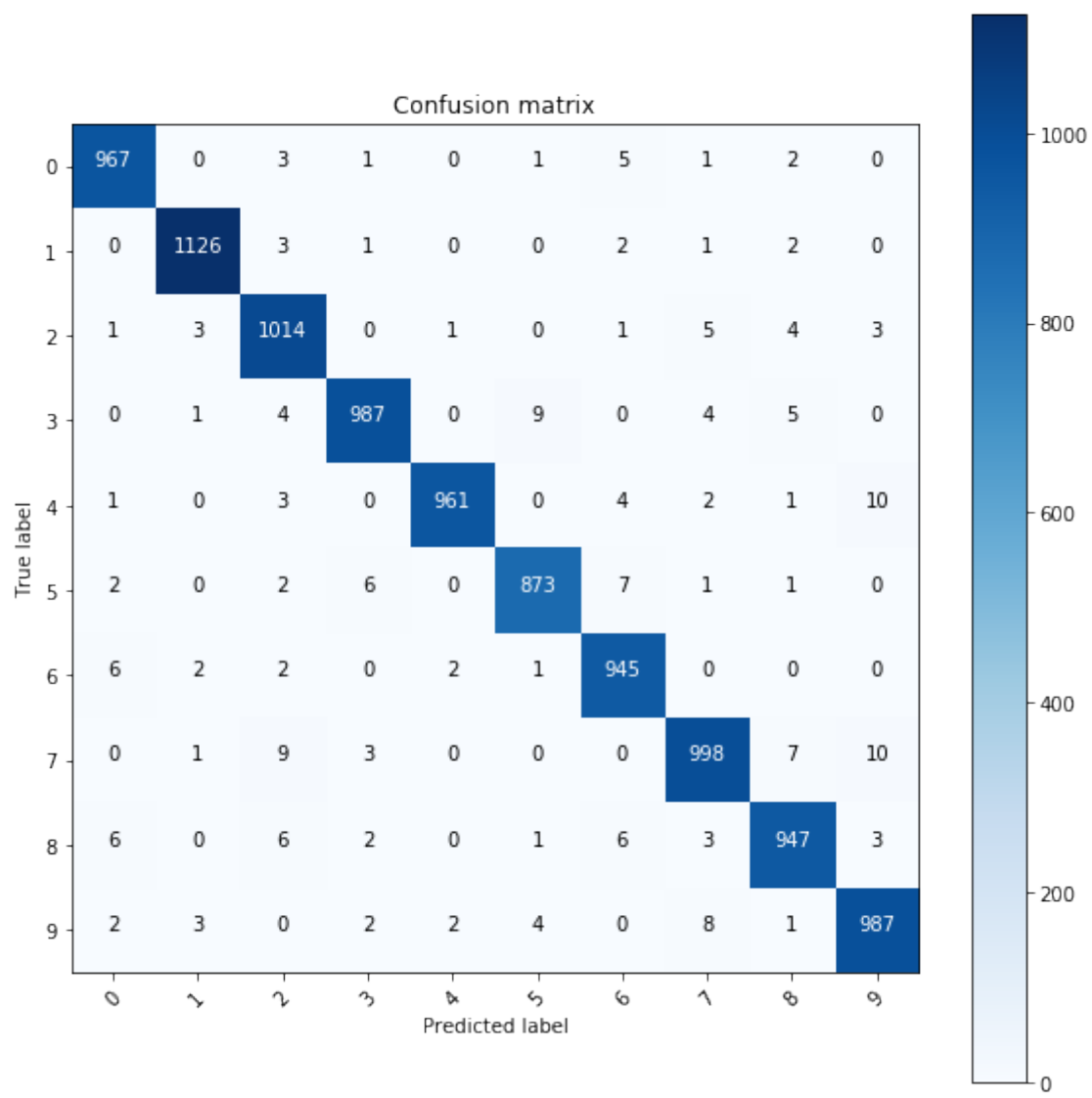
('Test Loss:', 0.065599114515818652)

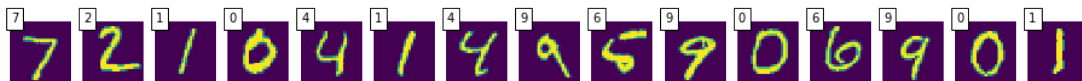
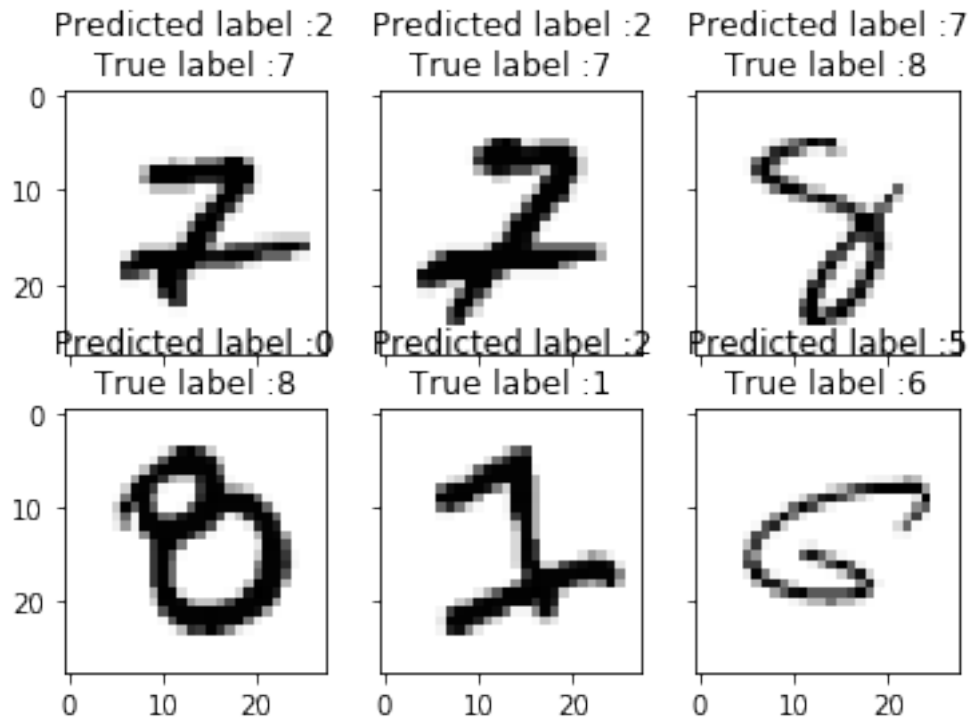
('Test Accuracy:', 0.98050000000000004)

Classification Report:

	precision	recall	f1-score	support
0	0.98	0.99	0.98	980
1	0.99	0.99	0.99	1135
2	0.97	0.98	0.98	1032
3	0.99	0.98	0.98	1010
4	0.99	0.98	0.99	982
5	0.98	0.98	0.98	892
6	0.97	0.99	0.98	958
7	0.98	0.97	0.97	1028
8	0.98	0.97	0.97	974
9	0.97	0.98	0.98	1009
avg / total	0.98	0.98	0.98	10000







### 1.3 Adding more Dense Layers and Dropout

#### 1.3.1 Task 3: Adding additional classification layers

- Add a dense layer between the flatten layer and the output layer
- Add a 25% dropout layer before the flatten layer
- Add a 50% dropout layer between the two dense layers
- Build the model, train the NN, plot the loss and accuracy evolution
- Evaluate the new model

In [19]: `model = Sequential()`

```

model.add(Conv2D(nb_filters, kernel_size=(nb_conv, nb_conv), padding='valid', activation='relu',
                input_shape=shape_ord))
model.add(Dropout(0.25))
model.add(Flatten())
model.add(Dense(128, activation='relu'))

```

```

model.add(Dropout(0.5))
model.add(Dense(10, activation='softmax'))

model.compile(loss='categorical_crossentropy',
              optimizer='adam',
              metrics=['accuracy'])

model.summary()

```

Layer (type)	Output Shape	Param #
conv2d_2 (Conv2D)	(None, 26, 26, 32)	320
dropout_1 (Dropout)	(None, 26, 26, 32)	0
flatten_2 (Flatten)	(None, 21632)	0
dense_2 (Dense)	(None, 128)	2769024
dropout_2 (Dropout)	(None, 128)	0
dense_3 (Dense)	(None, 10)	1290
Total params: 2,770,634		
Trainable params: 2,770,634		
Non-trainable params: 0		

### 1.3.2 Training

```

In [20]: hist = model.fit(X_train, Y_train, batch_size=batch_size,
                        epochs=nb_epoch, verbose=1,
                        validation_data=(X_val, Y_val))

```

Train on 42000 samples, validate on 18000 samples

Epoch 1/10

42000/42000 [=====] - 40s 952us/step - loss: 0.4073 - acc: 0.8766 - val\_loss: 0.1616 - val\_acc: 0.9524

Epoch 2/10

42000/42000 [=====] - 35s 822us/step - loss: 0.1616 - acc: 0.9524 - val\_loss: 0.1088 - val\_acc: 0.9670

Epoch 3/10

42000/42000 [=====] - 36s 860us/step - loss: 0.1088 - acc: 0.9670 - val\_loss: 0.0826 - val\_acc: 0.9747

Epoch 4/10

42000/42000 [=====] - 48s 1ms/step - loss: 0.0826 - acc: 0.9747 - val\_loss: 0.0685 - val\_acc: 0.9789

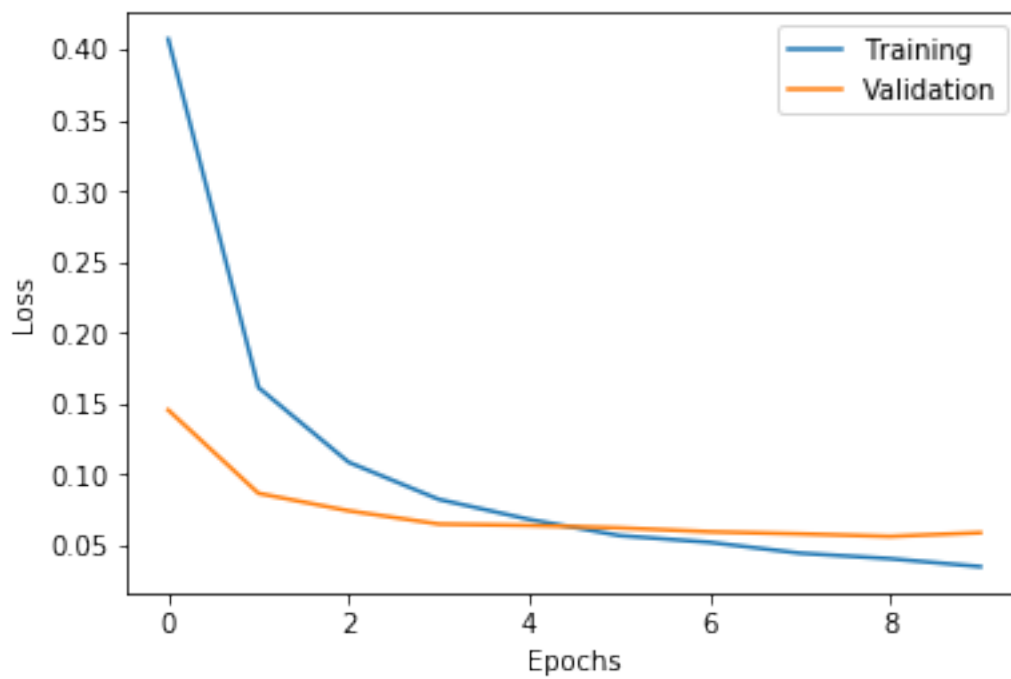
Epoch 5/10

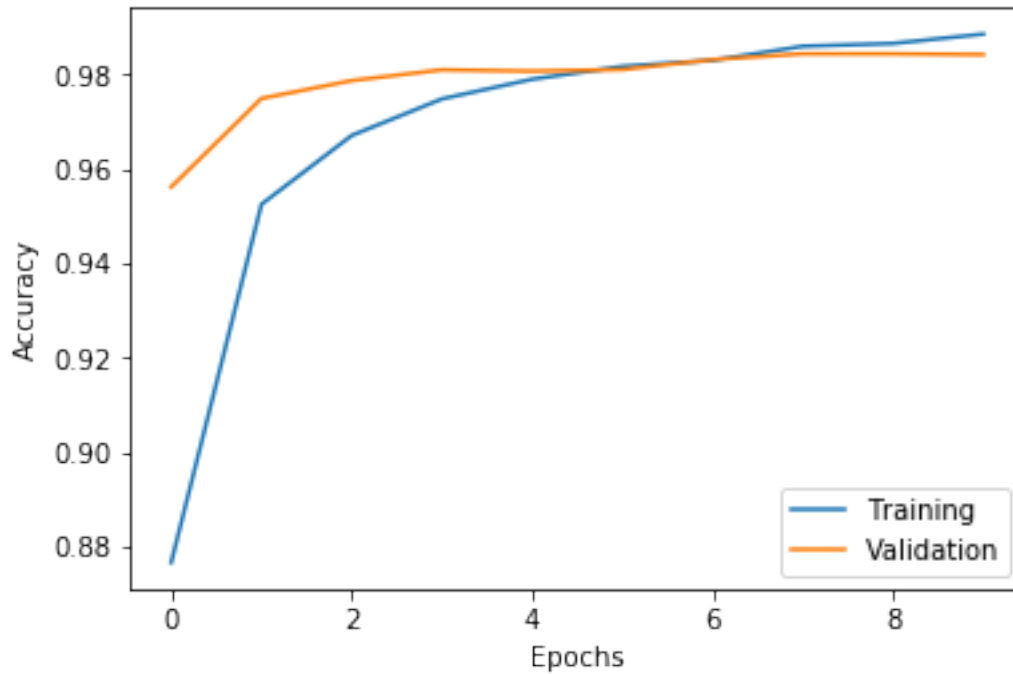
42000/42000 [=====] - 62s 1ms/step - loss: 0.0685 - acc: 0.9789 - val\_loss: 0.0685 - val\_acc: 0.9789

Epoch 6/10

```
42000/42000 [=====] - 83s 2ms/step - loss: 0.0571 - acc: 0.9816 - val_1
Epoch 7/10
42000/42000 [=====] - 80s 2ms/step - loss: 0.0524 - acc: 0.9829 - val_1
Epoch 8/10
42000/42000 [=====] - 88s 2ms/step - loss: 0.0447 - acc: 0.9859 - val_1
Epoch 9/10
42000/42000 [=====] - 94s 2ms/step - loss: 0.0408 - acc: 0.9865 - val_1
Epoch 10/10
42000/42000 [=====] - 80s 2ms/step - loss: 0.0352 - acc: 0.9885 - val_1
```

```
In [21]: plot_history(hist)
```





### 1.3.3 Evaluating

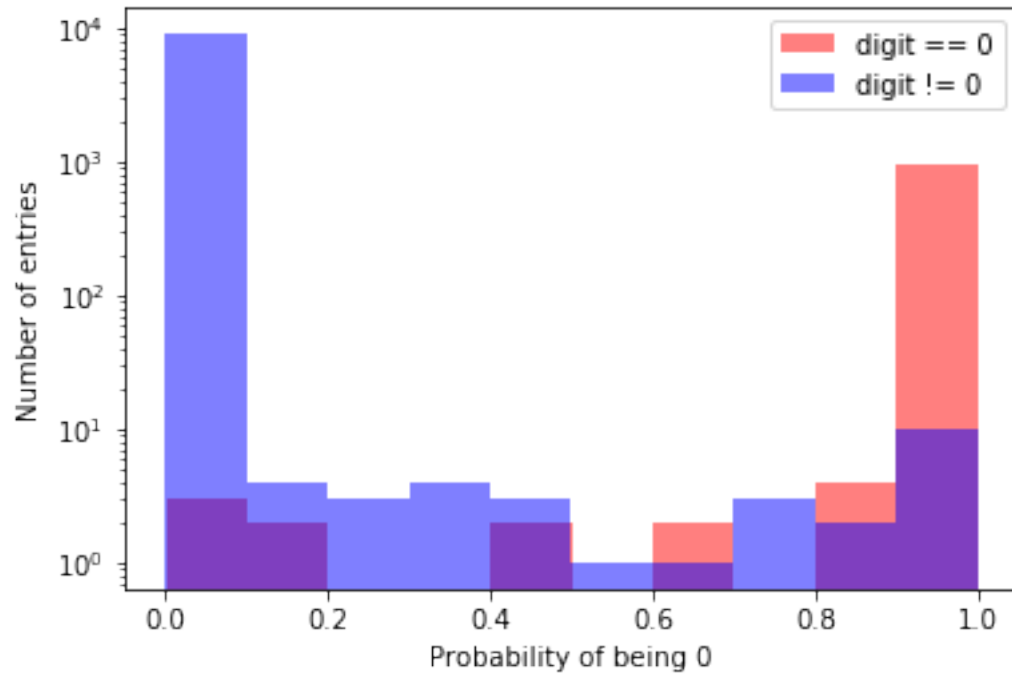
```
In [22]: # Evaluating the model on the test data
         evaluate(X_test, Y_test)
```

```
('Test Loss:', 0.048410624130575161)
```

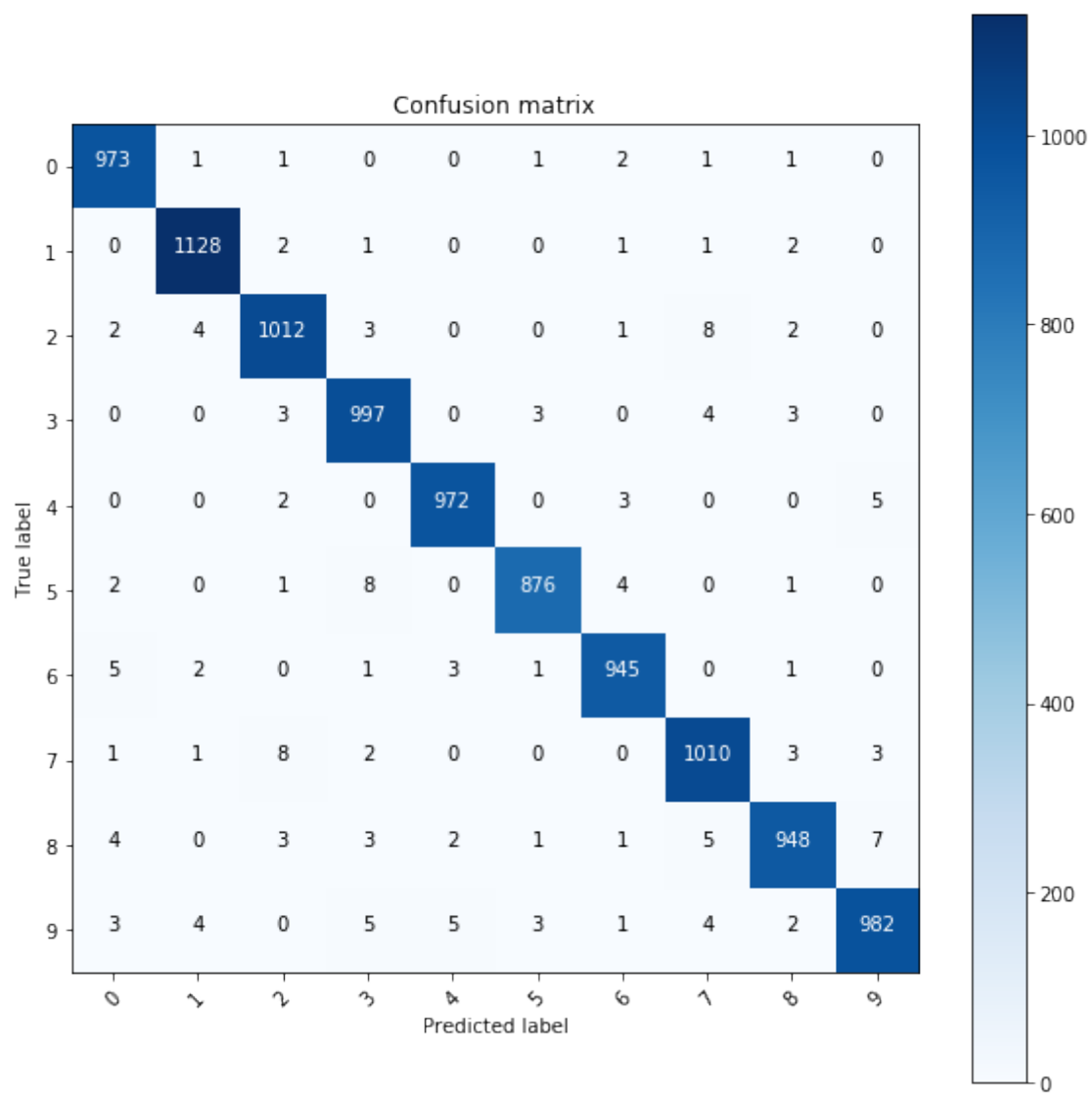
```
('Test Accuracy:', 0.98429999999999995)
```

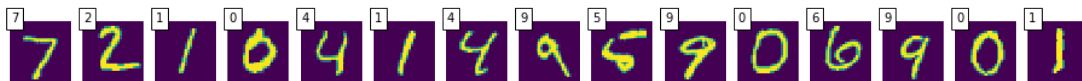
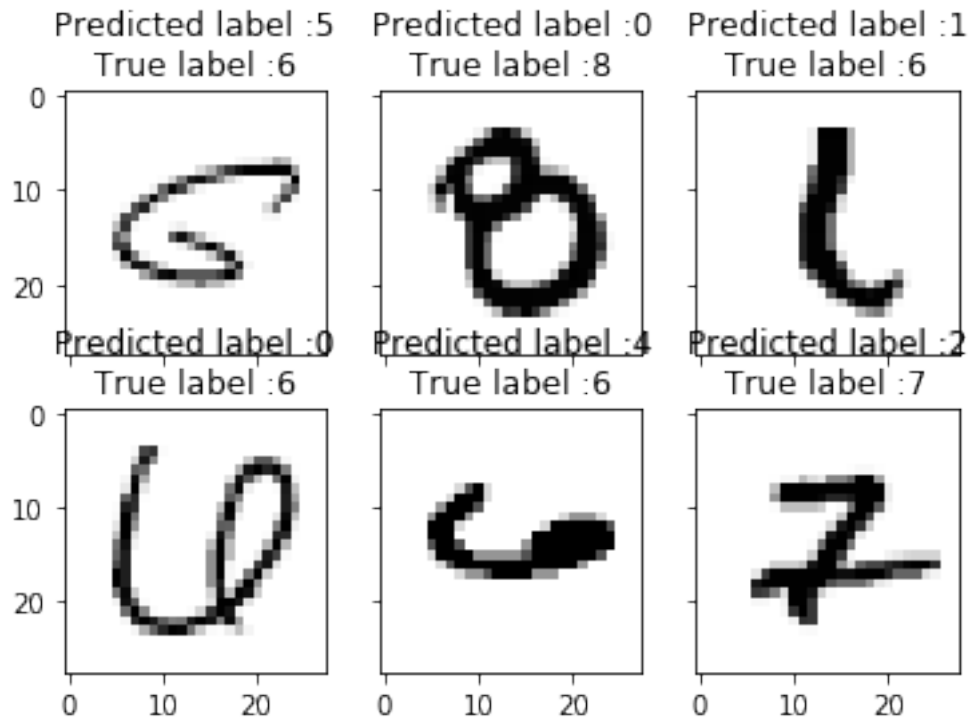
```
Classification Report:
```

	precision	recall	f1-score	support
0	0.98	0.99	0.99	980
1	0.99	0.99	0.99	1135
2	0.98	0.98	0.98	1032
3	0.98	0.99	0.98	1010
4	0.99	0.99	0.99	982
5	0.99	0.98	0.99	892
6	0.99	0.99	0.99	958
7	0.98	0.98	0.98	1028
8	0.98	0.97	0.98	974
9	0.98	0.97	0.98	1009
avg / total	0.98	0.98	0.98	10000









## 2 Adding an additional convolution layer and a pooling layer

### 2.0.1 Task 3: Adding additional classification layers

- Add another Conv2D layer after the first convolutional layer with 64 filter, 3x3 kernel and valid (no) padding
- Add another MaxPooling2D layer with a 2x2 pooling size
- Build the model, train the NN, plot the loss and accuracy evolution
- Evaluate the new model

In [23]: `model = Sequential()`

```

model.add(Conv2D(nb_filters, kernel_size=(nb_conv, nb_conv), padding='valid', activation='relu',
                 input_shape=shape_ord))
model.add(Conv2D(64, kernel_size=(nb_conv, nb_conv), padding='valid', activation='relu'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Dropout(0.25))

```

```

model.add(Flatten())
model.add(Dense(128, activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(10, activation='softmax'))

model.compile(loss='categorical_crossentropy',
              optimizer='adam',
              metrics=['accuracy'])

model.summary()

```

```

-----
Layer (type)                 Output Shape              Param #
-----
conv2d_3 (Conv2D)            (None, 26, 26, 32)       320
-----
conv2d_4 (Conv2D)            (None, 24, 24, 64)       18496
-----
max_pooling2d_1 (MaxPooling2 (None, 12, 12, 64)       0
-----
dropout_3 (Dropout)          (None, 12, 12, 64)       0
-----
flatten_3 (Flatten)          (None, 9216)              0
-----
dense_4 (Dense)              (None, 128)              1179776
-----
dropout_4 (Dropout)          (None, 128)              0
-----
dense_5 (Dense)              (None, 10)               1290
=====
Total params: 1,199,882
Trainable params: 1,199,882
Non-trainable params: 0
-----

```

## 2.0.2 Training

```

In [24]: hist = model.fit(X_train, Y_train, batch_size=batch_size,
                        epochs=nb_epoch, verbose=1,
                        validation_data=(X_val, Y_val))

```

Train on 42000 samples, validate on 18000 samples

Epoch 1/10

42000/42000 [=====] - 254s 6ms/step - loss: 0.3519 - acc: 0.8915 - val\_

Epoch 2/10

42000/42000 [=====] - 260s 6ms/step - loss: 0.1086 - acc: 0.9672 - val\_

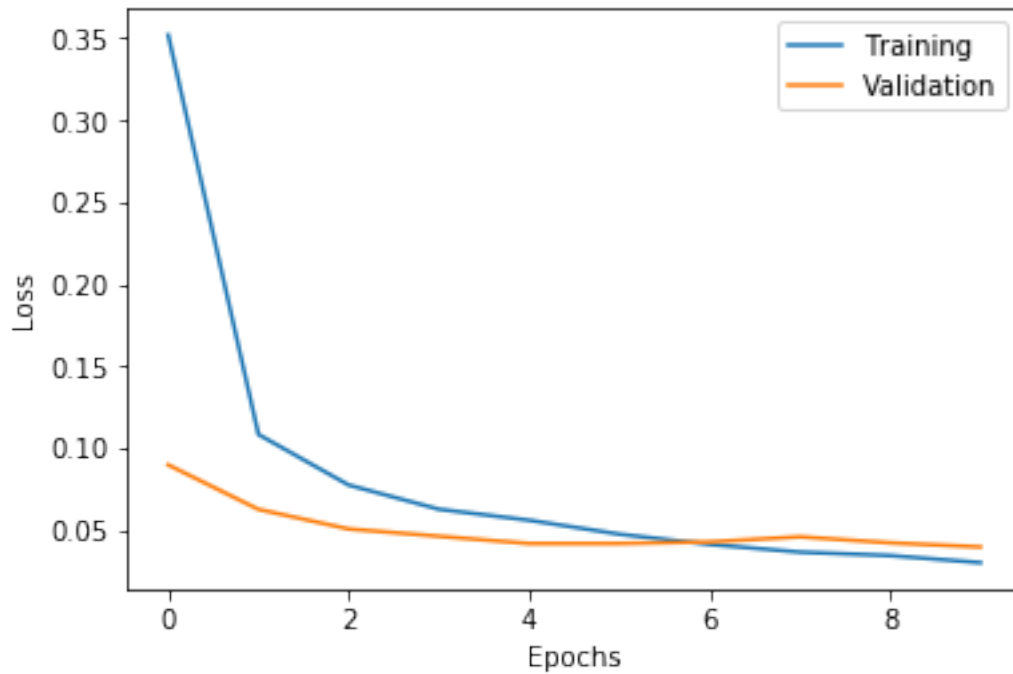
Epoch 3/10

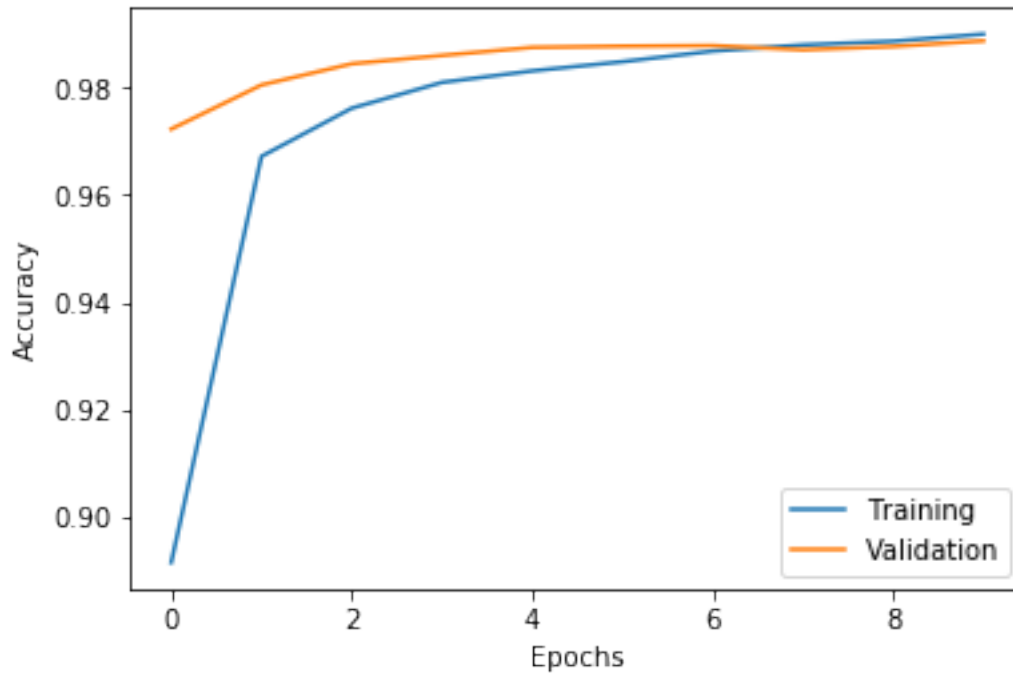
```

42000/42000 [=====] - 200s 5ms/step - loss: 0.0777 - acc: 0.9762 - val_
Epoch 4/10
42000/42000 [=====] - 189s 4ms/step - loss: 0.0630 - acc: 0.9810 - val_
Epoch 5/10
42000/42000 [=====] - 110s 3ms/step - loss: 0.0563 - acc: 0.9831 - val_
Epoch 6/10
42000/42000 [=====] - 107s 3ms/step - loss: 0.0478 - acc: 0.9848 - val_
Epoch 7/10
42000/42000 [=====] - 104s 2ms/step - loss: 0.0416 - acc: 0.9868 - val_
Epoch 8/10
42000/42000 [=====] - 117s 3ms/step - loss: 0.0369 - acc: 0.9880 - val_
Epoch 9/10
42000/42000 [=====] - 126s 3ms/step - loss: 0.0348 - acc: 0.9886 - val_
Epoch 10/10
42000/42000 [=====] - 103s 2ms/step - loss: 0.0305 - acc: 0.9900 - val_

```

```
In [25]: plot_history(hist)
```





### 2.0.3 Evaluating

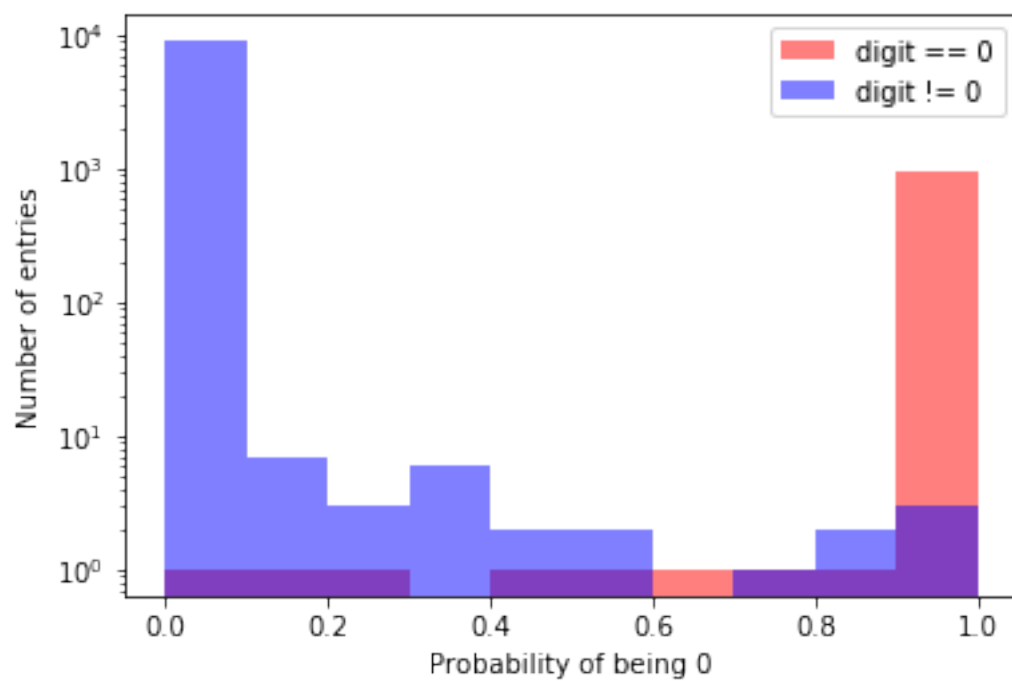
In [26]: `evaluate(X_test, Y_test)`

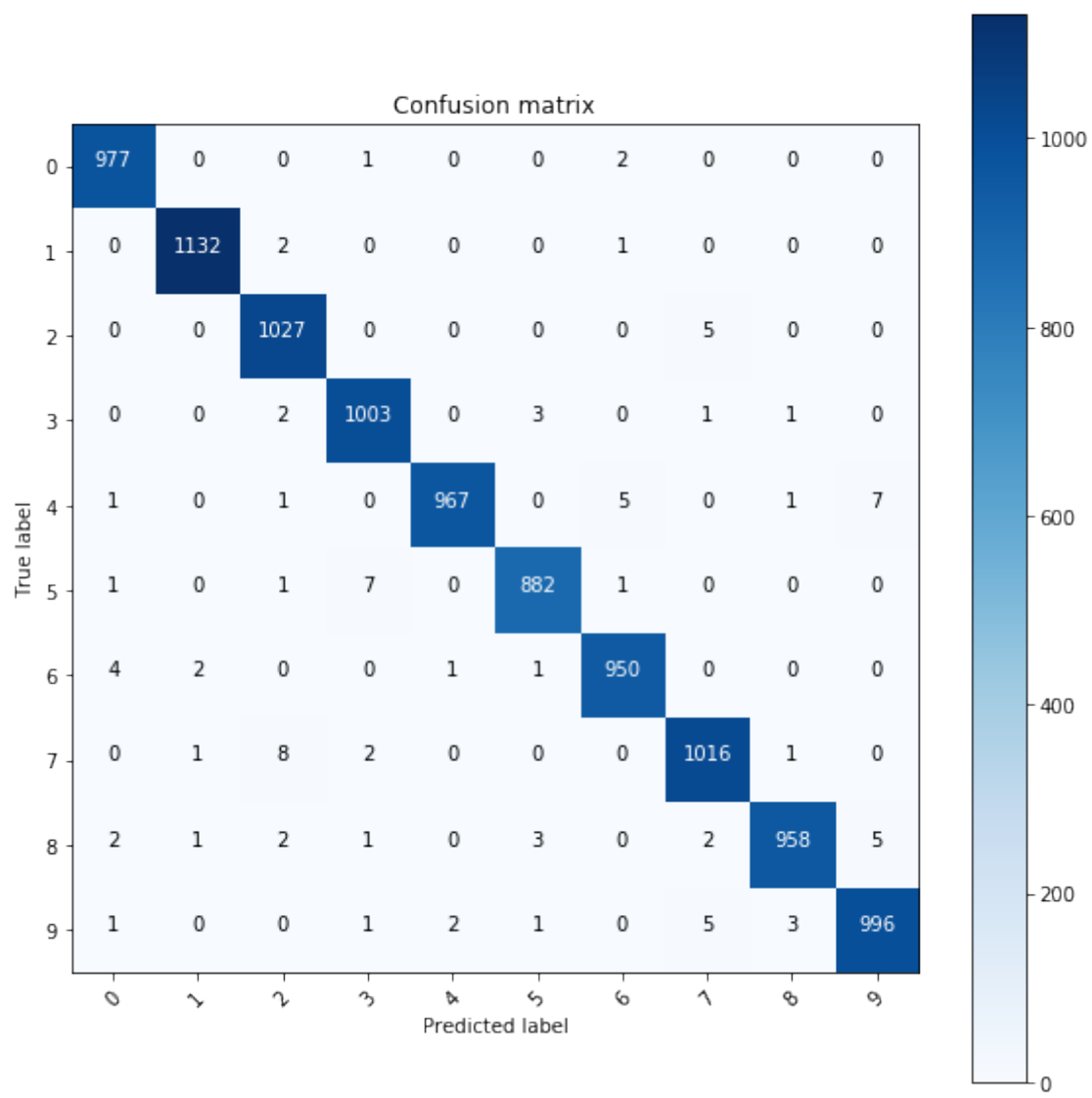
('Test Loss:', 0.032512901003119626)

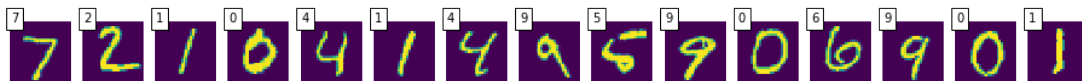
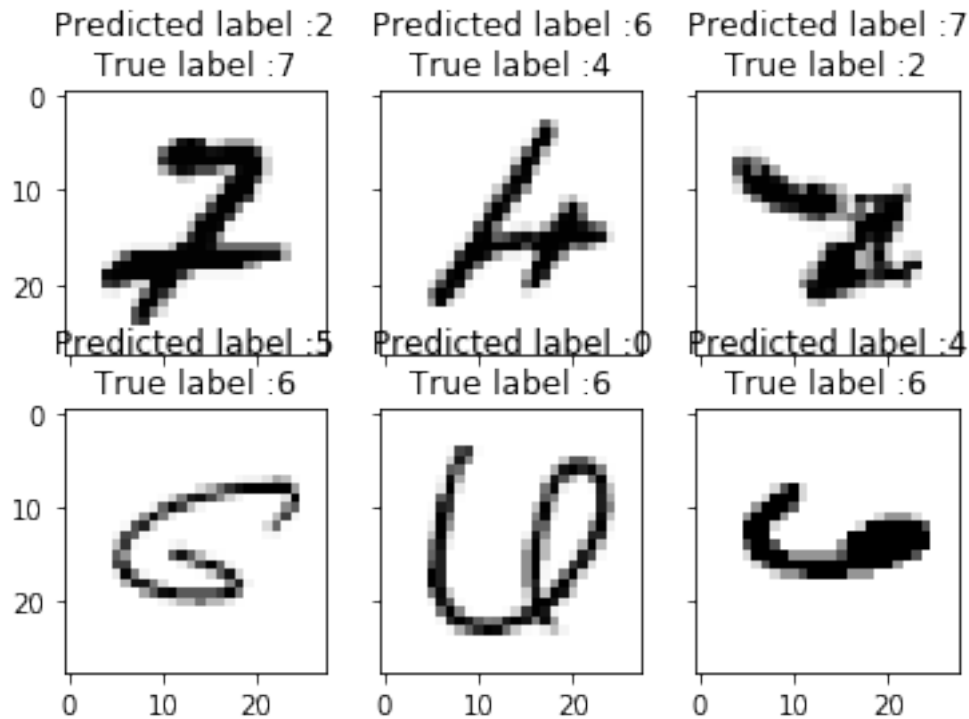
('Test Accuracy:', 0.990800000000000001)

Classification Report:

	precision	recall	f1-score	support
0	0.99	1.00	0.99	980
1	1.00	1.00	1.00	1135
2	0.98	1.00	0.99	1032
3	0.99	0.99	0.99	1010
4	1.00	0.98	0.99	982
5	0.99	0.99	0.99	892
6	0.99	0.99	0.99	958
7	0.99	0.99	0.99	1028
8	0.99	0.98	0.99	974
9	0.99	0.99	0.99	1009
avg / total	0.99	0.99	0.99	10000







### 3 Bonus: Understanding Convolutional Layers Structure

We will inspect and understand the convolutional layer of our previously defined quite shallow CNN, which contains two [Convolution, Convolution, MaxPooling] stages, and two Dense layers.

#### 3.0.1 Understanding layer shapes

An important feature of Keras layers is that each of them has an `input_shape` attribute, which you can use to visualize the shape of the input tensor, and an `output_shape` attribute, for inspecting the shape of the output tensor.

As we can see, the input shape of the first convolutional layer corresponds to the `input_shape` attribute (which must be specified by the user).

In this case, it is a 28x28 image with three color channels.



Since this convolutional layer has the padding set to same, its output width and height will remain the same, and the number of output channel will be equal to the number of filters learned by the layer, 16.

The following convolutional layer, instead, have the default padding, and therefore reduce width and height by  $(k - 1)$ , where  $k$  is the size of the kernel.

MaxPooling layers, instead, reduce width and height of the input tensor, but keep the same number of channels.

Activation layers, of course, don't change the shape.

```
In [27]: for i, layer in enumerate(model.layers):
          print ("Layer", i, "\t", layer.name, "\t\t", layer.input_shape, "\t", layer.output_shape)

('Layer', 0, '\t', 'conv2d_3', '\t\t', (None, 28, 28, 1), '\t', (None, 26, 26, 32))
('Layer', 1, '\t', 'conv2d_4', '\t\t', (None, 26, 26, 32), '\t', (None, 24, 24, 64))
('Layer', 2, '\t', 'max_pooling2d_1', '\t\t', (None, 24, 24, 64), '\t', (None, 12, 12, 64))
('Layer', 3, '\t', 'dropout_3', '\t\t', (None, 12, 12, 64), '\t', (None, 12, 12, 64))
('Layer', 4, '\t', 'flatten_3', '\t\t', (None, 12, 12, 64), '\t', (None, 9216))
('Layer', 5, '\t', 'dense_4', '\t\t', (None, 9216), '\t', (None, 128))
('Layer', 6, '\t', 'dropout_4', '\t\t', (None, 128), '\t', (None, 128))
('Layer', 7, '\t', 'dense_5', '\t\t', (None, 128), '\t', (None, 10))
```

### 3.0.2 Understanding weights shape

In the same way, we can visualize the shape of the weights learned by each layer.

In particular, Keras lets you inspect weights by using the `get_weights` method of a layer object.

This will return a list with two elements, the first one being the **weight tensor** and the second one being the **bias vector**.

In particular:

- **MaxPooling layer** don't have any weight tensor, since they don't have learnable parameters.
- **Convolutional layers**, instead, learn a  $(n_o, n_i, k, k)$  weight tensor, where  $k$  is the size of the kernel,  $n_i$  is the number of channels of the input tensor, and  $n_o$  is the number of filters to be learned.

For each of the  $n_o$  filters, a bias is also learned.

- **Dense layers** learn a  $(n_i, n_o)$  weight tensor, where  $n_o$  is the output size and  $n_i$  is the input size of the layer. Each of the  $n_o$  neurons also has a bias.

```
In [28]: for i, layer in enumerate(model.layers):
          if len(layer.get_weights()) > 0:
              W, b = layer.get_weights()
              print("Layer", i, "\t", layer.name, "\t\t", W.shape, "\t", b.shape)

('Layer', 0, '\t', 'conv2d_3', '\t\t', (3, 3, 1, 32), '\t', (32,))
('Layer', 1, '\t', 'conv2d_4', '\t\t', (3, 3, 32, 64), '\t', (64,))
('Layer', 5, '\t', 'dense_4', '\t\t', (9216, 128), '\t', (128,))
('Layer', 7, '\t', 'dense_5', '\t\t', (128, 10), '\t', (10,))
```