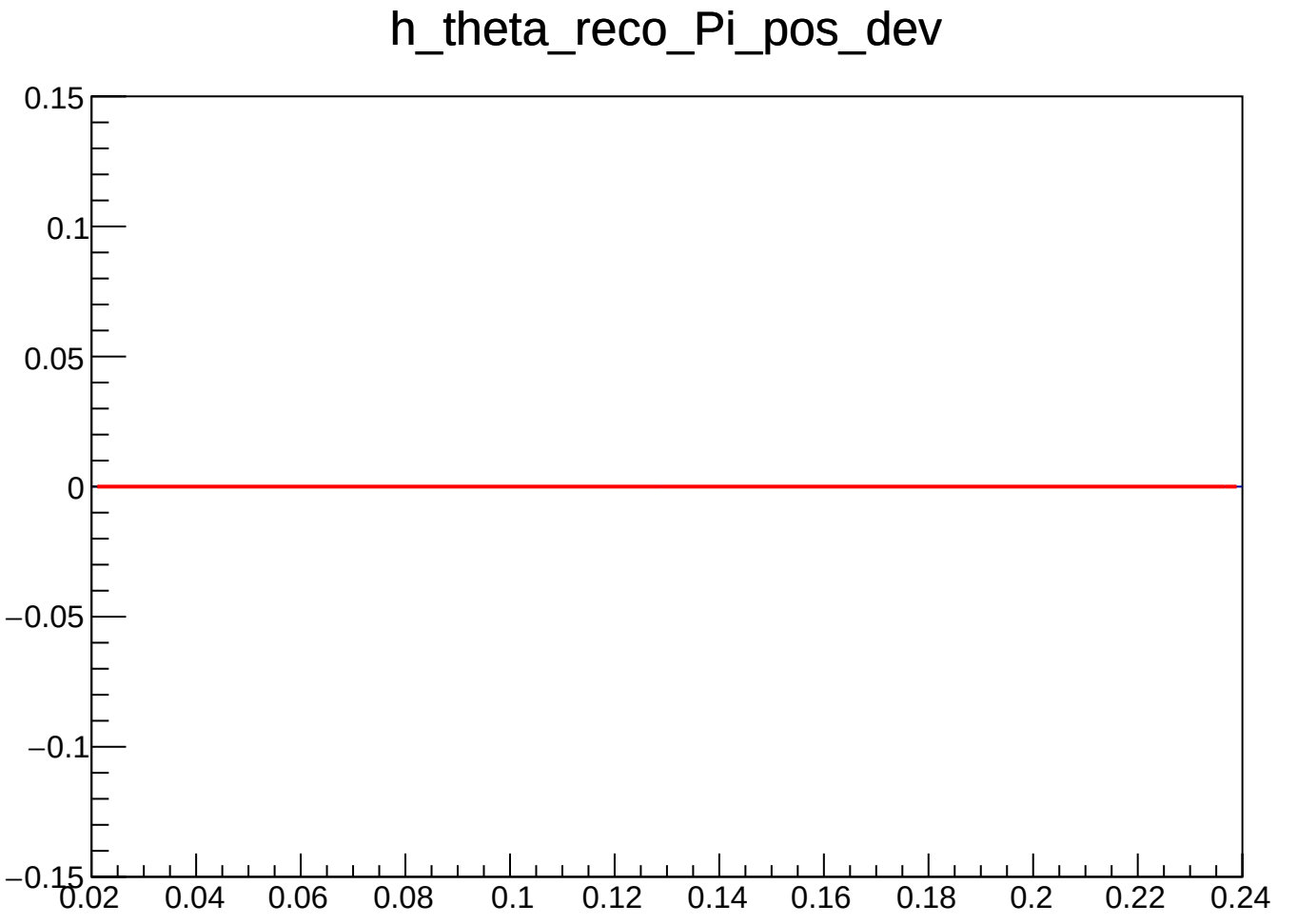
h_theta_reco_Pi_pos_dev
0.15
0.1
0.05
0
−0.05
−0.1
−0.15
0.02
0.04
0.06
0.08
0.1
0.12
0.14
0.16
0.18
0.2
0.22
0.24