Sistema de Balanças Automotivo

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Chapter 1

File Index

1.1 File List

Here is a list of all files with brief descriptions:

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Chapter 2

File Documentation

2.1 main.cpp File Reference

```
#include <Arduino.h>
#include "main.h"

#include <Arduino_FreeRTOS.h>
#include <semphr.h>
#include <queue.h>
#include <task.h>
```

Functions

```
    void TaskLeitura (void *pvParameters)
include FreeRTOS librarys
```

• void **TaskUpdateLCD** (void *pvParameters)

• void setup ()

mutex que vai controlar porta serial

- void loop ()
- void readButtons ()

read state of each button

• void printScales ()

print data in LCD about individual scales data

· void printLong ()

print data in LCD about longitudinal mass distribution

• void printLat ()

print data in LCD about lateral mass distribution

• void printTotal ()

print data in LCD about total mass of the car

• void readData ()

read analog data and store its in an vector

- void tara ()
- void processData ()
- int32_t mediaMovel (int32_t *array)

calculate media movel of an vector

Variables

• SemaphoreHandle_t threadSemaphore

2.1.1 Function Documentation

2.1.1.1 loop()

```
void loop ( )
```

2.1.1.2 mediaMovel()

calculate media movel of an vector

2.1.1.3 printLat()

```
void printLat ( )
```

print data in LCD about lateral mass distribution

2.1.1.4 printLong()

```
void printLong ( )
```

print data in LCD about longitudinal mass distribution

2.1.1.5 printScales()

```
void printScales ( )
```

print data in LCD about individual scales data

functions

2.1.1.6 printTotal()

```
void printTotal ( )
```

print data in LCD about total mass of the car

2.1.1.7 processData()

```
void processData ( )
```

process data, calculating media movel, removing tara, and converting to kg

2.1.1.8 readButtons()

```
void readButtons ( )
```

read state of each button

2.1.1.9 readData()

```
void readData ( )
```

read analog data and store its in an vector

2.1.1.10 setup()

```
void setup ( )
```

mutex que vai controlar porta serial

initialize serial communication at 9600 bits per second:

read EEPROM data

cria a mutex

Now set up two tasks to run independently.

2.1.1.11 tara()

```
void tara ( )
```

get the current analog data and store its to EEPROM this value will be subtract from de current data that is being redden

2.1.1.12 TaskLeitura()

```
\label{eq:condition} \begin{tabular}{ll} void & * pvParameters \end{tabular} \ ) \\ include FreeRTOS librarys \\ \\ define two tasks for read and print data \\ \end{tabular}
```

2.1.1.13 TaskUpdateLCD()

```
\label{eq:condition} \mbox{void TaskUpdateLCD (} \\ \mbox{void} \ * \ pvParameters \ )
```

2.1.2 Variable Documentation

2.1.2.1 threadSemaphore

SemaphoreHandle_t threadSemaphore

2.2 main.h File Reference

```
#include <LiquidCrystal.h>
#include <EEPROM.h>
```

Macros

• #define FE_PORT 0

defines analog inputs pin

- #define FD PORT 1
- #define **TE_PORT** 2
- #define TD_PORT 3
- #define FUNC PIN 2

defines digital inputs pin

- #define **T_PIN** 3
- #define **BUFFER_SIZE** 32

defines constants of buffer and media movel calculation

- #define bitshift 5
- #define UPDATE_LCD_HZ 10

Functions

```
• LiquidCrystal lcd (rs, en, d4, d5, d6, d7)
• void printScales ()
      functions
• void printLong ()
     print data in LCD about longitudinal mass distribution
• void printLat ()
     print data in LCD about lateral mass distribution

    void printTotal ()

     print data in LCD about total mass of the car
• void tara ()
· void readButtons ()
      read state of each button
· void readData ()
      read analog data and store its in an vector
• void processData ()

    int32 t mediaMovel (int32 t *array)

      calculate media movel of an vector
```

Variables

```
• const int rs = 13
• const int en = 12
• const int d4 = 11
• const int d5 = 10
• const int d6 = 9
• const int d7 = 8
• const double calibrationFactorDe = 0.48481
     initialize calibration data that converts Voltage (0-1023) to Kg
• const double calibrationFactorDd = 0.48481
• const double calibrationFactorTe = 0.48481
• const double calibrationFactorTd = 0.48481
• byte state = 0
     state of LCD (witch function is beeing displayed)
• boolean funcState = false
     state of each button
• boolean tState = false
• int32_t dataDe [ BUFFER_SIZE]
     data buffers

    int32_t dataDd [ BUFFER_SIZE]

• int32_t dataTe [ BUFFER_SIZE]
• int32_t dataTd [ BUFFER_SIZE]
• int32_t taraDe = 0
     data constants
• int32_t taraDd = 0
• int32_t taraTe = 0
• int32_t taraTd = 0
• double total = 0
• double de = 0
• double dd = 0
• double te = 0
• double td = 0
```

2.2.1 Macro Definition Documentation

2.2.1.1 bitshift

#define bitshift 5

2.2.1.2 BUFFER_SIZE

#define BUFFER_SIZE 32

defines constants of buffer and media movel calculation

2.2.1.3 FD_PORT

#define FD_PORT 1

2.2.1.4 FE_PORT

#define FE_PORT 0

defines analog inputs pin

2.2.1.5 FUNC_PIN

#define FUNC_PIN 2

defines digital inputs pin

2.2.1.6 T_PIN

#define T_PIN 3

2.2.1.7 TD_PORT

```
#define TD_PORT 3
```

2.2.1.8 TE_PORT

```
#define TE_PORT 2
```

2.2.1.9 UPDATE_LCD_HZ

```
#define UPDATE_LCD_HZ 10
```

2.2.2 Function Documentation

2.2.2.1 lcd()

```
LiquidCrystal lcd (
    rs ,
    en ,
    d4 ,
    d5 ,
    d6 ,
    d7 )
```

2.2.2.2 mediaMovel()

calculate media movel of an vector

2.2.2.3 printLat()

```
void printLat ( )
```

print data in LCD about lateral mass distribution

2.2.2.4 printLong()

```
void printLong ( )
```

print data in LCD about longitudinal mass distribution

2.2.2.5 printScales()

```
void printScales ( )
```

functions

functions

2.2.2.6 printTotal()

```
void printTotal ( )
```

print data in LCD about total mass of the car

2.2.2.7 processData()

```
void processData ( )
```

process data, calculating media movel, removing tara, and converting to kg

2.2.2.8 readButtons()

```
void readButtons ( )
```

read state of each button

2.2.2.9 readData()

```
void readData ( )
```

read analog data and store its in an vector

2.2.2.10 tara()

```
void tara ( )
```

get the current analog data and store its to EEPROM this value will be subtract from de current data that is being redden

2.2.3 Variable Documentation

2.2.3.1 calibrationFactorDd

```
const double calibrationFactorDd = 0.48481
```

2.2.3.2 calibrationFactorDe

```
const double calibrationFactorDe = 0.48481
```

initialize calibration data that converts Voltage (0-1023) to Kg

2.2.3.3 calibrationFactorTd

```
const double calibrationFactorTd = 0.48481
```

2.2.3.4 calibrationFactorTe

```
const double calibrationFactorTe = 0.48481
```

2.2.3.5 d4

```
const int d4 = 11
```

2.2.3.6 d5

```
const int d5 = 10
```

2.2.3.7 d6

```
const int d6 = 9
```

2.2.3.8 d7

```
const int d7 = 8
```

2.2.3.9 dataDd

```
int32_t dataDd[ BUFFER_SIZE]
```

2.2.3.10 dataDe

```
int32_t dataDe[ BUFFER_SIZE]
```

data buffers

2.2.3.11 dataTd

```
int32_t dataTd[ BUFFER_SIZE]
```

2.2.3.12 dataTe

```
int32_t dataTe[ BUFFER_SIZE]
```

2.2.3.13 dd

double dd = 0

2.2.3.14 de

double de = 0

2.2.3.15 en

const int en = 12

2.2.3.16 funcState

boolean funcState = false

state of each button

2.2.3.17 rs

const int rs = 13

2.2.3.18 state

byte state = 0

state of LCD (witch function is beeing displayed)

2.2.3.19 taraDd

 $int32_t taraDd = 0$

2.2.3.20 taraDe

```
int32\_t taraDe = 0
```

data constants

2.2.3.21 taraTd

```
int32\_t taraTd = 0
```

2.2.3.22 taraTe

```
int32\_t taraTe = 0
```

2.2.3.23 td

double td = 0

2.2.3.24 te

double te = 0

2.2.3.25 total

double total = 0

2.2.3.26 tState

boolean tState = false

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2.3 main.h

Go to the documentation of this file.

```
\frac{1}{2} // Created by eugen on 26/08/2021.
3 //
5 // include the library code:
6 #include <LiquidCrystal.h>
7 #include <EEPROM.h>
8
10 #define FE_PORT 0
11 #define FD_PORT 1
12 #define TE_PORT 2
13 #define TD_PORT 3
16 #define FUNC_PIN
17 #define T_PIN
18
20 #define BUFFER_SIZE 32
21 #define bitshift
22 #define UPDATE_LCD_HZ 10
2.3
24 // initialize the LCD by associating any needed LCD interface pin 25 // with the arduino pin number it is connected to 26 const int rs = 13, en = 12, d4 = 11, d5 = 10, d6 = 9, d7 = 8;
27 LiquidCrystal lcd(rs, en, d4, d5, d6, d7);
28
30 const double calibrationFactorDe = 0.48481;
31 const double calibrationFactorDd = 0.48481;
32 const double calibrationFactorTe = 0.48481;
33 const double calibrationFactorTd = 0.48481;
36 byte state = 0;
37
39 boolean funcState = false;
40 boolean tState = false;
41
43 int32_t dataDe[BUFFER_SIZE];
44 int32_t dataDd[BUFFER_SIZE];
45 int32_t dataTe[BUFFER_SIZE];
46 int32_t dataTd[BUFFER_SIZE];
47
49 int32_t taraDe = 0;
50 int32_t taraDd = 0;
51 int32_t taraTe = 0;
52 int32_t taraTd = 0;
53
54 double total = 0;
55 double de = 0;
56 double dd = 0;
57 \text{ double te} = 0;
58 \text{ double td} = 0;
59
61 void printScales();
62 void printLong();
63 void printLat();
64 void printTotal();
65 void tara();
67 void readButtons();
68 void readData();
69 void processData();
70 int32_t mediaMovel(int32_t *array);
```

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