# Visual Navigation and Charging Telematics for Autonomous Electric Vehicles



## Kai Li Lim

BEng (Hons) Nott., MSc Lanc.

Supervisor: Prof. Thomas Bräunl

Department of Electrical, Electronic and Computer Engineering
The University of Western Australia

This thesis is presented for the degree of Doctor of Philosophy



#### **Declaration**

#### I hereby certify that:

- This thesis has been substantially accomplished during enrolment in this degree.
- This thesis does not contain material which has been submitted for the award of any other degree or diploma in my name, in any university or other tertiary institution. In the future, no part of this thesis will be used in a submission in my name, for any other degree or diploma in any university or other tertiary institution without the prior approval of The University of Western Australia.
- This thesis does not contain any material previously published or written by another person, except where due reference has been made in the text and, where relevant, in the Authorship Declaration that follows.
- This thesis does not violate or infringe any copyright, trademark, patent, or other rights whatsoever of any person.

This thesis contains published work and/or work prepared for publication, some of which has been co-authored.

Kai Li Lim April 2019

# Acknowledgements

And I would like to acknowledge ...

This research was supported by an Australian Government Research Training Program (RTP) Scholarship.

This research was funded by [insert name of grant and grant identification numbers].

Technical assistance was kindly provided by [insert name of assistant(s)] for [insert description of assistance] that is described in [insert location in thesis].

## **Authorship Declaration**

In accordance with the regulations of the Graduate Research School, this thesis contains published work and/or work prepared for publications that are co-authored. The bibliographical details of the work and where it appears in the thesis are outlined below.

 K. L. Lim and T. Bräunl, "A Methodological Review of Visual Road Recognition Procedures for Autonomous Driving Applications," arXiv:1612.06830 [cs], Apr. 2017.
 Paper presented as Chapter 3.
 Estimated percentage of candidate's contribution is 80%.

2. **K. L. Lim** and T. Bräunl, "A Review of Recent Visual Odometry Methods and Its Applications for Autonomous Driving," arXiv:1612.06830 [cs], Dec. 2016.

Paper presented as **Chapter 3**.

Estimated percentage of candidate's contribution is 80%.

3. R. Reid, **K. L. Lim** and T. Bräunl, "Cooperative Multi-Robot Navigation — SLAM, Visual Odometry and Semantic Segmentation," in *Cooperative Localization and Navigation: Theory, Research, and Practice*, C. Gao, Ed. Boca Raton: CRC Press, 2019, [in press].

Paper presented as **Chapter 3**.

Estimated percentage of candidate's contribution is **80%**.

4. **K. L. Lim**, T. Drage and T. Bräunl, "Implementation of semantic segmentation for road and lane detection on an autonomous ground vehicle with LIDAR," in 2017 IEEE International Conference on Multisensor Fusion and Integration for Intelligent Systems (MFI), Daegu, 2017, pp. 429–434. doi: 10.1109/MFI.2017.8170358

Paper presented as Chapter 3.

Estimated percentage of candidate's contribution is **80%**.

5. **K. L. Lim**, T. Drage, R. Podolski, G. Meyer-Lee, S. Evans-Thompson, J. Y.-T. Lin, G. Channon, M. Poole, and T. Bräunl, "A Modular Software Framework for Autonomous

Vehicles," in 2018 IEEE Intelligent Vehicles Symposium (IV), Changshu, 2018, pp. 1780–1785. doi: 10.1109/IVS.2018.8500474

Paper presented as Chapter 3.

Estimated percentage of candidate's contribution is 80%.

6. **K. L. Lim**, T. Drage, C. Zhang, C. Brogle, W. W. L. Lai, T. Kelliher, M. Adina-Zada and T. Bräunl, "Evolution of a Reliable and Extensible High-Level Control System for an Autonomous Car," *IEEE Transactions on Intelligent Vehicles*, [under review].

Paper presented as Chapter 3.

Estimated percentage of candidate's contribution is **80%**.

7. C. Brogle, C. Zhang, **K. L. Lim** and T. Bräunl, "Hardware-in-the-Loop Autonomous Driving Simulation," *IEEE Transactions on Intelligent Vehicles*, [under review].

Paper presented as **Chapter 3**.

Estimated percentage of candidate's contribution is 80%.

8. S. Speidel, **K. L. Lim** and T. Bräunl, "REView: A Unified Telemetry Platform for IoT-Enabled Electric Vehicles and Charging Infrastructures," in *Connected Vehicles in the Internet of Things: Concepts, Technologies and Frameworks for the IoV*, Z. Mahmood, Ed. New York: Springer, 2019, [under review].

Paper presented as Chapter 3.

Estimated percentage of candidate's contribution is 80%.

9. **K. L. Lim**, S. Speidel and T. Bräunl, "A Comparative Study of AC and DC Electric Vehicle Charging Station Usage," *Renewable & Sustainable Energy Reviews*, [under review].

Paper presented as **Chapter 3**.

Estimated percentage of candidate's contribution is 80%.

The candidate's statement regarding his contribution to each of the works listed above are correct.

Kai Li Lim		
PhD Candidate	Signature	Date
Thomas Drage		
Co-author	Signature	Date
Chao Zhang		
Co-author	Signature	Date
	-	
Craig Brogle		
Co-author	Signature	Date
	-	
Stuart Speidel		
Co-author	Signature	Date

I, Thomas Bräunl, hereby certify that the students' statements regarding their contribution to each of the works listed above are correct. As all co-authors' signatures could not be obtained, I hereby authorise the inclusion of co-authored work in the thesis.

Coordinating Supervisor signature:

Date:

#### **Abstract**

The growing ubiquity of electric vehicles is often characterised through its increasing autonomy and connectivity. This has led to catalyse the foundations of smart cities and intelligent transportation systems, where the applications of electromobility is often given a pivotal role towards their realisation.

As the title suggests, this thesis presents its investigations into electromobility applications across two key areas — (1) computer vision-based autonomous driving, and (2) data management and analyses of electric vehicle charging stations.

The study into vision-based navigation aims to address the problem of developing an autonomous driving system that predominantly utilises the camera as the vehicle's primary environmental perception sensor. This research gap is attributed to the greater algorithmic complexity in computer vision, as compared to LiDARs or radars. Additionally, the general attainability of cameras, and the diminishing cost of parallel computation has further contributed towards the motivation for this study. To this end, the requirements for visual navigation are centred upon localisation and scene understanding. More specifically, this thesis describes applications pertaining to visual odometry and semantic segmentation following an extensive literature survey. These methods are first tested for its feasibility on datasets and mobile robots, and then verified on an autonomous Formula-SAE electric car as the test bed, enabling the vehicle to perform object detection, lane keeping and dead reckoning in real-time. Experiments were conducted for road scenes and traffic cone drives, yielding fast and accurate results for detections, classifications and odometry.

The electric vehicle charging station network managed by The REV Project comprise of 23 7 kW AC stations and a 50 kW DC fast charging station. Each station is connected to a centralised server over the mobile network, perpetually transmitting telemetric data to the server's daemons. The data generated from these stations effectuates the investigation into the charging behaviours across AC and DC stations, leading to the study of electric vehicle trends around Perth. Results from this study comprise of a combination of time series analyses that compares the cycles and energy consumption between AC and DC charges among local stations. A web-based telemetry monitoring platform, REView, is further described in this thesis. In addition to the charging stations, REView consolidates data from

the project's electric vehicle fleet and solar power generation into a unified framework that features on-demand monitoring for connected infrastructures. These are further detailed according to its back-end processes, encompassing its communication architectures, data management, data visualisation and presentation.

The cumulation of works that are presented here conforms to The REV Project's goal that describe contributions towards the fields of intelligent vehicles and the Internet of Vehicles. These contributions are exemplified in this thesis through the successful application of visual autonomous driving, and the analyses towards the electric vehicle trends in Perth, which should subsequently encourage further developments in this area.

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# **Chapter 1**

# **Getting started**

## 1.1 What is loren ipsum? Title with math $\sigma$

Lorem Ipsum is simply dummy text of the printing and typesetting industry (see Section 1.3). Lorem Ipsum [3] has been the industry's standard dummy text ever since the 1500s, when an unknown printer took a galley of type and scrambled it to make a type specimen book. It has survived not only five centuries, but also the leap into electronic typesetting, remaining essentially unchanged. It was popularised in the 1960s with the release of Letraset sheets containing Lorem Ipsum passages, and more recently with desktop publishing software like Aldus PageMaker including versions of Lorem Ipsum [1, 4, 5].

The most famous equation in the world:  $E^2 = (m_0c^2)^2 + (pc)^2$ , which is known as the **energy-mass-momentum** relation as an in-line equation.

A ETFX class file is a file, which holds style information for a particular LATFX.

CIF: 
$$F_0^j(a) = \frac{1}{2\pi i} \oint_{\gamma} \frac{F_0^j(z)}{z - a} dz$$
 (1.1)

# 1.2 Why do we use loren ipsum?

It is a long established fact that a reader will be distracted by the readable content of a page when looking at its layout. The point of using Lorem Ipsum is that it has a more-or-less normal distribution of letters, as opposed to using 'Content here, content here', making it look like readable English. Many desktop publishing packages and web page editors now use Lorem Ipsum as their default model text, and a search for 'lorem ipsum' will uncover many

2 Getting started

web sites still in their infancy. Various versions have evolved over the years, sometimes by accident, sometimes on purpose (injected humour and the like).

#### 1.3 Where does it come from?

Contrary to popular belief, Lorem Ipsum is not simply random text. It has roots in a piece of classical Latin literature from 45 BC, making it over 2000 years old. Richard McClintock, a Latin professor at Hampden-Sydney College in Virginia, looked up one of the more obscure Latin words, consectetur, from a Lorem Ipsum passage, and going through the cites of the word in classical literature, discovered the undoubtable source. Lorem Ipsum comes from sections 1.10.32 and 1.10.33 of "de Finibus Bonorum et Malorum" (The Extremes of Good and Evil) by Cicero, written in 45 BC. This book is a treatise on the theory of ethics, very popular during the Renaissance. The first line of Lorem Ipsum, "Lorem ipsum dolor sit amet..", comes from a line in section 1.10.32.

The standard chunk of Lorem Ipsum used since the 1500s is reproduced below for those interested. Sections 1.10.32 and 1.10.33 from "de Finibus Bonorum et Malorum" by Cicero are also reproduced in their exact original form, accompanied by English versions from the 1914 translation by H. Rackham

"Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur. Excepteur sint occaecat cupidatat non proident, sunt in culpa qui officia deserunt mollit anim id est laborum."

Section 1.10.32 of "de Finibus Bonorum et Malorum", written by Cicero in 45 BC: "Sed ut perspiciatis unde omnis iste natus error sit voluptatem accusantium doloremque laudantium, totam rem aperiam, eaque ipsa quae ab illo inventore veritatis et quasi architecto beatae vitae dicta sunt explicabo. Nemo enim ipsam voluptatem quia voluptas sit aspernatur aut odit aut fugit, sed quia consequuntur magni dolores eos qui ratione voluptatem sequi nesciunt. Neque porro quisquam est, qui dolorem ipsum quia dolor sit amet, consectetur, adipisci velit, sed quia non numquam eius modi tempora incidunt ut labore et dolore magnam aliquam quaerat voluptatem. Ut enim ad minima veniam, quis nostrum exercitationem ullam corporis suscipit laboriosam, nisi ut aliquid ex ea commodi consequatur? Quis autem vel eum iure reprehenderit qui in ea voluptate velit esse quam nihil molestiae consequatur, vel illum qui dolorem eum fugiat quo voluptas nulla pariatur?"

1914 translation by H. Rackham: "But I must explain to you how all this mistaken idea of denouncing pleasure and praising pain was born and I will give you a complete

account of the system, and expound the actual teachings of the great explorer of the truth, the master-builder of human happiness. No one rejects, dislikes, or avoids pleasure itself, because it is pleasure, but because those who do not know how to pursue pleasure rationally encounter consequences that are extremely painful. Nor again is there anyone who loves or pursues or desires to obtain pain of itself, because it is pain, but because occasionally circumstances occur in which toil and pain can procure him some great pleasure. To take a trivial example, which of us ever undertakes laborious physical exercise, except to obtain some advantage from it? But who has any right to find fault with a man who chooses to enjoy a pleasure that has no annoying consequences, or one who avoids a pain that produces no resultant pleasure?"

Section 1.10.33 of "de Finibus Bonorum et Malorum", written by Cicero in 45 BC: "At vero eos et accusamus et iusto odio dignissimos ducimus qui blanditiis praesentium voluptatum deleniti atque corrupti quos dolores et quas molestias excepturi sint occaecati cupiditate non provident, similique sunt in culpa qui officia deserunt mollitia animi, id est laborum et dolorum fuga. Et harum quidem rerum facilis est et expedita distinctio. Nam libero tempore, cum soluta nobis est eligendi optio cumque nihil impedit quo minus id quod maxime placeat facere possimus, omnis voluptas assumenda est, omnis dolor repellendus. Temporibus autem quibusdam et aut officiis debitis aut rerum necessitatibus saepe eveniet ut et voluptates repudiandae sint et molestiae non recusandae. Itaque earum rerum hic tenetur a sapiente delectus, ut aut reiciendis voluptatibus maiores alias consequatur aut perferendis doloribus asperiores repellat."

1914 translation by H. Rackham: "On the other hand, we denounce with righteous indignation and dislike men who are so beguiled and demoralized by the charms of pleasure of the moment, so blinded by desire, that they cannot foresee the pain and trouble that are bound to ensue; and equal blame belongs to those who fail in their duty through weakness of will, which is the same as saying through shrinking from toil and pain. These cases are perfectly simple and easy to distinguish. In a free hour, when our power of choice is untrammelled and when nothing prevents our being able to do what we like best, every pleasure is to be welcomed and every pain avoided. But in certain circumstances and owing to the claims of duty or the obligations of business it will frequently occur that pleasures have to be repudiated and annoyances accepted. The wise man therefore always holds in these matters to this principle of selection: he rejects pleasures to secure other greater pleasures, or else he endures pains to avoid worse pains."

# Chapter 2

# My second chapter

## 2.1 Reasonably long section title

I'm going to randomly include a picture Figure 2.1.

If you have trouble viewing this document contact Krishna at: kks32@cam.ac.uk or raise an issue at https://github.com/kks32/phd-thesis-template/

#### **Enumeration**

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Fig. 2.1 This is just a long figure caption for the minion in Despicable Me from Pixar

2.1 Short title

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- 1. The first topic is dull
- 2. The second topic is duller
  - (a) The first subtopic is silly
  - (b) The second subtopic is stupid
- 3. The third topic is the dullest

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## **Itemize**

- The first topic is dull
- The second topic is duller
  - The first subtopic is silly
  - The second subtopic is stupid
- The third topic is the dullest

# **Description**

The first topic is dull

The second topic is duller

**The first subtopic** is silly

The second subtopic is stupid

The third topic is the dullest

2.2 Hidden section 9

#### 2.2 Hidden section

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<sup>&</sup>lt;sup>1</sup>My footnote goes blah blah blah! ...



Fig. 2.2 Best Animations

I can cite Wall-E (see Fig. 2.2b) and Minions in despicable me (Fig. 2.2c) or I can cite the whole figure as Fig. 2.2

# Chapter 3

# My third chapter

# 3.1 First section of the third chapter

And now I begin my third chapter here ...

And now to cite some more people Read [6], Ancey et al. [2]

#### 3.1.1 First subsection in the first section

... and some more

#### 3.1.2 Second subsection in the first section

... and some more ...

#### First subsub section in the second subsection

... and some more in the first subsub section otherwise it all looks the same doesn't it? well we can add some text to it ...

#### 3.1.3 Third subsection in the first section

... and some more ...

#### First subsub section in the third subsection

... and some more in the first subsub section otherwise it all looks the same doesn't it? well we can add some text to it and some more and some more...

My third chapter

#### Second subsub section in the third subsection

... and some more in the first subsub section otherwise it all looks the same doesn't it? well we can add some text to it ...

## 3.2 Second section of the third chapter

and here I write more ...

## 3.3 The layout of formal tables

This section has been modified from "Publication quality tables in LATEX\*" by Simon Fear.

The layout of a table has been established over centuries of experience and should only be altered in extraordinary circumstances.

When formatting a table, remember two simple guidelines at all times:

- 1. Never, ever use vertical rules (lines).
- 2. Never use double rules.

These guidelines may seem extreme but I have never found a good argument in favour of breaking them. For example, if you feel that the information in the left half of a table is so different from that on the right that it needs to be separated by a vertical line, then you should use two tables instead. Not everyone follows the second guideline:

There are three further guidelines worth mentioning here as they are generally not known outside the circle of professional typesetters and subeditors:

- 3. Put the units in the column heading (not in the body of the table).
- 4. Always precede a decimal point by a digit; thus 0.1 not just .1.
- 5. Do not use 'ditto' signs or any other such convention to repeat a previous value. In many circumstances a blank will serve just as well. If it won't, then repeat the value.

A frequently seen mistake is to use '\begin{center}' ... '\end{center}' inside a figure or table environment. This center environment can cause additional vertical space. If you want to avoid that just use '\centering'

Table 3.1 A badly formatted table

	Species I		Speci	es II
Dental measurement	mean	SD	mean	SD
I1MD	6.23	0.91	5.2	0.7
I1LL	7.48	0.56	8.7	0.71
I2MD	3.99	0.63	4.22	0.54
I2LL	6.81	0.02	6.66	0.01
CMD	13.47	0.09	10.55	0.05
CBL	11.88	0.05	13.11	0.04

Table 3.2 A nice looking table

Dental measurement	Species I		Species II	
Dentai measurement	mean	SD	mean	SD
I1MD	6.23	0.91	5.2	0.7
I1LL	7.48	0.56	8.7	0.71
I2MD	3.99	0.63	4.22	0.54
I2LL	6.81	0.02	6.66	0.01
CMD	13.47	0.09	10.55	0.05
CBL	11.88	0.05	13.11	0.04

Table 3.3 Even better looking table using booktabs

Dental measurement	Species I		Species II	
	mean	SD	mean	SD
I1MD	6.23	0.91	5.2	0.7
I1LL	7.48	0.56	8.7	0.71
I2MD	3.99	0.63	4.22	0.54
I2LL	6.81	0.02	6.66	0.01
CMD	13.47	0.09	10.55	0.05
CBL	11.88	0.05	13.11	0.04

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# **Appendix A**

# How to install LATEX

### Windows OS

#### **TeXLive package - full version**

- 1. Download the TeXLive ISO (2.2GB) from https://www.tug.org/texlive/
- 2. Download WinCDEmu (if you don't have a virtual drive) from http://wincdemu.sysprogs.org/download/
- 3. To install Windows CD Emulator follow the instructions at http://wincdemu.sysprogs.org/tutorials/install/
- 4. Right click the iso and mount it using the WinCDEmu as shown in http://wincdemu.sysprogs.org/tutorials/mount/
- 5. Open your virtual drive and run setup.pl

or

## Basic MikTeX - TEX distribution

- Download Basic-MiKTEX(32bit or 64bit) from http://miktex.org/download
- 2. Run the installer
- 3. To add a new package go to Start » All Programs » MikTex » Maintenance (Admin) and choose Package Manager

4. Select or search for packages to install

## TexStudio - TeX editor

- Download TexStudio from http://texstudio.sourceforge.net/#downloads
- 2. Run the installer

#### Mac OS X

# MacTeX - TEX distribution

- Download the file from https://www.tug.org/mactex/
- 2. Extract and double click to run the installer. It does the entire configuration, sit back and relax.

## TexStudio - T<sub>E</sub>X editor

- Download TexStudio from http://texstudio.sourceforge.net/#downloads
- 2. Extract and Start

## **Unix/Linux**

## TeXLive - T<sub>E</sub>X distribution

#### **Getting the distribution:**

- 1. TexLive can be downloaded from http://www.tug.org/texlive/acquire-netinstall.html.
- 2. TexLive is provided by most operating system you can use (rpm,apt-get or yum) to get TexLive distributions

#### **Installation**

1. Mount the ISO file in the mnt directory

```
mount -t iso9660 -o ro, loop, noauto /your/texlive###.iso /mnt
```

- 2. Install wget on your OS (use rpm, apt-get or yum install)
- 3. Run the installer script install-tl.

```
cd /your/download/directory
./install-tl
```

- 4. Enter command 'i' for installation
- 5. Post-Installation configuration: http://www.tug.org/texlive/doc/texlive-en/texlive-en.html#x1-320003.4.1
- 6. Set the path for the directory of TexLive binaries in your .bashrc file

#### For 32bit OS

For Bourne-compatible shells such as bash, and using Intel x86 GNU/Linux and a default directory setup as an example, the file to edit might be

```
edit $~/.bashrc file and add following lines
PATH=/usr/local/texlive/2011/bin/i386-linux:$PATH;
export PATH
MANPATH=/usr/local/texlive/2011/texmf/doc/man:$MANPATH;
export MANPATH
INFOPATH=/usr/local/texlive/2011/texmf/doc/info:$INFOPATH;
export INFOPATH
```

#### For 64bit OS

```
edit $~/.bashrc file and add following lines
PATH=/usr/local/texlive/2011/bin/x86_64-linux:$PATH;
export PATH
MANPATH=/usr/local/texlive/2011/texmf/doc/man:$MANPATH;
export MANPATH
```

```
INFOPATH=/usr/local/texlive/2011/texmf/doc/info:$INFOPATH;
export INFOPATH
```

#### Fedora/RedHat/CentOS:

```
sudo yum install texlive
sudo yum install psutils
```

#### **SUSE:**

sudo zypper install texlive

#### **Debian/Ubuntu:**

```
sudo apt-get install texlive texlive-latex-extra
sudo apt-get install psutils
```

# Appendix B

# Installing the CUED class file

LATEX.cls files can be accessed system-wide when they are placed in the <texmf>/tex/latex directory, where <texmf> is the root directory of the user's TeXinstallation. On systems that have a local texmf tree (<texmflocal>), which may be named "texmf-local" or "localtexmf", it may be advisable to install packages in <texmflocal>, rather than <texmf> as the contents of the former, unlike that of the latter, are preserved after the LATeXsystem is reinstalled and/or upgraded.

It is recommended that the user create a subdirectory <texmf>/tex/latex/CUED for all CUED related LATeXclass and package files. On some LATeXsystems, the directory look-up tables will need to be refreshed after making additions or deletions to the system files. For TeXLive systems this is accomplished via executing "texhash" as root. MIKTeXusers can run "initexmf -u" to accomplish the same thing.

Users not willing or able to install the files system-wide can install them in their personal directories, but will then have to provide the path (full or relative) in addition to the filename when referring to them in LATEX.