INTELIGENCIA ARTIFICIAL 1 — 🗆 🗙

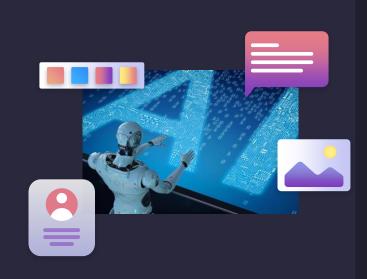
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VISION ARTIFICIAL
Previo: Sistemas inteligentes
con PyTorch





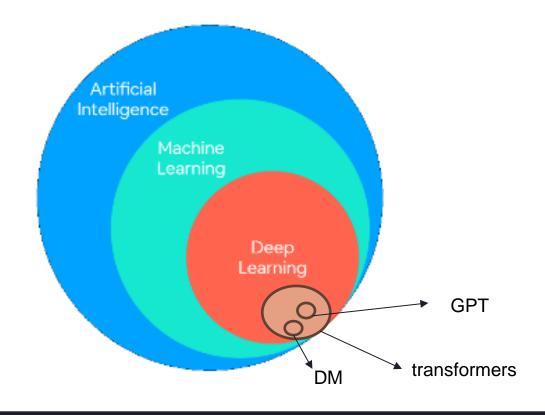
Tensores: Fundamentos de PyTorch















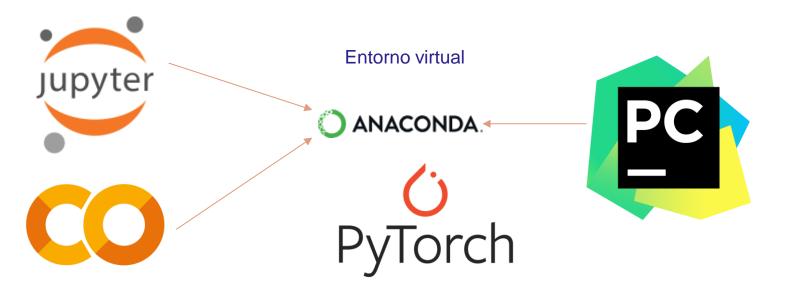






Entorno de experimentación

Entorno de programación









Programación

tradicional

\equiv

Comienza con...

Entradas



Reglas (Algoritmo)

- 1. Trocear verduras
- 2. Sofreír verduras
- 3. Añadir marisco y carne
- 4. Sazonar
- 5. Añadir arroz
- 6. Cocer fuego fuerte 8mins
- 7. Cocer fuego medio 10mins
- 8. Reposar 5 mins

genera...

Salida



Entradas







Reglas (Modelo)

- 1. Trocear verduras
- 2. Sofreír verduras
- 3. Añadir marisco y carne
- 4. Sazonar
- 5. Añadir arroz
- 6. Cocer fuego fuerte 8mins
- 7. Cocer fuego medio 10mins
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Machine Learning



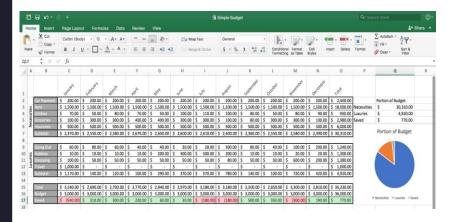
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Machine Learning

VS

Deep Learning



Datos estructurados



Datos no estructurados





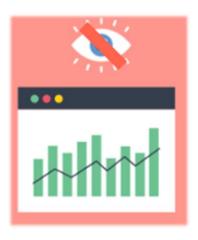




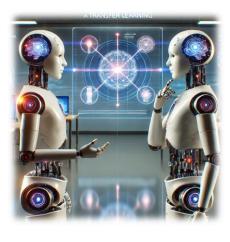
Tipos de aprendizaje



Aprendizaje supervisado



Aprendizaje NO supervisado



Transfer Learning







Machine Learning vs Deep Learning

Algoritmos fundacionales

Random Forest

Modelos Gradient Boosted

Naive Bayes

Vecino más cercano (K means)

SVMs

. . . .

Redes neuronales

Redes convolucionales

Redes recurrentes

LSTM

Transformers

. . . .

Depende de cómo representes la información puedes utilizar distintos tipos de algoritmos

Datos estructurados







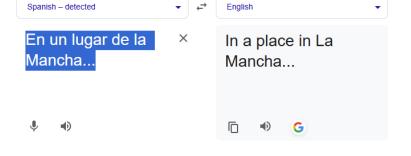




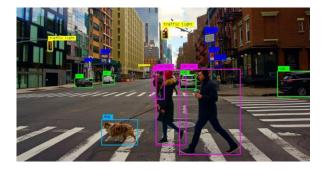


Deep Learning: Casos de uso



















¿Qué me aporta pytorch frente a tensorflow?

https://github.com/pytorch









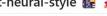




https://github.com/pytorch/examples

fast-neural-style 🔝 🚀





This repository contains a pytorch implementation of an algorithm for artistic style transfer. The algorithm can be used to mix the content of an image with the style of another image. For example, here is a photograph of a door arch rendered in the style of a stained glass painting.

The model uses the method described in Perceptual Losses for Real-Time Style Transfer and Super-Resolution along with Instance Normalization. The saved-models for examples shown in the README can be downloaded from here.



Superresolution using an efficient sub-pixel convolutional neural network

This example illustrates how to use the efficient sub-pixel convolution layer described in "Real-Time Single Image and Video Super-Resolution Using an Efficient Sub-Pixel Convolutional Neural Network" - Shi et al. for increasing spatial resolution within your network for tasks such as superresolution.

Time Sequence Prediction

This is a toy example for beginners to start with. It helps learn both PyTorch and time sequence prediction. Two LSTMCell units are used in this example to learn some sine wave signals starting at different phases. After learning the sine waves, the network tries to predict the signal values in the future. The results are shown in the picture below.

Deep Convolution Generative Adversarial Networks

This example implements the paper Unsupervised Representation Learning with Deep Convolutional Generative A

Language Translation



This example shows how one might use transformers for language translation. In particular, this implementation is loosely based on the Attention is All You Need paper.



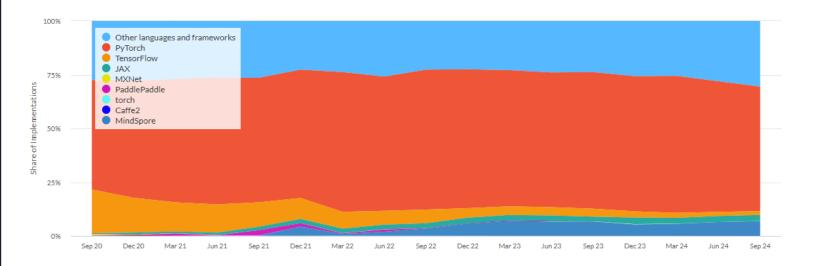
Trends

Quarter \$ 2020-09-0

2020-09-01 to 2024-09-30

Frameworks

Paper Implementations grouped by framework

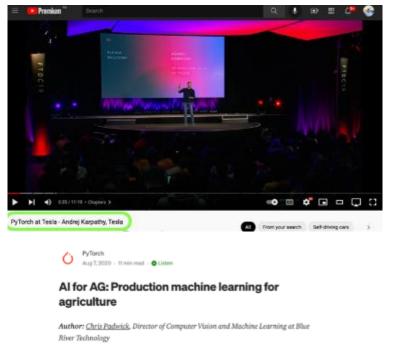








¿Quién usa pytorch?



OpenAI Standardizes on PyTorch

We are standardizing OpenAI's deep learning framework on PyTorch. In the past, we implemented projects in many frameworks depending on their relative strengths. We've now chosen to standardize to make it easier for our team to create and share optimized implementations of our models.









https://developers.google.com/machine-learning/guides/rules-of-ml

Rule #1: Don't be afraid to launch a product without machine learning if you can build a simple rule-based system that doesn't require Machine learning, do that

Rule #2: First, design and implement metrics

Rule #3: Choose machine learning over a complex heuristic.

Rule #4: Keep the first model simple and get the infrastructure right.

Rule #5: Test the infrastructure independently from the machine learning

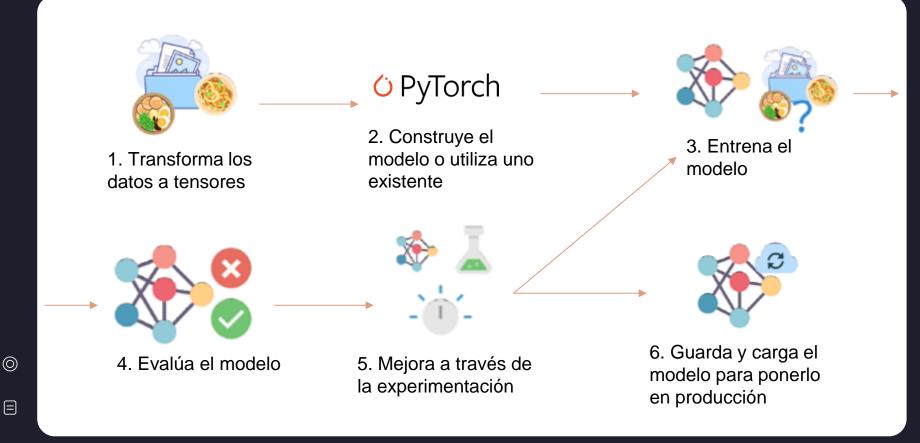
Rule #6: Be careful about dropped data when copying pipelines





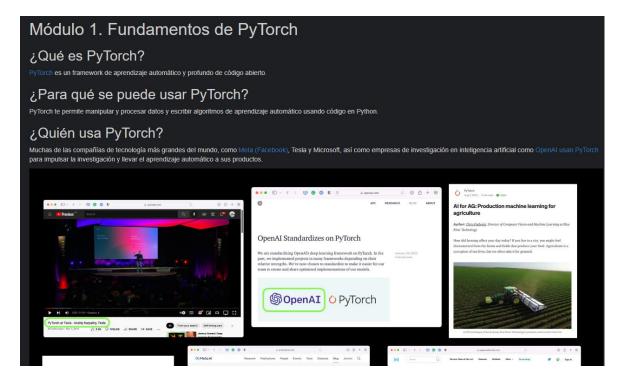








Vamos a por el cuaderno de jupyter 1



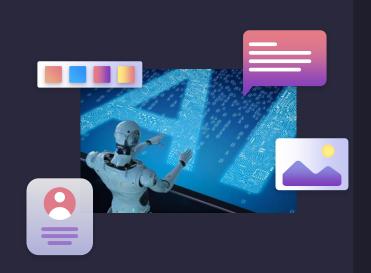






Construcción de redes neuronales con PyTorch

El flujo de trabajo de PyTorch

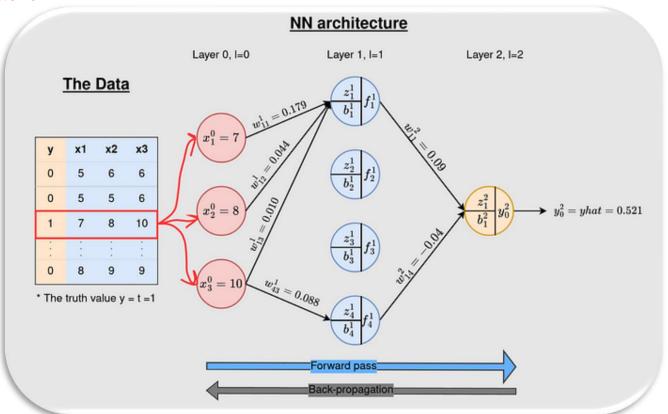








Recordatorio!









=

Tensorflow vs Pytorch

```
class ClasificadorBinario(torch.nn.Module): 2 usages
        super(ClasificadorBinario, self).__init__()
        self.layer1 = torch.nn.Linear(in_features: 2, out_features: 4)
        self.layer2 = torch.nn.Linear(in_features: 4, out_features: 4)
        self.layer3 = torch.nn.Linear(in_features: 4, out_features: 1)
        self.relu=torch.nn.ReLU()
        self.sigmoid=torch.nn.Sigmoid()
        self.loss=torch.nn.MSELoss()
        self.optimizer = torch.optim.Adam(self.parameters(), lr=0.01)
        x=self.layer1(x)
        x=self.relu(x)
        x=self.layer2(x)
                                        Forward =predict
        x=self.relu(x)
        x=self.layer3(x)
        x=self.sigmoid(x)
        return x
```

```
def fit(self,X,y,epocas): 1 usage
    for i in range(epocas):
        loss_epoca=0
        for xi, yi in zip(X,y):
            xi=torch.tensor(xi,dtype=torch.float).view(1,-1)
            yi=torch.tensor(yi,dtype=torch.float).view(1,-1)
            self.optimizer.zero_grad()
            output=self.forward(xi)
            loss=self.loss(output,yi)
            loss_epoca=loss_epoca+loss.item()
            loss.backward()
            self.optimizer.step()
            print(f"pérdida media en la época [{i}]:{loss_epoca/len(X)}")
```







El flujo de trabajo:

1. Preparación

2. Entrenamiento

3. Evaluación / Validación

```
Inicializar modelo
Definir función de pérdida
Definir optimizador
Cargar datos de entrenamiento y validación
Configurar hiperparámetros: epochs, batch_size,
learning_rate
```

```
Para cada epoch en range(num_epochs):
    model.train()
    Para cada batch en dataloader de entrenamiento:
        optimizador.zero_grad()
        entradas, etiquetas = batch
        predicciones = modelo(entradas)
        pérdida = función_de_pérdida(predicciones, etiquetas)
        pérdida.backward()
        optimizador.step()
```

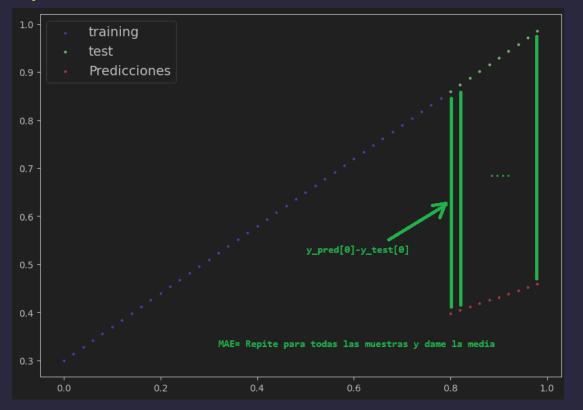
```
model.eval()
Con torch.no_grad(): # Desactiva el cálculo de gradientes
  Para cada batch en dataloader de validación:
        entradas, etiquetas = batch
        predicciones = modelo(entradas)
        pérdida_val = función_de_pérdida(predicciones, etiquetas)
        Guardar métricas de validación (precisión, pérdida, etc.)
```







Función de pérdida









El optimizador - cálculo automático de los gradientes: autograd

Es un sistema automático de diferenciación que calcula los gradientes de las operaciones realizadas sobre tensores

Al realizar operaciones con tensores que tienen requires_grad=True, PyTorch construye dinámicamente un gráfico computacional que registra las dependencias entre las operaciones. Luego, mediante el método backward(), el autograd recorre este gráfico para calcular los gradientes de manera eficiente, permitiendo optimizar modelos de aprendizaje profundo.

https://pytorch.org/tutorials/beginner/introyt/autogradyt_tutorial.html

El modelo en modo.train SI realiza autograd en modo evaluación NO realiza autograd



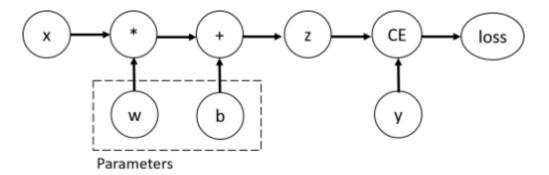




El grafo computación de AutoGrad: BackPropagation

```
import torch

x = torch.ones(5)  # tensor de entrada
y = torch.zeros(3)  # salida esperada
w = torch.randn(5, 3, requires_grad=True)
b = torch.randn(3, requires_grad=True)
z = torch.matmul(x, w)+b
loss =
torch.nn.functional.binary_cross_entropy_with_logits(z, y)
```









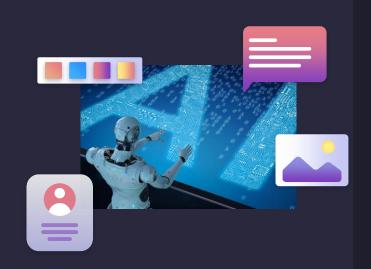
Vamos a por el cuaderno pytorch_autograd

```
def print_graph(g, level=0):
    if g is None:
        return
    print("\t" * level, g)
    for subg in g.next_functions:
        print_graph(subg[0], level + 1)
# Imprimir el grafo
print_graph(out.grad_fn)
[11]
  <SumBackward0 object at 0x7f87169337f0>
      <AddBackward0 object at 0x7f8716933d00>
          <MulBackward0 object at 0x7f8716933580>
              <SinBackward0 object at 0x7f87169335e0>
```



Construcción de redes neuronales con PyTorch

Regresión y clasificación con redes neuronales

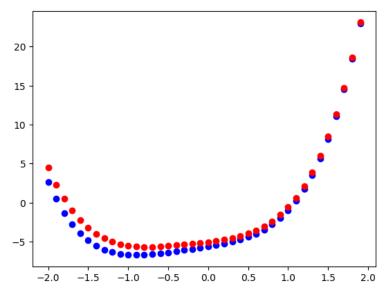




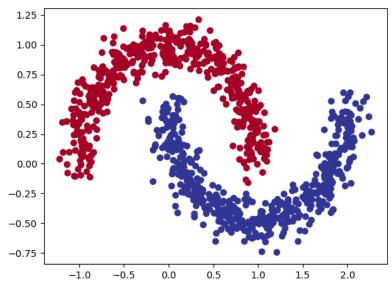




Ejercicio 1: Regresión de un polinomio



Ejercicio 2: Clasificación: make_moons



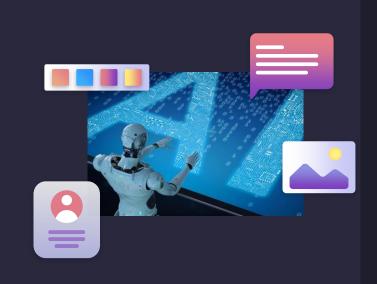






Manejos de datasets y loaders en PyTorch

Un problema clásico: Datasets y DataLoaders con Dígitos MNIST



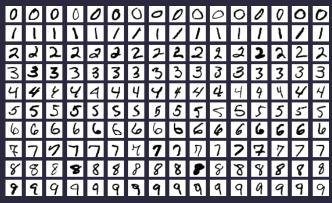




















https://pytorch.org/vision/main/datasets.html

- Incorpora datasets "Built-in" para problemas de ML y DL
- Datos para visión, texto y audio.
- Soporte para datasets personalizados.
- Optimizado: Descarga y preprocesamiento eficiente
- Con DataLoader permite la gestión de batches
- Integrado con torchvision.transforms para aumentación de datos.

CLASS torch.utils.data.Dataset [SOURCE]

An abstract class representing a Dataset.

All datasets that represent a map from keys to data samples should subclass it. All subclasses should overwrite
__getitem__(), supporting fetching a data sample for a given key. Subclasses could also optionally overwrite
__len__(), which is expected to return the size of the dataset by many Sampler implementations and the default
options of DataLoader. Subclasses could also optionally implement __getitems__(), for speedup batched samples
loading. This method accepts list of indices of samples of batch and returns list of samples.

NOT

DataLoader by default constructs an index sampler that yields integral indices. To make it work with a map-style dataset with non-integral indices/keys, a custom sampler must be provided.

Datasets

- Built-in datasets

Image classification

Image detection or segmentation

Optical Flow

Stereo Matching

Image pairs

Image captioning

Video classification

Video prediction

Base classes for custom datasets

Transforms v2







EJEMPLO DE CLASIFICACIÓN:BUILT-IN MNIST DIGITS DATASET

```
from torchvision import datasets, transforms
from torch.utils.data import DataLoader
import torch
# Transformaciones: convertir a tensor y normalizar
transform = transforms.Compose([
   transforms.ToTensor(),
   transforms.Normalize((0.5,), (0.5,)) # Media y desviación estándar
1)
# Cargar conjunto de datos MNIST (Dígitos)
train_dataset = datasets.MNIST(root='./data', train=True, transform=transform, download=True)
test dataset = datasets.MNIST(root='./data', train=False, transform=transform, download=True)
# Crear Loaders
train loader = DataLoader(train dataset, batch size=64, shuffle=True)
test loader = DataLoader(test dataset, batch size=64, shuffle=False)
```





https://pytorch.org/vision/main/datasets.html





DataLoader

- divide en lotes (batches)
- aplicar transformaciones o preprocesamientos al acceder a un dato en concreto
- carga los datos en memoria usando múltiples procesos

```
batch_size
```

shuffle

num workers

```
for batch in train_loader:
    procesar(batch)

with torch.no_grad():
    for batch in test_loader:
        images, labels = batch
        evaluar(images, labels)
```







Creando un Dataset personalizado

```
t = transforms.Compose([
    transforms.Resize((128, 128)),
    transforms.ToTensor(),
])

dataset = CustomImageDataset("path", transform=t)
dataloader = DataLoader(dataset, batch_size=32)
```





