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# EPICS 4 beginners

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Questions please at the end

[www.europeanspallationsource.se](http://www.europeanspallationsource.se)

# Outline: What is EPICS



- History, overview
- How does EPICS look like ?
- EPICS IOC, EPICS process variable "PV"
- Records and EPICS "database"
- Network protocol: Channel Access
- Questions
- Bonus: better network protocol: pvAccess
- Questions

# EPICS starting page



- 'Experimental Physics and Industrial Control System'
  - <http://www.aps.anl.gov/epics>
- Mailing list usually provides responses within a few hours
  - <http://www.aps.anl.gov/epics/tech-talk/index.php>

# EPICS history and collaboration



- ~1989: Started between LANL Ground Test Accelerator and ANL Advanced Photon Source
- Now:
  - **SNS**, ANL/APS, SLAC, LANL, JLAB/CEBAF, LBNL, Fermilab D0, Gemini, FRIB, **Laser Interferometer Gravitational Wave Observatory** in the US Canadian Light Source
  - Kek, **J-PARC** in Japan, KSTAR in Korea,
  - DESY, BESSY, .. in Germany; PSI/SLS in Switzerland; ITER, Ganil, SACLAy in France; Diamond light source, **ISIS** in UK; KEK-K, J-Parc in Japan; IHEP in China; NSRRC in Taiwan; PLS in South Korea; Australian Synchroton, ESS in Sweden, ...
- Yearly **collaboration meetings**
  - 2 meetings / year, rotating through the continents
  - @ ESS, **May 25th .. May 27<sup>th</sup> 2016**

# EPICS is used in big science



Von: Andrew Johnson anj@aps.anl.gov

Betreff: Congratulations to everyone at LIGO Datum: 11. Februar 2016 17:21

An: EPICS tech-talk tech-talk@aps.anl.gov

... on finally detecting gravitational waves from a pair of merging black holes.

<http://www.nature.com/news/einstein-s-gravitational-waves-found-at-last-1.19361>

The earliest tech-talk message from a LIGO email address was from David Barker in 1996. I believe EPICS has always been a fundamental part of the observatories' control systems.

- Andrew

# EPICS meeting October 2014





# Example from SNS

**File Edit Search Run CSS Window Help**

**Scan Editor OPI Editor CSS**

**Navigator**

- GS
- GIT\_cg1d [cg1d master]
- T\_share [share master]
- Id
- data
- DF
- Tuesday
- Turbine\_4\_CT
  - 20130108\_Turbine\_CT\_0180\_000.000.0000.fits
  - 20130108\_Turbine\_CT\_0180\_000.650\_0001.fits
  - 20130108\_Turbine\_CT\_0180\_001.300\_0002.fits
  - 20130108\_Turbine\_CT\_0180\_001.950\_0003.fits
  - 20130108\_Turbine\_CT\_0180\_002.600\_0004.fits
  - 20130108\_Turbine\_CT\_0180\_003.250\_0005.fits
  - 20130108\_Turbine\_CT\_0180\_003.900\_0006.fits
  - 20130108\_Turbine\_CT\_0180\_004.550\_0007.fits
  - 20130108\_Turbine\_CT\_0180\_005.200\_0008.fits
  - 20130108\_Turbine\_CT\_0180\_005.850\_0009.fits
  - 20130108\_Turbine\_CT\_0180\_006.500\_0010.fits
  - 20130108\_Turbine\_CT\_0180\_007.150\_0011.fits
  - 20130108\_Turbine\_CT\_0180\_007.800\_0012.fits
  - 20130108\_Turbine\_CT\_0180\_008.450\_0013.fits
  - 20130108\_Turbine\_CT\_0180\_009.100\_0014.fits
  - 20130108\_Turbine\_CT\_0180\_009.750\_0015.fits
  - 20130108\_Turbine\_CT\_0180\_010.400\_0016.fits
  - 20130108\_Turbine\_CT\_0180\_011.050\_0017.fits
  - 20130108\_Turbine\_CT\_0180\_011.700\_0018.fits
  - 20130108\_Turbine\_CT\_0180\_012.350\_0019.fits
  - 20130108\_Turbine\_CT\_0180\_013.000\_0020.fits
  - 20130108\_Turbine\_CT\_0180\_013.650\_0021.fits

**Display**

**Camera Control**

- Exposure Time (S) **180.000**
- Binning **1 1**
- ADC Speed **1.00 MHz**
- Shutter Mode **Auto**
- Camera State **Idle**
- Start** **Stop**

**Cooling**

- Cooler **On** **On**
- Temperature **-60.000** **-59.777**
- Status **Stabilized at set po**

**Advanced**

- Full Control (Simulated)**
- Full Control (Andor)**
- File I/O Configure**
- General Camera**

**Image Preview**

**Motors**

Motor	Readback	Position	Left/Move/Right	Limits
Lift Table	83.1 mm	<b>83.1 mm</b>	... <b>STOP</b>	
Short Axis	80.0 mm	<b>80.0 mm</b>	... <b>STOP</b>	
Long Axis	132.5 mm	<b>132.5 mm</b>	... <b>STOP</b>	
Large Rotation T.	90.0 deg	<b>90.0 deg</b>	... <b>STOP</b>	
Detector Table	225.0 mm	<b>225.0 mm</b>	... <b>Enabled</b>	
Small Rotation T.	181.4 deg	<b>181.4 deg</b>	... <b>STOP</b>	
Camera Vert.	70.0 mm	<b>70.0 mm</b>	... <b>STOP</b>	
Robofocus	50	<b>50</b>	In ↕ Out ↕ Cabinet...	

**Motor Guide**

- Lift Table**
- smaller - Short Axis**
- LARGER + Short Axis**
- Long Axis**
- + Lift Table + Long Axis**

**CT Scan Camera Scan**

**Configuration**

- Start **0** End **182** Step **0.650**
- Device **Large ..** **Small Rot. Table**
- Exposure **180.000** Delay **0 sec**  Simulate?
- Directory **/home/controls/cg1d/data/Tuesday/Turbine\_4\_CT**
- File name **turbine\_CT** **Go**

**Andor Message**

**Outline**

An outline is not available.

**Console Scan Monitor**

ID	Created	Name	State	%	Runtime	Finish	Command	Error
153	2013-01-08 17:54:24	Rotation Scan: Turbine_CT	Finished - OK		14:35:06	08:29:31	- end -	
152	2013-01-08 17:38:07	Rotation Scan: Turbine_CT_test	Finished - OK		00:15:35	17:53:42	- end -	

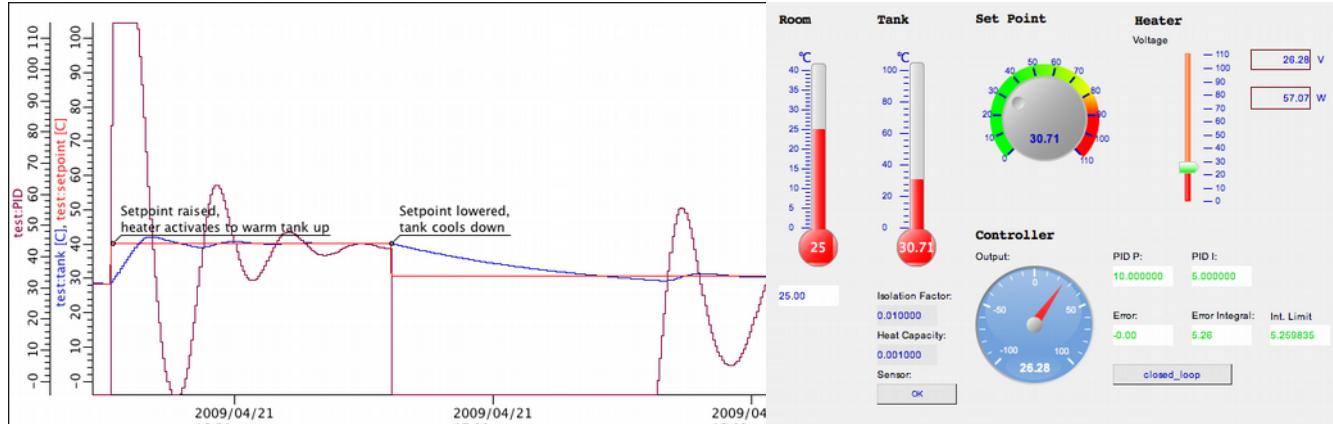
Scan Server Memory:

25.1 MB / 1744.0 MB (1.4 %)

# EPICS is distributed



- Operator interface
- Services: Archive, CCDB
- Front-end IOCs
- I/O, PLCs, ..



... for distributed control systems.

- Front-end: “Input/Output Controller” (IOC)
- Protocol: Channel Access, PV access
- Clients: Operator displays, alarm system, ...
- Very portable: Linux, OS X, Windows, VxWorks, UNIX, RTEMS

# What an IOC does



- Known set of ‘Records’
  - Read analog value
  - Write analog value
  - Perform computation
  - Control motor
- Runtime ‘Database’
  - Executes records
- Configuration
  - SCAN=1 second
  - INP=..what to read..
- Serve all via Channel Access

# What is a process variable

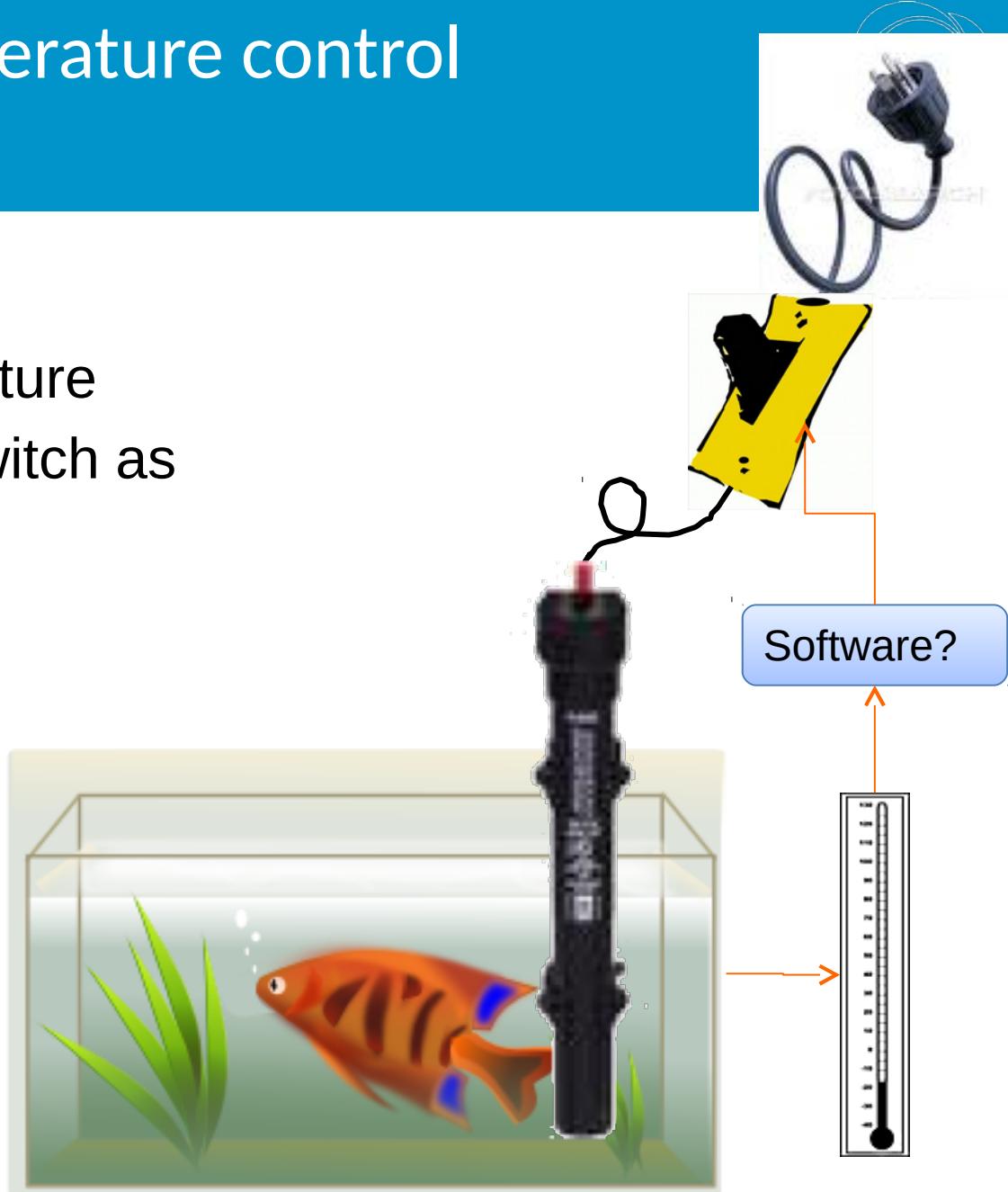


- Process variable (“PV”):
  - a physical value is represented in SW, with metadata
  - has a unit (Celsius, Volt, mm )
  - may be analog (=floating point or integer)
  - may be binary (=single bit)
  - may represent a bit field
- Is part of a “record”
- Is hosted in an EPICS IOC (“IOC”, soft IOC, hard IOC)

# Example: Temperature control

Task:

1. Read temperature
2. Open/close switch as needed
3. Repeat



# Pseudo code



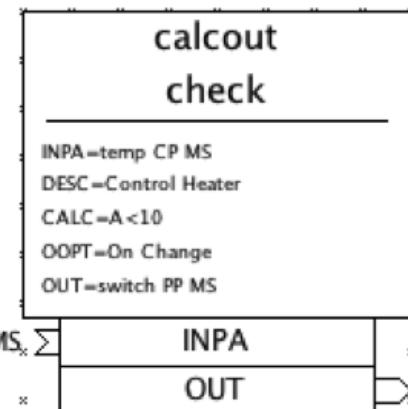
```
Sensor temp = connectToSensor();  
Switch switch = connectToSwitch();  
do forever {  
    if (temp.value() < 10)  
        switch.close();  
    else  
        switch.open();  
    sleep(1.0);  
}
```

# EPICS 'Database' for Fishtank

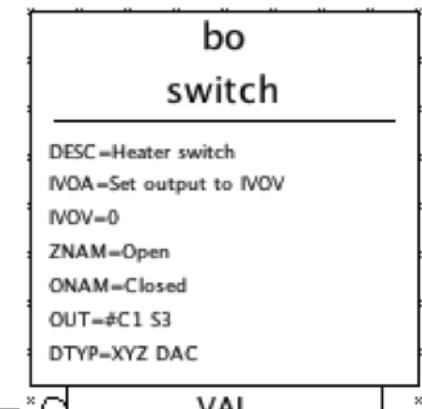
Analog  
Input  
Record

ai									
temp									
DESC=Read Temperature									
DTYP=XYZ ADC									
INP=#C1 S4									
SCAN=1 second									
HIGH=15									
HSV=MAJOR									
PREC=1									
EGU=Celsius									
LOPR=0									
HOPR=100									
LINR=typeJdegC									
SMOO=0.5									
VAL									

calc  
Record



Binary  
Output  
Record



# Record: Analog in



```
• record (ai, temp) {  
•   field(DESC, "Read Temperature")  
•   field(EGU, "Celsius")  
•   field(SCAN, "1 second")  
•   field(DTYP, "XYZ ADC")  
•   field(INP, "#C1 S4")  
•   field(PREC, "1")  
•   #(less important, fields on next side)
```

# Record: Analog in

```
# continued from last side
field(LINR, "typeJdegC")
field(HOPR, "100")
field(LOPR, "0")
field(SMOO, "0.5")
field(HIGH, "15")
field(HSV, "MAJOR")
}
```

# Record: binary out



- record (bo, **switch**)
- field(DESC, "Heater Switch")
- field(DTYP, "XYZ DAC")
- field(OUT, "#C1 S3")
- field(ZNAM, "#Open")
- field(ONAM, "#Closed")
- }

# Record: calcout



- record (calcout, **check**)
- field(DESC, "Control Heater")
- field(CALC, "a<10")
- field(INPA, "**temp CP MS**")
- field(OUT, "**switch**")
- field(OOPT, "On Change")
- }

# IOC Database



- A single record can handle the scanning, signal conditioning, alarming of a temperature, pressure, or similar analog reading.
- Combined with binary and computational records, it can express the data flow logic for a front-end computer
  - Avoiding the pitfalls of real-time, multithreaded and networked programming.
- Can have thousands of records in one IOC.
- kHz-rate processing with record chains is doable
  - Of course limited by CPU. Not 1000nds of kHz rate-records...

# Records for writing code



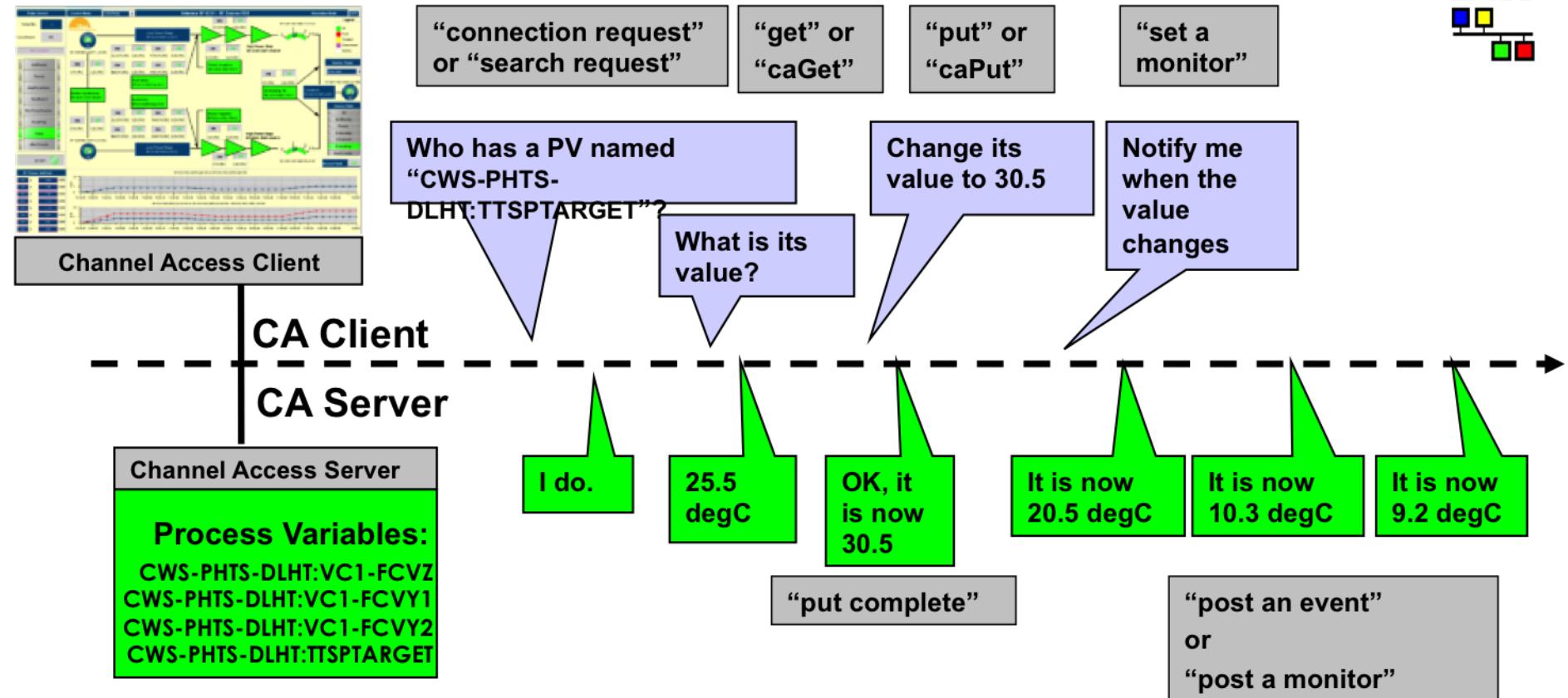
- "SCAN=1 second"  
instead of start thread,  
delay until next multiple of 1 second,  
lock required resources, ...
- "SMOO=0.5" configures the smoothing algorithm.
- Change scan rates at any time via the network:
  - scan rate
  - Smoothing
  - alarm levels

# EPICS Vocabulary



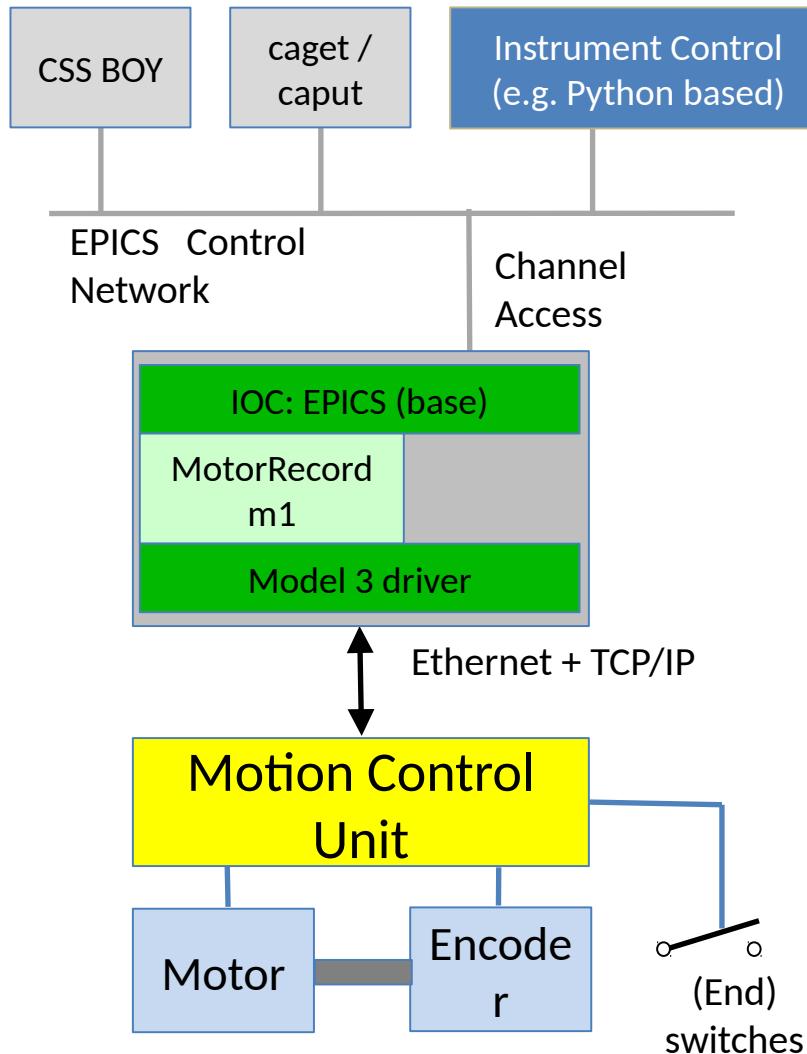
- **EPICS Base**  
Code for IOC, database support, basic records, channel access
- **IOC**  
Input Output Controller, the front-end software
- **Soft IOC**  
IOC software running on Linux, ..., typically communicating with networked I/O
- **Database**  
Executes the EPICS Records
- **Record**  
EPICS processing block
- **Driver**  
Code that talks to hardware. Devices with an ASCII-like command-set often use **StreamDevice** as a driver.
- **Channel Access**  
EPICS network protocol. Exposes Channels aka Process Variables
- **SNL**  
State notation language.

# Channel access in one slide



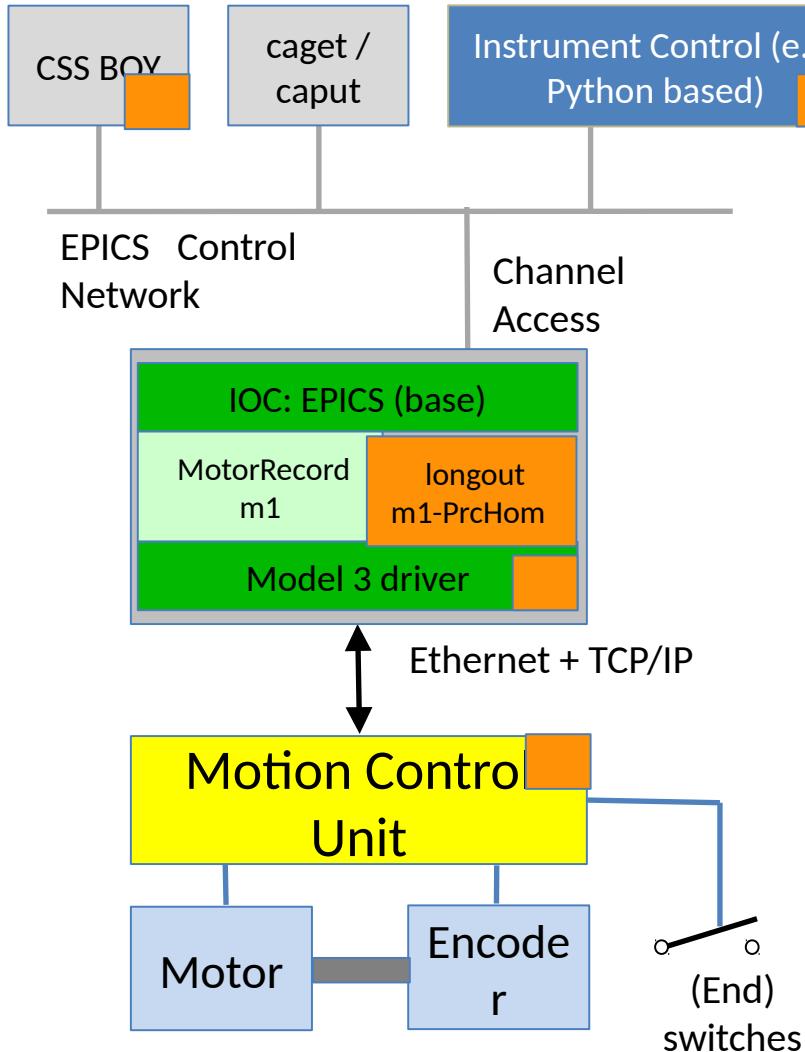
- Machine/Integrated Control Systems
  - HW platforms, network, archiver,
  - CCDB, naming convention
  - Make it possible to install EPICS @ InKind partners ("EEE" & "Dev Env")
- Science/DMSC:
  - Instrument control
- Science/NSS
  - MCAG, SE, Chopper, Detector, Scientists

# Motion Control Integration (today)



- 3 layers in control box:
  - EPICS IOC
  - Motor record (single axis)
  - Model 3 driver
- Basic functionalities for point-to-point movements
- Future extensions of functionality in additional records

# Motion Control Integration (tomorrow)



- 3 layers in IOC:
  - Motor record (single axis)
  - longout record (homing)
  - Model 3 driver
- Basic functionalities for point-to-point movements
- Future extensions of functionality in additional records
- Current development includes a.o. jerk, homing procedures
- Extensions need to be implemented in user interfaces, model 3 driver and motion control unit as well (strong coordination necessary)

# Move & monitor a motor (done on a simulator, Mac or raspi)

```

caput IOC:m1.VAL 60.1
Old : IOC:m1.VAL
      24.9
New : IOC:m1.VAL
      60.1

#Notes:
#caput: Channel accesss put
#camonitor: Channel accesss monitor
#IOC:m1..DMOV: Field "done moving"
#IOC:m1.RBV: Field Readback value

```

- camonitor IOC:m1.RBV IOC:m1.DMOV
- IOC:m1.RBV 2016-02-02 10:58:16.157350 **24.87**
- IOC:m1.DMOV 2016-02-02 10:58:16.658745 **1**
- IOC:m1.DMOV 2016-02-02 10:58:16.658745 **0**
- IOC:m1.RBV 2016-02-02 10:58:30.124368 **49.86**
- IOC:m1.RBV 2016-02-02 10:58:31.138087 **60.06**
- IOC:m1.DMOV 2016-02-02 10:58:31.639072 **1**

# Quiz - 1



- Can I monitor a PV on the command line ?
- Is a PV always a part of a record ?
- Is a record processed ?
- I can write a python script to control devices (Experiment control) ?
- An IOC can do real time processing ?

# Quiz - 2



- When a PV changes, is there a time stamp associated with the change ?
- May a PV have a high-or low limit ?
- Can a PV be used to monitor the room temperature ?

# Relax



- Time for questions

# Why another protocol?



- EPICS Version 3 is targeted towards **control** applications
  - Simple data types, essentially scalar values with (very) limited metadata
    - Timestamp, alarm, engineering units, etc.
- Simple example: array of sampled values from an ADC.
  - What was the sampling rate?
  - Applications have to know that – knowledge is separate from data
  - Or, create lots of extra channels to hold the metadata
  - Applications have to stitch the information together from different channels

# Scientific applications need even more



- Several (site-specific, incompatible) abstraction layers have been built on top of the simple EPICS channel structures
- (Large) data transport is inefficient
  - Use of EPICS channel access for large data transfer is not practical (solution: bypass EPICS)
  - Achieving synchronicity is difficult (sometimes even impossible)
  - E.g., set three parameters for an acquisition and start: needs minimum of three “ca\_put”s
- Channel Access does not guarantee (atomic) delivery of waveform data

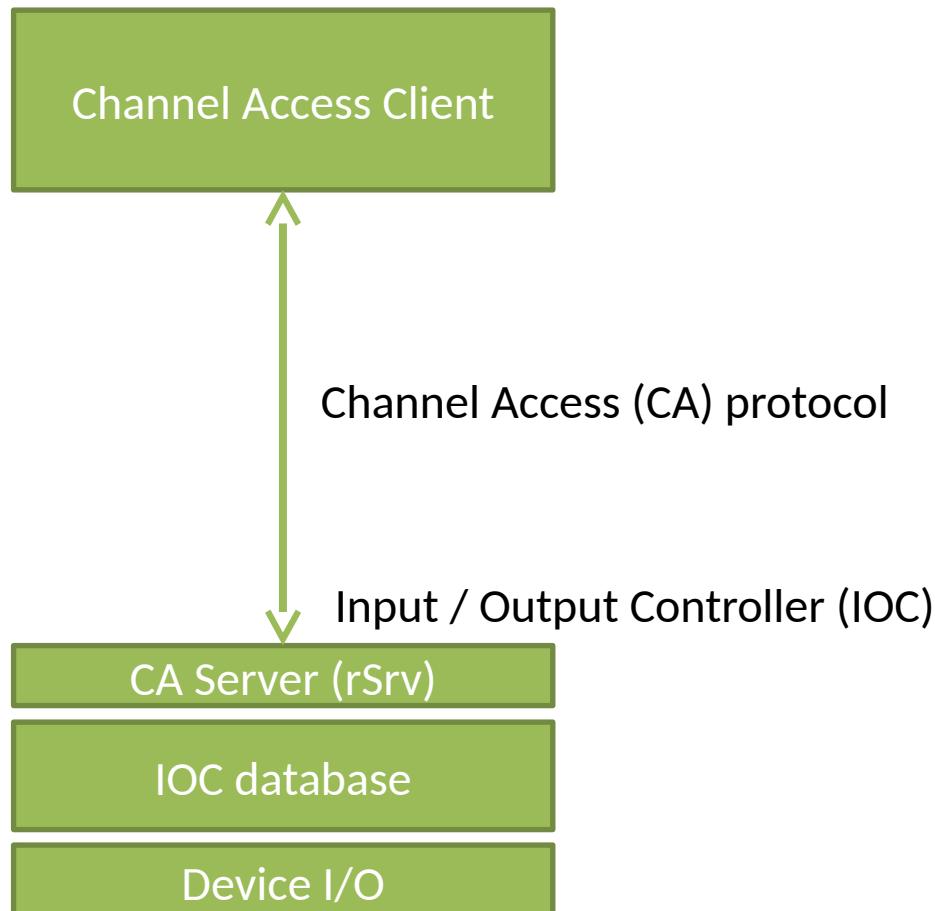
# New protocol, pvAccess



- Part of EPICS 7, which joined EPICS 3 and 4 together
- Structured data
- Introspection interface, “pvData”
- Dynamic typing
- Standard Scientific Types
- RPC and putGet added
- New smart database
- All APIs in C++ and Java
- Python
- High Performance

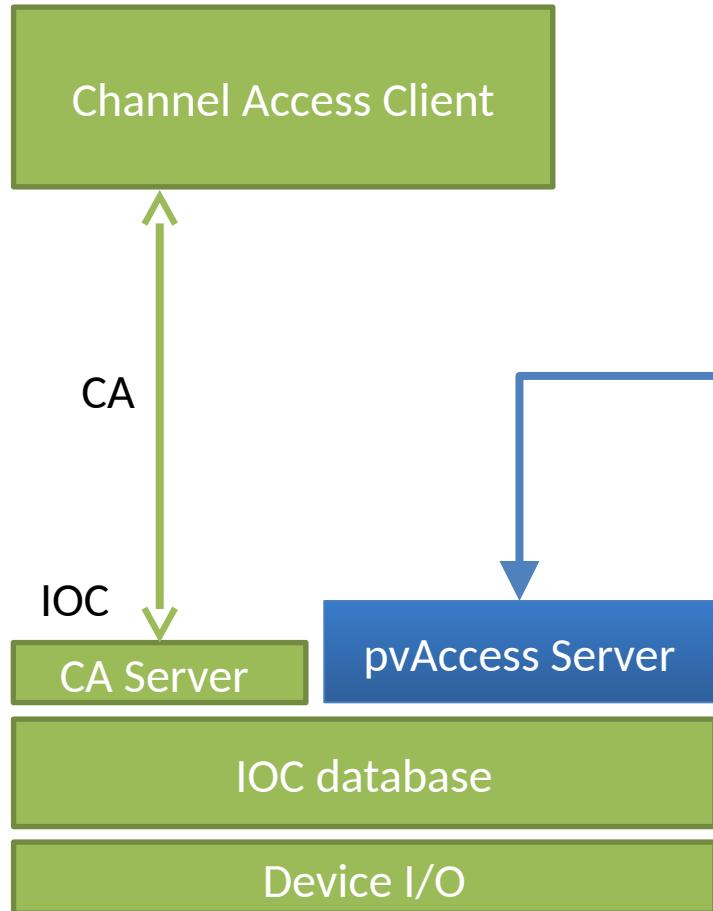
- EPICS 3 block diagram

EPICS in the nominal usage: An EPICS client communicates over Channel Access (CA) protocol to an Input/Output Controller (IOC) Channel Access server (module rSrv in an IOC)



- Version 4 Additions to EPICS

V4 IOC == V3 IOC + pvAccess Server

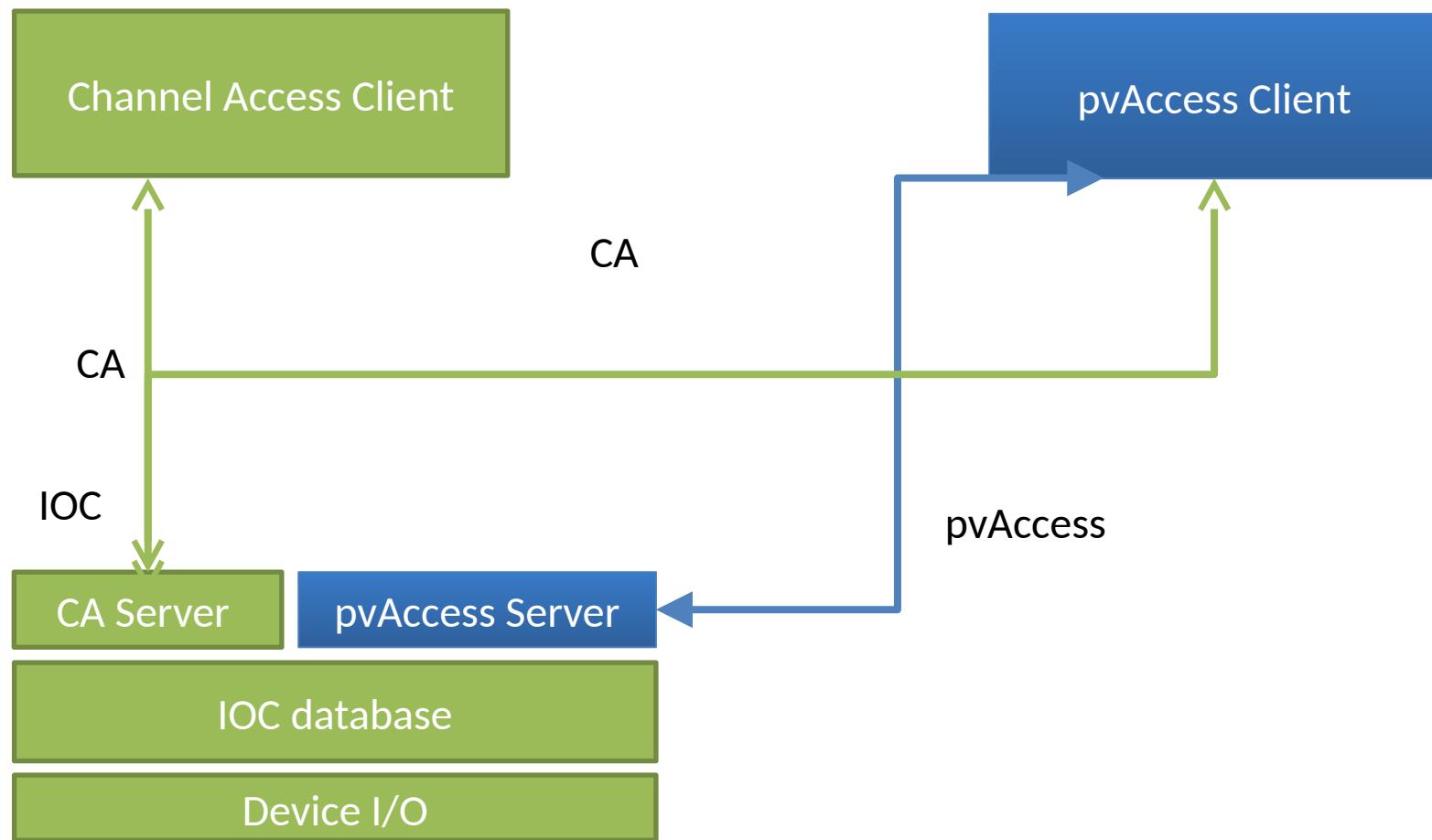


Use Case: Network efficient acquisition  
of archived meta data

Presently, only 1 PV per pvAccess channel.  
But plan is to get/monitor a group of PVs  
through one pvAccess channel.

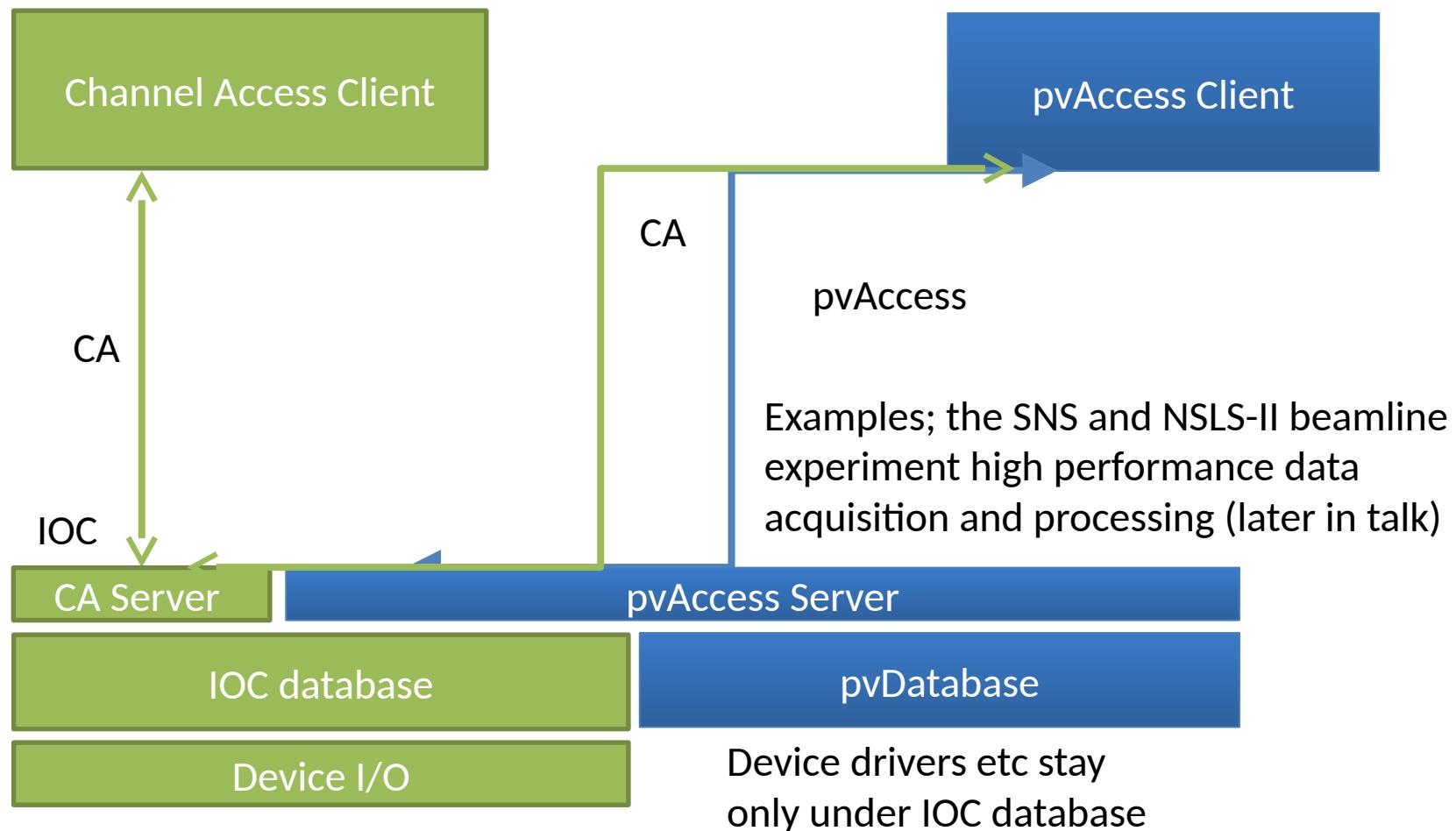
- Version 4 Additions to EPICS

The pvAccess API includes Channel Access support, so one client lib does both

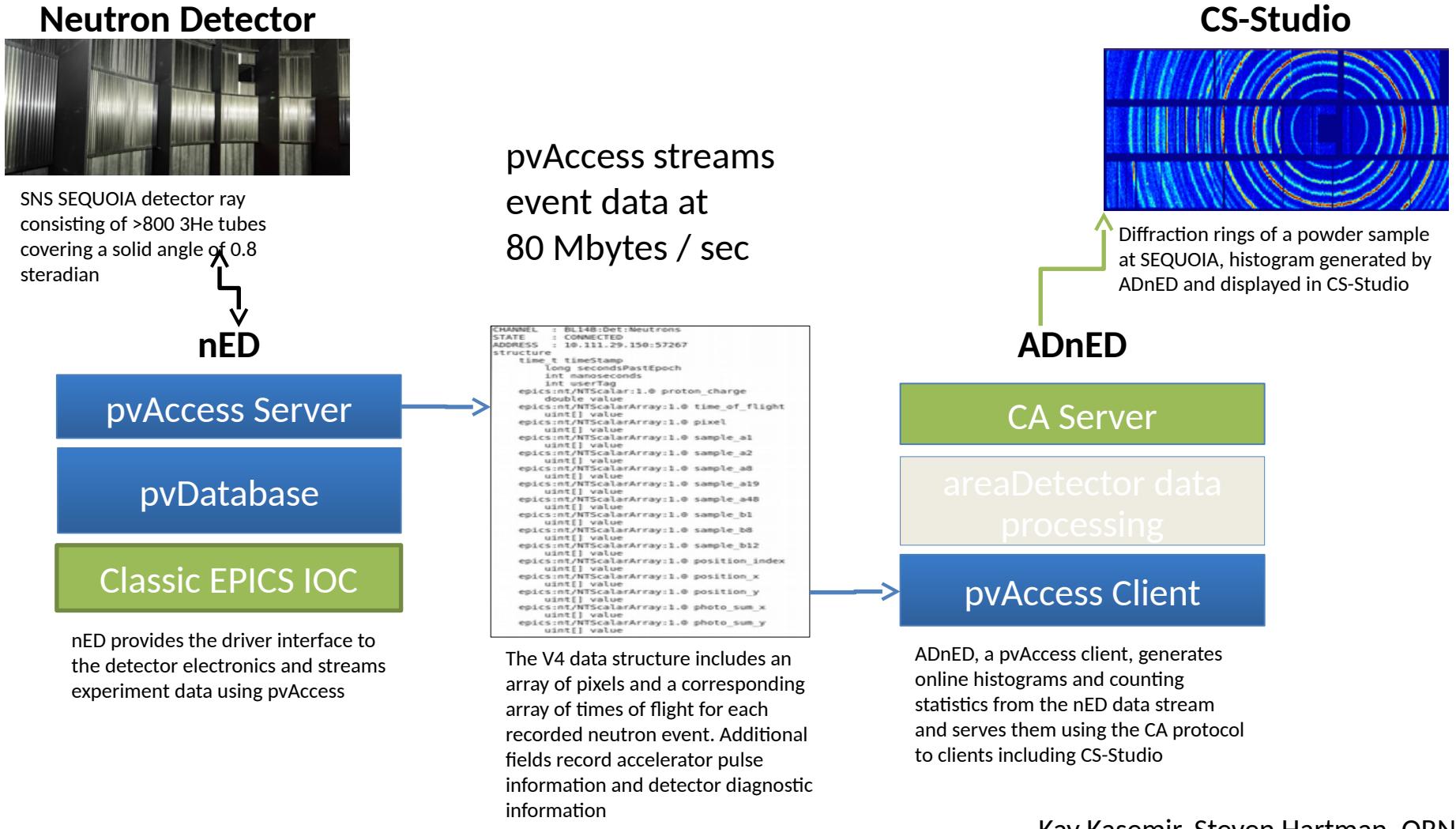


- Version 4 Additions to EPICS

A new smart database, “pvDatabase” can be used for data assembly and processing



# ORNL SNS Deployment: Neutron event data aggregation and transport



- ORNL SNS Deployment: Neutron event data aggregation and transport

### SNS Conclusions:

Five beam lines currently using EPICS V4

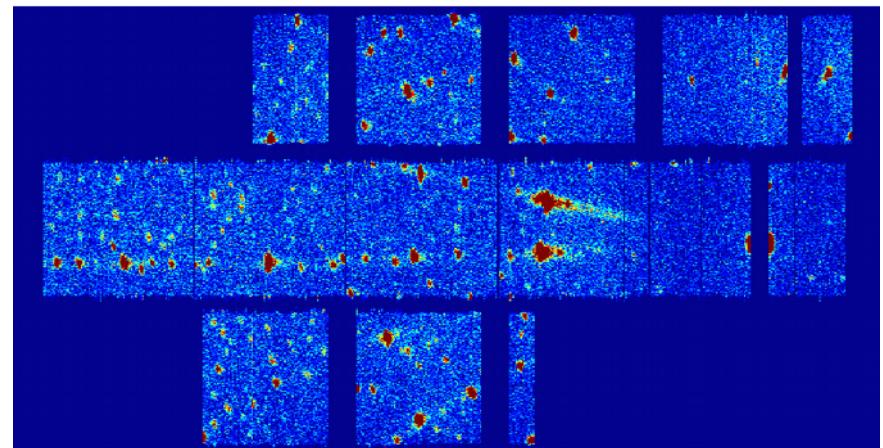
Plans to extend to all experiment beam lines.

Additionally, A pvaPy-based V4 client is used for detector calibration and diagnostics.

EPICS V4 meets the performance requirements for all existing SNS instruments

Demonstrated at data rates of 10M events per second

Excellent reliability.



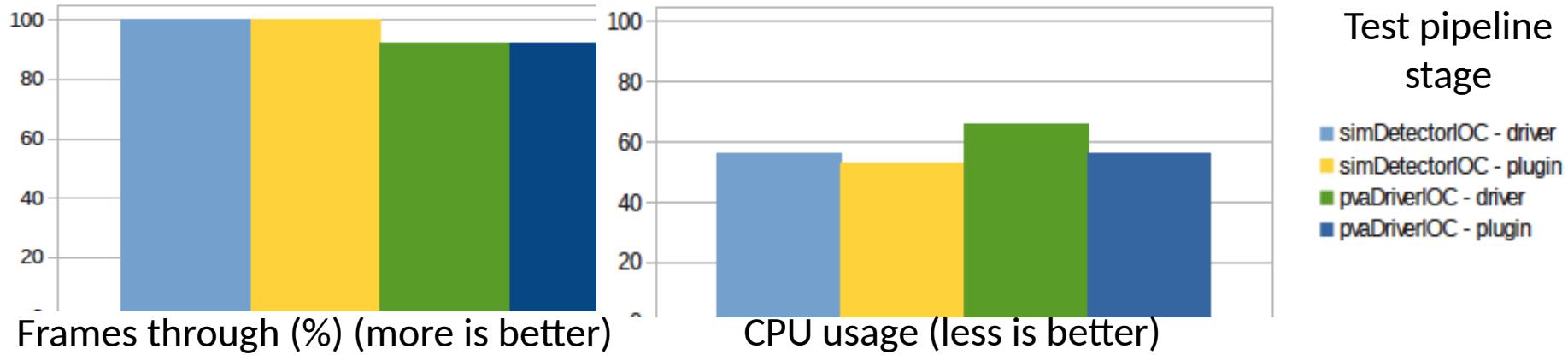
ADnED plot of a diffraction pattern from neutron scattering of a single-crystal sample at SNS CORELLI



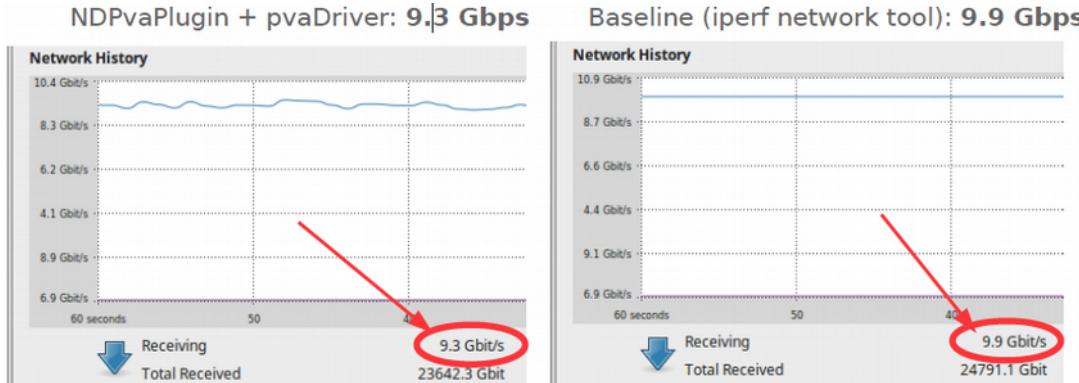
Fragment of the SNS V4 structure used for streaming experiment data at the 60 Hz rate of the pulsed neutron source

## NSLS-II Deployment (1) – beamline image data transport and fanout

Test simDetector datasource 5K x 5K @ 50Hz  $\approx$  10 Gb/s over 10Gig Ethernet.  
Non-blocking callbacks. AD ImageMode: Multiple. NumImages:10000

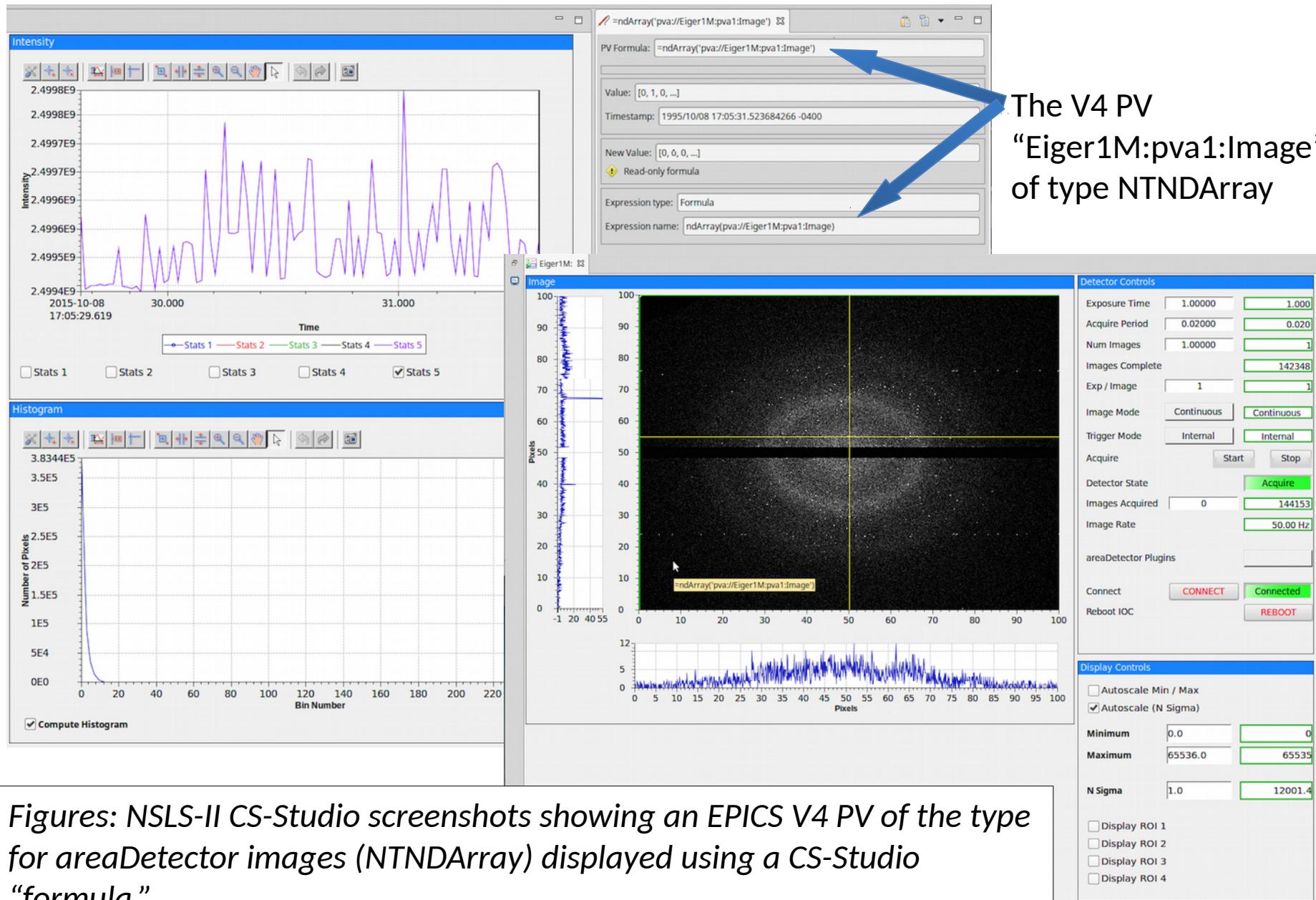


Transfer bandwidth: EPICS V4 & practical limit:

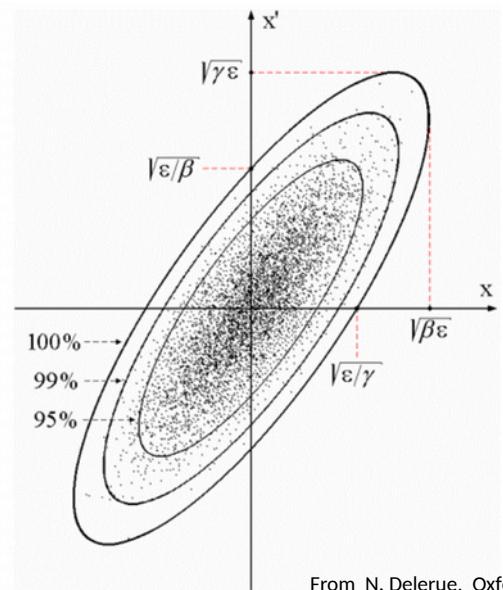
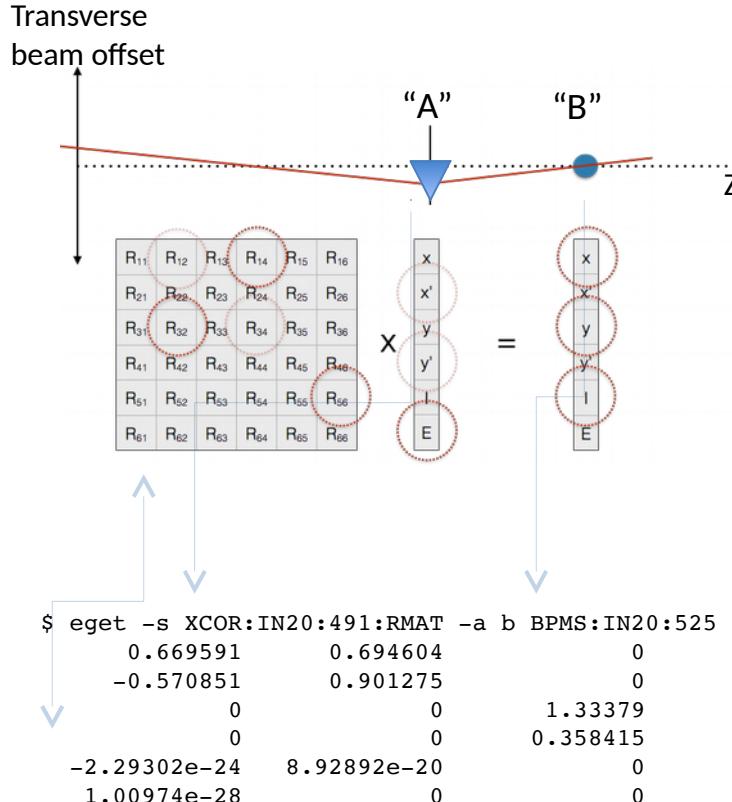


**Conclusions:** EPICS V4 based areaDetector pipeline has high throughput, few frames lost, with no CPU saturation. Network bandwidth is close the practical maximum.

## NSLS-II Deployment (1) - beamline image data transport and fanout



# • SLAC & ESS deployment: Modelling beam dynamics



```
$ eget XCOR:LI24:900:TWISS
  energy 5.00512
  psix 37.7625
  alphax 13.6562
  betax -2.78671
  etax -0.00698294
  etaxp 0.00107115
  psiy 31.9488
  alphay 116.762
  betay 5.2592
  etay 0
  etayp 0
  z 2438.72
```

Figure: EPICS V4 modelling service giving orbit response matrices and Twiss parameters for given devices. These are the basis of 95% of emittance minimization applications – feedback, steering, bumps, etc

# Questions



- Thank you