

$$g(t) = 2$$

$$f(t) = x^2 + 1$$

$$\begin{pmatrix} 1 \\ t \\ t^2 \end{pmatrix} \quad \begin{aligned} f_1(t) &= 1 \\ f_2(t) &= t \\ f_3(t) &= t^2 \end{aligned}$$

$$\begin{aligned} \langle g(t), f(t) \rangle &= \int_{-1}^1 g(t) \cdot f(t) \, dt \\ &= \int_{-1}^1 2 \cdot (x^2 + 1) \, dt \\ &= \int_{-1}^1 2x^2 + 2 \, dt = [\dots]_{-1}^1 \\ &= a \in \mathbb{R} \end{aligned}$$

$$\lambda_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \quad x_2 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \quad x_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad \begin{aligned} \langle v_i, v_j \rangle &= 0 & i \neq j \\ \langle v_i, v_i \rangle &= 1 \end{aligned}$$

$$x_1(t) = 1 \quad \tilde{v}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \quad \tilde{v}_1 \neq 0$$

$$\tilde{v}_1(t) = 1$$

$$1.1 \quad \tilde{v}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \quad \tilde{v}_1 \neq 0$$

$$1.2 \quad v_1 = \frac{\tilde{v}_1}{\|\tilde{v}_1\|} = \frac{1}{\sqrt{1^2 + 1^2 + 0^2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

$$v_1(t) = \frac{\tilde{v}_1(t)}{\|\tilde{v}_1(t)\|} = \dots = \underline{\underline{2t}} \text{ (Beispiel)}$$

Orange:
GS mit
Polynomen

$$2.1 \quad \begin{aligned} \tilde{v}_2 &= x_2 - \langle x_2, v_1 \rangle v_1 \\ \tilde{v}_2(t) &= t - \langle \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \rangle \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} - 1 \cdot \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ -1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix} \end{aligned}$$

$$2.2 \quad \tilde{v}_2 \neq 0, \quad v_2 = \frac{\tilde{v}_2}{\|\tilde{v}_2\|} = \frac{1}{\frac{1}{2} \sqrt{1^2 + (-1)^2 + (-2)^2 + 2^2}} \cdot \frac{1}{2} \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix}$$

$$= \frac{1}{\sqrt{10}} \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix}$$

$$3.1 \quad \begin{aligned} \tilde{v}_3 &= x_3 - \langle x_3, v_1 \rangle v_1 - \langle x_3, v_2 \rangle v_2 \\ &= \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} - \langle \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \rangle \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} - \langle \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \frac{1}{\sqrt{10}} \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix} \rangle \frac{1}{\sqrt{10}} \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \end{aligned}$$

$$3.2 \quad \tilde{v}_3 \neq 0, \quad v_3 = \frac{\tilde{v}_3}{\|\tilde{v}_3\|} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$ONS = (v_1, v_2, v_3) = \left(\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \frac{1}{\sqrt{10}} \begin{pmatrix} -1 \\ -1 \\ 2 \end{pmatrix}, \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \right)$$

$$\begin{aligned}
 & \Phi_{\mathbb{R}^4} \rightarrow \mathcal{W}(y) \quad y = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \\
 & = \langle y, v_1 \rangle v_1 + \langle y, v_2 \rangle v_2 + \langle y, v_3 \rangle v_3 \\
 & = \left\langle \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} \right\rangle \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} \\
 & \quad + \left\langle \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \frac{1}{\sqrt{10}} \begin{pmatrix} -1 \\ -1 \\ 2 \\ 2 \end{pmatrix} \right\rangle \frac{1}{\sqrt{10}} \begin{pmatrix} -1 \\ -1 \\ 2 \\ 2 \end{pmatrix} \\
 & \quad + \left\langle \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} \right\rangle \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} \\
 & = 2 \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} + 0 \cdot \frac{1}{\sqrt{10}} \begin{pmatrix} -1 \\ -1 \\ 2 \\ 2 \end{pmatrix} + 2 \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} = y
 \end{aligned}$$