

Math for Data Science – Exam – Fall 2025

NB: There are five sections in the exam. Indicative point scale, currently computed out of 40 points. No point without justification. Please give all documents at the end of the exam (including your draft paper and this document). Good luck!

1 Proofs – Vector spaces (5 pts)

1. **Sum of subspaces.** Let E be a vector space, F and G be two subspaces of E . We recall that their sum is defined by

$$F + G = \{u \in E, \exists (v, w) \in F \times G, u = v + w\}.$$

- (a) Is $F + G$ a subspace of E ? Prove it.
- (b) Let suppose that $F \cap G = \{0_E\}$ (direct sum). Show that for every $u \in F + G$, there exists a unique pair $(v, w) \in F \times G$ such that $u = v + w$. (Hint: prove existence, then uniqueness).
2. **Injectivity and kernel.** Let E and F be two vector spaces and $f : E \rightarrow F$ be a linear map.
- (a) Prove that $f(0_E) = 0_F$.
- (b) Prove that f is injective if and only if $\text{Ker}(f) = \{0_E\}$. (Hint: prove one implication, then the other).

2 Exercise – Determinant (6 pts)

Let $n \in \mathbb{N}^*$. We consider the determinant Δ_n defined by:

$$\Delta_n = \begin{vmatrix} 1 & 2 & 3 & \cdots & (n-1) & n \\ -1 & 0 & 3 & \cdots & (n-1) & n \\ -1 & -2 & 0 & \cdots & (n-1) & n \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ -1 & -2 & -3 & \cdots & 0 & n \\ -1 & -2 & -3 & \cdots & -(n-1) & 0 \end{vmatrix}$$

For example, we have:

$$\Delta_3 = \begin{vmatrix} 1 & 2 & 3 \\ -1 & 0 & 3 \\ -1 & -2 & 0 \end{vmatrix} \quad \Delta_4 = \begin{vmatrix} 1 & 2 & 3 & 4 \\ -1 & 0 & 3 & 4 \\ -1 & -2 & 0 & 4 \\ -1 & -2 & -3 & 0 \end{vmatrix} \quad \Delta_5 = \begin{vmatrix} 1 & 2 & 3 & 4 & 5 \\ -1 & 0 & 3 & 4 & 5 \\ -1 & -2 & 0 & 4 & 5 \\ -1 & -2 & -3 & 0 & 5 \\ -1 & -2 & -3 & -4 & 0 \end{vmatrix}$$

1. Compute Δ_1 , Δ_2 , Δ_3 and Δ_4 . (Hint: use elementary operations on the rows and/or columns of the matrix.)

2. Make a hypothesis on the value of Δ_n for every $n \in \mathbb{N}^*$ (hint: use $n!$). Explain your reasoning.
3. Prove your hypothesis by induction. (Hint: use your previous answers for initializing the proof. Then prove that if the property is true for a given n , then it is also true for $n + 1$.)

3 Proofs – Eigenvalues and eigenvectors (6 pts)

Let $A \in \mathbb{R}^{n \times n}$ and suppose (λ_i, v_i) , $i = 1, \dots, n$, are eigenpairs of A with the eigenvectors v_1, \dots, v_n linearly independent. We set $V = [v_1 \ \cdots \ v_n] \in \mathbb{R}^{n \times n}$ (columns of V are the v_i vectors) and $D = \text{diag}(\lambda_1, \dots, \lambda_n) \in \mathbb{R}^{n \times n}$.

1. (a) Prove by induction that for every integer $k \geq 1$, we have:

$$\forall i \in \mathbb{N}, 1 \leq i \leq n, A^k v_i = \lambda_i^k v_i,$$

- (b) Deduce the matrix identity:

$$A^k = V D^k V^{-1}.$$

2. Now assume A is invertible.

- (a) What does it mean for the eigenvalues of A ? and for D ?

- (b) Prove that for each i , $1 \leq i \leq n$, v_i is an eigenvector of A^{-1} associated with the eigenvalue λ_i^{-1} , i.e.,

$$A^{-1} v_i = \lambda_i^{-1} v_i,$$

- (c) Deduce the matrix identity:

$$A^{-1} = V D^{-1} V^{-1}.$$

3. Are A^k (for $k \geq 1$) and A^{-1} (when defined) diagonalizable? Justify based on the previous questions.

4 Computations – Diagonalization (9 pts)

We consider the matrix

$$A = \begin{pmatrix} 3 & -1 & 1 \\ 0 & 2 & 2 \\ -1 & 1 & 3 \end{pmatrix}$$

We want to know whether it is diagonalizable in $\mathcal{M}_3(\mathbb{R})$. We recall that the algebraic multiplicity of an eigenvalue λ is its multiplicity as a root of the characteristic polynomial of A , and the geometric multiplicity of λ is the dimension of the eigenspace associated to λ :

$$\text{Eig}(A, \lambda) = \{X \in \mathbb{R}^3 : AX = \lambda X\}.$$

1. (a) *Using the characteristic polynomial of A* , determine the eigenvalues of A and their algebraic multiplicities. (Hint: the characteristic polynomial that you obtain should be divisible by $P(\lambda) = (\lambda - 2)(\lambda - 4)$.)
(b) Using a property of the trace, check your previous answer.
2. For each eigenvalue, determine *a basis* of the corresponding eigenspace, and the geometric multiplicity of this eigenvalue.
3. Based on your previous answers, is A diagonalizable in $\mathcal{M}_3(\mathbb{R})$? Justify your answer.

5 Exercise – Orthogonality between $S_n(\mathbb{R})$ and $A_n(\mathbb{R})$ (14 pts)

We denote by $\mathcal{M}_n(\mathbb{R})$ the set of square matrices of size n with real entries, by $S_n(\mathbb{R})$ the subset of symmetric matrices and by $A_n(\mathbb{R})$ the subset of antisymmetric matrices.

Let $n \in \mathbb{N}^*$. We consider the application from $\mathcal{M}_n(\mathbb{R}) \times \mathcal{M}_n(\mathbb{R})$ to \mathbb{R} defined by:

$$(M, N) \mapsto (M | N) = \text{tr}(M^\top N).$$

1. Inner product and norm.

- (a) Show that $(\cdot | \cdot)$ is an inner product on $\mathcal{M}_n(\mathbb{R})$.
- (b) Deduce that the function from $\mathcal{M}_n(\mathbb{R})$ to \mathbb{R} defined by $M \mapsto \|M\| = \sqrt{\text{tr}(M^\top M)}$ is a norm on $\mathcal{M}_n(\mathbb{R})$.
- (c) We consider the standard basis of $\mathcal{M}_n(\mathbb{R})$ defined by the matrices E_{ij} , $i, j \in \llbracket 1, n \rrbracket$, where E_{ij} is the matrix with a 1 at entry (i, j) and 0 elsewhere. Show that this basis is orthonormal for the above defined inner product.

2. Application.

- (a) Let

$$W = \{A \in \mathcal{M}_3(\mathbb{R}) : \text{tr}(A) = 0\}.$$

We remark that W is a subspace of $\mathcal{M}_3(\mathbb{R})$. Using the above defined inner product on $\mathcal{M}_3(\mathbb{R})$, compute W^\perp , the orthogonal complement of W .

- (b) What are the dimensions of W and W^\perp ? Check your answer with a property from the course.

3. Subspaces.

- (a) Define $S_n(\mathbb{R})$ and $A_n(\mathbb{R})$ using a property of the transpose (i.e. with a set notation).
- (b) Show that $S_n(\mathbb{R})$ and $A_n(\mathbb{R})$ are two subspaces in $\mathcal{M}_n(\mathbb{R})$.
- (c) Show that $S_n(\mathbb{R})$ and $A_n(\mathbb{R})$ are complementary and orthogonal subspaces in $\mathcal{M}_n(\mathbb{R})$.
- (d) What is the dimension of $S_n(\mathbb{R})$ and $A_n(\mathbb{R})$? Propose a basis for each of these subspaces.

- 4. **Distance to $S_n(\mathbb{R})$.** We recall that for a subspace F of a normed vector space $(E, \|\cdot\|)$, we define the distance from a point $x \in E$ to F by

$$d(x, F) = \inf_{y \in F} \|x - y\|.$$

- (a) Show that for every $M \in \mathcal{M}_n(\mathbb{R})$, there exists a unique matrix $S \in S_n(\mathbb{R})$ such that $d(M, S_n(\mathbb{R})) = \|M - S\|$.
- (b) For every $M \in \mathcal{M}_n(\mathbb{R})$, compute the distance $d(M, S_n(\mathbb{R}))$ as a function of M .
- (c) **Bonus (2pt):** For $i, j \in \llbracket 1, n \rrbracket$, we denote by E_{ij} the matrix of $\mathcal{M}_n(\mathbb{R})$ with a 1 at entry (i, j) and 0 elsewhere. We consider $M = \sum_{i=1}^n E_{i1}$. Compute $d(M, S_n(\mathbb{R}))$.