

Section 4.1

Chapter 4 is about vector spaces, which make up the some of most fundamental structure in mathematics.

Vector spaces are the setting we work in.

Range from very basic/familiar

\mathbb{R} , \mathbb{R}^2 , etc.

to fancy/complicated

Normed spaces, Hilbert spaces, Sobolev spaces

Can be used to make sense of everything from simple operation like addition to the solutions to systems of differential equations.

Definition: A vector space is a nonempty set V of objects (vectors) along with well defined operations of vector addition, scalar multiplication such that following properties hold for all $\vec{u}, \vec{v}, \vec{w} \in V$ and all $a, b \in \mathbb{F}$ (\mathbb{R} or \mathbb{C})

① If $\vec{u}, \vec{v} \in V$ then $\vec{u} + \vec{v} \in V$ (closed under vec. addition)

② $\vec{u} + \vec{v} = \vec{v} + \vec{u}$ (commutativity)

$$③ (\vec{u} + \vec{v}) + \vec{w} = \vec{u} + (\vec{v} + \vec{w}) \text{ (Associativity)}$$

$$④ \exists \vec{0} \in V \text{ s.t. } \vec{u} + \vec{0} = \vec{u} \text{ for all } \vec{u} \in V$$

$$⑤ \text{ For each } \vec{u} \in V, \exists -\vec{u} \in V \text{ s.t. } \vec{u} + (-\vec{u}) = \vec{0}$$

$$⑥ \text{ If } \vec{u} \in V, c \in \mathbb{F} \text{ then } c\vec{u} \in V \text{ (closed under scalar mult.)}$$

$$⑦ c(\vec{u} + \vec{v}) = c\vec{u} + c\vec{v}$$

$$⑧ (c+d)\vec{u} = c\vec{u} + d\vec{u}$$

$$⑨ c(d\vec{u}) = (cd)\vec{u}$$

$$⑩ 1\vec{u} = \vec{u}$$

\mathbb{R}^2

Vector spaces can be familiar and easily represented.

Ex

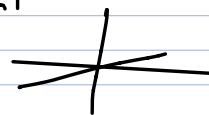
Consider set \mathbb{R}^n

$V =$ Elements/vectors in \mathbb{R}^n of form $\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$

Vector addition $\vec{x} + \vec{y} = \begin{bmatrix} x_1 + y_1 \\ \vdots \\ x_n + y_n \end{bmatrix}$

Scalar mult. $c\vec{x} = \begin{bmatrix} cx_1 \\ \vdots \\ cx_n \end{bmatrix}$

Used to all these operations, pretty familiar



EX

Set of continuous functions on $[0,1]$

$V =$ Vectors are functions. No convenient way to write as a list of components

Vector addition: $\overbrace{f+g}^{\text{is continuous function s.t.}}$
 $\underline{f(x) + g(x)} = \underline{(f+g)(x)}$ for all $x \in [0,1]$

Scalar mult: cf is cont. function s.t.
 $\underline{cf(x)} = \underline{c \cdot f(x)}$ for all $x \in [0,1]$

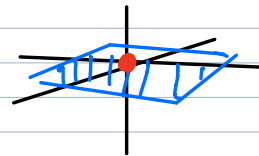
Often want to consider a part of a larger vector space.

Definition: A subspace, H , of a vector space V is a subset of V that satisfies following:

- ① Zero vector of V is in H
- ② H is closed under vector addition (i.e. $\vec{u}, \vec{v} \in H$ means $\vec{u} + \vec{v} \in H$)
- ③ H is closed under scalar multiplication (i.e. $c \in \mathbb{F}$, $\vec{u} \in H$ then $c\vec{u} \in H$)

Ex

Vector space \mathbb{R}^3
 xy -plane of form $\begin{bmatrix} x \\ y \\ 0 \end{bmatrix}$ is subspace



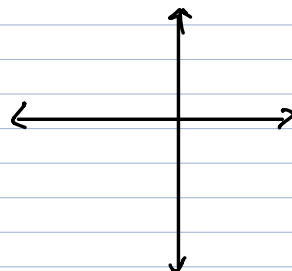
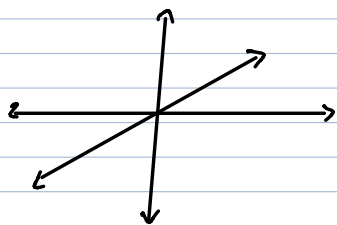
Ex

Polynomials on $[0,1]$ form subspace of $C([0,1])$

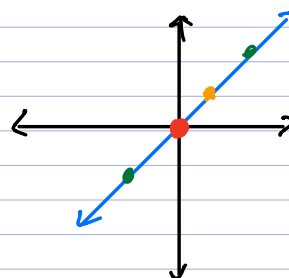
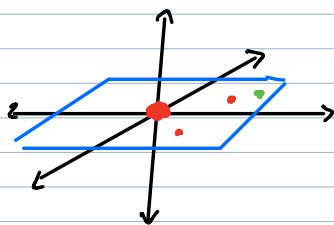
Every vector space has some subspace

- V a vector space. V is a subspace of itself
- V a vector space with zero vector $\vec{0}$.
 $H = \{ \vec{0} \}$ is subspace of V . (Trivial/zero subspace)

Vector spaces may be abstract but may be useful to imagine them having some geometry as \mathbb{R}^n or $C([0,1])$



Have similar ways to picture subspaces



May recall these pictures similar to when we introduced idea of span. Indeed, will see that if $\vec{v}_1, \dots, \vec{v}_k \in V$ then $\text{Span}\{\vec{v}_1, \dots, \vec{v}_k\}$ always subspace of V

Theorem: If $\vec{v}_1, \dots, \vec{v}_k$ are in V then $H = \text{Span}\{\vec{v}_1, \dots, \vec{v}_k\}$ is a subspace of V .

$\vec{y} \in \text{Span}\{\vec{v}_1, \dots, \vec{v}_k\}$

$\vec{y} = a_1 \vec{v}_1 + \dots + a_k \vec{v}_k$

$$\underline{\vec{y}_2} = \underline{b_1 \vec{v}_1 + \dots + b_n \vec{v}_n}$$

$$\vec{y}_1 + \vec{y}_2 \text{ in Span?}$$

$$\underbrace{(a_1 + b_1)}_{\uparrow} \underbrace{\vec{v}_1}_{\uparrow} + \dots + \underbrace{(a_n + b_n)}_{\uparrow} \underbrace{\vec{v}_n}_{\uparrow} \in \text{Span}\{\vec{v}_1, \dots, \vec{v}_n\} = H$$

$$\begin{aligned} c \vec{y}_1 &= c (a_1 \vec{v}_1 + \dots + a_n \vec{v}_n) \\ &= \underline{ca_1} \underline{\vec{v}_1} + \dots + \underline{ca_n} \underline{\vec{v}_n} \\ &\in \text{Span}\{\vec{v}_1, \dots, \vec{v}_n\} = H \end{aligned}$$

$$\text{Is } \vec{0} \in \text{Span}\{\vec{v}_1, \dots, \vec{v}_n\}?$$

$$\underbrace{0\vec{v}_1 + \dots + 0\vec{v}_n}_{\vec{0}} = \vec{0} \in \text{Span}\{\vec{v}_1, \dots, \vec{v}_n\}$$