

Section 1.5

Going to look at solution sets of our linear systems again, get some geometric intuition.

First going to look at a special case that is very important.

Homogeneous Systems

A system of form

$$A\vec{x} = \vec{0}$$

is called homogeneous. Very important.

Note:

$A\vec{x} = \vec{0}$ only has at least one solution. The trivial solution, $\vec{x} = \vec{0}$

$$\begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

$\underbrace{\hspace{10em}}_{m \times n} \quad \underbrace{\hspace{2em}}_{n \times 1} \quad \underbrace{\hspace{2em}}_{m \times 1}$

The bigger question is:

Are there other, **non-trivial** solutions to equation $A\vec{x} = \vec{0}$? Nonzero vector \vec{x} such that $A\vec{x} = \vec{0}$?

Since $A\vec{x} = \vec{0}$ always has one solution, for there to be a non-trivial solution the system must have at least one free-variable.

Ex Describe all solutions to $A\vec{x} = \vec{0}$ where

$$A = \begin{bmatrix} 1 & 3 & -3 & 7 \\ 0 & 1 & -4 & 5 \end{bmatrix} \quad \text{coefficient matrix}$$

$$\left[\begin{array}{cccc|c} 1 & 3 & -3 & 7 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{array} \right]$$

Eq. $A\vec{x} = \vec{0}$ is same as augmented matrix

$$\left[\begin{array}{cccc|c} 1 & 3 & -3 & 7 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{array} \right]$$

No matter what row operation we use, last row always 0's
It's a bit redundant

$$\left[\begin{array}{cccc} 1 & 3 & -3 & 7 \\ 0 & 1 & -4 & 5 \end{array} \right] \sim \left[\begin{array}{cccc} 1 & 0 & 9 & -8 \\ 0 & 1 & -4 & 5 \end{array} \right]$$

$$\begin{cases} x_1 = -9x_3 + 8x_4 \\ x_2 = 4x_3 - 5x_4 \\ x_3 \text{ free} \\ x_4 \text{ free} \end{cases}$$

$$\begin{bmatrix} -9x_3 \\ 4x_3 \\ x_3 \\ 0 \end{bmatrix} + \begin{bmatrix} 8x_4 \\ -5x_4 \\ 0 \\ 1 \end{bmatrix}$$

$$x_3 \begin{bmatrix} -9 \\ 4 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 8 \\ -5 \\ 0 \\ 1 \end{bmatrix} \quad \star$$

Notice that vector of constants we normally have is always $\begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$ for equation $A\vec{x} = \vec{0}$.
So don't bother writing it.

What does $x_3 \begin{bmatrix} -9 \\ 4 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 8 \\ -5 \\ 0 \\ 1 \end{bmatrix}$ look like?

Linear combination.

But since x_3, x_4 are free variables they can take values

Notice set $x_3 \begin{bmatrix} -9 \\ 4 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 8 \\ -5 \\ 0 \\ 1 \end{bmatrix}$ for all

values x_3, x_4 is exactly

$$\text{span} \left\{ \begin{bmatrix} -9 \\ 4 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 8 \\ -5 \\ 0 \\ 1 \end{bmatrix} \right\}$$

Set of all solutions to $A\vec{x} = \vec{0}$ is called Null Space of A

Recap

$A\vec{x} = \vec{0}$ always has trivial solution

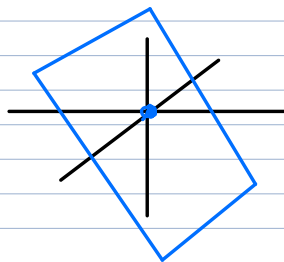
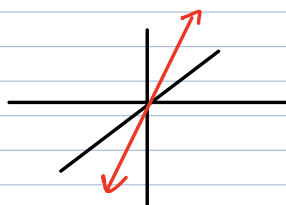
$A\vec{x} = \vec{0}$ has nontrivial solution iff system has free variable

Nontrivial solutions of $A\vec{x} = \vec{0}$ form a span $\{ \dots \}$ (if they exist)

(Later we will say that "Null space is a subspace of \mathbb{R}^n ")

Think about what it means for non-trivial solutions of $A\vec{x} = \vec{0}$ to be span $\{ \vec{v}_1, \dots, \vec{v}_k \}$

Solutions of $A\vec{x} = \vec{0}$ have some nice form passing through origin



Non-Homogeneous Systems

Knowing about solutions to $A\vec{x} = \vec{0}$ gives insight into solutions of $A\vec{x} = \vec{b}$

First recall distributivity of matrix equation
i.e.

$$A(\vec{x} + \vec{y}) = A\vec{x} + A\vec{y} \quad \star$$

Assume \vec{p} is solution to $A\vec{x} = \vec{b}$ ↙

Let \vec{q} be any solution to $A\vec{y} = \vec{0}$ ↘

Consider $A(\vec{p} + \vec{q})$

$$\begin{aligned} A(\vec{p} + \vec{q}) &= A(\vec{p}) + A(\vec{q}) \\ &\begin{array}{c} \text{b.c. } \vec{p} \text{ is sol. to } A\vec{x} = \vec{b} \\ \uparrow \end{array} \quad \begin{array}{c} \text{b.c. } \vec{q} \text{ is sol. to } A\vec{y} = \vec{0} \\ \downarrow \end{array} \\ &= \vec{b} + \vec{0} \\ &= \vec{b} \end{aligned}$$

$A\vec{x} = \vec{b}$

So if we have solution to non-hom. system
and add sol. of hom. sys., still get \vec{b} .

$$A\vec{x} = \vec{0}$$

Theorem Suppose $A\vec{x} = \vec{b}$ is consistent for some \vec{b} and let \vec{p} be a particular solution.
Then the solution set of $A\vec{x} = \vec{b}$ is

set of all vectors of form $\vec{w} = \vec{p} + \vec{v}$, where \vec{v} is any solution of $A\vec{x} = \vec{0}$.

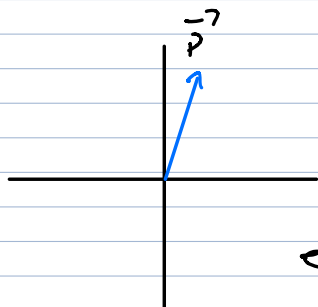
Geometric Viewpoint

Consider $A\vec{x} = \vec{0}$



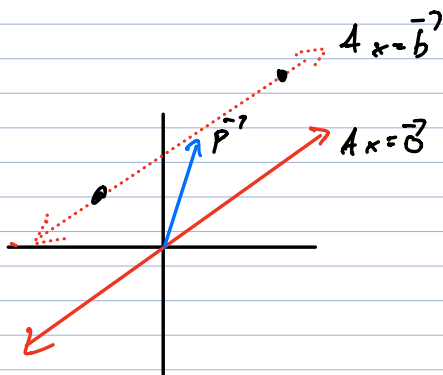
If there are nontrivial solutions to $A\vec{x} = \vec{0}$, they are of form $\text{span}\{\vec{v}_1, \dots, \vec{v}_k\}$

Consider $A\vec{x} = \vec{b}$ ★



Assume we managed to find one particular solution \vec{p}

every sol _{$A\vec{x} = \vec{b}$} = $\vec{p} + \text{Null space}$



vectors of form $\vec{p} + \vec{v}$
(for \vec{v} solution to $A\vec{x} = \vec{0}$)
would be on dotted line
This dotted line is
solution set $A\vec{x} = \vec{b}$

$$A\vec{x} = \vec{b}$$

Find
Null + space

Find one solution

Know all solutions to $A\vec{x} = \vec{b}$