

Let  $\varphi: \mathbb{H} \rightarrow \mathbb{R}$  be of class  $C^1$ . With  $x_0 \in \mathbb{H}$  given, suppose we have a way to solve the ODE  $\begin{cases} x(t) = x_0 \\ \dot{x}(t) = -\nabla \varphi(x(t)) \end{cases}$ ? Then:  $\frac{d}{dt} \varphi(x(t)) = \nabla \varphi(x(t)) \cdot \dot{x}(t) = -|\nabla \varphi(x(t))|^2 \leq 0$ , so

- $\varphi$  decreases along  $x(\cdot)$
- $\frac{d}{dt} \varphi(x(t)) = 0$  holds iff the motion is at a critical point of  $\varphi$ .

In particular, if  $\varphi$  has a unique stationary point which is also a global minimizer, then one expects  $x(\cdot)$  to converge to it.

How DOES ONE CONSTRUCT A SOLUTION? Well, one can appeal to the familiar PICARD-LINDELÖF iterations, which require smoothness. A rough-and-ready way is via numerical schemes due to EULER; to wit:

**Explicit:** Find  $x(t+\tau)$  that satisfies  $\frac{x(t+\tau) - x(t)}{\tau} = -\nabla \varphi(x(t))$

**Implicit:** .....  $\frac{x(t+\tau) - x(t)}{\tau} = -\nabla \varphi(x(t+\tau))$ .

We shall stick with the latter: set  $x_0^\tau = x_0$ ; then, given  $k \geq 0$ ,  $x_k^\tau$ , find  $x_{k+1}^\tau$  that satisfies

$$\frac{x_{k+1}^\tau - x_k^\tau}{\tau} = -\nabla \varphi(x_{k+1}^\tau), \text{ or}$$

$$\underbrace{\nabla_x \left( \frac{\|x - x_k^\tau\|^2}{2\tau} + \varphi(x) \right)}_{\psi_k^\tau(x)} \Big|_{x=x_{k+1}^\tau} = \frac{x_{k+1}^\tau - x_k^\tau}{\tau} + \nabla \varphi(x_{k+1}^\tau) = 0; \text{ i.e.,}$$

$x_{k+1}^\tau$  is a critical point of  $\psi_k^\tau(\cdot)$ .

say, global minimizer

Definition: We call a curve  $x: [0, \infty) \rightarrow \mathbb{H}$  "absolutely continuous", if it is differentiable a.e., has locally integrable derivative  $\dot{x}(\cdot)$ , and the fundamental thm. of calculus  $x(t) - x(s) = \int_s^t \dot{x}(u) du$ , sct holds.

- Such a curve  $x(\cdot)$  we call **gradient flow** for the convex, l.s.c.

$\varphi: \mathbb{H} \rightarrow \mathbb{R}$ , with initial point  $x_0 \in \mathbb{H}$ , if:  $x(0) = x_0$

$$\dot{x}(t) \in -\partial \varphi(x(t)), \text{ a.e. } t > 0.$$

- We construct an implicit Euler scheme for this by finding, given  $\tau > 0$  and  $x_k^\tau$ , a minimizer  $x_{k+1}^\tau$  of  $\mathcal{Y}_k^\tau(\cdot)$ . This exists, and is actually unique.

And we set  $x_k^\tau(t) := x_k^\tau$ , for  $(k-1)\tau < t \leq k\tau$ .

Then, we let  $\tau \downarrow 0$  and show the existence of a limit curve  $\dot{x}(\cdot)$ ....

Details in Ambrosio/Gigli.

Remark: Solutions of gradient flows are unique, and stable: if  $x(\cdot), y(\cdot)$  start at  $x_0, y_0$  and  $\varphi \in C^1$  is convex, then

$$\frac{d}{dt} \frac{\|x(t) - y(t)\|^2}{2} = \langle x(t) - y(t), \dot{x}(t) - \dot{y}(t) \rangle = -\langle x(t) - y(t), \nabla \varphi(x(t)) - \nabla \varphi(y(t)) \rangle \leq 0.$$

And if  $x_0, y_0$  are close, then  $x(\cdot), y(\cdot)$  stay close for all times.

Example: If  $\mathbb{H} = L^2(\mathbb{R}^d)$  and  $\varphi(u) \triangleq \frac{1}{2} \int_{\mathbb{R}^d} |\nabla u(x)|^2 dx$  for  $u \in W^{1,2}(\mathbb{R}^d)$

(and  $\varphi(u) = +\infty$  otherwise), then

$$\partial \varphi(u) \neq \emptyset \Leftrightarrow \Delta u \in L^2(\mathbb{R}^d)$$

and in this case  $\partial \varphi(u) = \{-\Delta u\}$ , and then the gradient flow of  $\varphi$  with respect to the  $L^2$ -scalar product is the heat equation: i.e.,

$$\frac{\partial u(t)}{\partial t} \in -\partial \varphi(u(t)) \Leftrightarrow \frac{\partial}{\partial t} u(t, x) = \Delta u(t, x).$$

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In words: The Heat Equation is the  $L^2$ -gradient flow of the Dirichlet Energy Functional

$$\varphi(u) = \frac{1}{2} \int_{\mathbb{R}^d} |\nabla u(x)|^2 dx ;$$

and can be solved by the implicit

EULER Scheme

$$u_{k+1}^\tau \text{ is the minimizer in } L^2 \text{ of } u \mapsto \frac{\|u - u_k^\tau\|_{L^2(\mathbb{R}^d)}^2}{2\tau} + \varphi(u)$$

and then sending  $\tau \downarrow 0$ .

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JORDAN-KINDERLEHRER OTTO (1998): The Heat Equation is the Quadratic-Wasserstein-Distance flow of the Entropy  $\int p \log(p)$ , and can be solved by the implicit EULER Scheme

$$p_{k+1}^\tau \text{ is the minimizer in } \mathcal{P}(\mathbb{R}^d) \text{ of } p \mapsto \frac{W_2^2(p, p_k^\tau)}{2\tau} + \int_{\mathbb{R}^d} p \log p$$

and then sending  $\tau \downarrow 0$ .