

CSC 212: Data Structures and Abstractions

Binary Search Trees

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Quick notes

- Final Project (about 5 weeks)
 - ✓ requires planning and long coding hours
 - ✓ there is a lot to learn
- Team Work
 - ✓ motivate each other
 - ✓ all team members must understand the topic and code
 - a presentation to the class will follow by the end of the semester
- Info Session (optional)
 - ✓ tomorrow during lab hours

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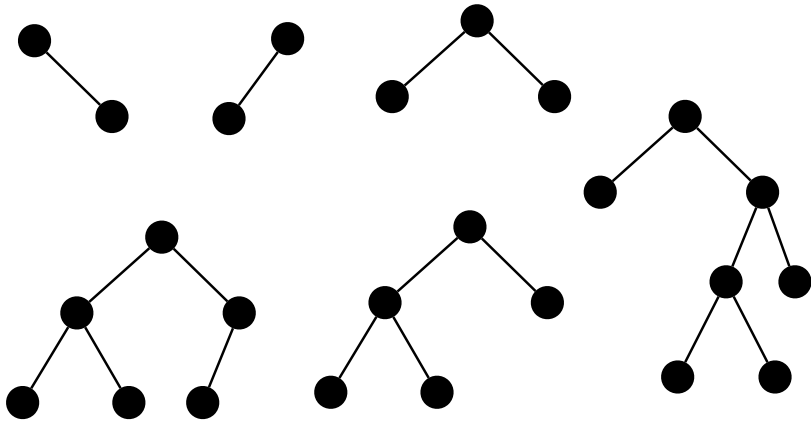
k-ary Trees

k-ary Trees

- In a **k-ary tree**, every node has between 0 and k children
- In a **full (proper)** k-ary tree, every node has exactly 0 or k children
- In a **complete** k-ary tree, every level is entirely filled, except possibly the deepest, where all nodes are as far left as possible
- In a **perfect** k-ary tree, every leaf has the same depth and the tree is full

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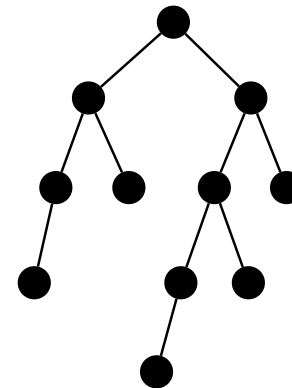
Quiz (k = 2)



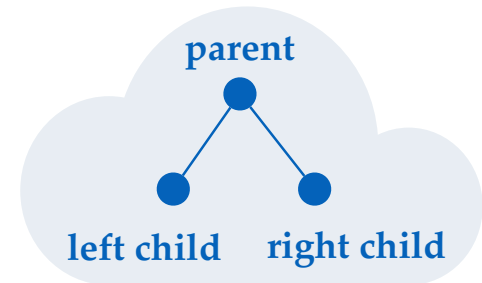
Full? Complete? Perfect?

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Binary Tree



A k-ary tree where **k** = 2

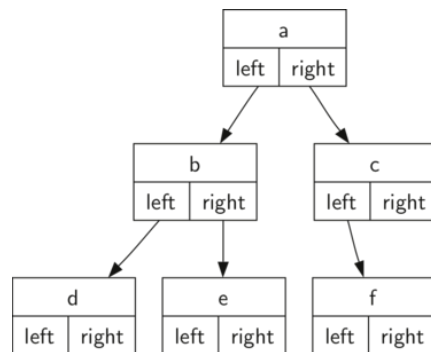


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How to implement binary trees?

Node:

data
left child
right child



<http://interactivepython.org/courselib/static/pythonds/Trees/NodesandReferences.html>

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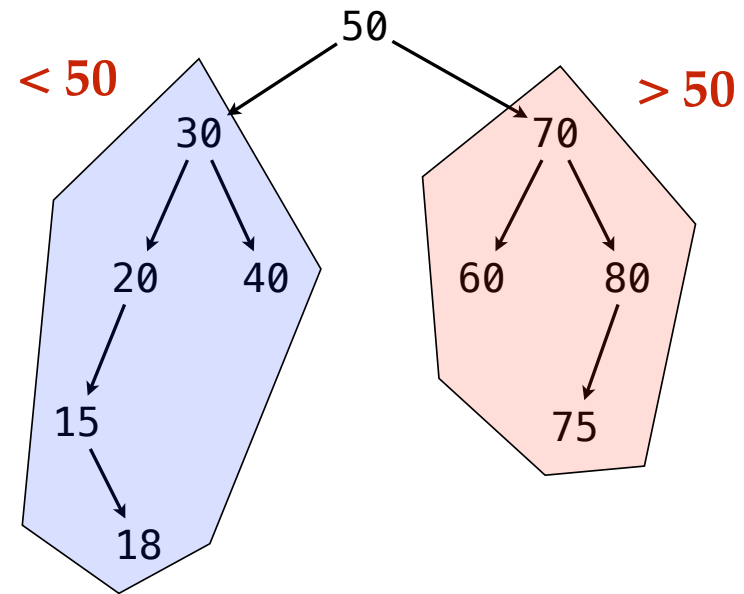
Binary Search Trees

Binary Search Tree

- A BST is a **binary tree**
- A BST has **symmetric order**
 - ✓ each node x in a BST has a key $\text{key}(x)$
 - ✓ for all nodes y in the left subtree of x , $\text{key}(y) < \text{key}(x)$ **
 - ✓ for all nodes y in the right subtree of x , $\text{key}(y) > \text{key}(x)$ **

(**) assume that the keys of a BST are pairwise distinct

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```
class BSTNode {  
  
    private:  
        int data;  
        BSTNode *left;  
        BSTNode *right;  
  
    public:  
        BSTNode(int d);  
        ~BSTNode();  
  
    friend class BSTree;  
};
```

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```
class BSTree {  
  
    private:  
        BSTNode *root;  
        void destroy(BSTNode *p);  
  
    public:  
        BSTree();  
        ~BSTree();  
  
        void insert(int d);  
        void remove(int d);  
        BSTNode *search(int d);  
  
};
```

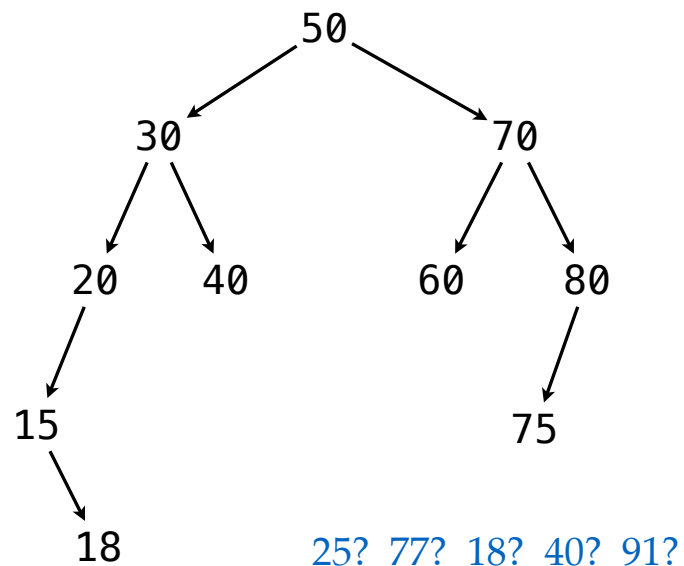
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Search into BSTs

Search

- Start at root node
- If the search key matches the current node's key then **found**
- If search key is greater than current node's key
 - ↙ search on right child
- If search key is less than current node's
 - ↘ search on left child
- Stop when current node is NULL (**not found**)

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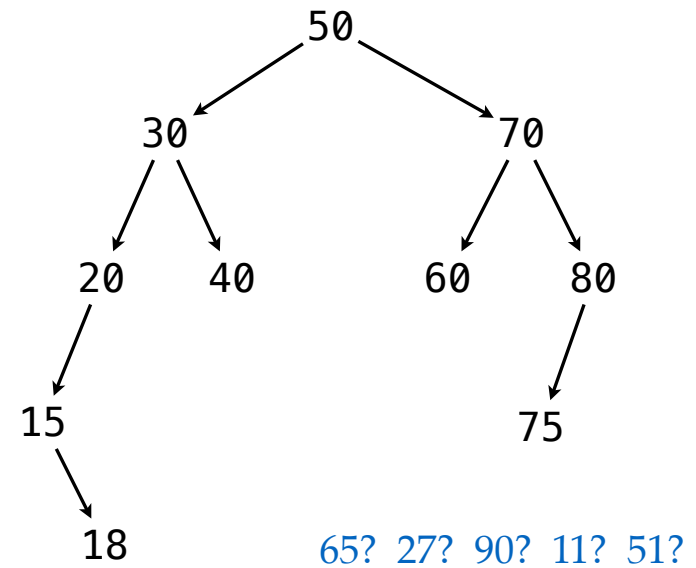
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Insert into BSTs

Insert

- Perform a Search operation
- If **found**, no need to insert (may increase counter)
- If **not found**, insert node where Search stopped

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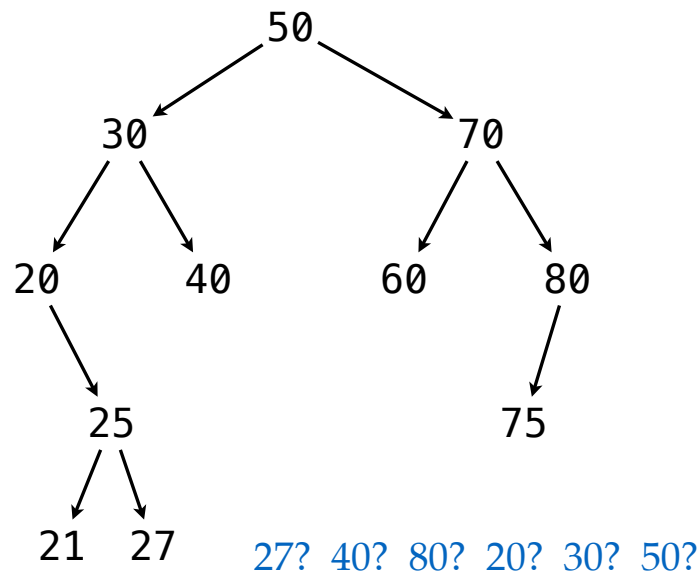
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Remove from BSTs

Remove

- **Case 1: node is a leaf**
 - ✓ trivial, delete node and set parent's pointer to NULL
- **Case 2: node has 1 child**
 - ✓ trivial, set parent's pointer to the only child and delete node
- **Case 3: node has 2 children**
 - ✓ find **successor** can also use predecessor
 - ✓ copy successor's data to node
 - ✓ delete successor

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BST Traversals

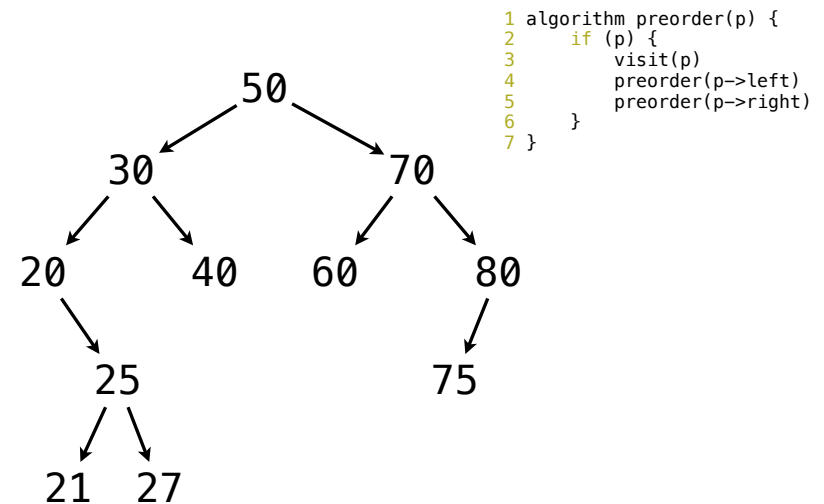
Traversals

- Preorder traversal
- Inorder traversal
- Postorder traversal

$\Theta(n)$

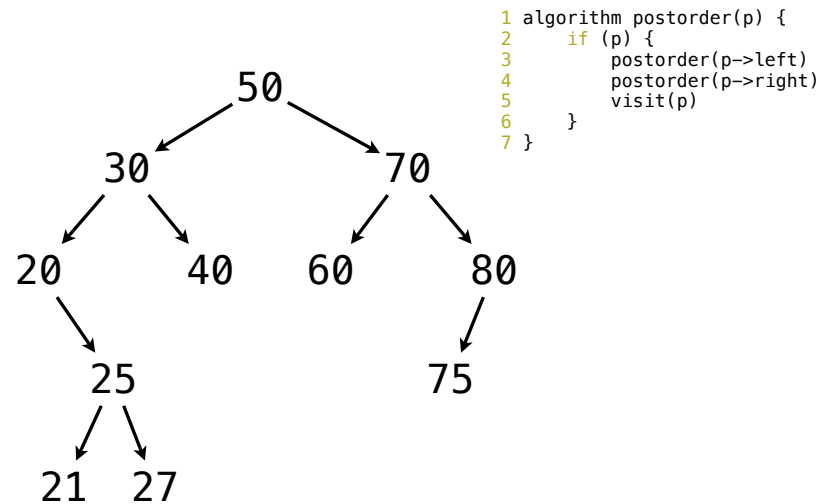
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Preorder traversal?

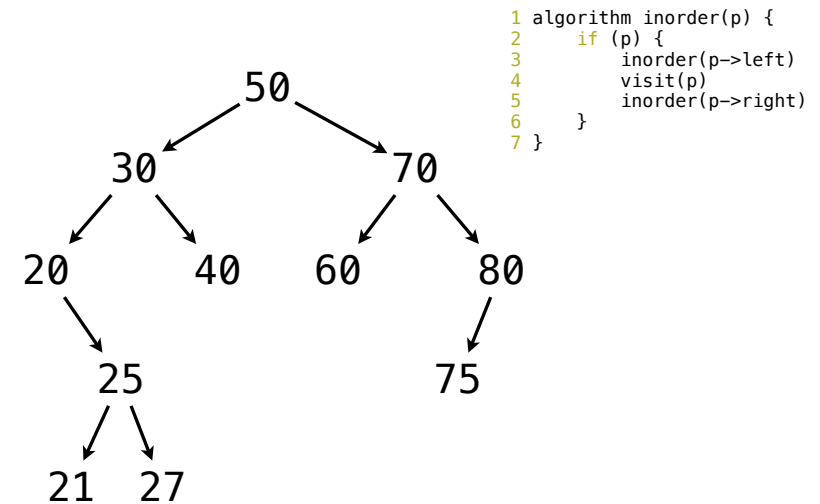


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Postorder traversal?



Inorder traversal?



How to destroy a binary tree?

How to print all elements in increasing order?

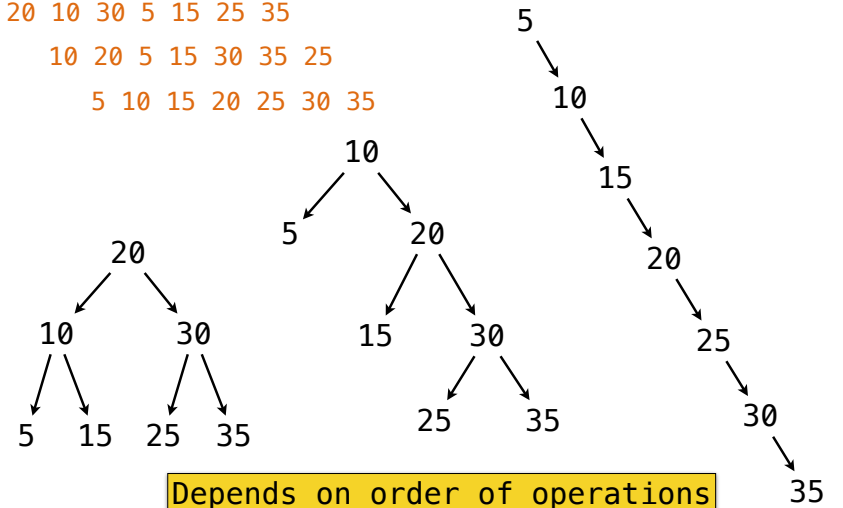
Analysis

Tree Shape?

20 10 30 5 15 25 35

10 20 5 15 30 35 25

5 10 15 20 25 30 35



Depends on order of operations

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Implications

Cost of basic Operations?

- ✓ Search
- ✓ Insert
- ✓ Remove

Worst-case?

Best-case?

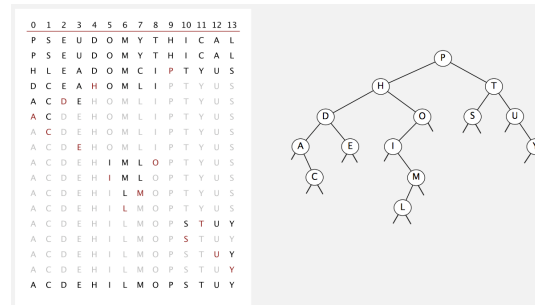
Average-case?

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Average-case analysis

- If **n distinct keys** are inserted into a BST in random order, expected number of compares for basic operations is **$\sim 2 \ln n \approx 1.39 \log n$**

✓ **proof:** 1-1 correspondence with quick-sort partitioning

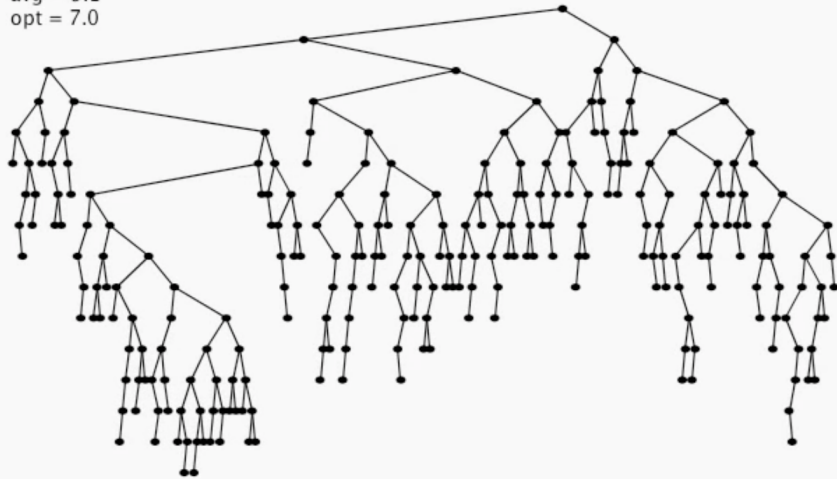


$h = O(\log n)$

<https://algs4.cs.princeton.edu/lectures/32BinarySearchTrees.pdf>

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N = 255
max = 16
avg = 9.1
opt = 7.0



<https://algs4.cs.princeton.edu/lectures/32BinarySearchTrees.pdf>

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Collections/ Dictionaries

	What?	Sequential (unordered)	Sequential (ordered)	BST
search	search for a key	$O(n)$	$O(\log n)$	$O(h)$
insert	insert a key	$O(n)$	$O(n)$	$O(h)$
delete	delete a key	$O(n)$	$O(n)$	$O(h)$
min/max	smallest/largest key	$O(n)$	$O(1)$	$O(h)$
floor/ ceiling	predecessor/ successor	$O(n)$	$O(\log n)$	$O(h)$
rank	number of keys less than key	$O(n)$	$O(\log n)$	$O(h)^{**}$

(**) requires the use of 'size' at every node

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