Evan Shebel

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OBJECTIVE

To obtain a challenging full time position in a high quality engineering environment where my mechanical design, innovative ideas, and ability to learn quickly will make me a valuable employee for the organization.

EDUCATION

University of Maryland, Baltimore County **Baltimore, Md**
Bachelors of Science in Mechanical Engineering ABET *2015*
Bachelors of Science in Mathematics *Expected Dec. 2017*

Certifications/Classes: *Earlbeck Gases and Technologies* 40-hour class on the fundamentals of GMAW, GTAW, SMAW, and oxy-fuel welding.

Parametric Modeling: *Proficient with* SolidWorks and Inventor. *Experience with* Pro/Engineer and ASME Y14.5.
Programming: *Proficient with* Matlab, Python, LabVeiw, Arduino, HTML
Office: *Proficient with* Microsoft Word, Excel, and PowerPoint
Machining: *Basic experience* using manual Mill and Lathe.

WORK AND UNDERGRADUATE/ INDEPENDENT PROJECTS

Sand Helper, LLC **Clarksville, Md**
Contract Mechanical Engineer *2017- Present*

- Participate in the design of electrically powered beach mobility wheelchairs.
- Create fabrication drawings to assist in the production of the beach wheelchairs.
- Seek and establish ways to increase efficiencies in the manufacturing process while reducing waste.

UPS **Burtonsville, Md**
Package Sorter- part time *2016- 2017*

- Manually sorted small-sized packages.
- Assisted on pre-load where packages were sorted before being placed into the trucks for final delivery.

Novel Motorcycle Design for Battery Electric Powertrain **Ellicott City, Md**
Shebel, Evan. 2016. Electric Motorcycle Frame U.S. Patent Application 62/351,276 Filed June 16, 2016

- Designed a motorcycle frame specifically for the constraints of a battery electric vehicle.
- Submitted a provisional utility patent for the design. More information is available in the projects section of my website above.

UAV Prototype **Jessup, Md**
UAV Solutions *2015*

- Worked among a five person team to redesign a quad rotor frame UAV for UAV Solutions. Achieved an increase in portability by having the frame fold to a volume small enough to fit into a police cruiser's trunk.
- Used lightweight materials such as carbon fiber to increase mission time to 30 minutes with a camera payload.
- Utilized management and organizational tools such as a system boundary diagram, system requirements specification, conceptual design review, production schedule, Gantt chart, and bill of materials throughout the design and build phases.

Arduino Controls Project **Baltimore, Md**
2015

- Used an Arduino as a way to compare an open and closed loop control system. The project incorporated a throttle (potentiometer), H-Bridge Stepper Motor Driver, DC brushed motor, planetary gear set, and eccentric mass (magnet).
- The 5V potentiometer was mapped to a motor with an unknown rpm range. The speed of the motor and magnet were determined by sampling data from a fixed hall-effect sensor. The project was run through Lab-View to collect the data.

Hobbies: Drawing, CAD modeling, teaching myself CAM, FEA. Riding/ Racing motorcycles. Trail Running,