

1. (15 points) Give an algebraic proof that a straight line in the world projects onto a straight line in the image. In particular

- (a) Write the parametric equation of a line in three-space.
- (b) Use the simplest form of the perspective projection camera from the start of the Lecture 5 notes to project points on the line into the image coordinate system. This will give you equations for the pixel locations  $x$  and  $y$  in terms of  $t$ . Note that  $t$  will be in the denominator.
- (c) Combine the two equations to remove  $t$  and rearrange the result to show that it is in fact a line. You should get the *implicit form* of the line.
- (d) Finally, under what circumstances is the line a point? Show this algebraically.

$$\begin{aligned} \text{(a)} \quad x(t) &= x_1 t + x_0 \\ y(t) &= y_1 t + y_0 \\ z(t) &= z_1 t + z_0 \end{aligned}$$

$$\begin{aligned} \text{(b)} \quad u &= \frac{fx}{z} = \frac{f(x_1 t + x_0)}{z_1 t + z_0} \\ v &= \frac{fy}{z} = \frac{f(y_1 t + y_0)}{z_1 t + z_0} \end{aligned}$$

$$\text{(c) rearrange equation for } u: t = \frac{fx_0 - uz_0}{uz_1 - fx_1}$$

$$\text{rearrange equation for } v: t = \frac{fy_0 - vz_0}{vz_1 - fy_1}$$

$$\text{set } \frac{fx_0 - uz_0}{uz_1 - fx_1} = \frac{fy_0 - vz_0}{vz_1 - fy_1}$$

we get

$$(y_0 z_1 - y_1 z_0)u - (x_0 z_1 - x_1 z_0)v + f(x_0 y_1 - x_1 y_0) = 0$$

- (d) The line will present as a point on the image when the line goes through the origin of camera coordinate. When this happens:

$$x(t) = 0$$

$$y(t) = 0$$

$$z(t) = z_1 t + z_0$$

For this set of 3D line equation,  $u = \frac{fx}{z} = 0$  and  $v = \frac{fy}{z} = 0$  which means it was projected to the origin as a point