

# Yuyang E. Lou

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[LinkedIn](#) • [GitHub](#) • [Website](#)

## EDUCATION

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University of Washington | Bachelor of Science in Computer Science

Expected Graduation: May 2027

## SKILLS

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**Languages:** Java, Python, C++, SQL, JavaScript, HTML/CSS

**Libraries & Frameworks:** Node.js, React.js, PostgreSQL, NumPy, OpenCV, PyTorch

**Tools & Technologies:** AWS (EC2, Lambda, S3), Kubernetes, Docker, Firebase, Junit, PyTest

## WORK EXPERIENCE

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### Open Source Contributor

Duck DB | Remote

May 2025 – Now

- Debugged [cross-language bindings](#) (C++/Python), strengthening integration between core systems and user APIs.
- Improved [data pipeline reliability](#) by addressing inconsistencies in how missing and special values were handled.
- Enhanced [developer experience](#) by documenting strict API rules, preventing misuse and improving clarity.

### Software Engineering Intern

University of Washington / Traffic Department Project

June – September 2025

- Developed a **deep learning model** for dashcam traffic sign detection, improving accuracy for transportation research.
- Built a **web-based annotation tool** linking detected signs with Google Street View and geospatial data.
- Collaborated with university researchers and the local Department of Transportation to support infrastructure planning.

### Research Assistant

Meta Fundamental AI Research | Seattle, WA

January- June 2025

- With Professor Ruta Desai at Meta FAIR, designed [Pref-LSTM](#), a hybrid memory architecture combining BERT-based preference detection with LSTM-based storage, improving long-horizon preference recall in LLMs.
- Curated and annotated **8.4K+ dialogues**, enabling high-quality evaluation of preference-driven conversational models.
- Achieved **92% accuracy** on custom dataset with BERT-based preference detector.

### Vision Team Member

Advanced Robotics at University of Washington | Seattle, WA

September 2023 – September 2025

- Developed a **real-time object detection system** using YOLOv8, enabling reliable adversarial robot plate recognition.
- Calibrated robot trajectory through signal processing techniques, diminishing noise in robotic path prediction by 45%.
- Built an internal annotation platform (Next.js, Prisma, SWR, PostgreSQL) that streamlined data labeling workflows.

### Software Engineer Intern

Fechii Fragrance & Flavors | Hybrid

May - September 2024

- Used **AWS S3** to store large mass spectrometry collection database and fragrance formula repositories.
- Used **AWS EC2** for fast, consistent data processing pipeline that executes spectra-matching engine written in C++.
- **Migrated visualization tools** from offline software to a web-based platform using React.js and Plotly.js.
- New Software increased the chemical report generation by **66%**, from 120 minutes to 40 minutes.

## PROJECTS

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### No-Deception

- Built a **google extension** that fact-check internet information against scientific articles using RAG with LLMs.
- Maintained a backend vector database using ChromaDB and python that hosts vectorized embeddings of scholar articles.
- Created frontend using react and REST API and deployed them as chromium based browser extensions.

### ScanLite

- Implemented an **Extended Kalman Filter**, fusing 6DOF gyroscope and depth camera to perform 3D pose estimation.
- Performed **Iterative Closest Point (ICP)** algorithm in parallel to handle gyroscope drift and computational delays.
- Built an **interactive visualization interface** using Open3D (and PyQt) to render scanned objects and pose updates in real time