

Chapter 3

Graphs



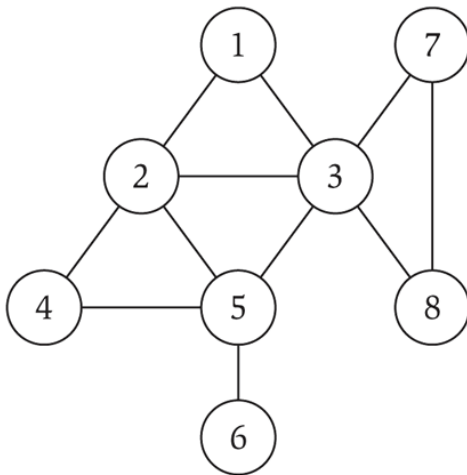
Slides by Kevin Wayne.
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3.1 Basic Definitions and Applications

Undirected Graphs

Undirected graph. $G = (V, E)$

- V = nodes.
- E = edges between pairs of nodes.
- Captures pairwise relationship between objects.
- Graph size parameters: $n = |V|$, $m = |E|$.



$V = \{ 1, 2, 3, 4, 5, 6, 7, 8 \}$

$E = \{ 1-2, 1-3, 2-3, 2-4, 2-5, 3-5, 3-7, 3-8, 4-5, 5-6 \}$

$n = 8$

$m = 11$

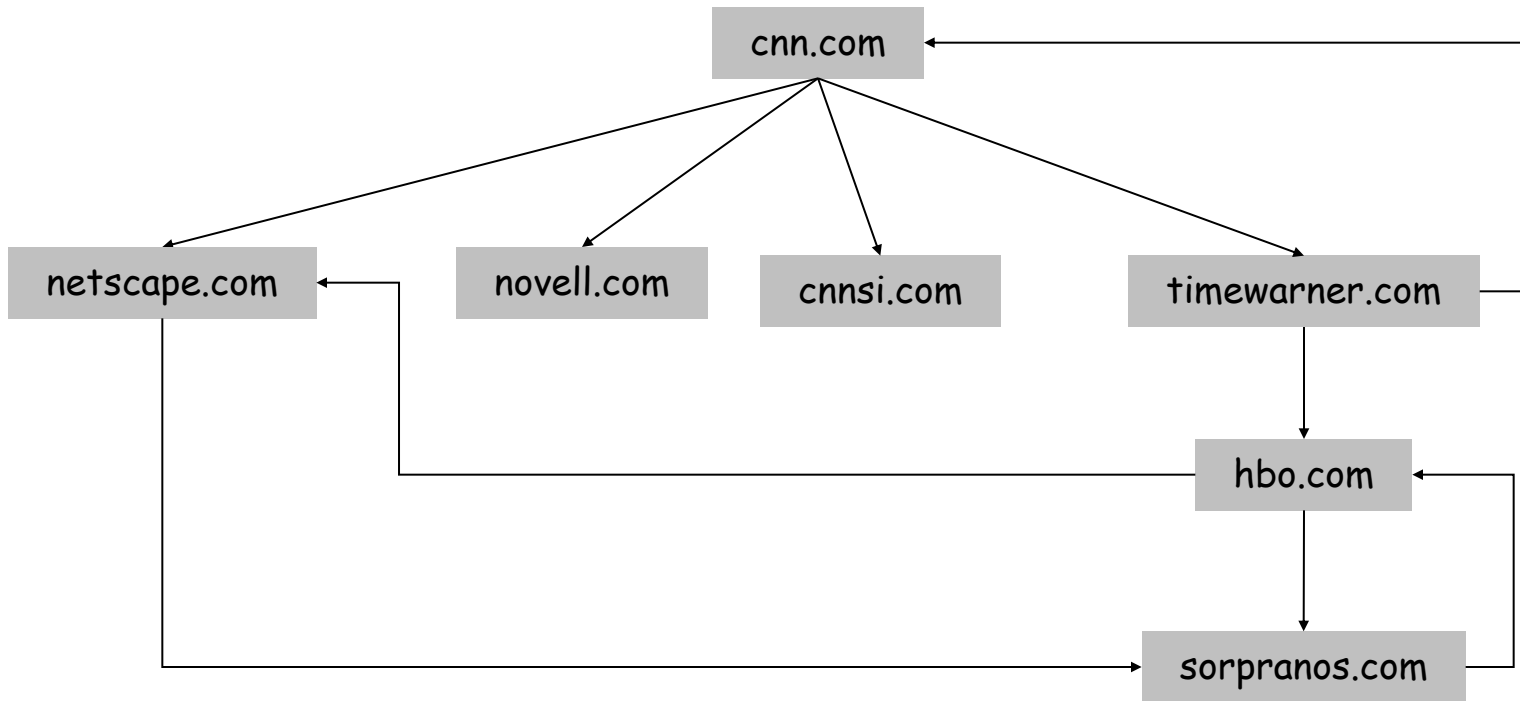
Some Graph Applications

<i>Graph</i>	<i>Nodes</i>	<i>Edges</i>
transportation	street intersections	highways
communication	computers	fiber optic cables
World Wide Web	web pages	hyperlinks
social	people	relationships
food web	species	predator-prey
software systems	functions	function calls
scheduling	tasks	precedence constraints
circuits	gates	wires

World Wide Web

Web graph.

- Node: web page.
- Edge: hyperlink from one page to another.



9-11 Terrorist Network

Social network graph.

- Node: people.
- Edge: relationship between two people.

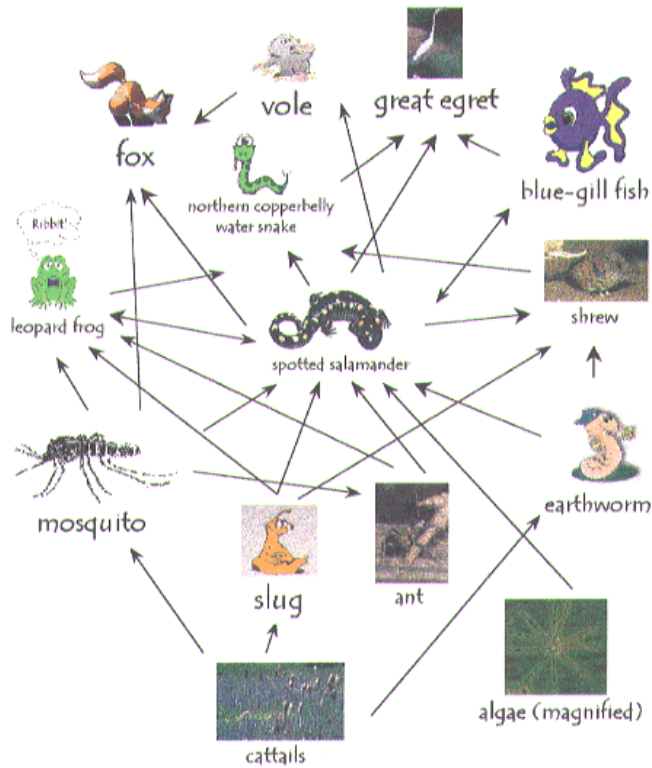


Reference: Valdis Krebs, http://www.firstmonday.org/issues/issue7_4/krebs

Ecological Food Web

Food web graph.

- Node = species.
- Edge = from prey to predator.

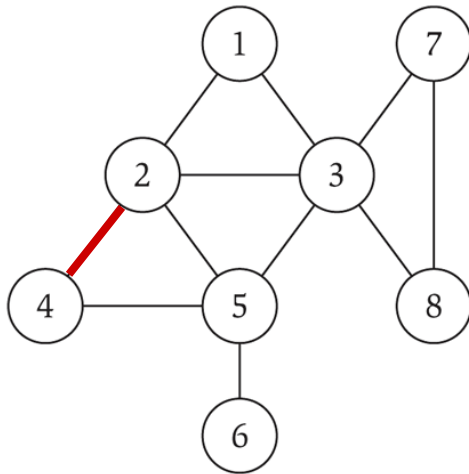


Reference: <http://www.twingroves.district96.k12.il.us/Wetlands/Salamander/SalGraphics/salfoodweb.gif>

Graph Representation: Adjacency Matrix

Adjacency matrix. n -by- n matrix with $A_{uv} = 1$ if (u, v) is an edge.

- Two representations of each edge.
- Space proportional to n^2 .
- Checking if (u, v) is an edge takes $\Theta(1)$ time.
- Identifying all edges takes $\Theta(n^2)$ time.



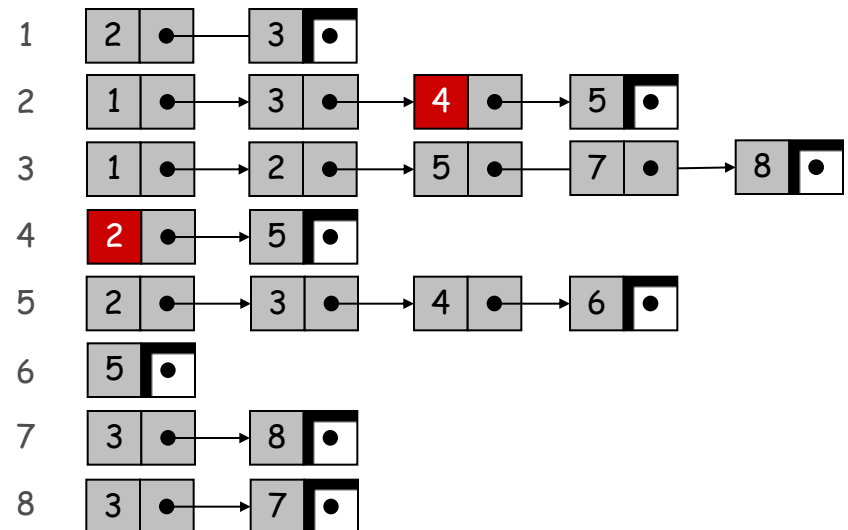
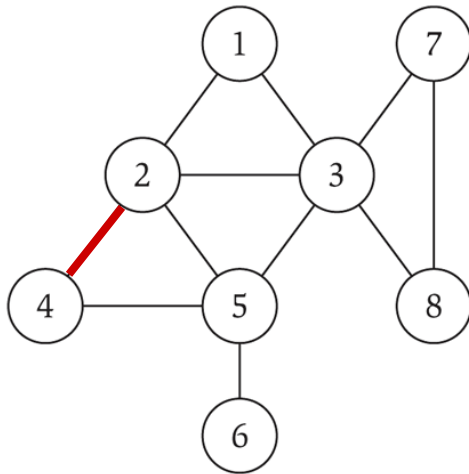
	1	2	3	4	5	6	7	8
1	0	1	1	0	0	0	0	0
2	1	0	1	1	1	0	0	0
3	1	1	0	0	1	0	1	1
4	0	1	0	1	1	0	0	0
5	0	1	1	1	0	1	0	0
6	0	0	0	0	1	0	0	0
7	0	0	1	0	0	0	0	1
8	0	0	1	0	0	0	1	0

Graph Representation: Adjacency List

Adjacency list. Node indexed array of lists.

- Two representations of each edge.
- Space proportional to $m + n$.
- Checking if (u, v) is an edge takes $O(\deg(u))$ time.
- Identifying all edges takes $\Theta(m + n)$ time.

degree = number of neighbors of u

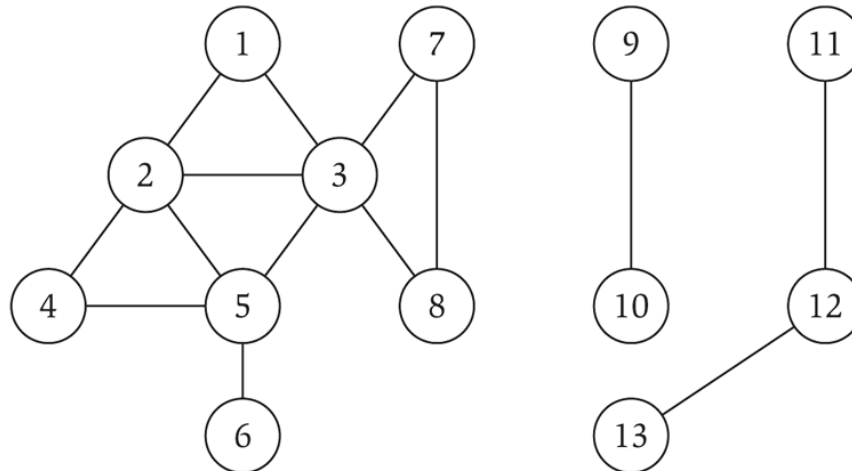


Paths and Connectivity

Def. A **path** in an undirected graph $G = (V, E)$ is a sequence P of nodes $v_1, v_2, \dots, v_{k-1}, v_k$ with the property that each consecutive pair v_i, v_{i+1} is joined by an edge in E .

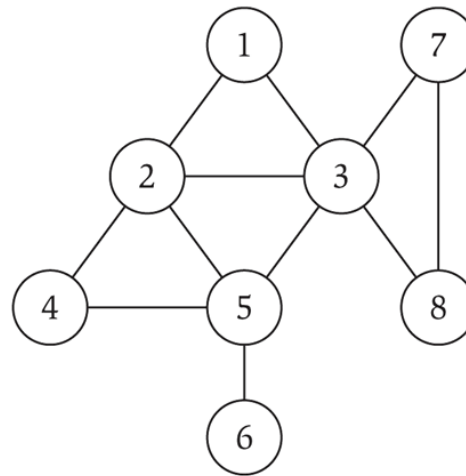
Def. A path is **simple** if all nodes are distinct.

Def. An undirected graph is **connected** if for every pair of nodes u and v , there is a path between u and v .



Cycles

Def. A **cycle** is a path $v_1, v_2, \dots, v_{k-1}, v_k$ in which $v_1 = v_k$, $k > 2$, and the first $k-1$ nodes are all distinct.



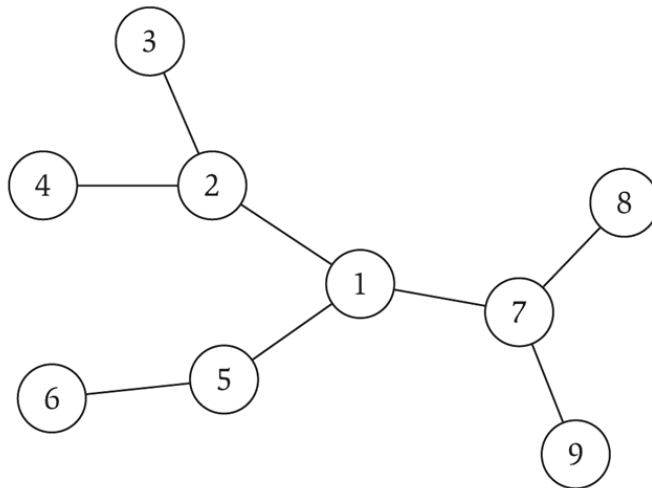
cycle $C = 1-2-4-5-3-1$

Trees

Def. An undirected graph is a **tree** if it is connected and does not contain a cycle.

Theorem. Let G be an undirected graph on n nodes. Any two of the following statements imply the third.

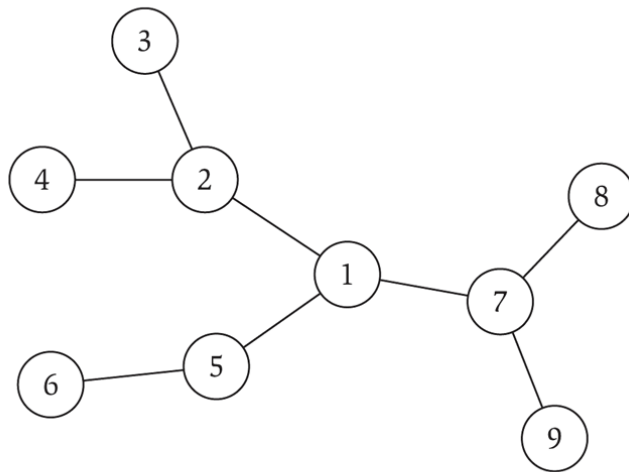
- G is connected.
- G does not contain a cycle.
- G has $n-1$ edges.



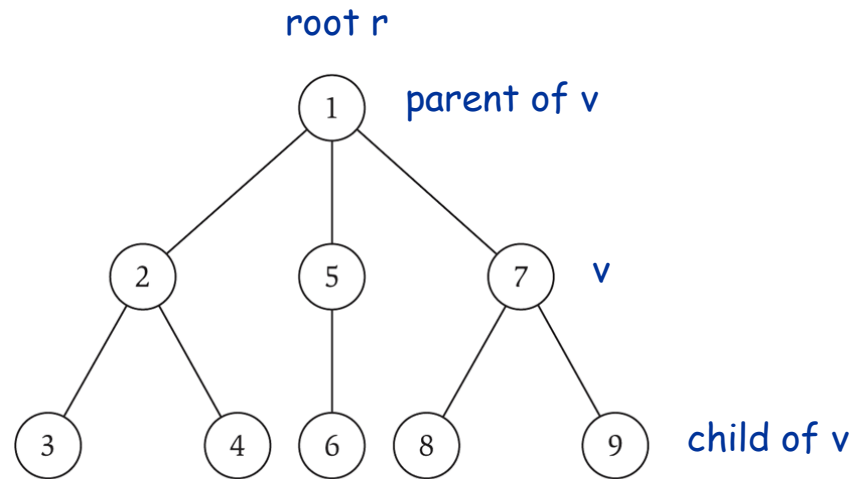
Rooted Trees

Rooted tree. Given a tree T , choose a root node r and orient each edge away from r .

Importance. Models hierarchical structure.



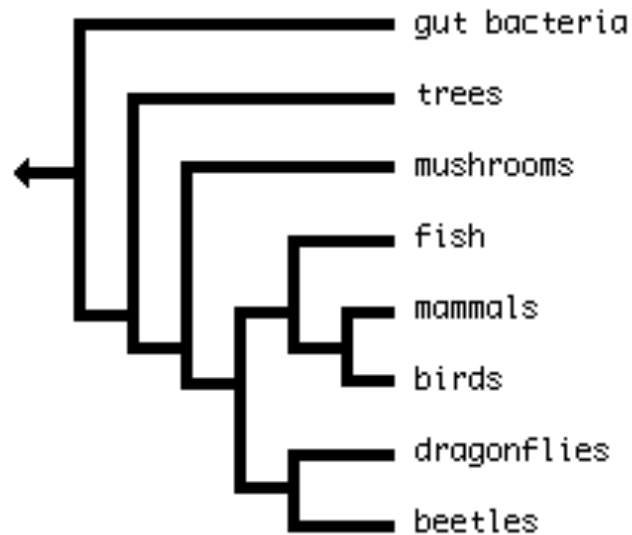
a tree



the same tree, rooted at 1

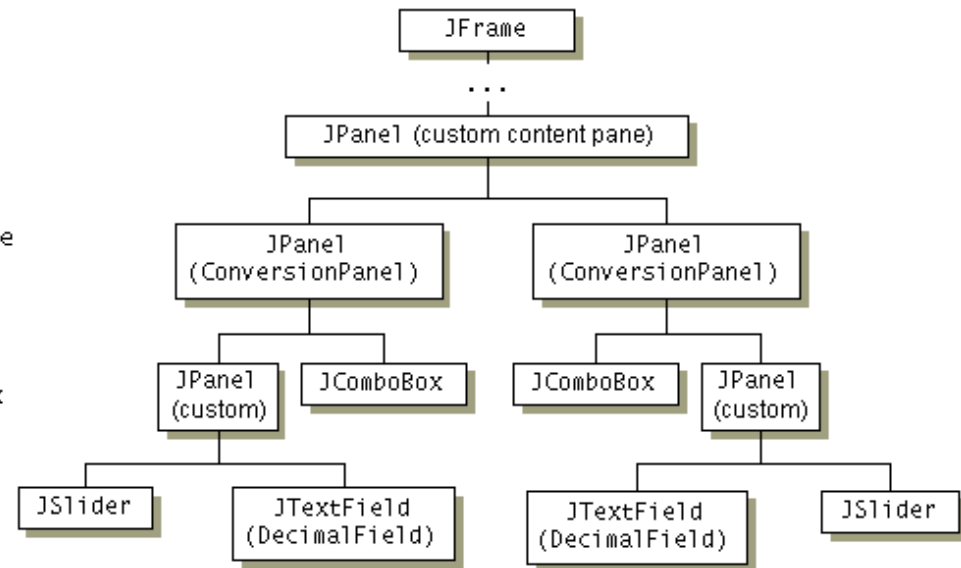
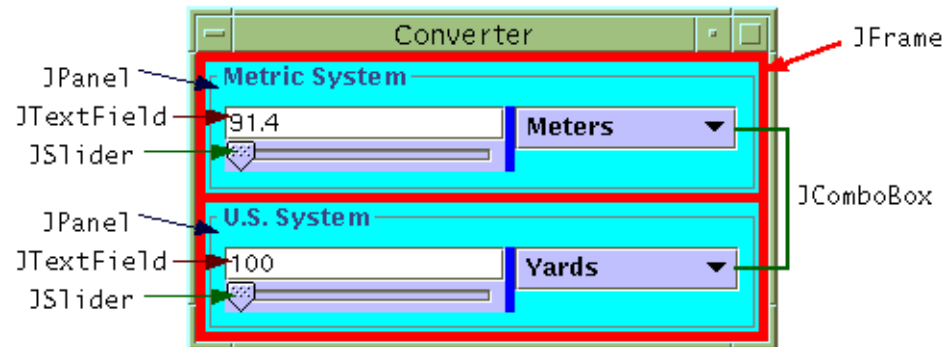
Phylogeny Trees

Phylogeny trees. Describe evolutionary history of species.



GUI Containment Hierarchy

GUI containment hierarchy. Describe organization of GUI widgets.



Reference: <http://java.sun.com/docs/books/tutorial/uiswing/overview/anatomy.html>

3.2 Graph Traversal

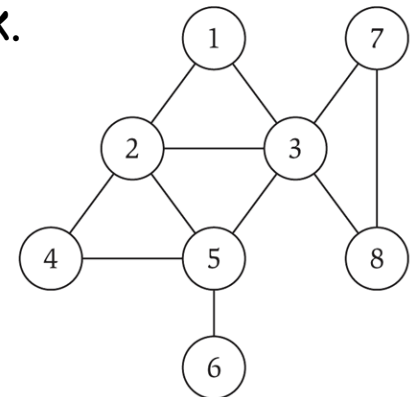
Connectivity

s-t connectivity problem. Given two node s and t, is there a path between s and t?

s-t shortest path problem. Given two node s and t, what is the length of the shortest path between s and t?

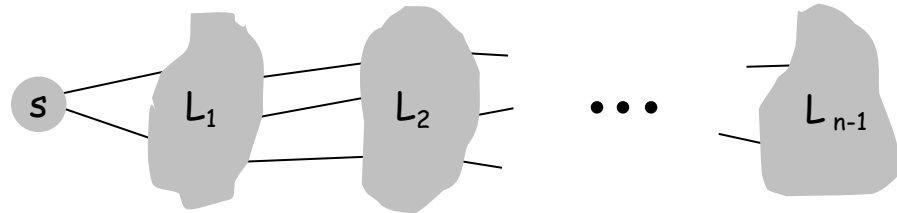
Applications.

- Friendster.
- Maze traversal.
- Kevin Bacon number.
- Fewest number of hops in a communication network.



Breadth First Search

BFS intuition. Explore outward from s in all possible directions, adding nodes one "layer" at a time.



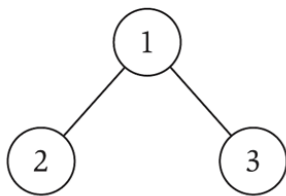
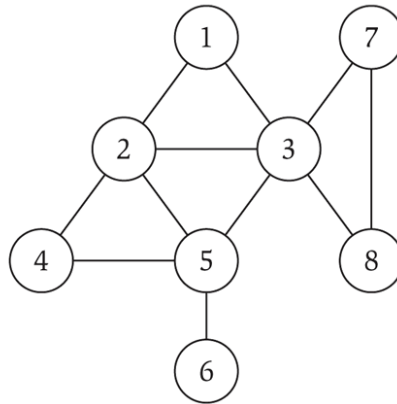
BFS algorithm.

- $L_0 = \{ s \}$.
- L_1 = all neighbors of L_0 .
- L_2 = all nodes that do not belong to L_0 or L_1 , and that have an edge to a node in L_1 .
- L_{i+1} = all nodes that do not belong to an earlier layer, and that have an edge to a node in L_i .

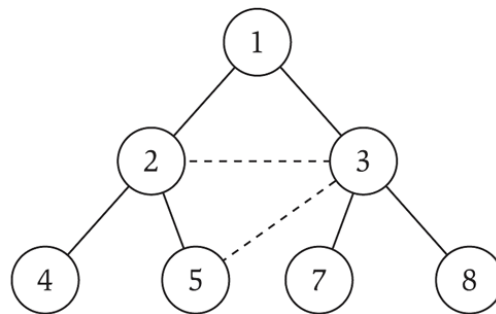
Theorem. For each i , L_i consists of all nodes at distance exactly i from s . There is a path from s to t iff t appears in some layer.

Breadth First Search

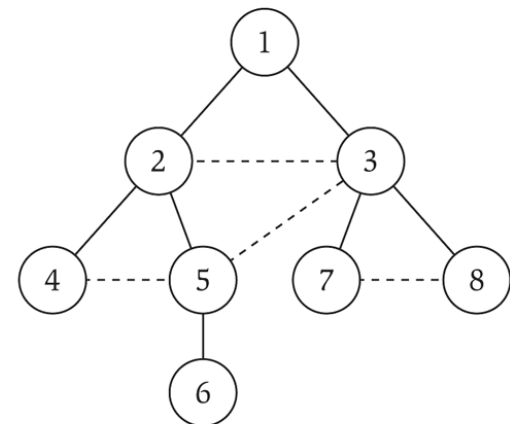
Property. Let T be a BFS tree of $G = (V, E)$, and let (x, y) be an edge of G . Then the level of x and y differ by at most 1.



(a)



(b)



(c)

L_0

L_1

L_2

L_3

Breadth First Search: Analysis

Theorem. The above implementation of BFS runs in $O(m + n)$ time if the graph is given by its adjacency representation.

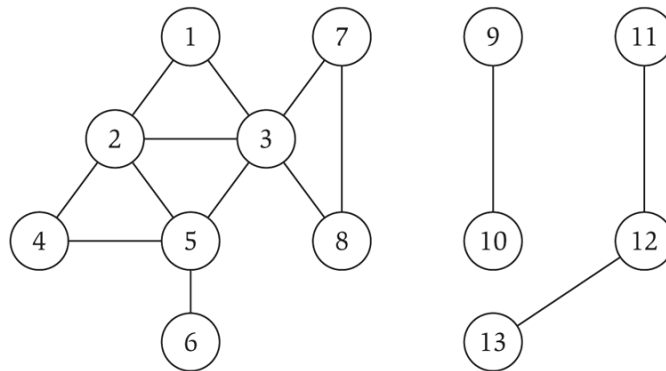
Pf.

- Easy to prove $O(n^2)$ running time:
 - at most n lists $L[i]$
 - each node occurs on at most one list; for loop runs $\leq n$ times
 - when we consider node u , there are $\leq n$ incident edges (u, v) , and we spend $O(1)$ processing each edge
- Actually runs in $O(m + n)$ time:
 - when we consider node u , there are $\deg(u)$ incident edges (u, v)
 - total time processing edges is $\sum_{u \in V} \deg(u) = 2m$ ▪

↑
each edge (u, v) is counted exactly twice
in sum: once in $\deg(u)$ and once in $\deg(v)$

Connected Component

Connected component. Find all nodes reachable from s .



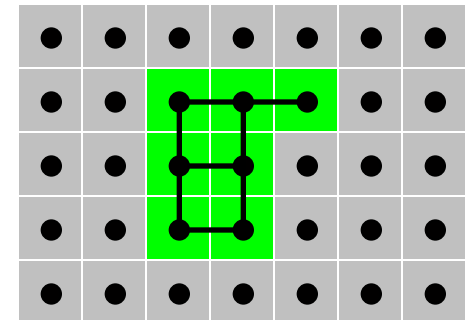
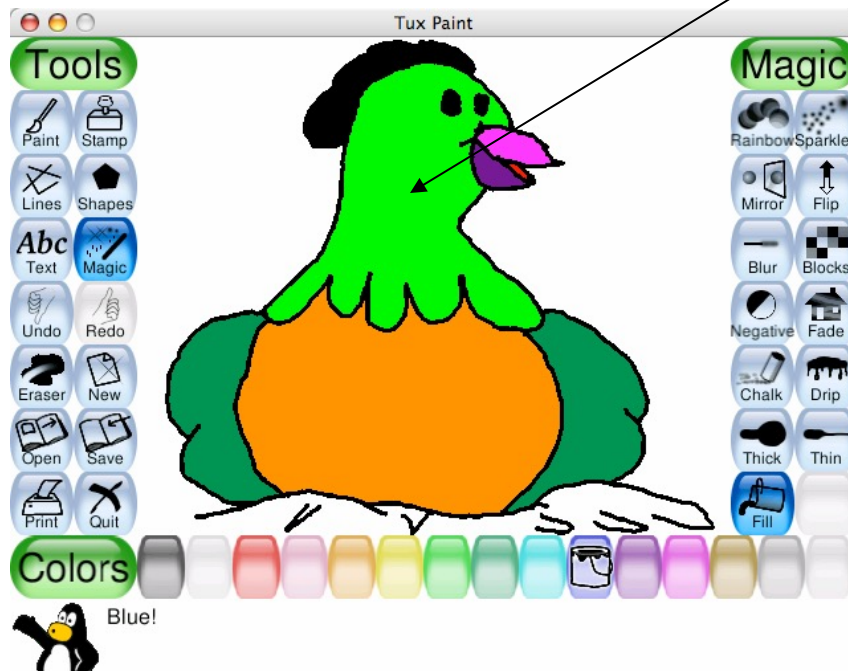
Connected component containing node 1 = $\{ 1, 2, 3, 4, 5, 6, 7, 8 \}$.

Flood Fill

Flood fill. Given lime green pixel in an image, change color of entire blob of neighboring lime pixels to blue.

- Node: pixel.
- Edge: two neighboring lime pixels.
- Blob: connected component of lime pixels.

recolor lime green blob to blue

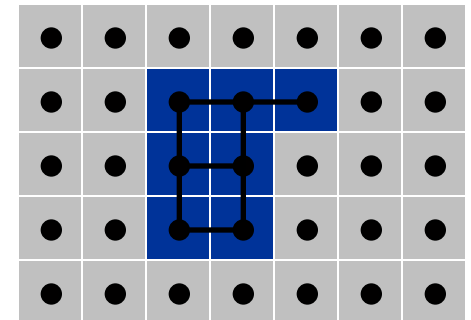


Flood Fill

Flood fill. Given lime green pixel in an image, change color of entire blob of neighboring lime pixels to blue.

- Node: pixel.
- Edge: two neighboring lime pixels.
- Blob: connected component of lime pixels.

recolor lime green blob to blue



Connected Component

Connected component. Find all nodes reachable from s .

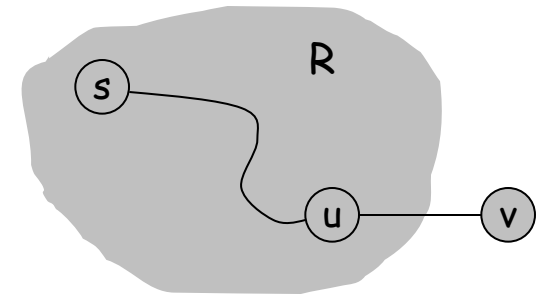
R will consist of nodes to which s has a path

Initially $R = \{s\}$

While there is an edge (u, v) where $u \in R$ and $v \notin R$

 Add v to R

Endwhile



it's safe to add v

Theorem. Upon termination, R is the connected component containing s .

- BFS = explore in order of distance from s .
- DFS = explore in a different way.

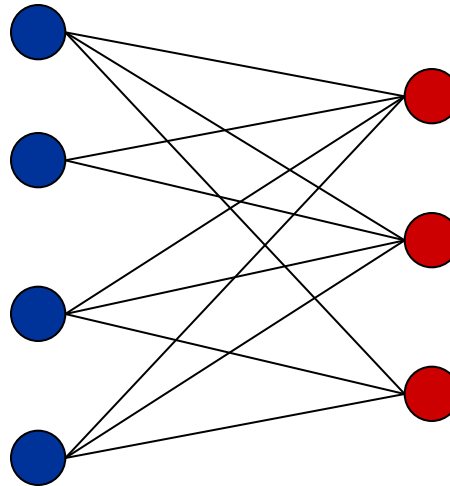
3.4 Testing Bipartiteness

Bipartite Graphs

Def. An undirected graph $G = (V, E)$ is **bipartite** if the nodes can be colored red or blue such that every edge has one red and one blue end.

Applications.

- Stable marriage: men = red, women = blue.
- Scheduling: machines = red, jobs = blue.

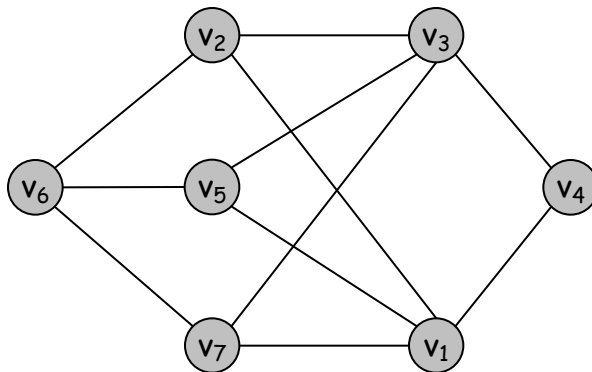


a bipartite graph

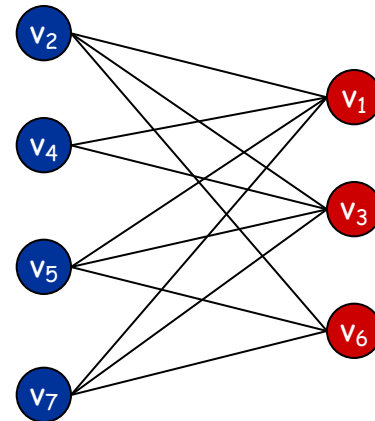
Testing Bipartiteness

Testing bipartiteness. Given a graph G , is it bipartite?

- Many graph problems become:
 - easier if the underlying graph is bipartite (matching)
 - tractable if the underlying graph is bipartite (independent set)
- Before attempting to design an algorithm, we need to understand structure of bipartite graphs.



a bipartite graph G

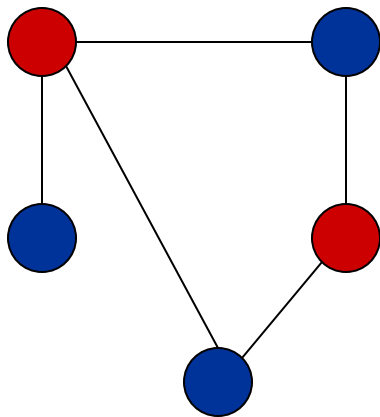


another drawing of G

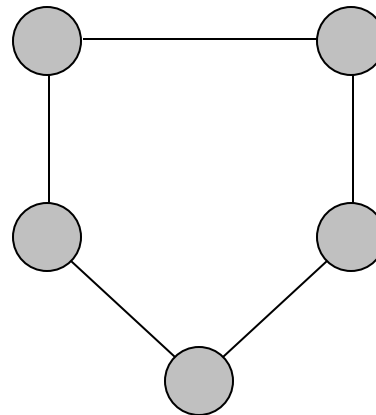
An Obstruction to Bipartiteness

Lemma. If a graph G is bipartite, it cannot contain an odd length cycle.

Pf. Not possible to 2-color the odd cycle, let alone G .



bipartite
(2-colorable)

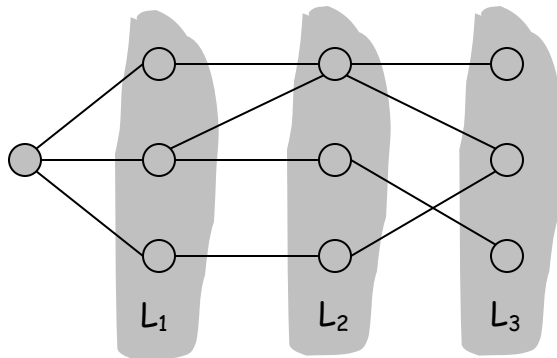


not bipartite
(not 2-colorable)

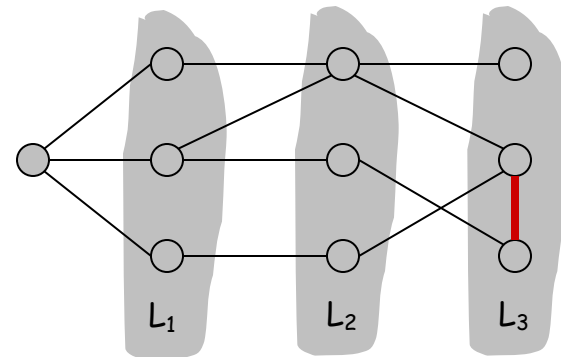
Bipartite Graphs

Lemma. Let G be a connected graph, and let L_0, \dots, L_k be the layers produced by BFS starting at node s . Exactly one of the following holds.

- (i) No edge of G joins two nodes of the same layer, and G is bipartite.
- (ii) An edge of G joins two nodes of the same layer, and G contains an odd-length cycle (and hence is not bipartite).



Case (i)



Case (ii)

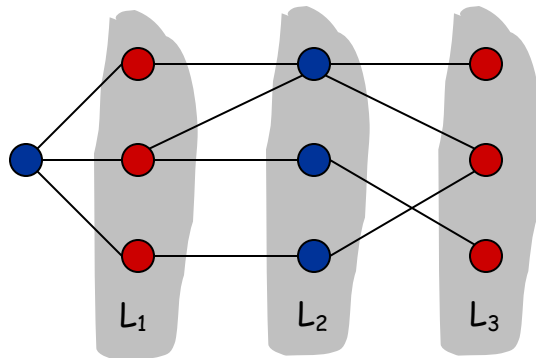
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- (ii) An edge of G joins two nodes of the same layer, and G contains an odd-length cycle (and hence is not bipartite).

Pf. (i)

- Suppose no edge joins two nodes in the same layer.
- By previous lemma, this implies all edges join nodes on same level.
- Bipartition: red = nodes on odd levels, blue = nodes on even levels.



Case (i)

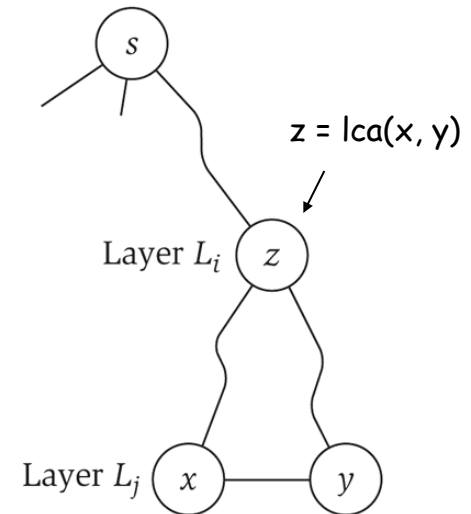
Bipartite Graphs

Lemma. Let G be a connected graph, and let L_0, \dots, L_k be the layers produced by BFS starting at node s . Exactly one of the following holds.

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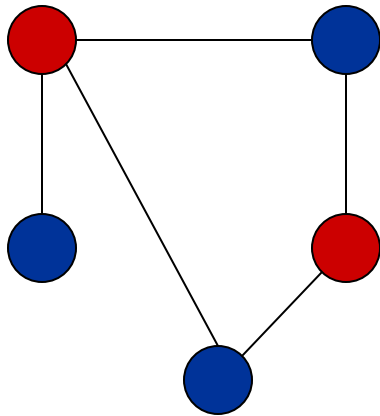
Pf. (ii)

- Suppose (x, y) is an edge with x, y in same level L_j .
- Let $z = \text{lca}(x, y) =$ lowest common ancestor.
- Let L_i be level containing z .
- Consider cycle that takes edge from x to y , then path from y to z , then path from z to x .
- Its length is $1 + \underbrace{(j-i)}_{\text{path from } y \text{ to } z} + \underbrace{(j-i)}_{\text{path from } z \text{ to } x}$, which is odd. ■

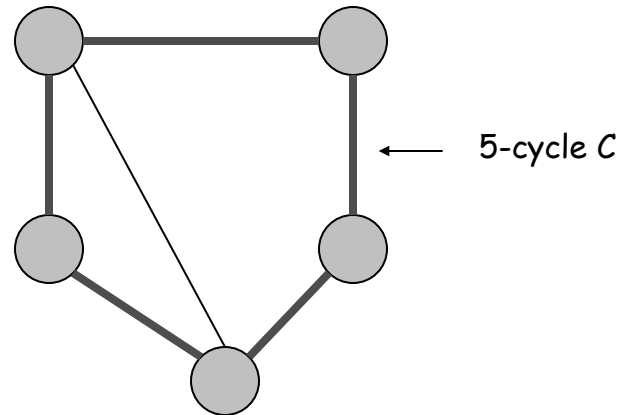


Obstruction to Bipartiteness

Corollary. A graph G is bipartite iff it contains no odd length cycle.



bipartite
(2-colorable)



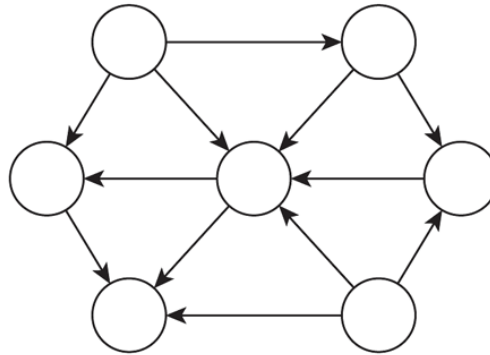
not bipartite
(not 2-colorable)

3.5 Connectivity in Directed Graphs

Directed Graphs

Directed graph. $G = (V, E)$

- Edge (u, v) goes from node u to node v .



Ex. Web graph - hyperlink points from one web page to another.

- Directedness of graph is crucial.
- Modern web search engines exploit hyperlink structure to rank web pages by importance.

Graph Search

Directed reachability. Given a node s , find all nodes reachable from s .

Directed s - t shortest path problem. Given two nodes s and t , what is the length of the shortest path between s and t ?

Graph search. BFS extends naturally to directed graphs.

Web crawler. Start from web page s . Find all web pages linked from s , either directly or indirectly.

Strong Connectivity

Def. Node u and v are **mutually reachable** if there is a path from u to v and also a path from v to u .

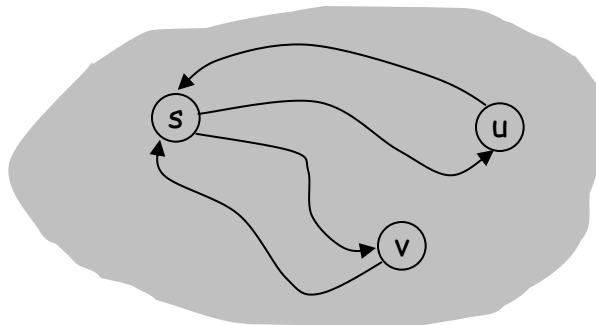
Def. A graph is **strongly connected** if every pair of nodes is mutually reachable.

Lemma. Let s be any node. G is strongly connected iff every node is reachable from s , and s is reachable from every node.

Pf. \Rightarrow Follows from definition.

Pf. \Leftarrow Path from u to v : concatenate u - s path with s - v path.

Path from v to u : concatenate v - s path with s - u path. ■

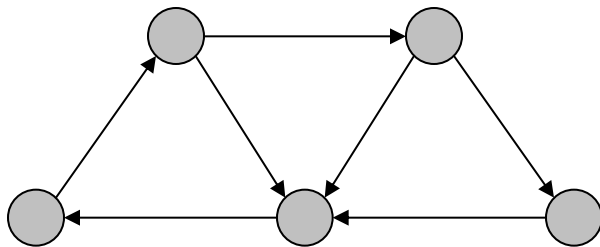


↑
ok if paths overlap

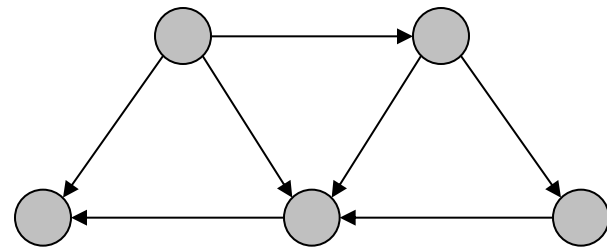
Strong Connectivity: Algorithm

Theorem. Can determine if G is strongly connected in $O(m + n)$ time.
Pf.

- Pick any node s .
- Run BFS from s in G .
- Run BFS from s in G^{rev} . ← reverse orientation of every edge in G
- Return true iff all nodes reached in both BFS executions.
- Correctness follows immediately from previous lemma. ▪



strongly connected



not strongly connected

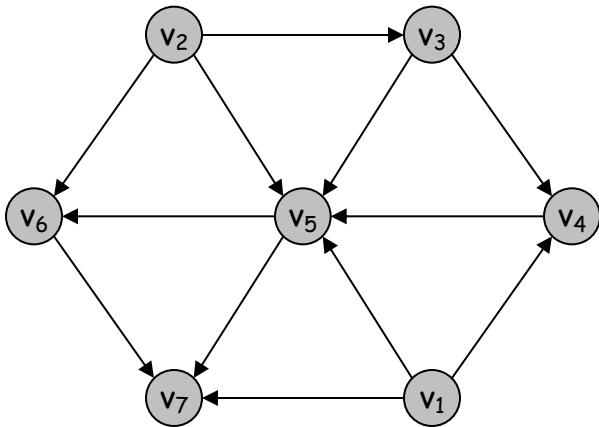
3.6 DAGs and Topological Ordering

Directed Acyclic Graphs

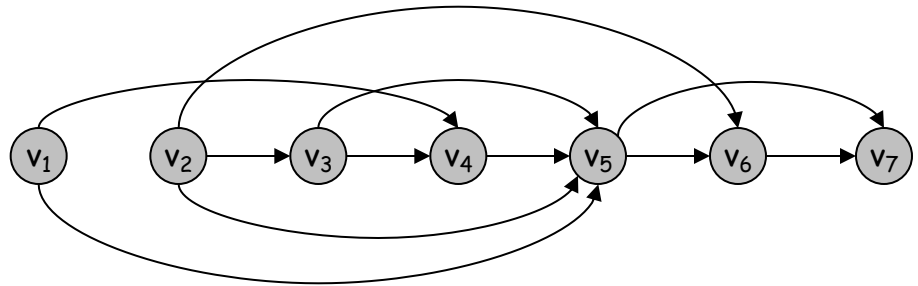
Def. An **DAG** is a directed graph that contains no directed cycles.

Ex. Precedence constraints: edge (v_i, v_j) means v_i must precede v_j .

Def. A **topological order** of a directed graph $G = (V, E)$ is an ordering of its nodes as v_1, v_2, \dots, v_n so that for every edge (v_i, v_j) we have $i < j$.



a DAG



a topological ordering

Precedence Constraints

Precedence constraints. Edge (v_i, v_j) means task v_i must occur before v_j .

Applications.

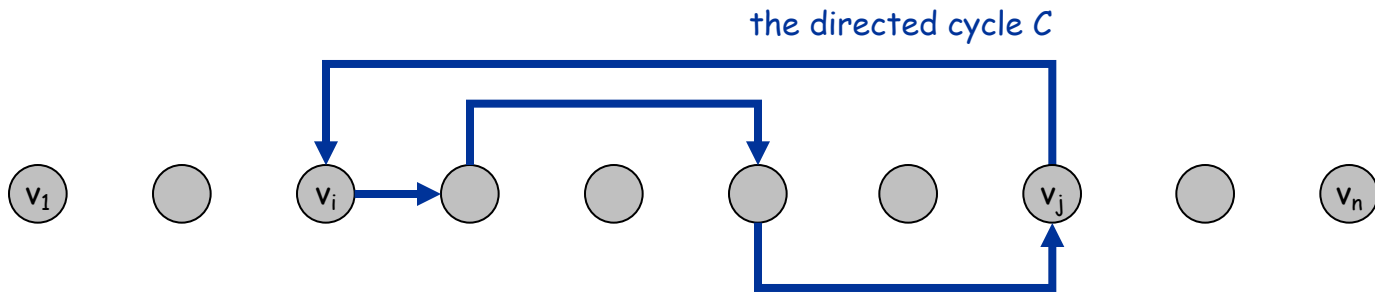
- Course prerequisite graph: course v_i must be taken before v_j .
- Compilation: module v_i must be compiled before v_j . Pipeline of computing jobs: output of job v_i needed to determine input of job v_j .

Directed Acyclic Graphs

Lemma. If G has a topological order, then G is a DAG.

Pf. (by contradiction)

- Suppose that G has a topological order v_1, \dots, v_n and that G also has a directed cycle C . Let's see what happens.
- Let v_i be the lowest-indexed node in C , and let v_j be the node just before v_i ; thus (v_j, v_i) is an edge.
- By our choice of i , we have $i < j$.
- On the other hand, since (v_j, v_i) is an edge and v_1, \dots, v_n is a topological order, we must have $j < i$, a contradiction. ■



Directed Acyclic Graphs

Lemma. If G has a topological order, then G is a DAG.

Q. Does every DAG have a topological ordering?

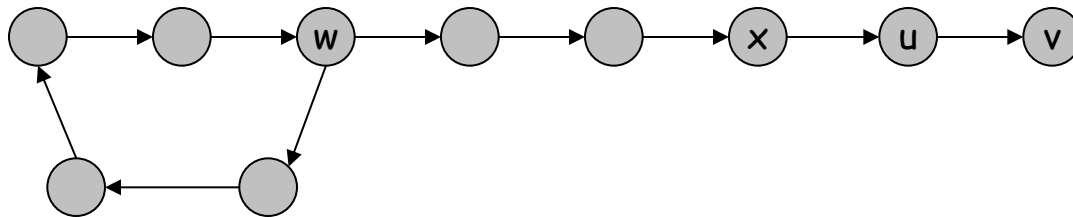
Q. If so, how do we compute one?

Directed Acyclic Graphs

Lemma. If G is a DAG, then G has a node with no incoming edges.

Pf. (by contradiction)

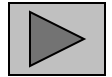
- Suppose that G is a DAG and every node has at least one incoming edge. Let's see what happens.
- Pick any node v , and begin following edges backward from v . Since v has at least one incoming edge (u, v) we can walk backward to u .
- Then, since u has at least one incoming edge (x, u) , we can walk backward to x .
- Repeat until we visit a node, say w , twice.
- Let C denote the sequence of nodes encountered between successive visits to w . C is a cycle. ▪



Directed Acyclic Graphs

Lemma. If G is a DAG, then G has a topological ordering.

Pf. (by induction on n)



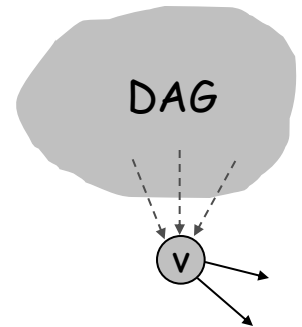
- Base case: true if $n = 1$.
- Given DAG on $n > 1$ nodes, find a node v with no incoming edges.
- $G - \{v\}$ is a DAG, since deleting v cannot create cycles.
- By inductive hypothesis, $G - \{v\}$ has a topological ordering.
- Place v first in topological ordering; then append nodes of $G - \{v\}$
- in topological order. This is valid since v has no incoming edges. ▪

To compute a topological ordering of G :

Find a node v with no incoming edges and order it first

Delete v from G

Recursively compute a topological ordering of $G - \{v\}$
and append this order after v



Topological Sorting Algorithm: Running Time

Theorem. Algorithm finds a topological order in $O(m + n)$ time.

Pf.

- Maintain the following information:
 - `count[w]` = remaining number of incoming edges
 - S = set of remaining nodes with no incoming edges
- Initialization: $O(m + n)$ via single scan through graph.
- Update: to delete v
 - remove v from S
 - decrement `count[w]` for all edges from v to w , and add w to S if `count[w]` hits 0
 - this is $O(1)$ per edge ▪