# OPTIMAL CONTROL FOR MAXIMIZING TWIST ROTATION ON TRAMPOLINE

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## Abstract



A direct multiple-shooting algorithm has been used to maximize twists in trampoline. somersaults positions velocities constrained to feasible movements. Optimization has shown that a large variety of techniques can be used to perform twisting somersaults.

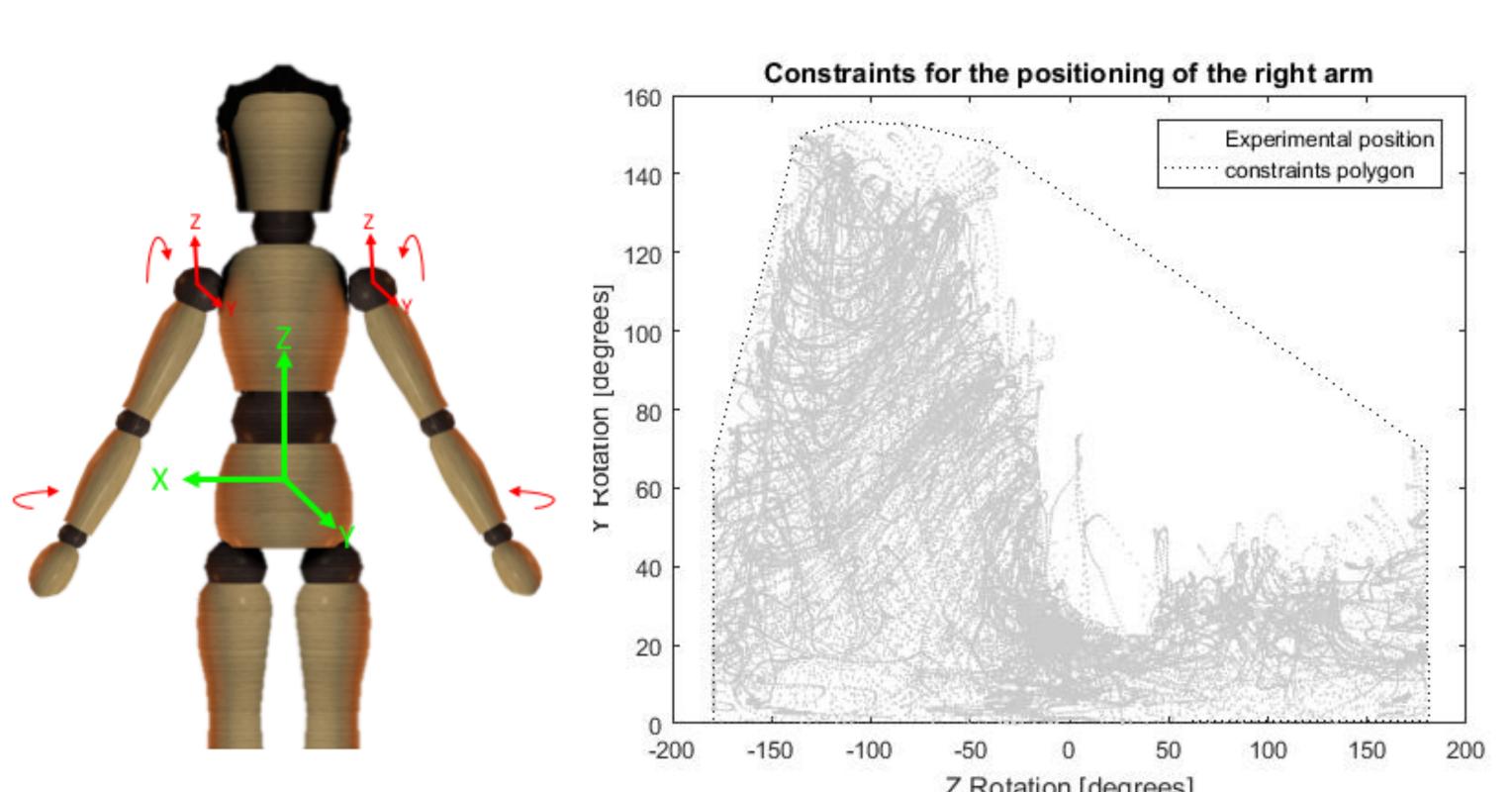
Key words: Optimization, trampoline, twisting somersaults

### Introduction

- Aerial twists in straight position are mainly performed using arm adduction to transfer angular momentum from transversal axis to longitudinal axis [1].
- Until now, optimization of arm movements to maximize the twists has been limited to optimal timing of 2D adduction arm movements [2].
- 3D arm position and velocity have an impact on the twist rotation during a somersault.
- Contact twists have undesirable side-effect, such as height loss. Efficient aerial twisting techniques may permit athletes to perform the same skills with a higher time of flight.
- The computer simulation makes it possible to try an infinity of arm techniques.

Explore complex and anatomically feasible arm movements to generate efficient innovative twisting techniques.

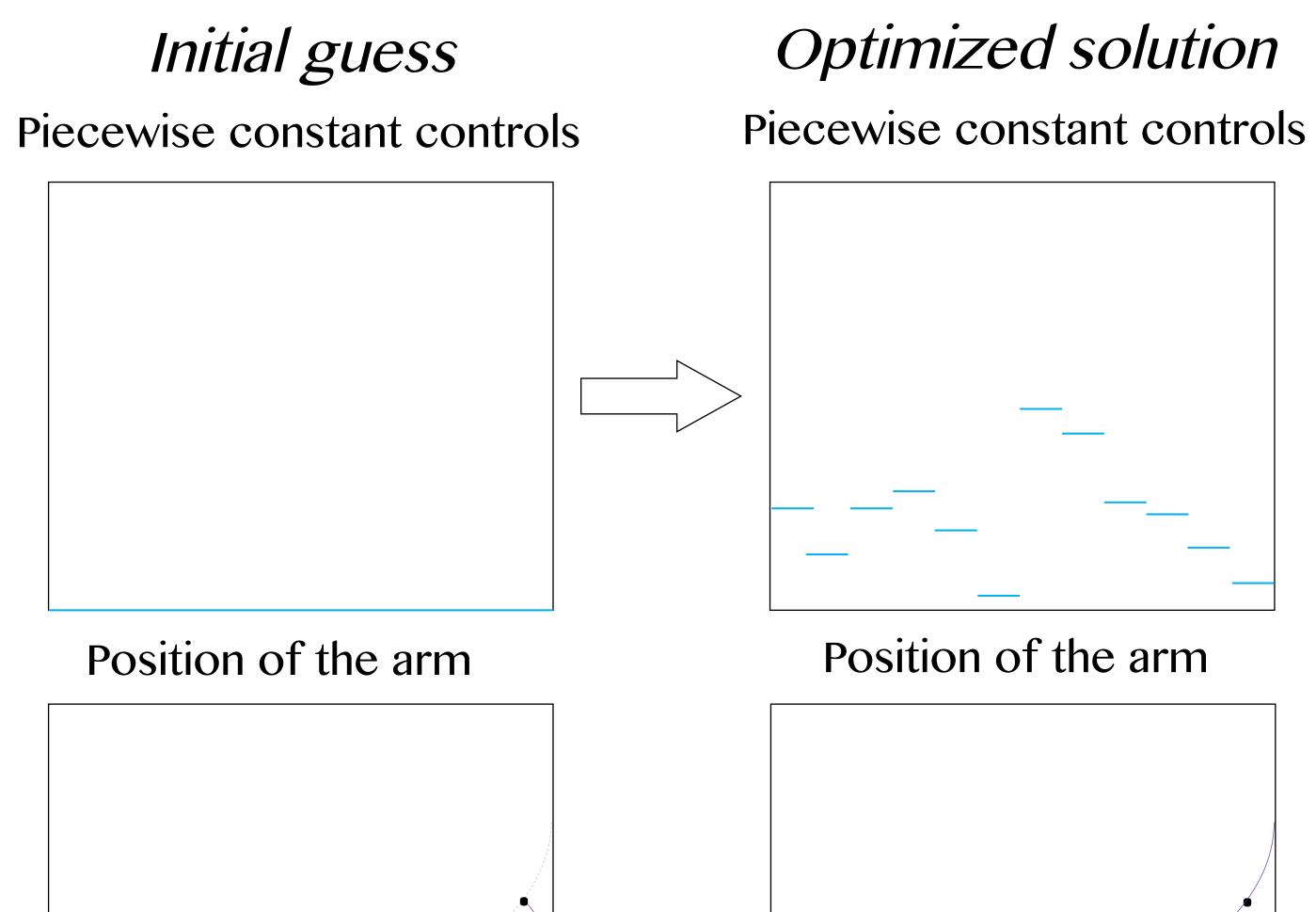
## Method



Accessible arm positions and movements according to the reference frames. Arm and body movements are solution of the differential equation:

$$\tau = M(q)\ddot{q} + N(q,\dot{q}) + G(q)$$

## Schematic of the direct multiple-shooting



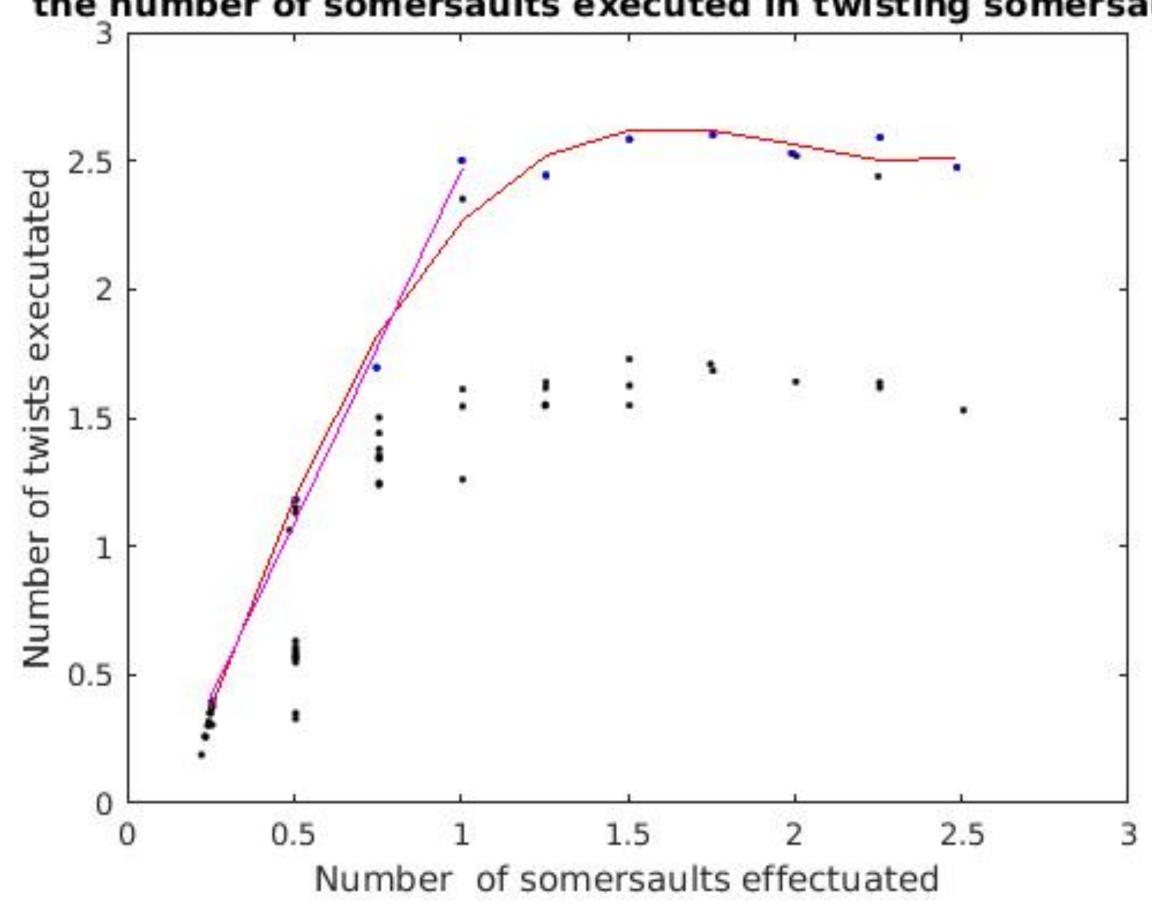
## Results & Discussion



Representation with fixed COM of 1 optimizations that converged out of 320 multi-start conditions.

The arm movements are anatomically feasible, but not necessarily feasible from a motor control point of view because arm movements require different phases.

#### Maximum number of twists effectuated in function of the number of somersaults executed in twisting somersaults



The multi-start approach combined with direct multiple shooting has shown its efficiency concluding that up to 2.5 twists may be performed in 1 somersault using only aerial arm techniques.

#### Future work

Robustness of the technique will be assessed by including noise [3] and we will try to teach the techniques. References

1. Yeadon (1999) Int Symp of Biomech in Sports

- 2. Yeadon et al. (2017) J of Biomech.
- 3. Hiley et al. (2013) Hum Mov Sc.