

¹ EyeIdentify3D: A Python package for gaze behavior classification of mobile eye-tracking data

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⁶ Summary

⁷ With the technological advances of mobile eye-tracking technologies, researchers can now place
⁸ participants in real-world settings (or in virtual environments that simulate the real world) and
⁹ measure their head and eye orientation to get the gaze orientation in 3D space. This raw
¹⁰ gaze orientation is hardly interpretable and must be post-processed to extract gaze behaviours
¹¹ (e.g., fixations, saccades, smooth pursuits, visual scanning). However, most open-source gaze
¹² classification algorithms were developed for screen-based eye-tracking, where data is recorded on
¹³ a 2D plane, and the participant's head is kept still. These algorithms are ill-suited for real-world
¹⁴ mobile eye-tracking data (360°), as the gaze-vector origin and endpoint can move substantially
¹⁵ due to head rotations, a challenge also present in head-mounted display systems used in virtual
¹⁶ reality research. Additionally, eye-tracking researchers often rely on study-specific analysis
¹⁷ pipelines, which leads to methodological discrepancies that impede cross-study comparison and
¹⁸ the interpretation of results, ultimately limiting our understanding of gaze behaviour-related
¹⁹ phenomena. To address this gap, we developed EyeIdentify3D, an automated and modular
²⁰ pipeline for analyzing 360° eye-tracking data.

²¹ Statement of need

²² EyeIdentify3D is a Python package for identifying multiple gaze behaviours (blinks, fixations,
²³ saccades, smooth pursuits, visual scannings) from mobile eye-tracking data. It was designed
²⁴ to:

- ²⁵ 1. Interpret data from various mobile eye-tracking systems (e.g., Pupil Invisible, Tobii),
²⁶ including those embedded in head-mounted displays (e.g., HTC Vive Pro, Pico Neo 3
²⁷ Pro Eye).
- ²⁸ 2. Provide a simple user interface that requires only a few lines of code to identify the
²⁹ desired gaze behaviours and extract related metrics.
- ³⁰ 3. Enable visual inspection of the classification results through figures and animation.

³¹ EyeIdentify3D was designed to be used in science and human performance analysis. Our
³² objective is to distribute the toolbox openly to help researchers more reliably identify and
³³ analyze gaze behaviours in real-world scenarios, which involve movements of the head, and
³⁴ promote standardization in gaze analysis, thereby improving our understanding of visual
³⁵ strategies.

³⁶ State of the field

³⁷ To address the need for automating the identification of gaze behaviours from eye-tracking
³⁸ data, a few open-source packages have been developed over the years. Most of the packages

39 have focused primarily on the identification of fixations, either from fixed-screen eye-tracker
 40 data ([Krassanakis et al., 2014](#)) or mobile eye-tracker data Munn & Pelz ([2009](#)). Some
 41 have extended their identification capabilities to include other behaviours such as saccades,
 42 blinks, and micro-saccades, although these have remained limited to fixed-screen eye-trackers
 43 ([Ghose et al., 2020](#), @ berger:2012). Notably, none of the existing packages have included
 44 the identification of gaze behaviours in dynamic environments that involve large eye and head
 45 movements, such as smooth pursuit and visual scanning. Existing eye-tracking data analysis
 46 packages are designed for Cartesian coordinates ([Munn & Pelz, 2009](#)) or areas of interest based
 47 analyses [West:2006]. EyeDentify3D differs by interpreting the eye-tracking data in spherical
 48 coordinates (360°), which is less prone to vergence errors and avoids the need to pre-define
 49 areas of interest, thus its gaze behaviour identification features could not be integrated into
 50 existing portable eye-tracking data analysis packages.

51 Gaze behaviour identification

52 For each trial recorded during an experiment, the eyes and head rotations are extracted from
 53 the data collected by the eye-tracker and the inertial measurement unit, respectively. The gaze
 54 orientation (head and eye rotations combined) expressed over a 360° range is then analyzed
 55 frame-by-frame. For each frame, the pipeline applies a step-by-step classification based on the
 56 following criteria:

- 57 1. **Invalid:** The eye-tracker has declared having low confidence in the gaze orientation
 58 measurement and considers the data invalid. This often happens when the eyes are
 59 closed (e.g., during a blink), the eye orientation is outside the eye-tracker's measurement
 60 range, or if the eye-tracker was not positioned properly on the participant.
- 61 2. **Blink:** The eye openness is below the user-defined threshold ([Chen & Hou, 2021](#)).
- 62 3. **Saccade:** Two criteria must be met to detect a saccade. 1) The eye movement must be
 63 faster than a dynamical threshold determined using a rolling median over a user-defined
 64 window size. 2) The eye movement acceleration must exceed a user-defined threshold
 65 for a user-defined number of frames. This ensures that the eyes move rapidly between
 66 two targets, accelerating as they leave the first target and decelerating as they approach
 67 the second ([Van Opstal & Van Gisbergen, 1987](#)).
- 68 4. **Visual scanning:** The gaze (head + eyes) velocity is larger than a user-defined threshold
 69 ([McGuckian et al., 2020](#)). Visual scanning should be identified after saccades, as visual
 70 scanning behaviours could also present high eye velocity.
- 71 5. **Inter-saccadic interval:** Our inter-saccadic interval classification was adapted from
 72 Larsson et al. ([2015](#)) implementation, designed for screen-based eye-tracking data, by
 73 replacing Cartesian coordinates (2D plane) with spherical coordinates (360° range of
 74 motion). The frames that remained unidentified after the previous steps are grouped
 75 into intervals. Intervals longer than a user-defined duration threshold are considered
 76 inter-saccadic intervals. These intervals are subdivided into windows of a user-defined size.
 77 Each window is classified as either coherent or incoherent based on the gaze movement
 78 (moving in a consistent direction or not). Adjacent coherent and incoherent windows are
 79 merged together to form segments. Then, these segments are further classified as either
 80 **fixation** or **smooth pursuit** behaviours based on the four criteria described in Larsson et
 81 al. ([2015](#)):
 - 82 ■ Dispersion: $p_D < \eta_D$
 - 83 ■ Consistent direction: $p_{CD} > \eta_{CD}$
 - 84 ■ Positional displacement: $p_{PD} > \eta_{PD}$
 - 85 ■ Spatial range: $p_R > \eta_{maxFix}$

86 All behaviours are mutually exclusive, except for invalid and blink, which can occur together.
 87 For example, a frame cannot be classified as both a visual scanning and a smooth pursuit. Thus,
 88 the order of identification is important, as the first behaviour identified will take precedence
 89 over the others. More details on the definition of events and how they are identified can be

⁹⁰ found in the [documentation](#).

⁹¹ Finally, EyeIdentify3D enables the visualization of the classified gaze data and the
⁹² extraction/export of metrics related to the behaviours (e.g., mean duration, time ratio spent in
⁹³ each behaviour, number of occurrences, saccade amplitude, smooth pursuit trajectory length,
⁹⁴ etc.).

⁹⁵ Software design

⁹⁶ The package is organized around two types of classes: Data and BehaviorType. Classes
⁹⁷ inheriting from Data are responsible for loading, storing, and preprocessing the raw eye-
⁹⁸ tracking data exported from different eye-trackers, and classes inheriting from BehaviorType
⁹⁹ are responsible for identifying and analyzing specific gaze behaviours. This separation facilitates
¹⁰⁰ extending the capabilities of EyeIdentify3D by independently supporting new eye-trackers or
¹⁰¹ gaze behaviors. The modular design also allows users to customize their analysis pipeline by
¹⁰² selecting which gaze behaviours they want to identify and in what order.

¹⁰³ Research impact statement

¹⁰⁴ The package has already been used in sport psychology to analyze the gaze behaviour
¹⁰⁵ of basketball players ([Trempe et al., 2025](#)), and has been used in pilot studies involving
¹⁰⁶ trampolinists and boxers. As shown in the examples folder, the package is fully ready to be
¹⁰⁷ used by researchers and currently supports four commonly used eye-trackers. Moreover, the
¹⁰⁸ package's test coverage exceeds 90%, ensuring the reliability and reproducibility of its results.
¹⁰⁹ To help researchers get started with the package, we provide detailed documentation available
¹¹⁰ at <https://evecharbie.github.io/EyeIdentify3d>

¹¹¹ Note on the implementation

¹¹² We believe that the choices made in EyeIdentify3D are the most suitable for the analysis of
¹¹³ gaze behaviour in 3D space (especially in a sporting context). However, we are very open to
¹¹⁴ implementing other identification methods that might be more suitable in other application
¹¹⁵ contexts.

¹¹⁶ Acknowledgements

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¹¹⁸ Conflict of interest

¹¹⁹ The authors declare no conflict of interest.

¹²⁰ AI usage disclosure

¹²¹ During the preparation of this work, the developer used ChatGPT, Claude, and Copilot to
¹²² speed up development and enhance code clarity. Aider and Claude were also used to write tests.
¹²³ After using these tools/services, the developer reviewed and edited the content as needed and
¹²⁴ takes full responsibility for the content of the repository. ChatGPT and Grammarly were also
¹²⁵ used in the writing of the manuscript to revise the clarity and language.

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