UNIVERSITY of WISCONSIN-MADISON Computer Sciences Department

CS 537 Introduction to Operating Systems Andrea C. Arpaci-Dusseau Remzi H. Arpaci-Dusseau

CONCURRENCY: LOCKS

Questions answered in this lecture:

Review threads and mutual exclusion for critical sections

How can locks be used to protect shared data structures such as linked lists?

Can locks be implemented by disabling interrupts?

Can locks be implemented with loads and stores?

Can locks be implemented with atomic hardware instructions?

Are spinlocks a good idea?

ANNOUNCEMENTS

Midterm Survey

- Turn up volume on microphone!
- What to do with discussion sections???
- Lecture pace is fast, but generally good
- Projects are challenging and interesting (but too much on passing tests?)
- Exam not any fun (fewer, more difficult questions)

1st Exam: Solutions posted, individual responses available

Project 3: Only xv6 part – rearrange address space of processes

- Watch parts of two videos
- Will need to submit user programs for testing

Read as we go along!

• Chapter 28

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CONCURRENCY: Locks

Questions answered in this lecture:

Review: Why threads and mutual exclusion for critical sections?

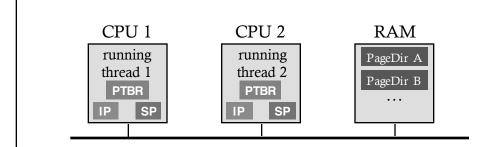
How can locks be used to protect shared data structures such as linked lists?

Can locks be implemented by **disabling interrupts**?

Can locks be implemented with loads and stores?

Can locks be implemented with atomic hardware instructions?

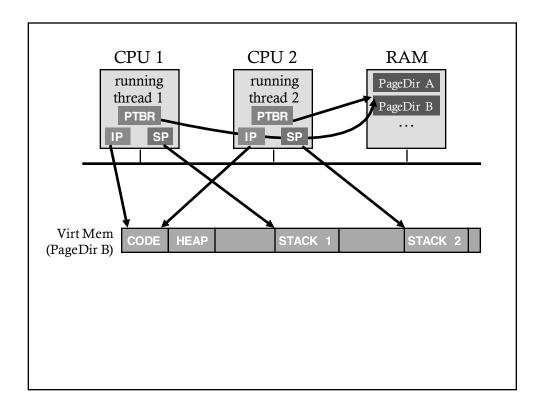
When are spinlocks a good idea?



Virt Mem (PageDir B) CODE HEAP

Review:

Which registers store the same/different values across threads?



REVIEW: WHAT IS NEEDED FOR CORRECTNESS?

Balance = balance + 1;

Instructions accessing shared memory must execute as uninterruptable group

• Need instructions to be atomic

mov 0x123, %eax add %0x1, %eax - critical section mov %eax, 0x123

More general:
Need **mutual exclusion** for critical sections
• if process A is in critical section C, process B can't (okay if other processes do unrelated work)

OTHER EXAMPLES

Consider multi-threaded applications that do more than increment shared balance

Multi-threaded application with shared linked-list

- All concurrent:
 - Thread A inserting element a
 - Thread B inserting element b
 - Thread Clooking up element c

SHARED LINKED LIST

```
Void List_Insert(list_t *L,
                                    typedef struct __node_t {
                int key) {
                                        int key;
   node_t *new =
                                        struct __node_t *next;
      malloc(sizeof(node_t));
                                    } node_t;
   assert(new);
   new->key = key;
   new->next = L->head;
                                    Typedef struct __list_t {
   L->head = new;
                                        node_t *head;
                                    } list_t;
int List_Lookup(list_t *L,
                                    Void List Init(list t *L)
               int key) {
                                        L->head = NULL;
   node_t *tmp = L->head;
   while (tmp) {
      if (tmp->key == key)
      return 1;
                                 What can go wrong?
      tmp = tmp->next;
                         Find schedule that leads to problem?
return 0;
```

LINKED-LIST RACE

new->key = key

new->next = L->head

new->key = key

new->key = key

new->next = L->head

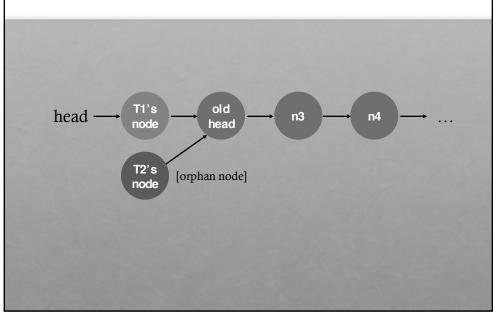
L->head = new

L->head = new

Both entries point to old head

Only one entry (which one?) can be the new head.

RESULTING LINKED LIST



LOCKING LINKED LISTS

```
Void List Insert(list t *L,
                                 typedef struct node t {
                 int key) {
                                   int key;
  node t *new =
                                   struct __node_t *next;
     malloc(sizeof(node_t));
                                 } node t;
  assert(new);
  new->key = key;
                                 Typedef struct __list_t {
  new->next = L->head;
                                   node t *head;
  L->head = new;
                                 } list t;
int List Lookup(list t *L,
                                Void List Init(list t *L) {
                 int key) {
                                   L->head = NULL;
  node t *tmp = L->head;
  while (tmp) {
     if (tmp->key == key)
                                    How to add locks?
        return 1;
     tmp = tmp->next;
return 0;
```

LOCKING LINKED LISTS

```
typedef struct   node t {
                             typedef struct node t {
   int key;
                                int key;
   struct __node_t *next;
                                struct __node_t *next;
} node t;
                             } node t;
Typedef struct __list_t {
                             Typedef struct __list_t {
   node t *head;
                                node t *head;
} list_t;
                                pthread mutex t lock;
                             } list t;
Void List_Init(list_t *L) {
   L->head = NULL;
                             Void List_Init(list_t *L) {
                                L->head = NULL;
                                pthread_mutex_init(&L->lock,
How to add locks?
                                  NULL);
pthread mutex t lock; }
One lock per list
```

LOCKING LINKED LISTS : Approach #1

```
Void List_Insert(list_t *L,
                                                 int key) {
  Pthread_mutex_lock(&L->lock); node_t *new =
                                     malloc(sizeof(node_t));
Consider everything critical section assert(new);
  Can critical section be smaller?
                                  new->key = key;
                                  new->next = L->head;
 Pthread_mutex_unlock(&L->lock), ->head = new;
                               int List_Lookup(list_t *L,
                                                int key) {
 Pthread_mutex_lock(&L->lock); node_t *tmp = L->head;
                                  while (tmp) {
                                     if (tmp->key == key)
                                       return 1;
                                     tmp = tmp->next;
Pthread_mutex_unlock(&L->lock)
```

LOCKING LINKED LISTS: APPROACH #2

```
Void List_Insert(list_t *L,
                                                 int key) {
                                  node_t *new =
                                     malloc(sizeof(node_t));
 Critical section small as possible
                                  assert(new);
  Pthread_mutex_lock(&L->lock); new->key = key; new->head;
 Pthread_mutex_unlock(&L->lock),->head = new;
                               int List_Lookup(list_t *L,
                                                 int key) {
 Pthread_mutex_lock(&L->lock); node_t *tmp = L->head;
                                  while (tmp) {
                                     if (tmp->key == key)
                                        return 1;
                                     tmp = tmp->next;
Pthread_mutex_unlock(&L->lock), return 0;
```

LOCKING LINKED LISTS : Approach #3

```
Void List_Insert(list_t *L,
                                                int key) {
                                 node_t *new =
                                    malloc(sizeof(node_t));
     What about Lookup()?
                                 assert(new);
                                 new->key = key;
  Pthread_mutex_lock(&L->lock); new - next = L->head;
Pthread_mutex_unlock(&L->lock), ->head = new;
                               int List_Lookup(list_t *L,
                                                int key) {
 Pthread_mutex_lock(&L->lock); node_t *tmp = L->head;
                                 while (tmp) {
                                    if (tmp->key == key)
 If no List_Delete(), locks not needed
                                       return 1;
                                    tmp = tmp->next;
Pthread_mutex_unlock(&L->lock)
```

IMPLEMENTING SYNCHRONIZATION

Build higher-level synchronization primitives in OS

• Operations that ensure correct ordering of instructions across threads

Motivation: Build them once and get them right

Monitors
Locks Semaphores
Condition Variables

Loads
Stores Test&Set
Disable Interrupts

LOCK IMPLEMENTATION GOALS

Correctness

- · Mutual exclusion
 - Only one thread in critical section at a time
- Progress (deadlock-free)
 - If several simultaneous requests, must allow one to proceed
- Bounded (starvation-free)
 - Must eventually allow each waiting thread to enter

Fairness

Each thread waits for same amount of time

Performance

CPU is not used unnecessarily (e.g., spinning)

IMPLEMENTING SYNCHRONIZATION

To implement, need atomic operations

Atomic operation: No other instructions can be interleaved

Examples of atomic operations

- · Code between interrupts on uniprocessors
 - Disable timer interrupts, don't do any I/O
- · Loads and stores of words
 - · Load r1, B
 - · Store r1, A
- · Special hw instructions
 - · Test&Set
 - · Compare&Swap

IMPLEMENTING LOCKS: W/ INTERRUPTS

```
Turn off interrupts for critical sections

Prevent dispatcher from running another thread

Code between interrupts executes atomically

Void acquire(lockT *1) {
    disableInterrupts();
}

Void release(lockT *1) {
    enableInterrupts();
}

Disadvantages??

Only works on uniprocessors

Process can keep control of CPU for arbitrary length

Cannot perform other necessary work
```

IMPLEMENTING LOCKS: W/ LOAD+STORE

```
Codeuses a single shared lock variable

Boolean lock = false; // shared variable

Void acquire(Boolean *lock) {
    while (*lock) /* wait */;
    *lock = true;
}

Void release(Boolean *lock) {
    *lock = false;
}

Why doesn't this work? Example schedule that fails with 2 threads?
```

RACE CONDITION WITH LOAD AND STORE

```
*lock == 0 initially
```

Thread 1 Thread 2

while(*lock == 1)

while(*lock == 1)

*lock = 1

*lock = 1

Both threads grab lock!

Problem: Testing lock and setting lock are not atomic

DEMO

Critical section not protected with faulty lock implementation

PETERSON'S ALGORITHM

```
Assume only two threads (tid = 0, 1) and use just loads and stores

int turn = 0; // shared

Boolean lock[2] = {false, false};

Void acquire() {
    lock[tid] = true;
    turn = 1-tid;
    while (lock[1-tid] && turn == 1-tid) /* wait */;

}

Void release() {
    lock[tid] = false;
}
```

DIFFERENT CASES: ALL WORK

```
Only thread 0 wants lock
Lock[0] = true;
turn = 1;
while (lock[1] && turn ==1);
Thread 0 and thread 1 both want lock;
Lock[0] = true;
turn = 1;
Lock[1] = true;
while (lock[1] && turn ==1);
while (lock[0] && turn == 0);
```

DIFFERENT CASES: ALL WORK

```
Thread 0 and thread 1 both want lock
```

DIFFERENT CASES: ALL WORK

```
Thread 0 and thread 1 both want lock;
```

PETERSON'S ALGORITHM: INTUITION

Mutual exclusion: Enter critical section if and only if

Other thread does not want to enter

Other thread wants to enter, but your turn

Progress: Both threads cannot wait forever at while() loop

Completes if other process does not want to enter

Other process (matching turn) will eventually finish

Bounded waiting (not shown in examples)

Each process waits at most one critical section

Problem: doesn't work on modern hardware (cache-consistency issues)

XCHG: ATOMIC EXCHANGE, OR TEST-AND-SET

LOCK IMPLEMENTATION WITH XCHG

XCHG IMPLEMENTATION

```
typedef struct __lock_t {
   int flag;
} lock_t;

void init(lock_t *lock) {
   lock->flag = 0;
}

void acquire(lock_t *lock) {
   while(xchg(&lock->flag, 1) == 1);
   // spin-wait (do nothing)
}

void release(lock_t *lock) {
   lock->flag = 0;
}
```

DEMO XCHG

Critical section protected with our lock implementation!!

OTHER ATOMIC HW INSTRUCTIONS

OTHER ATOMIC HW INSTRUCTIONS

LOCK IMPLEMENTATION GOALS

Correctness

- · Mutual exclusion
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- Progress (deadlock-free)
 - If several simultaneous requests, must allow one to proceed
- Bounded (starvation-free)
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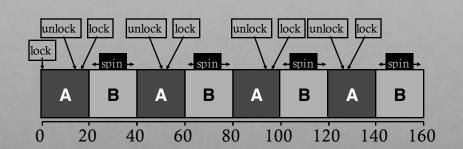
Fairness

Each thread waits for same amount of time

Performance

CPU is not used unnecessarily

BASIC SPINLOCKS ARE UNFAIR



Scheduler is independent of locks/unlocks

FAIRNESS: TICKET LOCKS

```
Idea: reserve each thread's turn to use a lock.
Each thread spins until their turn.
Use new atomic primitive, fetch-and-add:
int FetchAndAdd(int *ptr) {
  int old = *ptr;
  *ptr = old + 1;
  return old;
}
Acquire: Grab ticket;
Spin while not thread's ticket != turn
Release: Advance to next turn
```

TICKET LOCK EXAMPLE		
A lock(): B lock(): C lock(): A unlock(): B runs A lock(): B unlock(): C runs C unlock(): A runs A unlock(): C lock():	Ticket	

TICKET LOCK EXAMPLE		
A lock(): gets ticket 0, spins until turn = 0 → B lock(): gets ticket 1, spins until turn=1 C lock(): gets ticket 2, spins until turn=2 A unlock(): turn++(turn=1) B runs A lock(): gets ticket 3, spins until turn=3 B unlock(): turn++ (turn=2) C runs C unlock(): turn++ (turn=3) A runs A unlock(): turn++(turn=4) C lock(): gets ticket 4, runs	o 1 2 3 4 5 6 7	

TICKET LOCK IMPLEMENTATION

```
typedef struct __lock_t {
        int ticket;
        int turn;
        while (lock->turn != myturn); // spin
}

void lock_init(lock_t *lock) {
        lock->ticket = 0;
        lock->turn = 0;
}
```

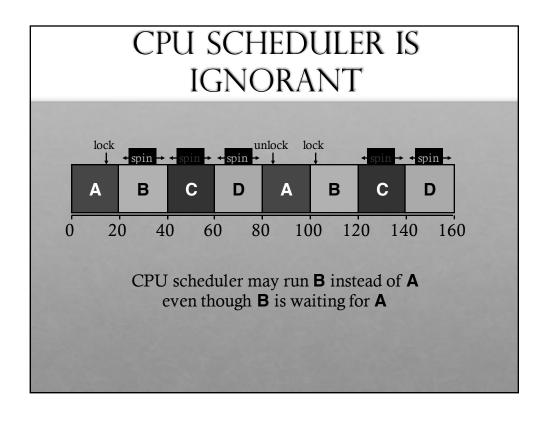
SPINLOCK PERFORMANCE

Fast when...

- many CPUs
- locks held a short time
- advantage: avoid context switch

Slow when...

- one CPU
- locks held a long time
- disadvantage: spinning is wasteful



YIELD() typedef struct $_lock_t$ { void acquire(lock_t *lock) { int ticket; int myturn = FAA(&lock->ticket); int turn; } while(lock->turn != myturn) } yield(); void $lock_init(lock_t *lock)$ {

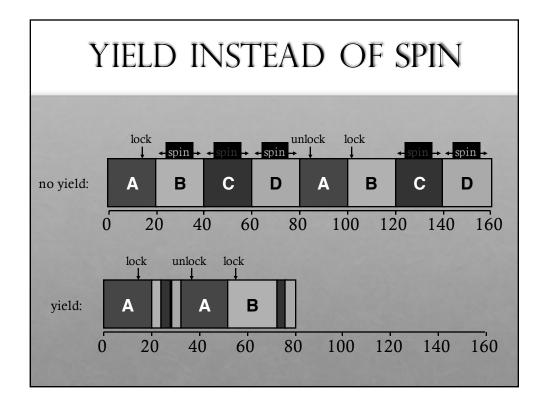
lock->ticket = 0;

lock > turn = 0;

void release (lock_t *lock) {

FAA(&lock->turn);

TICKET LOCK WITH



SPINLOCK PERFORMANCE

Waste...

Without yield: O(threads * time_slice)
With yield: O(threads * context_switch)

So even with yield, spinning is slow with high thread contention

Next improvement: Block and put thread on waiting queue instead of spinning