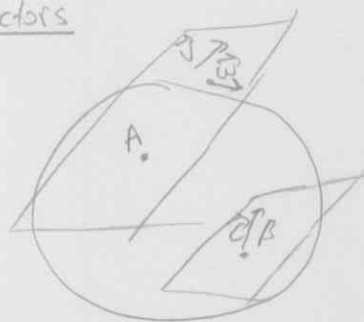


Fundamentals

(Diff geo)

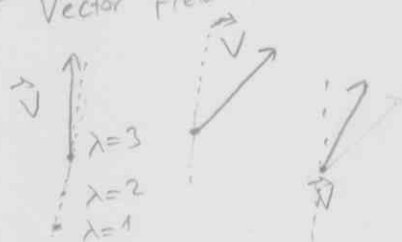


Vectors



vector live at T_A = tangent space attached to A
vectors at different points live in distinct tangent spaces
distinct vector spaces

Vector field \vec{V} \leftrightarrow integral curves



integral curves which \vec{V} is tangents

$$\begin{aligned} X^\alpha &= X^\alpha(\lambda) \\ V^\alpha &= \frac{dX^\alpha}{d\lambda} ; X^\alpha(\lambda=0) \text{ initial condition} \\ \frac{df}{d\lambda} &= \partial_\alpha f V^\alpha, f=f(X^\alpha) \end{aligned}$$

Covectors (dual vectors, one-forms)

linear functions of vectors \rightarrow scalars

$$\omega_\alpha V^\alpha = \text{scalar}$$

Tensors

Multilinear functions of vectors and covectors \rightarrow scalars

$$T^{\alpha}{}_{\beta} \omega_\alpha V^\beta = \text{scalar}$$

Metric

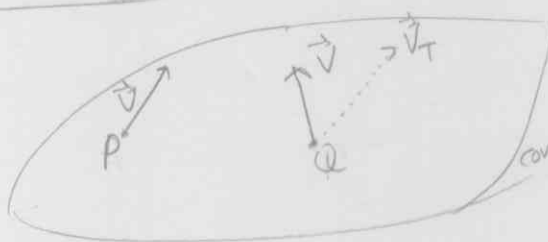
$g_{\alpha\beta} V^\alpha V^\beta$ = squared length of V^α (negative, positive, zero)

inverse = $g^{\alpha\beta}$ $g^{\alpha\beta} g_{\beta\gamma} = \delta^\alpha_\gamma$, $g^{\alpha\beta} \omega_\alpha \omega_\beta$ = squared length of ω_α

$$V_\alpha = g_{\alpha\beta} V^\beta$$

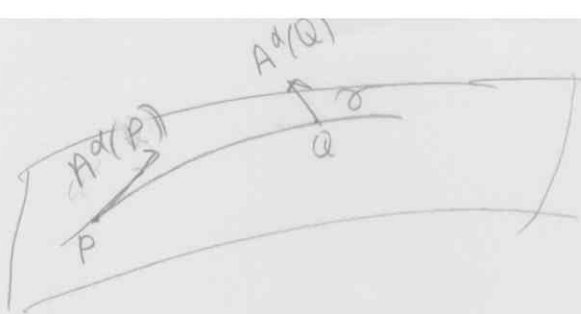
$$\omega^\alpha = g^{\alpha\beta} \omega_\beta$$

Covariant derivative



connection ∇ -rule to take a vector at Q and bring it to P : parallel transport
new structure
cov-derivative: $\vec{V}(Q) - \vec{V}_T(Q)$

$$\nabla_\alpha V^\beta = \partial_\alpha V^\beta + \Gamma^\beta_{\alpha\gamma} V^\gamma$$



$A^\alpha(Q) \notin \mathbb{R}(P)$, $A^\alpha(Q) - A^\alpha(P)$ are not defined as tensorial operations.

Consider a curve σ , its tangent vector u^α and a vector field A^α defined in the neighbourhood of σ . Let point P on the curve have coordinates x^α and Q have coordinates $x^\alpha + dx^\alpha$

$$\begin{aligned} dA^\alpha &= A^\alpha(Q) - A^\alpha(P) = A^\alpha(x^\alpha + dx^\alpha) - A^\alpha(x^\alpha) \\ &= A^\alpha(x^\alpha) + \partial_\mu A^\alpha(x^\alpha) dx^\mu - A^\alpha(x^\alpha) \\ &= A^\alpha_{;\mu} dx^\mu \end{aligned}$$

To check the tensoriality

$$\frac{\partial A^{\alpha'}}{\partial x^{\beta'}} = \frac{\partial}{\partial x^{\beta'}} \frac{\partial x^\alpha}{\partial x^{\beta'}} A^\alpha(x^\alpha) = \frac{\partial x^\alpha}{\partial x^{\beta'}} \frac{\partial x^\beta}{\partial x^\alpha} \partial_\beta A^\alpha + \frac{\partial^2 x^\alpha}{\partial x^{\beta'} \partial x^{\beta'}} A^\alpha$$

There is an extra $\frac{\partial^2 x^\alpha}{\partial x^{\beta'} \partial x^{\beta'}}$ term but due to δ contraction it gives 0 and output is the

which is not tensorial operation

The derivative should have the form

$$DA^\alpha = A^\alpha_T(P) - A^\alpha(P)$$

where $A^\alpha_T(P)$ is the vector transported from Q to P

$$DA^\alpha = dA^\alpha + \delta A^\alpha \quad \text{where} \quad \delta A^\alpha = A^\alpha_T(P) - A^\alpha(Q)$$

D : covariant differentiation

$$DA^\alpha = A^\alpha_T(P) - A^\alpha(P)$$

We demand that δA^α be linear in both A^μ and dx^β so that $\delta A^\alpha = \Gamma^\alpha_{\mu\beta} A^\mu dx^\beta$ for some (non tensorial) field $\Gamma^\alpha_{\mu\beta}$ called the connection

$$DA^\alpha = \partial_\beta A^\alpha dx^\beta + \Gamma^\alpha_{\mu\beta} A^\mu dx^\beta, \text{ dividing through by } dx^\beta$$

$$\frac{DA^\alpha}{d\lambda} = \partial_\beta A^\alpha u^\beta + \Gamma^\alpha_{\mu\beta} A^\mu u^\beta \Rightarrow \frac{DA^\alpha}{d\lambda} = \nabla_\beta A^\alpha u^\beta \quad \text{where } u^\beta \text{ is tangent vector}$$

$$\text{and } \nabla_\beta A^\alpha = \partial_\beta A^\alpha + \Gamma^\alpha_{\mu\beta} A^\mu \quad \text{Covariant derivative of the vector } A^\alpha$$

$$\nabla_\beta A^\alpha = A^\alpha_{;\beta}, \quad \frac{DA^\alpha}{d\lambda} \equiv \nabla_u A^\alpha$$

$$\Gamma_{\mu\rho}^{\alpha} A^{\mu} = \nabla_{\rho} A^{\alpha} - \partial_{\rho} A^{\alpha}$$

$$\begin{aligned} \Gamma_{\mu'\rho'}^{\alpha'} A^{\mu'} &= \frac{\partial x^{\beta}}{\partial x^{\rho'}} \nabla_{\beta} \left(\frac{\partial x^{\alpha'}}{\partial x^{\alpha}} A^{\alpha} \right) - \frac{\partial x^{\beta}}{\partial x^{\rho'}} \partial_{\beta} \left(\frac{\partial x^{\alpha'}}{\partial x^{\alpha}} A^{\alpha} \right) \\ &= \frac{\partial x^{\beta}}{\partial x^{\rho'}} \frac{\partial x^{\alpha'}}{\partial x^{\alpha}} \left(\nabla_{\beta} A^{\alpha} + \Gamma_{\beta\gamma}^{\alpha} A^{\gamma} \right) - \frac{\partial x^{\beta}}{\partial x^{\rho'}} \frac{\partial^2 x^{\alpha'}}{\partial x^{\rho} \partial x^{\alpha}} A^{\alpha} - \frac{\partial x^{\beta}}{\partial x^{\rho'}} \frac{\partial x^{\alpha'}}{\partial x^{\alpha}} \partial_{\beta} A^{\alpha} \\ \Gamma_{\mu'\rho'}^{\alpha'} \frac{\partial x^{\mu'}}{\partial x^{\mu}} A^{\mu} &= \frac{\partial x^{\beta}}{\partial x^{\rho'}} \frac{\partial x^{\alpha'}}{\partial x^{\alpha}} \Gamma_{\beta\mu}^{\alpha} A^{\mu} - \frac{\partial x^{\beta}}{\partial x^{\rho'}} \frac{\partial^2 x^{\alpha'}}{\partial x^{\rho} \partial x^{\mu}} A^{\mu} \end{aligned}$$

$$\begin{aligned} \Gamma_{\mu'\rho'}^{\alpha'} \frac{\partial x^{\mu'}}{\partial x^{\mu}} &= \frac{\partial x^{\beta}}{\partial x^{\rho'}} \frac{\partial x^{\alpha'}}{\partial x^{\alpha}} \Gamma_{\beta\mu}^{\alpha} - \frac{\partial x^{\beta}}{\partial x^{\rho'}} \frac{\partial^2 x^{\alpha'}}{\partial x^{\rho} \partial x^{\mu}} \\ \Gamma_{\mu'\rho'}^{\alpha'} &= \frac{\partial x^{\beta}}{\partial x^{\rho'}} \frac{\partial x^{\alpha'}}{\partial x^{\alpha}} \frac{\partial x^{\mu}}{\partial x^{\mu'}} \Gamma_{\beta\mu}^{\alpha} - \frac{\partial x^{\beta}}{\partial x^{\rho'}} \frac{\partial^2 x^{\alpha'}}{\partial x^{\rho} \partial x^{\mu}} \frac{\partial x^{\mu}}{\partial x^{\mu'}} \end{aligned}$$

- Connection is not a tensor
- D must obey the Leibnitz rule.
- $D = d$ for a scalar

$$\begin{aligned} D(A^{\alpha} p_{\alpha}) &\equiv d(A^{\alpha} p_{\alpha}) = (DA^{\alpha}) p_{\alpha} + A^{\alpha} Dp_{\alpha} \\ &= (\partial_{\beta} A^{\alpha} dx^{\beta}) p_{\alpha} + A^{\alpha} (\partial_{\beta} p_{\alpha} dx^{\beta}) \end{aligned}$$

$$\frac{Dp_{\alpha}}{d\lambda} = \nabla_{\beta} p_{\alpha} dx^{\beta}$$

$$D \frac{T^{\mu}_{\sigma\gamma}}{d\lambda} = \nabla_{\alpha} T^{\mu}_{\sigma\gamma} u^{\alpha} \quad \text{where } u^{\alpha} \text{ is the tangent vector}$$

Extend to other tensors \rightarrow Leibniz

scalar: $\nabla_\alpha f = \partial_\alpha f$

$$\nabla(A^{...} B^{...}) = (\nabla A^{...}) B^{...} + A^{...} (\nabla B^{...})$$

vector: $\nabla_\alpha (\omega_\beta V^\beta) = \partial_\alpha (\omega_\beta V^\beta) = (\partial_\alpha \omega_\beta) V^\beta + \omega_\beta \partial_\alpha V^\beta$
 $= (\nabla_\alpha \omega_\beta) V^\beta + \omega_\beta (\nabla_\alpha V^\beta)$

$$(\nabla_\alpha \omega_\beta) V^\beta = -\omega_\beta (\partial_\alpha V^\beta + \Gamma_{\alpha\gamma}^\beta V^\gamma) + (\partial_\alpha \omega_\beta) V^\beta + \omega_\beta (\partial_\alpha V^\beta)$$

$$(\nabla_\alpha \omega_\beta) V^\beta = (\partial_\alpha \omega_\beta - \omega_\gamma \Gamma_{\alpha\beta}^\gamma) V^\beta$$

$$\nabla_\alpha \omega_\beta = \partial_\alpha \omega_\beta - \Gamma_{\alpha\beta}^\gamma \omega_\gamma$$

Connection in GR

- symmetric $\Gamma_{\beta\alpha}^\gamma = \Gamma_{\alpha\beta}^\gamma$

- metric compatible $\nabla_\alpha g_{\beta\gamma} = 0$

$$\Gamma_{\beta\gamma}^\alpha = \frac{1}{2} g^{\alpha\mu} (\partial_\beta g_{\mu\gamma} + \partial_\gamma g_{\mu\beta} - \partial_\mu g_{\beta\gamma})$$

"Christoffel symbols"

Covariant derivation along a curve

$$\nabla_\alpha V^\beta = \partial_\alpha V^\beta + \Gamma_{\alpha\gamma}^\beta V^\gamma$$

V^α : vector field

$$\frac{DV^\beta}{d\lambda} = u^\alpha (\nabla_\alpha V^\beta) = \frac{dX^\alpha}{d\lambda} \nabla_\alpha V^\beta$$

$$= \frac{dX^\alpha}{d\lambda} (\partial_\alpha V^\beta + \Gamma_{\alpha\gamma}^\beta V^\gamma) = \frac{dV^\beta}{d\lambda} + \Gamma_{\alpha\gamma}^\beta u^\alpha V^\gamma$$



curve $\gamma - X^\alpha = X^\alpha(\lambda)$
 $u^\alpha = \frac{dX^\alpha}{d\lambda}$

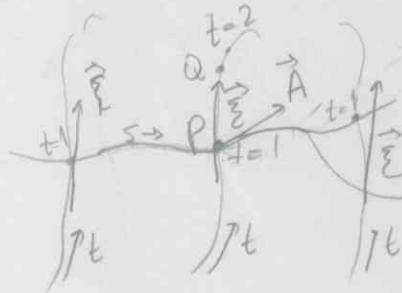
Lie Derivative

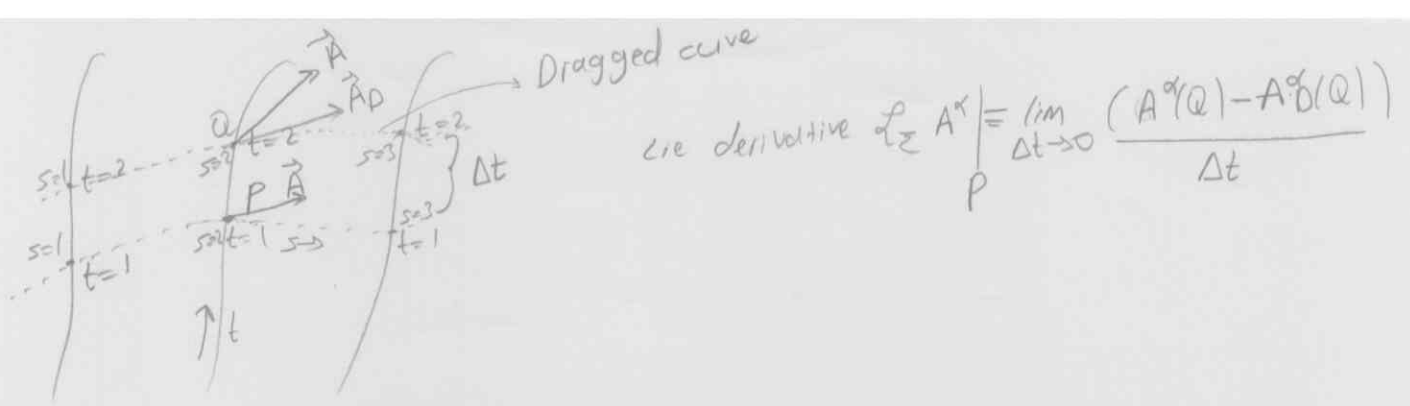
- without $\Gamma \rightarrow$ more primitive
- two vector fields, \vec{X}, \vec{A}

Integral curves of $\vec{X}, X^\alpha(t)$

$$\vec{X}^\alpha = \frac{dX^\alpha}{dt}$$

Integral curve of \vec{A} through $P - Z^\alpha(s), A^\alpha = \frac{dZ^\alpha}{ds}$





Lie derivative $\mathcal{L}_\Sigma A^\alpha = \lim_{\Delta t \rightarrow 0} \frac{(A^\alpha(Q) - A^\alpha(P))}{\Delta t}$

$$\begin{aligned}\mathcal{L}_\Sigma A^\alpha &= \Sigma^\beta \partial_\beta A^\alpha - A^\beta \partial_\beta \Sigma^\alpha \\ &= \Sigma^\beta \nabla_\beta A^\alpha - A^\beta \nabla_\beta \Sigma^\alpha : \Gamma \text{ cancel out} \\ &= -\mathcal{L}_A \Sigma^\alpha\end{aligned}$$

Scalars

$$\mathcal{L}_\Sigma f = \Sigma^\alpha \partial_\alpha f$$

Covectors

$$\begin{aligned}\mathcal{L}_\Sigma (\omega_\alpha V^\alpha) &= \Sigma^\beta \partial_\beta (\omega_\alpha V^\alpha) = (\Sigma^\beta \partial_\beta \omega_\alpha) V^\alpha + \omega_\alpha (\Sigma^\beta \partial_\beta V^\alpha) \\ &= (\mathcal{L}_\Sigma \omega_\alpha) V^\alpha + \omega_\alpha \mathcal{L}_\Sigma V^\alpha\end{aligned}$$

$$(\mathcal{L}_\Sigma \omega_\alpha) V^\alpha = -\omega_\alpha (\Sigma^\beta \partial_\beta V^\alpha - V^\beta \partial_\beta \Sigma^\alpha) + (\Sigma^\beta \partial_\beta \omega_\alpha) V^\alpha + \omega_\alpha (\Sigma^\beta \partial_\beta V^\alpha)$$

$$(\mathcal{L}_\Sigma \omega_\alpha) V^\alpha = (\omega_\beta \partial_\alpha \Sigma^\beta) V^\alpha + (\Sigma^\beta \partial_\beta \omega_\alpha) V^\alpha$$

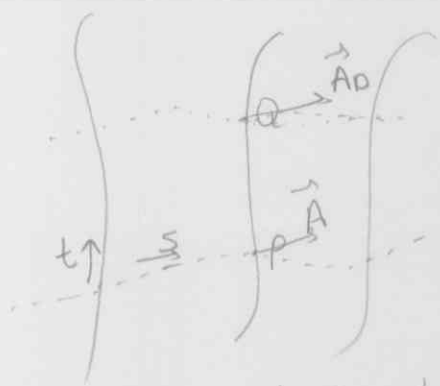
$$\begin{aligned}\mathcal{L}_\Sigma \omega_\alpha &= \omega_\beta \partial_\alpha \Sigma^\beta + \Sigma^\beta \partial_\beta \omega_\alpha \\ &= \omega_\beta \nabla_\alpha \Sigma^\beta + \Sigma^\beta \nabla_\beta \omega_\alpha\end{aligned}$$

Tensors

$$\mathcal{L}_\Sigma T^{\alpha\beta} = \Sigma^\gamma \partial_\gamma T^{\alpha\beta} - T^{\gamma\beta} \partial_\gamma \Sigma^\alpha - T^{\alpha\gamma} \partial_\gamma \Sigma^\beta$$

$$\mathcal{L}_\Sigma T_{\alpha\beta} = \Sigma^\gamma \partial_\gamma T_{\alpha\beta} + T_{\gamma\beta} \partial_\alpha \Sigma^\gamma + T_{\alpha\gamma} \partial_\beta \Sigma^\gamma$$

$$\mathcal{L}_\Sigma T^\alpha{}_\beta = \Sigma^\gamma \partial_\gamma T^\alpha{}_\beta - T^\gamma{}_\beta \partial_\gamma \Sigma^\alpha + T^\alpha{}_\gamma \partial_\beta \Sigma^\gamma$$



Describe all curves as $X^\alpha(t, s)$

s is fixed, t varies \rightarrow integral curves of $\Sigma \rightarrow \Sigma^\alpha = \left(\frac{\partial X^\alpha}{\partial t} \right)_s$
 s varies, t is fixed \rightarrow dragged curves of $\tilde{A} \rightarrow A_D^\alpha = \left(\frac{\partial X^\alpha}{\partial s} \right)_t$

At P , $X^\alpha = 0$, $t=0, s=0$

$$X^\alpha(t, s) = a^\alpha t + b^\alpha s + \frac{1}{2} c^\alpha t^2 + d^\alpha s t + \frac{1}{2} e^\alpha s^2 + O(3)$$

$$\Sigma^\alpha = \left(\frac{\partial X^\alpha}{\partial t} \right)_s = a^\alpha + c^\alpha t + d^\alpha s + O(2)$$

$$A_D^\alpha = \left(\frac{\partial X^\alpha}{\partial s} \right)_t = b^\alpha + e^\alpha s + d^\alpha t + O(2)$$

$$A^\alpha = A_P^\alpha + p^\alpha t + q^\alpha s + O(2) \quad : \text{No relation with } X^\alpha(t, s)$$

when $t=0$, $A^\alpha = A_D^\alpha$
 integral curves of $A =$ Dragged curve

$$A_P^\alpha + q^\alpha s = b^\alpha + e^\alpha s$$

$$A_P^\alpha = b^\alpha$$

$$q^\alpha = e^\alpha$$

$$A^\alpha = b^\alpha + p^\alpha t + e^\alpha s$$

$$\mathcal{L}_\Sigma A^\alpha = \frac{A^\alpha(t) - A_D^\alpha(t)}{t} = \frac{b^\alpha + p^\alpha t + e^\alpha s - b^\alpha - e^\alpha s - d^\alpha t}{t} = p^\alpha - d^\alpha$$

$$\cdot \Sigma^P \partial_P A^\alpha = \left(\frac{\partial X^P}{\partial t} \right)_s \partial_P A^\alpha = \left(\frac{\partial A^\alpha}{\partial t} \right)_s \Big|_{P, s=0} = p^\alpha$$

$$\cdot A^P \partial_P \Sigma^\alpha = \frac{A_D^P \partial_P \Sigma^\alpha + (A^P - A_D^P) \partial_P \Sigma^\alpha}{O(t)}$$

$$= \left(\frac{\partial X^P}{\partial s} \right)_t \partial_P \Sigma^\alpha$$

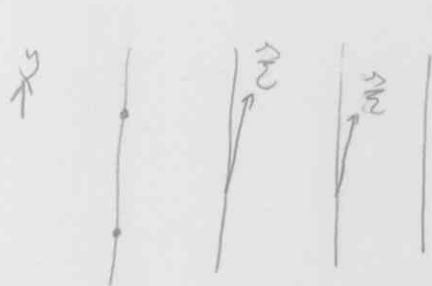
$$= \lim_{t \rightarrow 0} \left(\frac{\partial \Sigma^\alpha}{\partial s} \right)_{t=0} + \lim_{t \rightarrow 0} (p^\alpha - d^\alpha) t \partial_P \Sigma^\alpha$$

$$A^P \partial_P \Sigma^\alpha = d^\alpha$$

$$\mathcal{L}_\Sigma A^\alpha = p^\alpha - d^\alpha = \Sigma^P \partial_P A^\alpha - A^P \partial_P \Sigma^\alpha$$

Killing vectors

In some coordinates (t, x, y, z) , suppose that $\partial_y g_{\mu\nu} \neq 0$ $\xrightarrow{\text{in the coordinate system we chose}}$



$$\xi^{\mu*} = (0, 0, 1, 0)$$

$$\mathcal{L}_\xi g_{\mu\nu} = \underbrace{\xi^\lambda \partial_\lambda g_{\mu\nu}}_{\substack{\partial_y g_{\mu\nu} \\ \neq 0}} + g_{\lambda\nu} \underbrace{\frac{\partial \xi^\lambda}{\partial y}}_0 + g_{\mu\lambda} \underbrace{\frac{\partial \xi^\lambda}{\partial y}}_0$$

$$\mathcal{L}_\xi g_{\mu\nu} \neq 0$$

$\mathcal{L}_\xi g_{\mu\nu} = 0$ in all coordinate systems

$\xi^\alpha =$ killing vector

$$0 = \mathcal{L}_\xi g_{\alpha\beta} = \xi^\gamma \underbrace{\nabla_\gamma g_{\alpha\beta}}_{=0} + \underbrace{g_{\alpha\beta} \nabla_\gamma \xi^\gamma}_{\text{metric compatibility}} + g_{\alpha\gamma} \nabla_\beta \xi^\gamma + g_{\beta\gamma} \nabla_\alpha \xi^\gamma$$

$$= \nabla_\alpha \xi_\beta + \nabla_\beta \xi_\alpha$$

$$\nabla_\alpha \xi_\beta + \nabla_\beta \xi_\alpha = 0 \quad \text{Killing's equation}$$

$$\nabla_{(\alpha} \xi_{\beta)} = 0$$

$\nabla_\alpha \xi_\beta =$ anti-symmetric

Example: Minkowski metric

$$ds^2 = -dt^2 + dx^2 + dy^2 + dz^2$$

- 10 $\left\{ \begin{array}{l} 4 \text{ translational Killing vectors} \\ 3 \text{ rotational KV} \\ 3 \text{ boost KV} \end{array} \right.$

Example: spherical symmetry, static

$$ds^2 = -A(r)dt^2 + B(r)dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2)$$

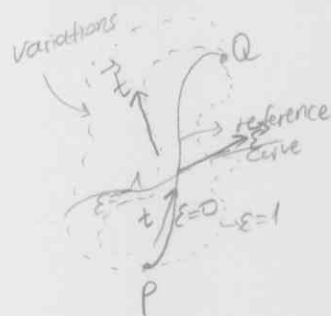
$$\xi_{(t)}^\alpha = (1, 0, 0, 0)$$

$$\xi_{(\phi)}^\alpha = (0, 0, 0, 1)$$

$$\xi_{(r)}^\alpha = (0, 0, \sin\phi, \cot\theta \cos\phi)$$

$$\xi_{(\theta)}^\alpha = (0, 0, -\cos\phi, \cot\theta \sin\phi)$$

Geodesics



A timelike geodesic extremizes proper time between two (neighbourhood) points

2-parameter family of curves: $X^\alpha(t, \epsilon) = X^\alpha(t) + \epsilon \delta X^\alpha(t) + O(\epsilon^2)$
 + vary, ϵ fixed \rightarrow motion along each curve
 ϵ vary, t fixed \rightarrow motion across each curves

standard way but we will do it in a different way

$$t^\alpha = \left(\frac{\partial X^\alpha}{\partial t} \right)_\epsilon$$

$$\mathcal{L}_\epsilon t^\alpha = 0 = \mathcal{L}_t \epsilon^\alpha$$

$$\epsilon^\alpha = \left(\frac{\partial X^\alpha}{\partial \epsilon} \right)_t$$

$$\begin{aligned} \mathcal{L}_\epsilon t^\alpha &= \epsilon^\beta \partial_\beta t^\alpha - t^\beta \partial_\beta \epsilon^\alpha \\ &= \left(\frac{\partial X^\beta}{\partial \epsilon} \right) \left(\frac{\partial t^\alpha}{\partial X^\beta} \right) - \left(\frac{\partial X^\beta}{\partial t} \right) \left(\frac{\partial \epsilon^\alpha}{\partial X^\beta} \right) \\ &= \left(\frac{\partial t^\alpha}{\partial \epsilon} \right) - \left(\frac{\partial \epsilon^\alpha}{\partial t} \right) = \frac{\partial}{\partial \epsilon} \frac{\partial X^\alpha}{\partial t} - \frac{\partial}{\partial t} \frac{\partial X^\alpha}{\partial \epsilon} = 0 \end{aligned}$$

For all curves
 $t(P) = 0$
 $t(Q) = 1$



$$\begin{aligned} d\tau^2 &= -ds^2 = -g_{\alpha\beta} dx^\alpha dx^\beta \quad d\tau: \text{proper time} \\ d\tau &= \sqrt{-g_{\alpha\beta} dx^\alpha dx^\beta} \\ &= \sqrt{-g_{\alpha\beta} \frac{dx^\alpha}{dt} \frac{dx^\beta}{dt}} dt = \sqrt{-g_{\alpha\beta} t^\alpha t^\beta} dt \end{aligned}$$

$$\Delta\tau = \int_P^Q \sqrt{-g_{\alpha\beta} t^\alpha t^\beta} dt$$

$$S = - \int_0^1 \sqrt{-g_{\alpha\beta} t^\alpha t^\beta} dt$$

$$L = - \sqrt{-g_{\alpha\beta} t^\alpha t^\beta} \Rightarrow L = L(g_{\alpha\beta}, t^\alpha)$$

$$\begin{aligned} \delta S &= S(\epsilon) - S(0) = \epsilon \left. \frac{\partial S}{\partial \epsilon} \right|_{\epsilon=0} = \epsilon \int_0^1 \frac{\partial L}{\partial \epsilon} dt \\ \frac{\partial L}{\partial \epsilon} &= \epsilon^\mu \partial_\mu L = \epsilon^\mu \nabla_\mu L = \epsilon^\mu \left(\frac{\partial L}{\partial g_{\alpha\beta}} \nabla_\mu g_{\alpha\beta} + \frac{\partial L}{\partial t^\alpha} \nabla_\mu t^\alpha \right) \\ &= \frac{\partial L}{\partial t^\alpha} \epsilon^\mu \nabla_\mu t^\alpha = p_\alpha t^\mu \nabla_\mu \epsilon^\alpha \end{aligned}$$

$$\frac{\partial L}{\partial \epsilon} = p_\alpha t^\mu \nabla_\mu \epsilon^\alpha = p_\alpha \frac{D\epsilon^\alpha}{dt}$$

$$\epsilon^{-1} \delta S = \int_0^1 p_\alpha \frac{D\epsilon^\alpha}{dt} dt = \int_0^1 \left(\frac{D}{dt} (p_\alpha \epsilon^\alpha) - \epsilon^\alpha \frac{Dp_\alpha}{dt} \right) dt$$

$D=d$

$$\varepsilon^{-1} \delta S = \underbrace{p_\alpha \varepsilon^\alpha}_0 - \int_0^1 \varepsilon^\alpha \frac{dp_\alpha}{dt} dt = 0$$

All of the variations
begin at P and end at Q

Rules of variation: ε^α is arbitrary between P and Q, but zero at P and Q

$$\frac{dp_\alpha}{dt} = 0 \quad (\text{geodesic equation})$$

$$p_\alpha = \frac{\partial L}{\partial \dot{x}^\alpha} ; L = -\sqrt{-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta}$$

$$L = -(-g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu)^{1/2}$$

$$p_\alpha = \frac{\partial L}{\partial \dot{x}^\alpha} = -\frac{1}{2} (-g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu)^{-1/2} \cdot (-g_{\mu\nu}) \left(\frac{\partial \dot{x}^\mu}{\partial \dot{x}^\alpha} \dot{x}^\nu + \dot{x}^\mu \frac{\partial \dot{x}^\nu}{\partial \dot{x}^\alpha} \right)$$

$$= \frac{1}{2} \frac{1}{(-L)} (g_{\alpha\nu} \dot{x}^\nu + g_{\mu\alpha} \dot{x}^\mu)$$

$$p_\alpha = -\frac{1}{L} \dot{x}^\alpha$$

$$p_\alpha = -\frac{1}{L} \dot{x}^\alpha$$

$$\frac{dp_\alpha}{dt} = 0 \rightarrow \frac{d}{dt} \left(\frac{\dot{x}^\alpha}{1-L} \right) = \left(\frac{1}{1-L} \right) \frac{d\dot{x}^\alpha}{dt} - \left(\frac{1}{1-L^2} \right) \frac{d(-L)}{dt} \dot{x}^\alpha = 0$$

$$\frac{d\dot{x}^\alpha}{dt} = \frac{1}{(-L)} \frac{d(-L)}{dt} \dot{x}^\alpha$$

$$\frac{d\dot{x}^\alpha}{dt} = K \dot{x}^\alpha$$

Affine variation, we choose $t \equiv$ proper time τ

$$L = -1, K = 0$$

$$L = -\sqrt{-g_{\alpha\beta} \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau}} = -\sqrt{\frac{d\tau^2}{d\tau^2}} = -1$$

$$\boxed{\frac{d}{d\tau} \left(\frac{dx^\alpha}{d\tau} \right) = 0}$$

geodesic equation
(proper time parametrization)

Killing's eqn: $\nabla_\alpha \xi_\beta + \nabla_\beta \xi_\alpha = 0$

$$\text{Geodesic eqn.} \begin{cases} \dot{x}^\alpha = \frac{dx^\alpha}{d\tau} \rightarrow \frac{d\dot{x}^\alpha}{d\tau} = K \dot{x}^\alpha \\ u^\alpha = \frac{dx^\alpha}{d\tau} \rightarrow \frac{du^\alpha}{d\tau} = 0 \end{cases}$$

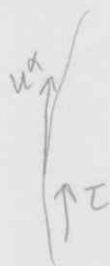
$\tau \rightarrow \frac{a\tau+b}{c}$: leaves unchanged the
affine
parameter
eqn

$$\frac{d}{d\tau} = \frac{d}{dt} + \Gamma^\alpha_{\beta\gamma} u^\beta \frac{d}{d\tau}$$

$$\frac{d^2 x^\alpha}{d\tau^2} + \Gamma^\alpha_{\beta\gamma} \frac{dx^\beta}{d\tau} \frac{dx^\gamma}{d\tau} = 0$$

Conserved quantities

Assume: geodesic: $\frac{Du^\alpha}{d\tau} = 0$



Killing vector ξ^α

Conserved quantity: $C = u_\alpha \xi^\alpha$

$$\frac{dC}{d\tau} = 0$$

$$\frac{dC}{d\tau} = \frac{D(u_\alpha \xi^\alpha)}{d\tau} = \frac{Du_\alpha}{d\tau} \xi^\alpha + u_\alpha \frac{D\xi^\alpha}{d\tau} = u^\alpha \frac{D\xi_\alpha}{d\tau}$$

$$= \underbrace{u^\alpha u^\beta \nabla_\beta \xi_\alpha}_{\text{symmetric antisymmetric}} = 0$$

$$= \frac{1}{2} u^\alpha u^\beta \nabla_\beta \xi_\alpha + \frac{1}{2} u^\beta u^\alpha \nabla_\alpha \xi_\beta = \frac{1}{2} u^\alpha u^\beta (\nabla_\beta \xi_\alpha + \nabla_\alpha \xi_\beta) = 0$$

Example:

$$ds^2 = -A(r)dt^2 + B(r)dr^2 + r^2 d\Omega^2$$

$$\xi^\alpha_{(t)} = (1, 0, 0, 0), \quad \xi^\alpha_{(\phi)} = (0, 0, 0, 1)$$

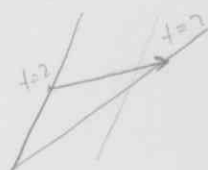
$$\tilde{E} = -u_\alpha \xi^\alpha_{(t)} \equiv \frac{\text{Energy at infinity}}{\text{mass}}$$

$$\tilde{L} = u_\alpha \xi^\alpha_{(\phi)} \equiv \frac{\text{Angular momentum at infinity}}{\text{mass}}$$

Curvature

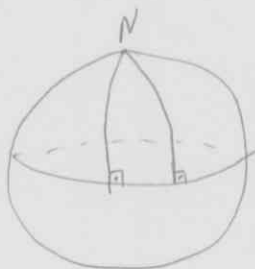
$$[\nabla_\alpha, \nabla_\beta] A^\mu = \underbrace{R^\mu{}_{\nu\alpha\beta}}_{\text{Riemann curvature tensor}} A^\nu$$

Flat space:



- zero relative acceleration
- non zero relative velocity

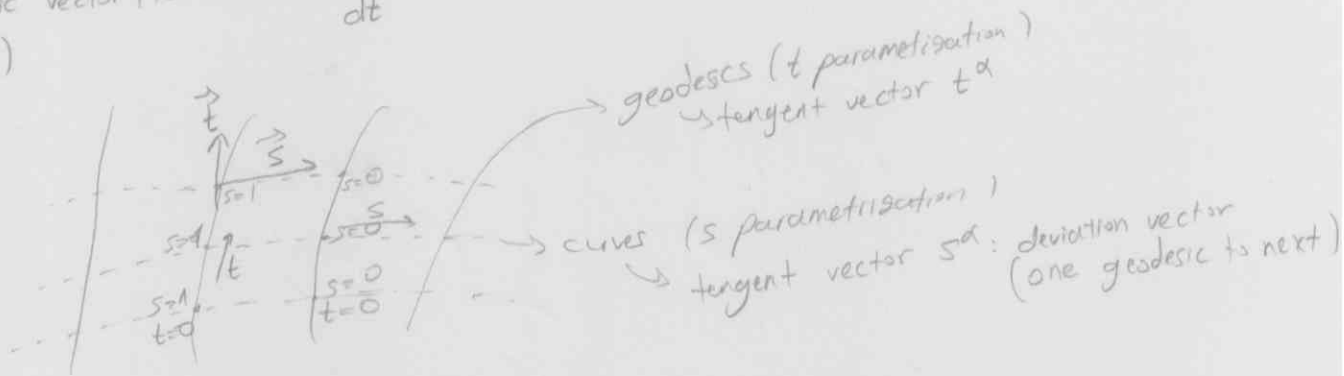
sphere:



- non zero relative acceleration
- non zero relative velocity

Geometrical set up:

geodesic vector-field t^α ; $\frac{Dt^\alpha}{dt} = 0$; $t^\beta \nabla_\beta t^\alpha = 0$
(affine)



two parameter family of curves

$$X^\alpha(t, s)$$

s fixed, t varies \rightarrow geodesic $t^\alpha = \left(\frac{\partial X^\alpha}{\partial t} \right)_s$
 t fixed, s varies \rightarrow cross curves $s^\alpha = \left(\frac{\partial X^\alpha}{\partial s} \right)_t$

$$\mathcal{L}_s t^\alpha = 0 = \mathcal{L}_t s^\alpha$$

$$s^\beta \nabla_\beta t^\alpha = t^\beta \nabla_\beta s^\alpha$$

relative separation between geodesics: s^α

relative velocity between geodesics: $\frac{Ds^\alpha}{dt} = t^\beta \nabla_\beta s^\alpha$

relative acceleration between geodesics: $\frac{D}{dt} \left(\frac{Ds^\alpha}{dt} \right) = t^\gamma \nabla_\gamma (t^\beta \nabla_\beta s^\alpha)$

$$\begin{aligned} \frac{D^2 s^\alpha}{dt^2} &= t^\gamma \nabla_\gamma (s^\beta \nabla_\beta t^\alpha) - (t^\gamma \nabla_\gamma s^\beta) \nabla_\beta t^\alpha + t^\gamma s^\beta \nabla_\gamma \nabla_\beta t^\alpha \\ &= \underbrace{(t^\gamma \nabla_\gamma s^\beta) \nabla_\beta t^\alpha}_{(2)} + t^\gamma s^\beta \underbrace{(\nabla_\gamma \nabla_\beta - \nabla_\beta \nabla_\gamma) t^\alpha}_{R^\alpha_{\mu\gamma\beta} t^\mu} + \underbrace{t^\gamma s^\beta \nabla_\gamma \nabla_\beta t^\alpha}_{(1)} \end{aligned}$$

$$(1) = s^\beta \nabla_\beta (t^\gamma \nabla_\gamma t^\alpha) - (s^\beta \nabla_\beta t^\gamma) \nabla_\gamma t^\alpha$$

$$\frac{Dt^\alpha}{dt} = 0$$

$$(1) = -(s^\beta \nabla_\beta t^\gamma) \nabla_\gamma t^\alpha$$

$$(2) = (t^\gamma \nabla_\gamma s^\beta) \nabla_\beta t^\alpha = (s^\gamma \nabla_\gamma t^\beta) \nabla_\beta t^\alpha \quad \} (1) + (2) = 2$$

$$\frac{D^2 s^\alpha}{dt^2} = R^\alpha_{\mu\gamma\beta} t^\mu t^\gamma s^\beta = -R^\alpha_{\mu\beta\gamma} t^\mu s^\beta t^\gamma$$

gravity \longleftrightarrow Riemann

• Curved manifold is locally flat

Pick a point P in space time

There exist coordinates x^μ such that

$$g_{\mu\nu}(P) \stackrel{*}{=} \eta_{\mu\nu}$$

$$\Gamma^\lambda_{\mu\nu}(P) \stackrel{*}{=} 0 \iff \partial_\lambda g_{\mu\nu}(P) \stackrel{*}{=} 0$$

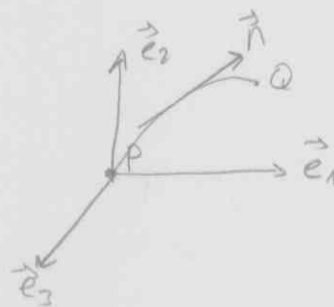
$$\partial_\lambda \partial_\rho g_{\mu\nu}(P) \neq 0 \iff R^\lambda{}_{\rho\mu\nu}(P) \neq 0$$

1- Construct orthonormal basis $e^\alpha_{(\mu)}$ at P

$$g_{\alpha\beta} e^\alpha_{(\mu)} e^\beta_{(\nu)} = \eta_{\mu\nu}$$

2- Select the unique geodesic that relates Q to P

Tangent vector n^α . ($g_{\alpha\beta} n^\alpha n^\beta = \pm 1$)



3- Decompose tangent vector in orthonormal basis

$$n^\alpha = \underbrace{n^{(\mu)}}_{\text{coefficients}} e^\alpha_{(\mu)}$$

4- $x^\mu_Q = (\text{proper time or distance between } P \text{ and } Q) \cdot n^{(\mu)}$

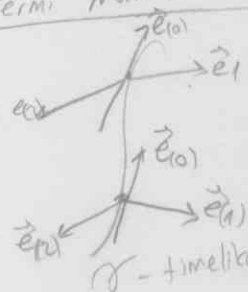
$$\rightarrow g_{\mu\nu} = \eta_{\mu\nu} - \frac{1}{3} \frac{R_{\mu\lambda\nu\rho}(P)}{1/R^2} \frac{x^\lambda x^\rho}{\sim s^2} + O(s^3/R^3)$$

R : Radius of the curvature

$$g_{\mu\nu}(P) \stackrel{x=0}{=} \eta_{\mu\nu}$$

$$\partial_\lambda g_{\mu\nu}(P) \stackrel{x=0}{=} 0 \iff \Gamma^\lambda_{\mu\nu}(P) = 0$$

Fermi Normal Coordinates

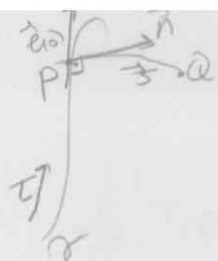


1- Pick a point on γ , construct an orthonormal basis with $e^\alpha_{(0)} = u^\alpha$

$$g_{\alpha\beta} e^\alpha_{(\mu)} e^\beta_{(\nu)} = \eta_{\mu\nu}$$

2- Define $e^\alpha_{(\mu)}$ at any point on γ by parallel transport

$$\frac{D e^\alpha_{(\mu)}}{dt} = u^\beta \nabla_\beta e^\alpha_{(\mu)} = 0$$



3- we are going to select the unique geodesic that lies in the class σ orthogonally.

on σ , $g_{\mu\nu} n^\mu e_{\nu 0}^P = 0$: $\vec{e}_{(0)} \cdot \vec{n} = 0$ due to orthogonality

4- Decomposition of the tangent vector \vec{n} into the orthonormal basis that lives at that point of encounter

$n^\alpha = n^{(\hat{j})} e_{(\hat{j})}^\alpha$ (that excludes $e_{(0)}^\alpha$ because of the (3-))

Fermi coordinates: t_Q = proper time at intersection point P
 $\tau(P) = t_Q$

$X_{\hat{Q}}^{\hat{j}} = \left(\text{proper distance from } P \text{ to } Q \right) n^{(\hat{j})}$

$$g_{tt} = -1 - R_{tptq}(t) X^p X^q + O(S^3/R^3)$$

$$g_{tj} = \frac{2}{3} R_{jptq}(t) X^p X^q + O(S^3/R^3)$$

$$g_{jk} = \delta_{jk} - \frac{1}{3} R_{jpkq} X^p X^q + O(S^3/R^3)$$

$$g_{\mu\nu}(\sigma) = \eta_{\mu\nu}$$

$$\Gamma_{\mu\nu}^\lambda(\sigma) = 0$$

$$2-) \quad t^\alpha = \frac{dx^\alpha}{d\lambda} \quad u^\alpha = \frac{dx^\alpha}{d\lambda^2}$$

$$\frac{Dt^\alpha}{d\lambda} = K t^\alpha$$

$$\frac{Du^\alpha}{d\lambda^2} = 0$$

$$u^\alpha = \frac{d\lambda}{d\lambda^2} \frac{dx^\alpha}{d\lambda} = \frac{d\lambda}{d\lambda^2} t^\alpha$$

$$\begin{aligned} \frac{Du^\alpha}{d\lambda^2} &= \frac{d\lambda}{d\lambda^2} \frac{Du^\alpha}{d\lambda} = \frac{d\lambda}{d\lambda^2} \frac{D}{d\lambda} \left(\frac{d\lambda}{d\lambda^2} t^\alpha \right) \\ &= \frac{d\lambda}{d\lambda^2} \left(\underbrace{\frac{Dt^\alpha}{d\lambda}}_{K t^\alpha} \frac{d\lambda}{d\lambda^2} + \frac{D}{d\lambda} \left(\frac{d\lambda}{d\lambda^2} \right) t^\alpha \right) = 0 \end{aligned}$$

$$K t^\alpha \left(\frac{d\lambda}{d\lambda^2} \right) + \frac{D}{d\lambda} \left(\frac{d\lambda}{d\lambda^2} \right) t^\alpha = 0$$

$$\frac{D}{d\lambda} f = -K f$$

$$\int \frac{df}{f} = \int -K d\lambda$$

$$\frac{d\lambda^2}{d\lambda} = e^{\int K(\lambda) d\lambda}$$

$D=d$ for scalar functions

$$f = e^{-\int K(\lambda) d\lambda} = \frac{d\lambda}{d\lambda^2}$$

3-)

$$a-) \quad \varepsilon = -t_\alpha t^\alpha$$

$$\frac{D\varepsilon}{d\lambda} = -2t_\alpha \frac{Dt^\alpha}{d\lambda} = -2t_\alpha K t^\alpha = +2\varepsilon K$$

$D=d$ for scalar

$$\frac{d\varepsilon}{d\lambda} = +2\varepsilon K$$

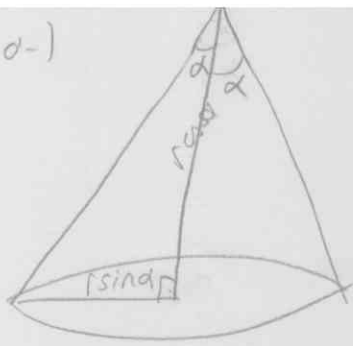
$$\boxed{\varepsilon = \varepsilon_0 e^{+2 \int \varepsilon(\lambda) K(\lambda) d\lambda}}$$

$$b) \quad P = \int_\alpha t^\alpha$$

$$\frac{D}{d\lambda} \left(\frac{\int_\alpha t^\alpha}{P} \right) = \frac{D(\int_\alpha)}{d\lambda} t^\alpha + \int_\alpha \frac{Dt^\alpha}{d\lambda} = \underbrace{\frac{t^\alpha t^\alpha}{P}}_{\text{symmetric}} \underbrace{\frac{D P}{d\lambda}}_{\text{anti-symmetric}} + \int_\alpha K t^\alpha = P K$$

$$P = P_0 e^{\int K d\lambda}$$

a-)



$$z = r \cos \alpha$$

$$\rho = r \sin \alpha$$

$$ds^2 = d\rho^2 + \rho^2 d\phi^2 + dz^2 \quad \text{cylinder metric}$$

$$d\rho = dr \sin \alpha$$

$$dz = dr \cos \alpha$$

$$ds^2 = \underline{dr^2 \sin^2 \alpha} + r^2 \sin^2 \alpha d\phi^2 + \underline{dr^2 \cos^2 \alpha}$$

$$= dr^2 + r^2 \sin^2 \alpha d\phi^2$$

$$ds^2 = dr^2 + \underline{(r \sin \alpha)^2} d\phi^2$$

b) $x = r \cos \phi$

c) $y = r \sin \phi$

$$\} \rightarrow dx^2 + dy^2 = dr^2 + \underline{r^2} d\phi^2$$

$$\phi' = \phi \sin \alpha$$

$$x = r \cos \phi'$$

$$y = r \sin \phi'$$

$$dx = dr \cos \phi' - r \sin \phi' \sin \phi' d\phi'$$

$$dy = dr \sin \phi' + r \sin \phi' \cos \phi' d\phi'$$

$$dx^2 + dy^2 = dr^2 + r^2 \sin^2 \alpha d\phi'^2 //$$

$$0 \leq \phi \leq 2\pi \rightarrow$$

covers the whole plane

$$0 \leq \phi' \leq 2\pi \sin \alpha$$

$$0 \leq \underbrace{\phi - \phi'}_{\Delta \phi} \leq 2\pi(1 - \sin \alpha)$$

There is a missing part $\Delta \phi = 2\pi(1 - \sin \alpha) = \beta$