

CSC 317: Data Structures and Algorithm Analysis

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Outline I

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Divide-and-Conquer Approach

- Insertion Sort – **incremental approach**
 - It increased length of sorted section by one in each iteration
- **Divide-and-conquer approach**
 - **Divide** the problem into a number of smaller sub-problems of the same problem
 - **Conquer** the sub-problems by solving them recursively
 - **Combine** the solutions to the sub-problems into the solution of the original problem

Divide-and-Conquer for Sorting

- **Problem:** An array $A[1..n]$ has n unsorted elements, $A[1], A[2], \dots, A[n]$
- Find a **divide-and-conquer** algorithm to sort the array
- Here is the algorithm
 - **Divide:** $A[1], A[2], \dots, A[n]$ into two subarrays
 - $A[1..k]$ and $A[k+1 .. n]$
 - Best if k is the middle element of $A[1..n]$
 - **Conquer:** recursively sort $A[1..k]$ and $A[k+1 .. n]$
 - **Combine:** merge $A[1..k]$ and $A[k+1 .. n]$, if necessary
- Time complexity $T(n)$??
 - Time for dividing the problem in to two subproblems $T_{divide}(n)$
 - Time for sorting $A[1..k]$ $T(k)$
 - Time for sorting $A[k+1..n]$ $T(n - k)$
 - Time for combining sorted subarrays $A[1..k]$ and $A[k+1 .. n]$ $T_{combine}(n)$
 - $T(n) = T_{divide}(n) + [T(k) + T(n - k)] + T_{combine}(n)$

Divide-and-Conquer: Example 1 — Merge Sort

- Data is in array **A**
- We want to sort elements in **A[p .. r]**
- **Divide** the problem into two sub-problems
 - Find **A[q]** such that, **A[q]** is approximately at the middle of **A[p .. r]**
 - We compute $q = \lfloor (p + r)/2 \rfloor$
 - Divide the problem into two subproblems **A[p .. q]** and **A[q+1 .. r]**
- **Conquer** — Solve each subproblem recursively
 - Merge sort items in **A[p .. q]**, and **A[q+1 .. r]**
 - Merge sort items in **A[q+1 .. r]**

```

MERGE-SORT(A, p, r)
1  if p < r
2    q = ⌊(p + r)/2⌋
3    MERGE-SORT(A, p, q)
4    MERGE-SORT(A, q + 1, r)
5    MERGE(A, p, q, r)

```

Figure: Merge sort algorithm

- **Combine** sorted items in **A[p .. q]** and **A[q + 1 .. r]**
 - We use **MERGE(A, p, q, r)** function for combining
 - $T(n) = T_{\text{divide}}(n) + [T(k) + T(n - k)] + T_{\text{combine}}(n)$
 - $T(n) = O(1) + [T(\lfloor n/2 \rfloor) + T(\lceil n/2 \rceil)] + O(n)$

Combine two sorted subarrays: Merge procedure

```

MERGE(A, p, q, r)
1  n1 = q - p + 1
2  n2 = r - q
3  let L[1 .. n1 + 1] and R[1 .. n2 + 1] be new arrays
4  for i = 1 to n1
5    L[i] = A[p + i - 1]
6  for j = 1 to n2
7    R[j] = A[q + j]
8  L[n1 + 1] = ∞
9  R[n2 + 1] = ∞
10 i = 1
11 j = 1
12 for k = p to r
13   if L[i] ≤ R[j]
14     A[k] = L[i]
15     i = i + 1
16   else A[k] = R[j]
17     j = j + 1

```

- We want to merge elements in
 - **A[p .. q]** and **A[q+1 .. r]**

- Lines 1 and 2: determine lengths of two subarrays
- line 3: creates two new arrays L and R
- Lines 4-5: copy **A[p .. q]** in L
- Lines 6-7: copy **A[q+1 .. r]** in R
- Lines 8-9: mark right ends of L and R
- Lines 10-11: i and j are pointers for arrays L and R; initial values 1 and 1
- Line 12 to 17: merge items in L and R stores in A
- What is the time complexity?
- Use **loop invariant** to proof correctness of the procedure
- We need to consider only lines 12 to 17 for inductive proof

Divide-and-Conquer: Example 2 — Quicksort

```
QUICKSORT( $A, p, r$ )  
1  if  $p < r$   
2     $q = \text{PARTITION}(A, p, r)$   
3    QUICKSORT( $A, p, q - 1$ )  
4    QUICKSORT( $A, q + 1, r$ )
```

- The procedure sorts elements in $A[p \dots r]$
- Line 1: if number of items more than one, partition at q
- Line 2: the array is partitioned
 - q is determined by $\text{PARTITION}(A, p, r)$
 - After partition
 - Items in $A[p \dots q-1]$ are \leq than $A[q]$
 - Items in $A[q+1 \dots r]$ are $>$ than $A[q]$
- Line 3 Sort items in $A[p \dots q-1]$ recursively
- Line 4: Sorts items in $A[q+1 \dots r]$ recursively

Divide-and-conquer: Divide the Problem

```
PARTITION( $A, p, r$ )  
1   $x = A[r]$   
2   $i = p - 1$   
3  for  $j = p$  to  $r - 1$   
4    if  $A[j] \leq x$   
5       $i = i + 1$   
6      exchange  $A[i]$  with  $A[j]$   
7  exchange  $A[i + 1]$  with  $A[r]$   
8  return  $i + 1$ 
```

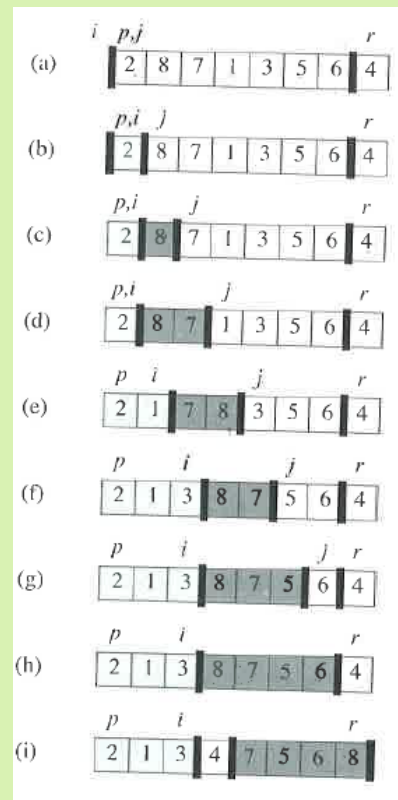
- Use item in $A[r]$ as pivot element
- Items $\leq A[r]$ in $A[p, r]$ are moved to the left
- Items $> A[r]$ in $A[p, r]$ are moved to the right
- This will leave a position open, where $A[r]$ is inserted

Partitioning: An example

PARTITION(A, p, r)

```

1   $x = A[r]$ 
2   $i = p - 1$ 
3  for  $j = p$  to  $r - 1$ 
4      if  $A[j] \leq x$ 
5           $i = i + 1$ 
6          exchange  $A[i]$  with  $A[j]$ 
7  exchange  $A[i + 1]$  with  $A[r]$ 
8  return  $i + 1$ 
    
```



Why we need O , Ω , and Θ ?

- Time complexity $T(n)$ of the MERGE SORT algorithm shown to the right can be a recurrence equation
- $T(n) = c_1 + T(\lfloor n/2 \rfloor) + T(\lceil n/2 \rceil) + c_2 n$
- Solving the equation above is simplified if we use only $T(\lfloor n/2 \rfloor)$ or $T(\lceil n/2 \rceil)$
- But that will lead to inequalities
 - $T(n) \geq c_1 + 2T(\lfloor n/2 \rfloor) + c_2 n$, and
 - $T(n) \leq c_1 + 2T(\lceil n/2 \rceil) + c_2 n$,
- If we solve the first inequality, the expression obtained would be lower than what would be obtained if we solve the original equation
 - This expression would be $\Omega(T(n))$, **asymptotic lower bound**
- If we solve the second inequality, the expression obtained would be higher than what would be obtained if we solve the original equation
 - This expression would be $O(T(n))$, **asymptotic upper bound**

MERGE-SORT(A, p, r)

```

1  if  $p < r$ 
2       $q = \lfloor (p + r) / 2 \rfloor$ 
3      MERGE-SORT( $A, p, q$ )
4      MERGE-SORT( $A, q + 1, r$ )
5      MERGE( $A, p, q, r$ )
    
```

Figure: Merge Sort Algorithm

- If we solve the original equation, we would get $\Theta(T(n))$.
- Note: lower bound for problem is NOT **asymptotic lower bound** of an algorithm
- Note: upper bound for problem is NOT **asymptotic upper bound** of an algorithm

O — asymptotic upper bound

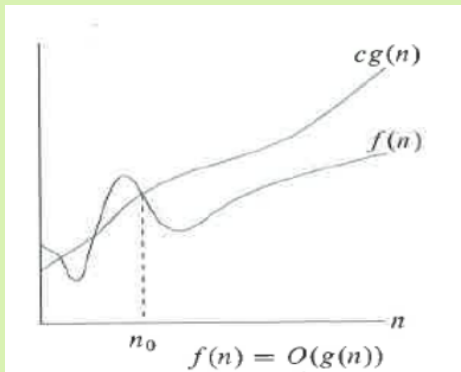
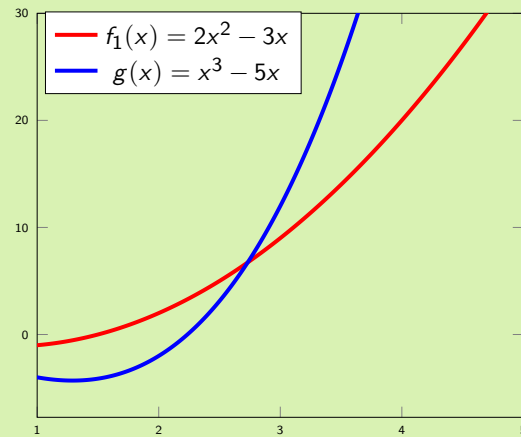


Figure: Illustration of big 'oh' concept

For a given function $g(n)$, the $O(g(n))$ denotes a set of functions,

$$O(g(n)) = \{f(n) : \text{there exist } c \text{ and } n_0 \text{ such that } 0 \leq f(n) \leq cg(n) \text{ for all } n \geq n_0\}$$



- $O(g(x)) = O(x^3 - 5x) = x^3 - 5x$
- For $x = 2$, $f_1(2) = 2(2^2) - 3 \times 2 = 2$
- For $x = 2$, $g(2) = 2^3 - 5 \times 2 = -2$
- For $x = 3$, $f_1(3) = 2(3^2) - 3 \times 3 = 9$
- For $x = 3$, $g(3) = 3^3 - 5 \times 3 = 12$
- Thus, $f_1(3) < g(3)$
- In general, for $x \geq 3$, $f_1(x) < g(x)$
- Therefore, $O(g(x)) = f_1(x)$

O — asymptotic upper bound

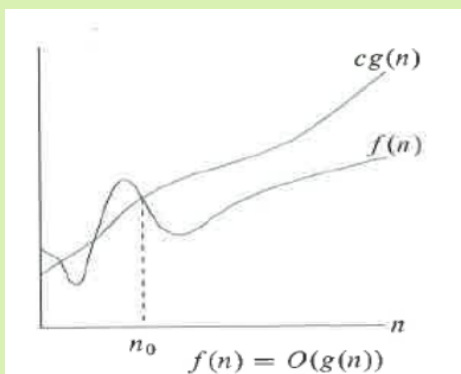
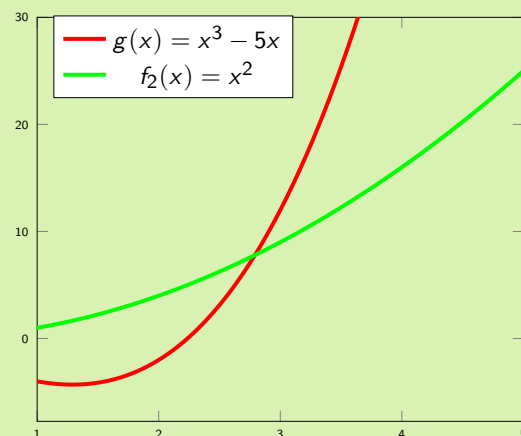


Figure: Illustration of big 'oh' concept

For a given function $g(n)$, the $O(g(n))$ denotes a set of functions,

$$O(g(n)) = \{f(n) : \text{there exist } c \text{ and } n_0 \text{ such that } 0 \leq f(n) \leq cg(n) \text{ for all } n \geq n_0\}$$



- $O(g(x)) = O(x^3 - 5x) = x^3 - 5x$
- For $x = 2$, $f_2(2) = (2^2) = 4$
- For $x = 2$, $g(2) = 2^3 - 5 \times 2 = -2$
- For $x = 3$, $f_2(3) = (3^2) = 9$
- For $x = 3$, $g(3) = 3^3 - 5 \times 3 = 12$
- Thus, $f_2(3) < g(3)$
- In general, for $x \geq 3$, $f_2(x) < g(x)$
- Therefore, $O(g(x)) = f_2(x)$

Ω — asymptotic lower bound

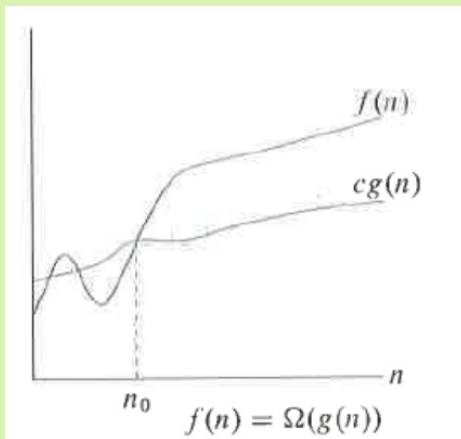
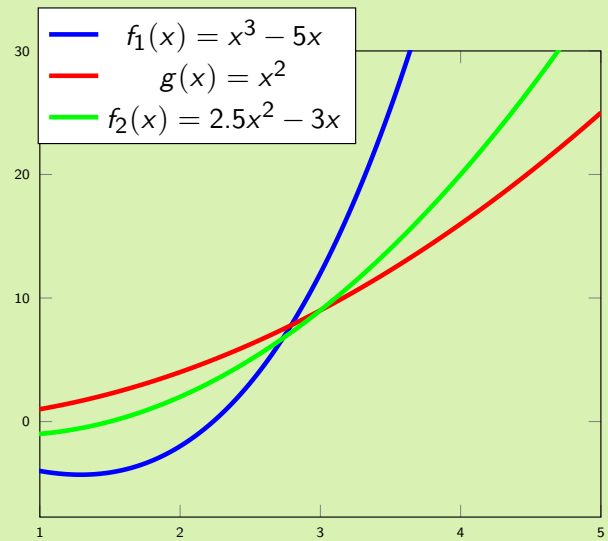


Figure: Big- Ω concept

For a given function $g(n)$, the $\Omega(g(n))$ denotes a set of functions,

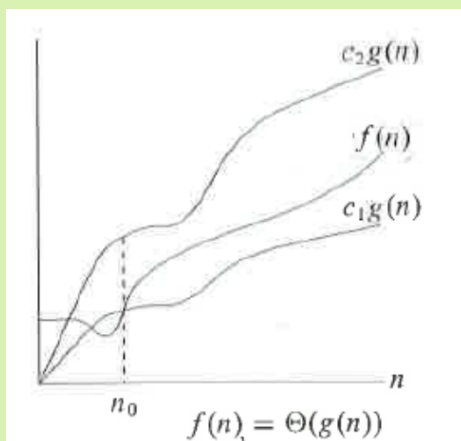
$$\Omega(g(n)) = \{f(n) : \text{there exist } c \text{ and } n_0 \text{ such that } 0 \leq cg(n) \leq f(n) \text{ for all } n \geq n_0\}$$



● $\Omega(g(x)) = \Omega(x^2) = f_1(x)$

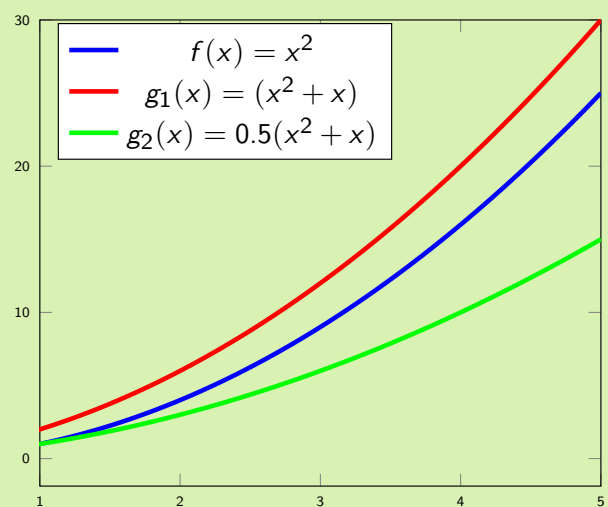
● $\Omega(g(x)) = \Omega(x^2) = f_2(x)$

Θ — asymptotic tight bound



For a given function $g(n)$, the $\Theta(g(n))$ denotes a set of functions,

$$\Theta(g(n)) = \{f(n) : \text{there exist } c_1, c_2 \text{ and } n_0 \text{ such that } 0 \leq c_1g(n) \leq f(n) \leq c_2g(n) \text{ for all } n \geq n_0\}$$



● $\Theta(x^2 + x) = x^2$

O , Ω , and Θ at a glance

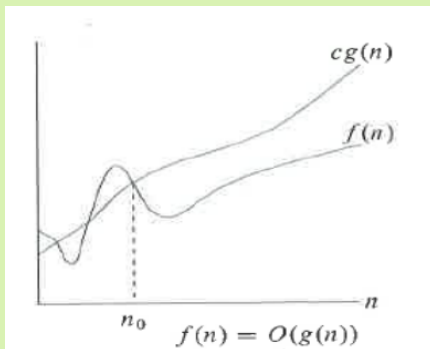


Figure: O concept

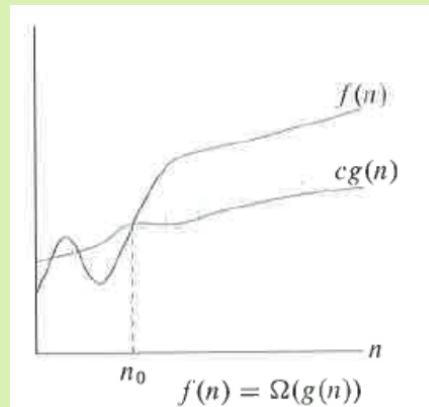


Figure: Ω concept

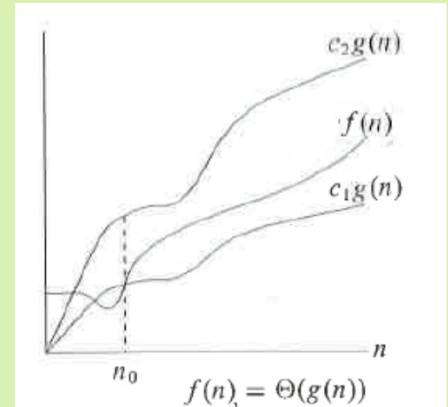


Figure: Θ concept

Theorem 3.1 For any two functions $f(n)$ and $g(n)$, we have $f(n) = \Theta(g(n))$ if and only if $f(n) = O(g(n))$ and $f(n) = \Omega(g(n))$.

Standard notations and common functions

- Monotonicity
 - **Monotonically increasing** function $f(n)$: for $m \leq n \Rightarrow f(m) \leq f(n)$.
 - **Monotonically decreasing** function $f(n)$: for $m \leq n \Rightarrow f(m) \geq f(n)$.
 - **Strictly increasing** function $f(n)$: for $m < n \Rightarrow f(m) < f(n)$.
 - **Strictly decreasing** function $f(n)$: for $m < n \Rightarrow f(m) > f(n)$.

- Floors and ceilings
- Modular arithmetic
- Polynomials
- Exponential
- Logarithms

- Factorials $n! = \sqrt{2\pi n} \left(\frac{n}{e}\right)^n \left(1 + \Theta\left(\frac{1}{n}\right)\right)$

- Functional iteration

$$f^{(i)}(n) = \begin{cases} n & \text{if } i = 0 \\ f(f^{(i-1)}(n)) & \text{if } i > 0 \end{cases} \quad (1)$$

For example, if $f(n) = 2n$, then $f^{(2)}(n) = f(f^{(1)}(n)) = f(f(f^{(0)}(n))) = f(f(n)) = f(2n) = 2 \times 2n = 2^2 n$

- The iterated logarithmic function

$$\lg^* n = \min\{i \geq 0 : \lg^{(i)} n \leq 1\}$$

- Examples, $\lg^* 16 = 3$, $\lg^* 65536 = 4$, $\lg^*(2^{65536}) = 5$
- The value of this function is **really really** small, even for a very large number.