

Advanced Statistical Computing
Week 2: Monte Carlo Study of Statistical
Procedures and Permutation Tests

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Sampling distribution

Sampling distribution

DATA X (possibly equal to (X_1, \dots, X_n))

STATISTIC $T = T(X)$

The distribution of T is called *sampling distribution*

EXAMPLE OF THEORETICAL SAMPLING DISTRIBUTION:

If $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} N(0, \sigma^2)$, then $T = \sqrt{n}\bar{X}/S_X \sim t_{n-1}$

DETERMINATION BY SIMULATION:

- For $b = 1, \dots, B$
 - generate independent replicate X^b of data X
 - compute $T^b = T(X^b)$
- Make a plot (histogram, density, ecdf) of T^1, \dots, T^B .

Standard error

DATA X (possibly equal to (X_1, \dots, X_n))

STATISTIC $T = T(X)$

The standard deviation of T is called *standard error* or *se*

EXAMPLE OF THEORETICAL STANDARD ERROR:

If $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} N(0, \sigma^2)$, then se of \bar{X} is σ/\sqrt{n} .

DETERMINATION OF STANDARD ERROR BY SIMULATION:

- For $b = 1, \dots, B$
 - generate replicate X^b of data
 - compute $T^b = T(X^b)$
- Compute root of sample variance of T^1, \dots, T^B , i.e.

$$\hat{se} = \sqrt{\frac{1}{B} \sum_{b=1}^B (T^b - \bar{T})^2}, \quad \text{where } \bar{T} = \frac{1}{B} \sum_{b=1}^B T^b.$$

Estimators

Bias

DATA X (possibly equal to (X_1, \dots, X_n))

ESTIMATOR $T = T(X)$ OF QUANTITY θ

The bias of T is $ET - \theta$

EXAMPLE OF THEORETICAL BIAS:

If $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} N(\theta, \sigma^2)$, then bias of \bar{X} for θ is 0.

DETERMINATION OF BIAS BY SIMULATION:

- For $b = 1, \dots, B$
 - generate replicate X^b of data
 - compute $T^b = T(X^b)$
- Compute

$$\widehat{bias} = \frac{1}{B} \sum_{b=1}^B T^b - \theta.$$

Mean square error

DATA X (possibly equal to (X_1, \dots, X_n))

ESTIMATOR $T = T(X)$ OF QUANTITY θ

The *mean square error* (MSE) of T is $E(T - \theta)^2$.
(It is also the sum of the squared bias and the squared se.)

EXAMPLE OF THEORETICAL MSE:

If $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} N(\theta, \sigma^2)$, then MSE of \bar{X} for θ is σ^2/n .

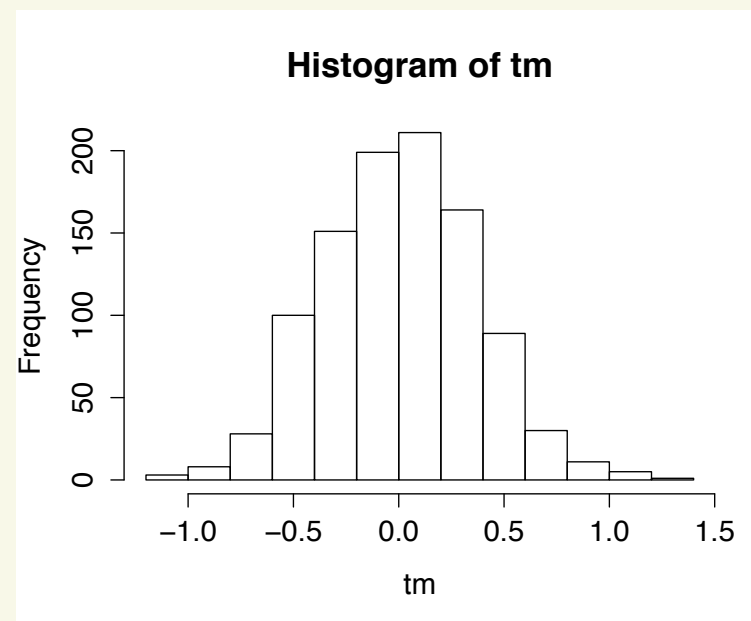
DETERMINATION OF MSE BY SIMULATION:

- For $b = 1, \dots, B$
 - generate replicate X^b of data
 - compute $T^b = T(X^b)$
- Compute mean sum of squares

$$\widehat{MSE} = \frac{1}{B} \sum_{b=1}^B (T^b - \theta)^2.$$

R

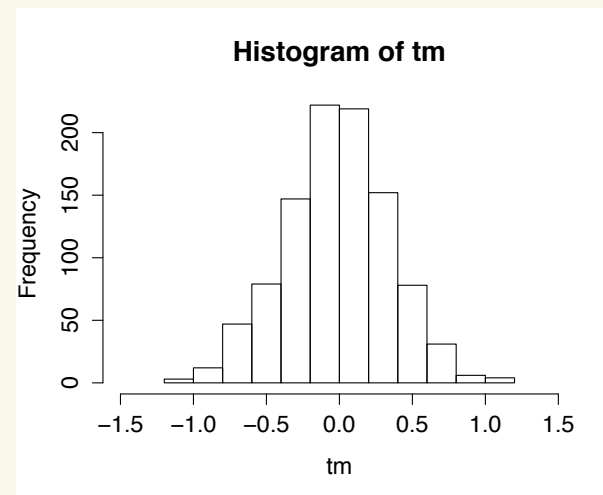
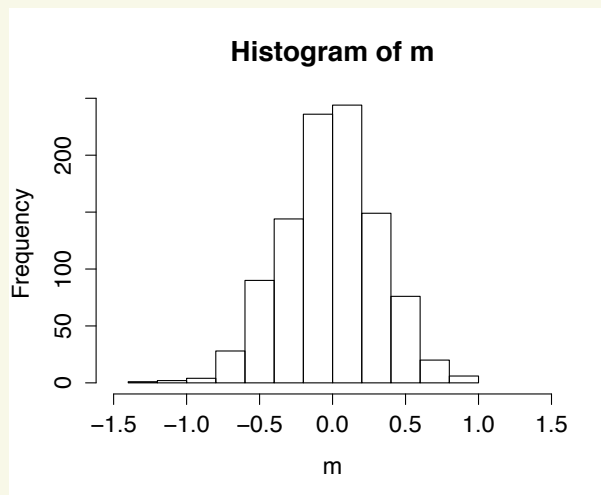
```
> B=1000
> tm = numeric(B)
> for (i in 1: B){ x=rnorm(10)
+                  tm[i]=mean(x,trim=0.3) }
> hist(tm)
> sd(tm)
[1] 0.3638536
> mean(tm)-0
[1] 0.00902773
> mean((tm-0)^2)
[1] 0.1323385
```



```

> B=1000
> m=tm = numeric(B)
> for (i in 1: B){ x=rnorm(10)
+                   m[i]=mean(x)
+                   tm[i]=mean(x,trim=0.3) }
> hist(m,xlim=c(-1.5,1.5)); hist(tm,xlim=c(-1.5,1.5))
> sd(m); sd(tm)
[1] 0.3222936
[1] 0.3566153
> mean(m)-0; mean(tm)-0
[1] -0.009780955
[1] -0.01743183
> mean((m-0)^2); mean((tm-0)^2)
[1] 0.103865
[1] 0.1273511

```



Simulation error

By making B larger the simulation error can be made arbitrarily small.

$B = 10000$ is desirable, but $B = 1000$ typical, and only $B = 100$ may be feasible.

If EZ is estimated by \bar{Z}_B for iid Z^1, \dots, Z^B , then

$$\bar{Z}_B - EZ \sim\sim N(0, \text{var } Z/B).$$

Thus the *se of simulation* is $\sqrt{\text{var } Z/B}$, and can be estimated by

$$\sqrt{B^{-1} \sum_{b=1}^B (Z^b - \bar{Z})^2 / B}.$$

EXAMPLE: If the MSE $E(T - \theta)^2$ is estimated by $\widehat{MSE} = B^{-1} \sum_{b=1}^B (T^b - \theta)^2$, then the *se of simulation* can be estimated by

$$\frac{1}{B} \sqrt{\sum_{b=1}^B [(T^b - \theta)^2 - \widehat{MSE}]^2}.$$

```
> B=100
> tm = numeric(B)
> for (i in 1: B){ x=rnorm(10)
+                 tm[i]=mean(x,trim=0.3) }
> mean((tm-0)^2)
[1] 0.1603573
> sqrt(sum(((tm-0)^2-mean((tm-0)^2))^2)/B # se of simulation error in MSE
[1] 0.02689583
>
> B=1000
> tm = numeric(B)
> for (i in 1: B){ x=rnorm(10)
+                 tm[i]=mean(x,trim=0.3) }
> mean((tm-0)^2)
[1] 0.125947
> sqrt(sum(((tm-0)^2-mean((tm-0)^2))^2)/B # se of simulation error in MSE
[1] 0.005799775
```

Tests

Size

DATA X (possibly equal to (X_1, \dots, X_n))

TEST STATISTIC $T = T(X)$, REJECTS H_0 IF $T \in K$.

The *size* of the test is $\alpha = P_{H_0}(T \in K)$.

EXAMPLE OF THEORETICAL SIZE

Tests are constructed so that the size equals the *level*, e.g. 5%, in prescribed situation.

DETERMINATION OF SIZE BY SIMULATION:

- For $b = 1, \dots, B$
 - generate replicate X^b of data *using its null distribution*
 - compute $T^b = T(X^b)$
- Compute

$$\hat{\alpha} = \frac{1}{B} \sum_{b=1}^B 1_{T^b \in K} = \text{fraction rejections.}$$

[If H_0 is composite, must simulate using the worst case null distribution, or repeatedly simulate using all null distributions and take the maximum of the simulated $\hat{\alpha}$.]

Power

DATA X (possibly equal to (X_1, \dots, X_n))

TEST STATISTIC $T = T(X)$ THAT REJECTS H_0 IF IT FALLS IN CRITICAL REGION K

The *power* is $P_\theta(T \in K)$ viewed as function of the alternative $\theta \in H_1$.

EXAMPLE OF THEORETICAL POWER

Power of the t -test can be expressed using non-central t -distributions.

DETERMINATION OF POWER BY SIMULATION:

- For $b = 1, \dots, B$
 - generate replicate X^b of data *using alternative* θ
 - compute $T^b = T(X^b)$
- Compute

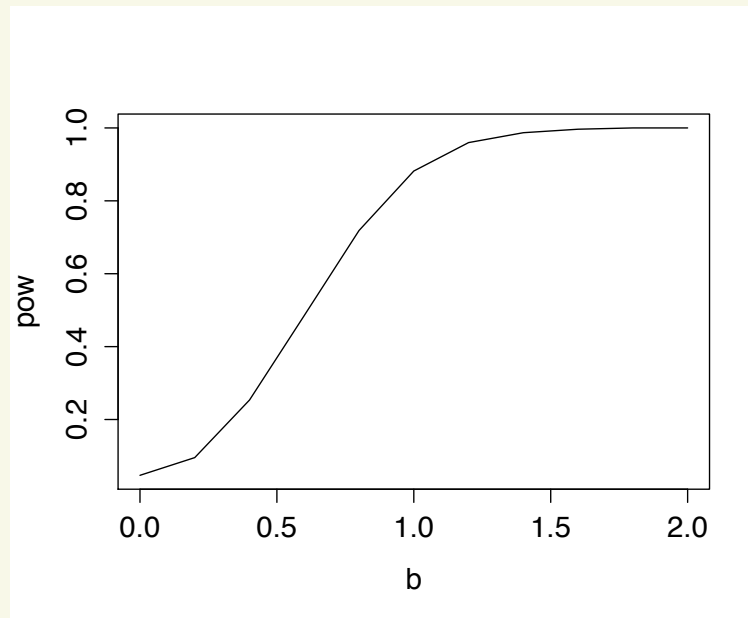
$$\frac{1}{B} \sum_{b=1}^B 1_{T^b \in K}.$$

- Repeat for all alternatives.

```
> tmtest=function(x){n=length(x)
+                      k=trunc(0.3*n)
+                      y=sort(x)[(k+1):(n-k)]
+                      mean(y)/sd(y)}
>
> B=10000
> s=numeric(B)
> for (i in 1:B) s[i]=tmtest(rnorm(20))
> CV=quantile(s,.975)          # determine critical value by simulation
>
> a=numeric(1000)
> B=10000
> for (i in 1:B){x=rnorm(20)
+                a[i]=(abs(tmtest(x))>CV)}
> mean(a)
[1] 0.0478
```


R

```
> b=seq(0,2,by=0.2)
> pow=numeric(length(b))
> for (j in 1:length(b)){
+   t=numeric(B)
+   for (i in 1:B){x=rnorm(20,b[j],1)
+                     t[i]=ttest(x) }
+   pow[j]=mean(abs(t)>CV) }
> plot(b,pow,type="l")
```



[Is it useful to resimulate new normal samples for every b ?]

Coverage

DATA X (possibly equal to (X_1, \dots, X_n))

CONFIDENCE INTERVAL $[L(X), U(X)]$ FOR PARAMETER θ

The *coverage* is $\inf_{\theta} P_{\theta}(L(X) \leq \theta \leq U(X))$

EXAMPLE OF THEORETICAL COVERAGE

Theoretical confidence intervals have given coverage, e.g. 95%, in the prescribed situation.

DETERMINATION OF CONFIDENCE LEVEL BY SIMULATION:

- For $b = 1, \dots, B$
 - generate replicate X^b of data *using parameter* θ
 - compute $L^b = L(X^b)$, $U^b = U(X^b)$,
- Compute

$$\hat{C}_{\theta} = \frac{1}{B} \sum_{b=1}^B 1_{L^b \leq \theta \leq U^b}.$$

- Repeat for all θ . Compute $\min_{\theta} \hat{C}_{\theta}$.

[In practice you cannot use *all* θ .]

Simulation error

By making B larger the simulation error can be made arbitrarily small.

$B = 10000$ is desirable, but $B = 1000$ typical, and only $B = 100$ may be feasible.

When estimating a proportion $p = P(Z = 1)$ by a sample fraction \bar{Z} , for iid $Z_1, \dots, Z_B \in \{0, 1\}$,

$$\bar{Z} - p \sim\sim N(0, p(1 - p)/B).$$

The *se of simulation* can be estimated by

$$\sqrt{\bar{Z}(1 - \bar{Z})/B} \leq \sqrt{1/(4B)}.$$

Permutation Tests

Permutation test

IDEA

Take any reasonable test statistic.

Compare its observed value to the set of values obtained by applying the statistic after *permuting* the data in such a way that the *distribution under H_0 does not change*.

Advantages: very flexible, no theory needed, correct level guaranteed

Disadvantage: computationally very expensive.

The *level is guaranteed*, because:

- conditionally, given any observed data, we reject with probability less than, say 5 %,
- hence unconditionally, we reject with probability less than 5 %.

Two sample test

DATA X_1, \dots, X_m and Y_1, \dots, Y_n independent random samples from F and G .

TEST STATISTIC Reject H_0 if $T = T(X_1, \dots, X_m, Y_1, \dots, Y_n)$ is large.

Let Z_1, \dots, Z_N be the *pooled sample* $X_1, \dots, X_m, Y_1, \dots, Y_n$, i.e. $N = m + n$.

Under $H_0: F = G$ this is i.i.d. and so is every permutation $Z_{\pi(1)}, \dots, Z_{\pi(N)}$.

PERMUTATION TEST

- For every partition b of the observed values z_1, \dots, z_N into 2 sets of sizes m and n compute T^b with the X 's and Y 's taken equal to the two sets.
- For $tobs = T(x_1, \dots, x_m, y_1, \dots, y_n)$ the observed value, compute

$$\hat{p} = \frac{1}{B} \sum_{b=1}^B 1_{T^b > tobs}.$$

IN PRACTICE

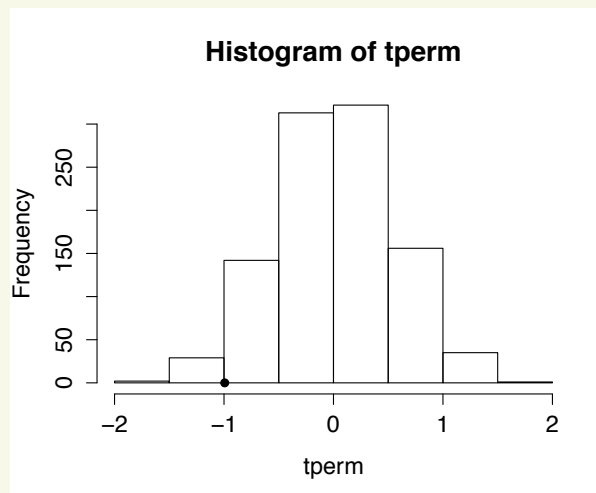
The number of partitions $\binom{N}{m}$ is too large and one takes a large number of *random partitions* instead.

[The observations may be multivariate. E.g. in genomics, of dimension 20000.]

```

> mu=0.5
> x=rnorm(20); y=rnorm(25,mu,2)
> tm2=function(x,y) mean(x,trim=0.2)-mean(y,trim=0.2)
> tobs=tm2(x,y)
> B=1000; tperm=numeric(B)
> z=c(x,y); N=length(z); m=length(x)
> for (i in 1:B) {xco=sample(1:N,m)
+               tperm[i]=tm2(z[xco],z[-xco])}
> mean(tperm>tobs); mean(tperm<tobs)
[1] 0.969
[1] 0.031
>
> tobs
[1] -0.9936397
> hist(tperm); points(tobs,0,pc=19)

```



Paired two-sample test

DATA $(X_1, Y_1), \dots, (X_n, Y_n)$ random sample from bivariate distribution.

TEST STATISTIC Reject H_0 if $T = T(X_1, \dots, X_n, Y_1, \dots, Y_n)$ is large.

Under H_0 : (X, Y) is exchangeable, every of the 2^n possible permutations within the pairs (X_i, Y_i) gives the same distribution.

PERMUTATION TEST

- For every of the 2^n possible (re)assignments b of the X or Y -label within the pairs compute T^b .
- For $t = T(x_1, \dots, x_m, y_1, \dots, y_n)$ the observed value, compute

$$\hat{p} = \frac{1}{B} \sum_{b=1}^B 1_{T^b > t}.$$

IN PRACTICE

The number of (re)assignments 2^n is too large and one takes a large number of *random assignments* instead.

Symmetry

DATA Random sample X_1, \dots, X_n of univariate distribution.

Under the hypothesis H_0 that the distribution is symmetric about 0 $S_1 X_1, \dots, S_n X_n$ and X_1, \dots, X_n have the same distribution for S_1, \dots, S_n random signs.

PERMUTATION TEST

- For every of the 2^n possible sign vectors compute $T^b = T(S_1 X_1, \dots, S_n X_n)$.
- For $t = T(x_1, \dots, x_m, y_1, \dots, y_n)$ the observed value, compute

$$\hat{p} = \frac{1}{B} \sum_{b=1}^B 1_{T^b > t}.$$

IN PRACTICE

The number of sign vectors is too large and one takes a large number of *random sign vectors* instead.

When you do simulations

- Good documentation is essential
- Write separate programs for each case
- Or keep a precise record
- Save as much of the output as you can
- Do that in a structured way (multidimensional arrays)
- Summarize later
- Make programs “re-startable”
- To continue smoothly after a computer crash
- Or to divide the work over more computers