This week:

Clarify who’s doing what

Confirm hardware components

Map out system inputs and outputs

Make high-level block diagram

Do what we can for Technical document

Next week:

Program movement controls (either on controller or other preferred method of control)

Program skeleton communication (at least establish local connection via wireless and static addresses

Put robot together

Complete Technical Document (on Saturday)

Third week:

Spit shine programming (spit is optional)

Test robot and correct accordingly

Correct any alterations needed for Technical document

Turn in week:

Make video presentation (preferably before Wednesday)

Robot and Team picture

Last minute fixes

Turn it in!!!!!! (no later than Friday)