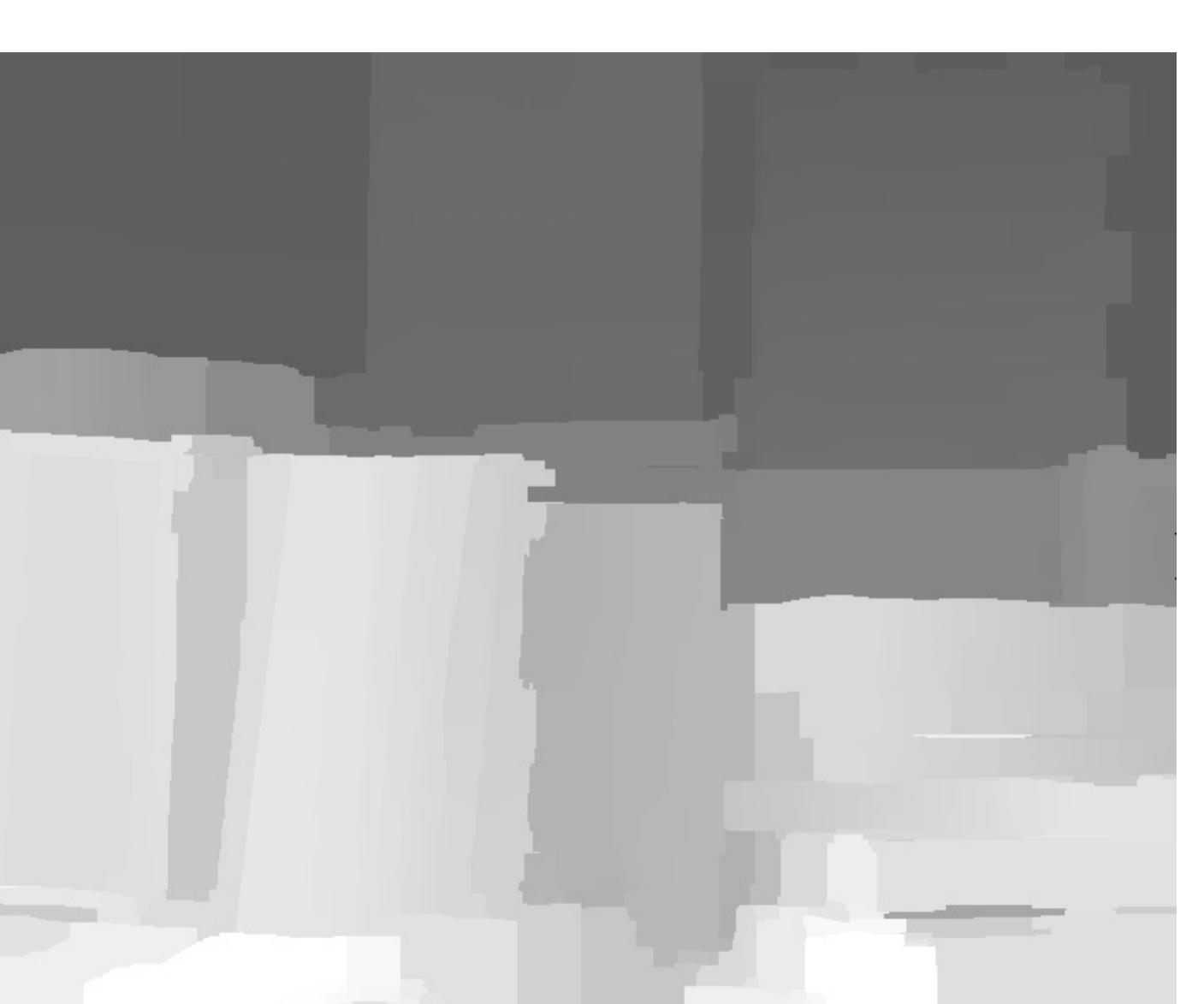


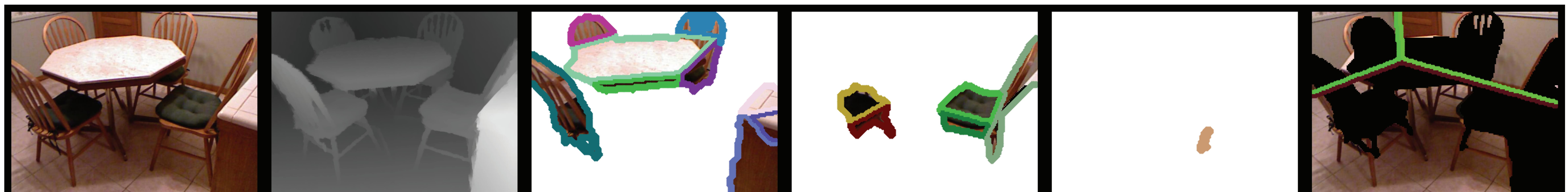
Depthmap stereo



Optical flow



Layered depthmap estimation



Input image

Input depthmap



Output layered depthmap

