ExaNLA Survey Response Report

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Submission Details

Library Name: CASTEP

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Selected NLA Operations

1. Other NLA Operation

2. Symmetric/Hermitian Eigenvalue Problems

3. Matrix-Matrix Multiplication (GEMM)

1. Codes Information

Basic information about your application/simulation codes.

Library Name:

CASTEP

Current Version:

25.1.2

Contact Information:

Not specified

Name:

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Organization:

University of York

Application Domain:

Not specified

What is the primary application domain of your codes?:

Materials Science

Materials Science:

Not specified

What are the main functionalities of your code?:

Ground state DFT, Time-dependent DFT, Crystal structure prediction, Molecular dynamics, Excited-state dynamics, Phase transitions, Defect calculations, Surface science, Other

If you selected "Other", please specify::

Vibrational spectra (IR, Raman, INS), NMR spectra, Core-loss and low-loss EELS, optical properties

Climate/Weather Modeling:

What are the main functionalities of your code?:

Not specified

If you selected "Other", please specify::

Not specified

Fluid Dynamics:

Not specified

What are the main functionalities of your code?:

Not specified

If you selected "Other", please specify::

Not specified

Other Domain Functions:

Not specified

What are the main functionalities of your code?:

Not specified

Use Case Information:

Not specified

Does your codes have multiple distinct use cases?:

Yes, multiple distinct use cases

Which use case are you describing in this submission?:

Ground state DFT

Library Description:

Density functional theory for materials modelling, using the plane-wave pseudopotential method. Can use ultrasoft pseudopotentials (Vanderbilt scheme) or norm-conserving.

2. Other NLA Operation

Other NLA Operation:

Yes

Please specify your NLA operation:

3D, 2D and 1D FFT

3. Matrix-Matrix Multiplication (GEMM)

Matrix-Matrix Multiplication (GEMM):

Yes

Matrix Properties:

Not specified

Matrix Structure:

Dense matrices, Tall-and-skinny matrices, Triangular matrices, Banded matrices, Distributed matrices, Mixed real/complex

Matrix Distribution:

Block row/column distribution, Communication-avoiding distribution, Replicated on all processes, Hybrid CPU-GPU distribution, Hierarchical/multilevel distribution, Custom domain decomposition

Matrix Storage Format:

Dense (column-major/row-major), Diagonal/Block-diagonal

Which types of matrix multiplications do you perform?:

Standard multiplication (AB), Scaled multiplication (\pm AB), A Full GEMM (\pm AB + 2 C), Transpose multiplication (A@B, AB@) Hermitian multiplication (A†B, AB†)

Typical Dimensions:

Not specified

Matrix Size Range:

Extreme (> 100,000), Very Large (10,000 - 100,000)

Typical Matrix Shapes:

Square matrices (m "H n "H k), Tall-skinny matrices (m >>

Batch Size:

Small (< 10)

Distributed-Memory NLA Library Usage:

Not specified

General Distributed Memory Libraries (CPU/GPU):

Not specified

Special/Advanced Implementations:

Not specified

Are there any NLA libraries you are interested in using (but have not yet adopted)?:

ELPA, PETSc

Future Requirements:

Not specified

Desired Features:

Other: Row/column distributions rather than block-cyclic; when block-cyclic, proper optimisations for block-size 1

Benchmarking Requirements:

Not specified

Benchmark Input Types:

Both synthetic and real data, Mini-apps or extracted kernels from real applications

Can You Provide Data or Mini-apps?:

Yes, both matrices and mini-apps

Scaling Requirements:

Not specified

Working Precision:

Mixed precision (e.g., FP32 multiplication with FP64 accumulation), Double precision (64-bit)

Standard Eigenvalue Problems (Ax = »x)

Symmetric/Hermitian

Primary Use Cases:

Kohn-Sham equations (standard DFT)

Matrix Properties and Structure:

Dense, Matrix-free (only matrix-vector products available), Matrix-free with preconditioner, Complex valued, Real valued

Matrix Properties:

Not specified

Matrix Distribution:

Not specified

Matrix Storage Format:

Not specified

Positive definiteness:

Eigenvalue distribution: **Not specified**

Problem Scale: Not specified

Computation Requirements:

Not specified

Percentage of eigenvalues:

Not specified

What to compute:

Not specified

Eigenvalue location:

Not specified

Required tolerance/precision:

Not specified

Residual tolerance type:

Not specified

Absolute residual tolerance:

Not specified

Relative residual tolerance:

Not specified

Hybrid residual tolerance:

Not specified

Orthogonality tolerance:

Not specified

Working Precision:

Not specified

Workload Characteristics:

Not specified

Computation Pattern: capability or capacity:

Not specified

Distributed-Memory NLA Library Usage:

Not specified

Distributed-Memory Dense Linear Algebra:

Not specified

Iterative Eigensolvers:

Not specified

High-Level & Interface Libraries:

Not specified

Are there any NLA libraries you are interested in using (but have not yet adopted)?:

Not specified

Benchmarking Requirements:

Not specified

Benchmark Input Types:

Not specified

Can You Provide Data or Mini-apps?:

Not specified

Scaling Requirements:

5. Generalized Eigenvalue Problems (Ax = »Bx)

Symmetric/Hermitian A, SPD B

Matrix Structure:

A is dense, B is sparse, Complex valued, Real valued, A is dense, B is dense

Reduction to Standard Eigenproblem (using B):

Not specified

Reduction to Standard Eigenproblem:

Yes, sometimes (depends on solver or problem)

Reduction Method:

Cholesky factorization of B (B = LLW or B = L*L)

Matrix Properties:

Not specified

Eigenvalue distribution:

Varies

Problem Scale:

Medium (1,000 - 10,000)

Computation Requirements:

Not specified

Percentage of eigenvalues:

1-10%

What to compute:

Varies

Eigenvalue location:

Smallest eigenvalues

Required tolerance/precision:

Not specified

Residual tolerance type:

Both absolute and relative

Absolute residual tolerance:

High (10^-9)

Relative residual tolerance:

High (10^-9)

Hybrid residual tolerance:

Not specified

Orthogonality tolerance:

Very high (10^-12)

Working Precision:

Double precision (64-bit)

Workload Characteristics:

Not specified

Computation Pattern: capability or capacity:

Large-scale single problems (e.g., one large generalized eigenproblem at a time, using significant computational resources), Mix of large and small problems (varying resource requirements), Repeated similar-sized problems (e.g., time evolution or parameter sweeps), Many independent smaller problems (e.g., batch processing multiple generalized eigenproblems simultaneously)

Distributed-Memory NLA Library Usage:

Not specified

Distributed-Memory Dense Linear Algebra:

Iterative Eigensolvers:

Not specified

High-Level & Interface Libraries: **Not specified**

Are there any NLA libraries you are interested in using (but have not yet adopted)?: ScaLAPACK, ELPA, FEAST

Benchmarking Requirements: **Not specified**

Benchmark Input Types:

Both synthetic and real data, Mini-apps or extracted kernels from real applications

Can You Provide Data or Mini-apps?:

Yes, both matrices and mini-apps

Scaling Requirements:

Both strong and weak scaling needed