

VISUAL OBJECT TRACKING : Final Report

Version 1 : Simple Multi Object Tracker

FPS Benchmark

| FPS | Average | Lower | Higher |
|-------|---------|-------|--------|
| Value | 38 | 31 | 43 |

TrackEval Benchmark

| Metrics | HOTA | MOTA | IDF1 | ID Switch | Frag |
|---------|-------|------|------|-----------|------|
| Value | 16.83 | 2.7 | 18.9 | 1444 | 311 |

The metrics are not very good. In our logic, while computing the Jaccard matrix, we pair tracks with a detection only if that detection is the highest for the given track and its value exceeds 0.5.

Version 2 : Multi Object Tracker using Hungarian Algorithm to match the tracks

FPS Benchmark

| FPS | Average | Lower | Higher |
|-------|---------|-------|--------|
| Value | 36 | 23 | 42 |

TrackEval Benchmark

| Metrics | HOTA | MOTA | IDF1 | ID Switch | Frag |
|---------|--------|------|--------|-----------|------|
| Value | 17.043 | 11.2 | 20.033 | 893 | 273 |

We can see small improvements in some metrics, this version is clearly better than the first one. It also cost very little FPS.

Version 3 : Version 2 + Kalman Filter Update (Visual change only)

FPS Benchmark

| FPS | Average | Lower | Higher |
|-------|---------|-------|--------|
| Value | 34 | 18 | 40 |

TrackEval Benchmark

| Metrics | HOTA | MOTA | IDF1 | ID Switch | Frag |
|---------|--------|------|--------|-----------|------|
| Value | 17.043 | 11.2 | 20.033 | 893 | 273 |

This version is solely visual, so the metrics will remain unchanged. The application of the Kalman filter does not significantly increase the processing time; we observed an average loss of only 2 FPS compared to version 2.

Version 4 : Multi Object Tracker using deep learning features to better match the tracks + Kalman Filter

FPS Benchmark

| FPS | Average | Lower | Higher |
|-------|---------|-------|--------|
| Value | 2 | 1 | 5 |

TrackEval Benchmark

| Metrics | HOTA | MOTA | IDF1 | ID Switch | Frag |
|---------|--------|--------|------|-----------|------|
| Value | 17.722 | 11.939 | 20.2 | 747 | 278 |

Extracting the features and the histogram from each detection is really time consuming so the FPS are very low compared to the others version.

The model used is a pretrained ResNet18 (around 11 millions parameters).

The performance is not much better than in the other version.

Version 5 : Version 1 + Optimizing the way we compute the jaccard matrix by not calculating anything if the two bounding box are too different.

FPS Benchmark

| FPS | Average | Lower | Higher |
|-------|---------|-------|--------|
| Value | 38 | 31 | 64 |

TrackEval Benchmark

| Metrics | HOTA | MOTA | IDF1 | ID Switch | Frag |
|---------|-------|------|------|-----------|------|
| Value | 16.83 | 2.7 | 18.9 | 1444 | 311 |

We can see some gains in FPS especially in the higher bound. We can explain that by the fact that some particular frames have some detection boxes that are not overlapping on the tracks boxes so we do not compute anything which leads to an FPS spike.