Test Matrix

The following table illustrates the test matrix used for the simulation scenarios described in the paper. It includes both JAMA and additional parameters relevant to the simulation setup.

		JAMA Parameter				Additional Parameter									
					()	Ego car NPC car									
Test Case No.	JAMA Scenario No.	Road Geometry	Vehicle behavior	Position of NPC	Motion of NPC	Traffic Lanes	Starting Position	Max Accelerate, Decelerate Rate (m/s²)	Max speed (m/s)	Types of NPC	Starting Position	Max Accelerate, Decelerate Rate (m/s²)	Target Speed (m/s)	Goal	
Case No. 1	Scenario No. 2	Non-intersection	Going Straight	Lead (L)	Decelerate	{"TrafficLane.112"}, {"TrafficLane.114"}, {"TrafficLane.278"}, {"TrafficLane.122"}	(-447.51, -3.07, -24.21)	1, 2.5	16.67	Taxi	("TrafficLane.112", 0f)	1, 1	{"TrafficLane.112", 0.5f}, {"TrafficLane.114", 0.5f}, {"TrafficLane.278", 0f}, {"TrafficLane.122", 0f}	("TrafficLane.122", 0f)	
Case No. 2	Scenario No. 2	Non-intersection	Going Straight	Lead (L)	Decelerate	("TrafficLane.112"), ("TrafficLane.114"), ("TrafficLane.278"), ("TrafficLane.122"), ("TrafficLane.514"), ("TrafficLane.515"), ("TrafficLane.516"), ("TrafficLane.14"), ("TrafficLane.14"), ("TrafficLane.135")	(-444.56, -3.35, -23.87)	1, 2.5	13.89	Taxi	("TrafficLane.112", 0f)	1, 1	("TrafficLane.112", 10f), ("TrafficLane.114", 5f), ("TrafficLane.122", 5f), ("TrafficLane.122", 5f), ("TrafficLane.514", 10f), ("TrafficLane.514", 10f), ("TrafficLane.515", 5f), ("TrafficLane.516", 5f), ("TrafficLane.315", 3f), ("TrafficLane.33", 0f)	("TrafficLane.335", 0f)	
Case No. 3	Scenario No. 2	Non-intersection	Going Straight	Lead (L)	Decelerate	{"TrafficLane.112"}, {"TrafficLane.114"}, {"TrafficLane.278"}, {"TrafficLane.122"}	(-444.56, -3.35, -23.87)	1, 2.5	13.89	Taxi	("TrafficLane.112", 0f)	1, 1	{"TrafficLane.112", 2f}, {"TrafficLane.114", 1f}, {"TrafficLane.278", 0f}, {"TrafficLane.122", 0.2f}	("TrafficLane.122", 0.2f)	
Case No. 4	Scenario No. 2	Non-intersection	Going Straight	Lead (L)	Stop	{"TrafficLane.282"}, {"TrafficLane.514"}, {"TrafficLane.515"}, {"TrafficLane.516"}, {"TrafficLane.124"}	(-444.56, -3.44, -23.87)	1, 2.5	16.67	Taxi	("TrafficLane.282", 15f)	1, 1	{"TrafficLane.282", 0f}, {"TrafficLane.514", 0f}, {"TrafficLane.515", 0f}, {"TrafficLane.516", 0f}, {"TrafficLane.124", 0f}	("TrafficLane.124", 60f)	
Case No. 5	Scenario No. 2	Non-intersection	Going Straight	Lead (L)	Decelerate and stop	{"TrafficLane.282"}, {"TrafficLane.514"}, {"TrafficLane.515"}, {"TrafficLane.516"}, {"TrafficLane.124"}	(-165.85, -1.63, -27.47)	1, 2.5	16.67	Taxi	("TrafficLane.282", 15f)	1, 1	{"TrafficLane.282", 10f}, {"TrafficLane.514", 10f}, {"TrafficLane.515", 10f}, {"TrafficLane.516", 10f}, {"TrafficLane.124", 10f}	("TrafficLane.124", 60f)	
Case No. 6	Scenario No. 2	Non-intersection	Going Straight	Lead (L)	Decelerate	{"TrafficLane.282"}, {"TrafficLane.514"}, {"TrafficLane.515"}, {"TrafficLane.516"}, {"TrafficLane.124"}	(-164.9, -1.63, -27.73)	1, 2.5	16.67	Taxi	("TrafficLane.282", 15f)	1, 1	{"TrafficLane.282", 10f], {"TrafficLane.514", 10f], {"TrafficLane.515", 10f], {"TrafficLane.516", 10f} {"TrafficLane.124", 0f}	("TrafficLane.124", 60f)	
Case No. 7	Scenario No. 2	Non-intersection	Going Straight	Lead (L)	Decelerate	{"TrafficLane.282"}, {"TrafficLane.514"}, {"TrafficLane.515"}, {"TrafficLane.516"}, {"TrafficLane.124"}	(-168.87, -1.52, -27.18)	1, 2.5	16.67	Taxi	("TrafficLane.282", 15f)	0.5, 0.5	{"TrafficLane.282", 0f}, {"TrafficLane.514", 0f}, {"TrafficLane.515", 0f}, {"TrafficLane.516", 0f}, {"TrafficLane.124", 0f}	("TrafficLane.124", 60f)	
Case No. 8	Scenario No. 2	Non-intersection	Going Straight	Lead (L)	Decelerate	{"TrafficLane.15"}, {"TrafficLane.17"}, {"TrafficLane.289"}, {"TrafficLane.29"}, {"TrafficLane.286"}, {"TrafficLane.33"}	(-20.41, -1.57, -176.22)	1, 2.5	16.67	Taxi	("TrafficLane.15", 15f)	2, 2	{"TrafficLane.15", 0f}, {"TrafficLane.17", 0f}, {"TrafficLane.289", 0f}, {"TrafficLane.29", 0f}, {"TrafficLane.29", 0f}, {"TrafficLane.38", 0f},	("TrafficLane.33", 0f)	
Case No. 9	Scenario No. 2	Non-intersection	Going Straight	Lead (L)	Decelerate	{"TrafficLane.514"}, {"TrafficLane.515"}, {"TrafficLane.516"}, {"TrafficLane.124"}	(-147.40, -1.70, 153.02)	1, 2.5	16.67	Taxi	("TrafficLane.514", 10f)	1, 1	{"TrafficLane.514", 5f}, {"TrafficLane.515", 5f}, {"TrafficLane.516", 5f}, {"TrafficLane.124", 5f}	("TrafficLane.124", 0f)	
Case No. 10	Scenario No. 2	Non-intersection	Going Straight	Lead (L)	Decelerate	{"TrafficLane.264"}, {"TrafficLane.354"}, {"TrafficLane.210"}, {"TrafficLane.333"}	(-173.82, -0.82, -214.52)	1, 2.5	16.67	Taxi	("TrafficLane.264", 15f)	2, 2	{"TrafficLane.264", 0f}, {"TrafficLane.354", 0f}, {"TrafficLane.210", 0f}, {"TrafficLane.333", 0f}	("TrafficLane.333", 0f)	
Case No. 11	Scenario No. 2	Non-intersection	Going Straight	Lead (L)	Stop	{"TrafficLane.15"}, {"TrafficLane.17"}, ("TrafficLane.289"}, {"TrafficLane.29"}, {"TrafficLane.286"}, {"TrafficLane.33"}	(-20.41, -1.57, -176.22)	1, 2.5	4.17	Taxi	("TrafficLane.282", 0f)	2, 2	{"TrafficLane.15", 0f}, {"TrafficLane.17", 0f}, {"TrafficLane.289", 0f}, {"TrafficLane.29", 0f}, {"TrafficLane.286", 0f}, {"TrafficLane.33", 0f}	("TrafficLane.33", 0f)	

Test Matrix Table

			JAMA P	arameter		Additional Parameter								
		_	-	n)	-		Ego	car		NPC car				
Test Case No.	JAMA Scenario No.	Road Geometry	Vehicle behavior	Position of NPC	Motion of NPC	Traffic Lanes	Starting Position	Max Accelerate, Decelerate Rate (m/s²)	Max speed (m/s)	Types of NPC	Starting Position	Max Accelerate, Decelerate Rate (m/s²)	Target Speed (m/s)	Goal
Case No. 12	Scenario No. 4	Non-intersection	Going Straight	Parallel (Pl-f)	Cut-in	{"TrafficLane.111"}, {"TrafficLane.113"}, {"TrafficLane.114"}, {"TrafficLane.278"}, {"TrafficLane.122"}, {"TrafficLane.282"}	(-427.18, -3.46, -20.51)	1, 2.5	16.67	Taxi	("TrafficLane.111", 10f)	1, 1	{"TrafficLane.111", 10f}, {"TrafficLane.113", 8f}, {"TrafficLane.114", 5f}, {"TrafficLane.278", 5f}, {"TrafficLane.122", 5f}, {"TrafficLane.282", 0f}	("TrafficLane.282", 20f)
Case No. 13	Scenario No. 4	Non-intersection	Going Straight	Parallel (Pl-f)	Cut-in	{"TrafficLane.111"}, {"TrafficLane.113"}, {"TrafficLane.114"}, {"TrafficLane.278"}, {"TrafficLane.122"}, {"TrafficLane.282"}	(-425.02, -3.47, -20.16)	1, 2.5	16.67	Taxi	("TrafficLane.111", 10f)	1, 1	{"TrafficLane.111", 10f}, {"TrafficLane.113", 7f}, {"TrafficLane.114", 5f}, {"TrafficLane.278", 5f}, {"TrafficLane.122", 5f}, {"TrafficLane.122", 5f},	("TrafficLane.282", 20f)
Case No. 14	Scenario No. 4	Non-intersection	Going Straight	Parallel (Pl-f)	Cut-in	{"TrafficLane.111"}, {"TrafficLane.114"}, {"TrafficLane.278"}, {"TrafficLane.122"}, {"TrafficLane.282"}	(-436.60, -3.39, -22.44)	1, 2.5	16.67	Taxi	("TrafficLane.111", 0f)	1, 1	{"TrafficLane.111", 5f}, {"TrafficLane.114", 5f}, {"TrafficLane.278", 5f}, {"TrafficLane.122", 5f}, {"TrafficLane.282", 0f}	("TrafficLane.282", 20f)
Case No. 15	Scenario No. 4	Non-intersection	Going Straight	Parallel (PI-f)	Cut-in	{"TrafficLane.111"}, {"TrafficLane.114"}, {"TrafficLane.278"}, {"TrafficLane.122"}, {"TrafficLane.282"}	(-381.54, -2.63, -12.26)	1, 2.5	16.67	Taxi	("TrafficLane.111", 0f)	1, 1	{"TrafficLane.111", 5f}, {"TrafficLane.114", 5f}, {"TrafficLane.278", 5f}, {"TrafficLane.122", 0f}, {"TrafficLane.282", 0f}	("TrafficLane.282", 20f)

Test Matrix Table (cont.)