

Design and Verification of a 4-Bit Arithmetic Logic Unit using Quartus, Verilog HDL, and Timing Diagrams

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Abstract—In this paper, we present the design and verification of a 4-bit Arithmetic Logic Unit (ALU) capable of performing four different arithmetic or logical operations. The ALU was designed using Quartus and implemented using Verilog HDL. A timing diagram was used to verify the functionality of the ALU. The paper outlines the design process, including the specification of the required operations, the creation of the Verilog HDL code, and the simulation and verification of the ALU using a timing diagram. The results of the simulation demonstrate the successful implementation of the four operations and the proper functioning of the ALU.

Index Terms—component, formatting, style, styling, insert

I. INTRODUCTION

An arithmetic logic unit (ALU) is a fundamental component of digital circuits that performs arithmetic and logical operations on binary numbers. In this project, we aim to design and implement a 4-bit ALU capable of performing four different operations: addition, subtraction, bitwise AND, and bitwise OR. The design of the ALU was carried out using Quartus, a software tool for designing digital circuits. Verilog HDL, a hardware description language, was used to implement the ALU. To verify the functionality of the ALU, we used a timing diagram, a graphical representation of the signals in a digital circuit over time. The use of a timing diagram allowed us to ensure that the ALU was operating correctly under various input conditions. The successful implementation of the ALU has potential applications in various digital circuits, including microprocessors and microcontrollers. The remainder of this paper outlines the design and verification process of the 4-bit ALU.

II. OPERATION

A. State Diagram

The state diagram of the system is shown in the figure 1. Here 5 operations are done. RESET, AND, ADD, NOR, and SUB. For each operation, we use 000,001,010,011 and 100 opcodes respectively.

B. Truth Table

The figure 2 shows some of the results and a few of their notable ZFs (Zero Flags), SFs (Sign Flags), and CFs (Carry Flags). When the output is zero or $Y = 0000$, $ZF = 1$ otherwise $ZF = 0$. $SF = 1$ when output, $Y = 1xxx$ or when the MSB bit is 1, else $SF = 0$. $CF = 1$ when the carry bit is 1 or when $Y =$

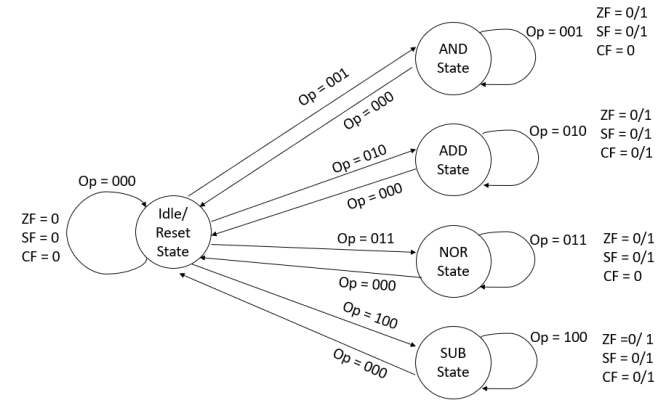


Fig. 1. Simplified state diagram of an ALU with five operations: RESET, AND, ADD, NOR, SUB

In decimal	A				B				RESET (op = 000)	ADD (op = 001)	AND (op = 010)	NOR (op = 011)	SUB (A-B) (op = 100)		
-	A3	A2	A1	A0	B3	B2	B1	B0	-	-	Y3	Y2	Y1	Y0	-
0 (+/-) 0	0	0	0	0	0	0	0	0	-	0000 (ZF=1, SF=0, CF=0)	0	0	0	0	0000
0 (+/-) 15	0	0	0	0	1	1	1	1	-	1111 (ZF=0, SF=1, CF=0)	0	0	0	0	10001 (ZF=0, SF=0, CF=1)
15 (+/-) 0	1	1	1	1	0	0	0	0	-	1111 (ZF=0, SF=1, CF=0)	0	0	0	0	0000
.	-
.	-
.	-
15 (+/-) 13	1	1	1	1	1	1	0	1	-	11100 (ZF=0, SF=1, CF=1)	1	1	0	1	0010 (ZF=0, SF=0, CF=0)
15 (+/-) 14	1	1	1	1	1	1	1	0	-	11101 (ZF=0, SF=1, CF=1)	1	1	1	0	0001
15 (+/-) 15	1	1	1	1	1	1	1	1	-	11110 (ZF=0, SF=1, CF=1)	1	1	1	1	0000

Fig. 2. Truth Table

1xxxx (overflow), otherwise $CF = 0$. For AND gate and NOR gate, it is said to take bitwise inputs of A and B, means if $A = 1010$ ($A3 = 1, A2 = 0, A1 = 1, A0 = 0$) and $B = 0101$ ($B3 = 0, B2 = 1, B1 = 0, B0 = 1$) AND operation would be $Y = 0000$ ($Y3 = 0$ [because $A3 = 1, B3 = 0$ means 0], $Y2 = 0$ [because $A2 = 0, B2 = 1$ means 0], $Y1 = 0$ [because $A1 = 1, B1 = 0$ means 0], $Y0 = 0$ [because $A0 = 1, B0 = 0$ means 0]). And NOR operation would be $Y = 0000$ ($Y3 = 0$ [because $A3 = 1, B3 = 0$ means 0], $Y2 = 0$ [because $A2 = 0, B2 = 1$ means 0], $Y1 = 0$ [because $A1 = 1, B1 = 0$ means 0], $Y0 =$

0 [because A0 =1 B0 = 0 means 0]). This also applies to other 4-bit combinations of A, B. 16 possible inputs for A and 16 possible inputs for B. So, 16 * 16 = 256. 256 total combinations of outputs possible including repetitions.

a) Table Simplified :

Input A	A3	A2	A1	A0
Input B	B3	B2	B1	B0
Output Y	Y3	Y2	Y1	Y0

Y4 = Carry

Fig. 3. Simplified

C. Timing Diagram

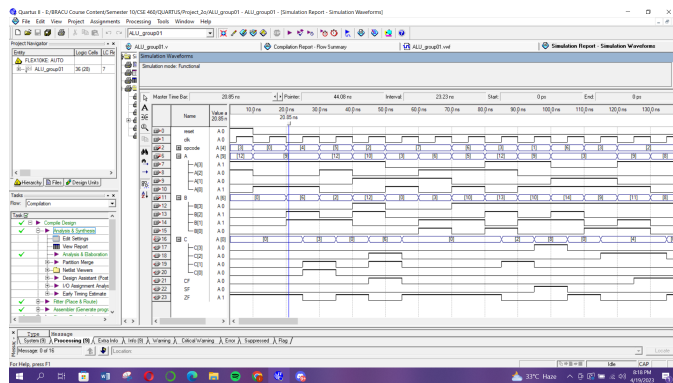


Fig. 4. Timing Diagram after simulating the Verilog code from Appendix 1

D. Conclusion

In this research, we present an effective method for verifying VHDL behavioral coding. Additionally, we have put up a number of algorithms with various design levels. Quartus has been used to implement our suggestions in Verilog. The number of bus lines has been reduced, and all designs have been put into practice and evaluated. This VHDL-based ALU design was successfully created, implemented and tested.

APPENDIX

Verilog Code

```

module ALUgroup01(A, B, opcode, clk, reset, C, CF,
ZF,SF);
input clk,reset;
input [3:0] A;
input [3:0] B;
input [2:0] opcode;
output reg [3:0] C;
output reg CF;
output reg ZF;
output reg SF;
// Temporary variable to store the result reg [4:0] temp;

```

```

reg [3:0]prevC = 4'b0000;
always @(posedge clk, posedge reset)
begin
if (reset == 1)
begin
temp = 5'b000000;
C = temp[3:0];
CF = 0;
ZF = 1;
SF = 0;
end
else
begin
prevC = C;
case (opcode)
3'b000: //RESET operation
begin
C = prevC;
CF = CF;
end
3'b001: //AND operation
begin
temp = (A & B);
C = temp[3:0];
CF = 0;
end
3'b010: //ADD operation
begin
temp = (A + B);
C = temp[3:0];
if (temp[4] == 1)
begin
CF = 1;
end
else
begin
CF = 0;
end
end
3'b011: //NOR operation
begin
temp = (A ~ B);
C = temp[3:0];
CF = 0;
end
3'b100: //SUB operation
begin
C = A - B;
if (A < B)
begin
CF = 0;
end
else
begin
CF = 1;
end
end end

```

```
default:
begin temp = 5'bxxxxx;
C = 4'bxxxx;
CF = 1'bx;
end
endcase
if (C == 4'b0000)
begin
ZF = 1;
end
else
begin
ZF = 0;
end
SF = C[3];
end
end
endmodule
```

A. Compilation Report

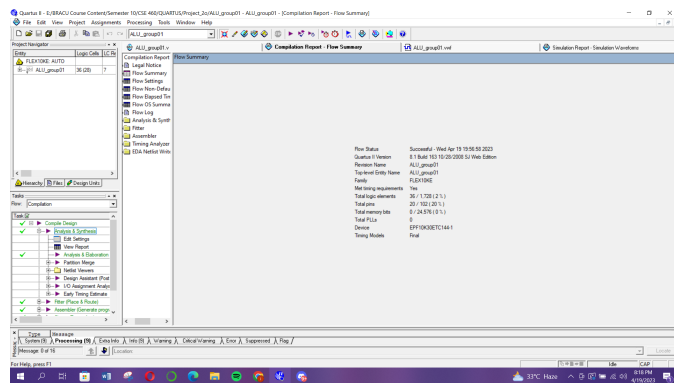


Fig. 5. Compilation report after running the Verilog code from Appendix 1