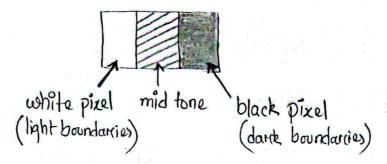
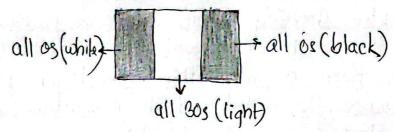
## Question 02 Sharred concept of CNN: CNN have a couple of concepts called pareametre local connectivity. Parametre sharing is sharing sharring and weights by all neurons in a particular feature map. To restorate parcametre sharring occurs when a feature map is generated from the result of convolution between a filter input data from a unit within this layer plane share same weights, hence its called weight parametre sharring So, this is the shared concept of CNN Convolution networks to detect vertical boundaries is an image (6x6) with 2 convolution filters for rst layer, of 3X3 -1 W1 = W2 = -1 0 1his Simplified 6x6 image with left half of image is 10 & right half is 0 We can look at it like this, The tens gives us white pixel intensity (light boundaries) & ones gives us black Pixel infonsity (darck boundaries)



When convule with 3x3 filter, fiter can be visualited like\_



for filter 1:



all 05 (uhile)

all 305 (light)

from 4x4 we get all block boundaries at corner of smage since all zeroes on the right and lelf & all 30s in middle e fitter 2 would give black white boundaries,

all 30s (white)

all 0s (black) The fitter 2 would give black white boundaries,