Multiple Choice Questions for Lecture 4: Searching Algorithm in AI Types of Search Algorithms

- 1. What are the two main types of search algorithms in AI?
 - o A) Fast search and slow search
 - o B) Easy search and hard search
 - C) Uninformed search and informed search
 - o D) Manual search and automatic search

Answer: C) Uninformed search and informed search

- 2. What is another name for uninformed search?
 - o A) Smart search
 - o B) Blind algorithm
 - o C) Quick search
 - o D) Directed search

Answer: B) Blind algorithm

- 3. In uninformed search, what information does the agent have?
 - o A) Path cost and number of steps
 - o B) Only when it reaches a goal
 - o C) Distance to the goal
 - o D) Background information about the problem

Answer: B) Only when it reaches a goal

- 4. What information does informed search use?
 - o A) Only the path cost
 - o B) The exact steps to reach the goal
 - o C) Background information about the problem
 - D) Only the branching factor

Answer: C) Background information about the problem

Uninformed Search Strategies

- 5. Breadth-First Search (BFS) explores:
 - A) The deepest nodes first
 - o B) The lowest cost nodes first
 - o C) All nodes at the current depth before moving to the next level
 - o D) Nodes randomly

Answer: C) All nodes at the current depth before moving to the next level

- 6. What data structure does Breadth-First Search use?
 - A) FIFO queue
 - o B) LIFO stack
 - o C) Priority queue
 - o D) Hashtable

Answer: A) FIFO queue

- 7. What does Uniform-Cost Search (UCS) prioritize?
 - A) The closest node to the goal
 - o B) The lowest-cost path when multiple paths exist
 - o C) The deepest node in the tree
 - o D) Random nodes

Answer: B) The lowest-cost path when multiple paths exist

- 8. When does Uniform-Cost Search (UCS) act like Breadth-First Search (BFS)?
 - A) When the goal is very far
 - o B) When paths have different costs
 - o C) When all transitions have equal costs
 - o D) When using a priority queue

Answer: C) When all transitions have equal costs

9. What data structure is used in Depth-First Search (DFS)?

- o A) FIFO queue
- o B) LIFO stack
- o C) Priority queue
- o D) Set

Answer: B) LIFO stack

- 10. Depth-First Search (DFS) explores:
 - o A) All nodes at the current level before moving deeper
 - o B) Branch nodes deeply before backtracking
 - o C) Random nodes
 - o D) Only the shortest paths

Answer: B) Branch nodes deeply before backtracking

- 11. What is Bidirectional Search?
 - o A) A search that goes in multiple random directions
 - o B) A search that runs from both start and goal states until they meet
 - o C) A search that only goes left and right
 - o D) A search that changes direction based on costs

Answer: B) A search that runs from both start and goal states until they meet

- 12. What is the main advantage of Bidirectional Search?
 - o A) It always finds the optimal solution
 - o B) It only needs to explore half the path compared to traditional methods
 - o C) It never gets stuck in loops
 - o D) It doesn't need any memory

Answer: B) It only needs to explore half the path compared to traditional methods

Informed Search Strategies

- 13. What function does Greedy Best-First Search use to evaluate nodes?
 - $\circ \quad A) \ f(n) = g(n) + h(n)$

o B)
$$f(n) = g(n)$$

$$\circ$$
 C) $f(n) = h(n)$

o D)
$$f(n) = 1/g(n)$$

Answer: C) f(n) = h(n)

14. What does h(n) represent in search algorithms?

- o A) The height of the node
- o B) The estimated cost from node n to the goal
- o C) The path cost from the start to node n
- o D) The number of children of node n

Answer: B) The estimated cost from node n to the goal

15. What is a limitation of Greedy Best-First Search?

- o A) It's too slow
- o B) It can get stuck in loops or dead ends
- o C) It uses too much memory
- \circ D) It's too complicated to implement

Answer: B) It can get stuck in loops or dead ends

16. What function does A* search use to evaluate nodes?

$$\circ \quad A) \ f(n) = g(n) + h(n)$$

o B)
$$f(n) = g(n)$$

o C)
$$f(n) = h(n)$$

o D)
$$f(n) = g(n) - h(n)$$

Answer: A) f(n) = g(n) + h(n)

17. In A^* search, what does g(n) represent?

- o A) The goal state
- \circ B) The path cost from the start to node n
- $\circ\quad$ C) The estimated cost from node n to the goal

o D) The total search cost

Answer: B) The path cost from the start to node n

- 18. How does A* search combine UCS and Greedy Best-First Search?
 - o A) It alternates between using each algorithm
 - B) UCS keeps solution cost low, Greedy Best-First helps find solutions quickly
 - o C) It runs both and takes the best result
 - o D) It only uses parts of each algorithm

Answer: B) UCS keeps solution cost low, Greedy Best-First helps find solutions quickly

Important Concepts

- 19. What is a "complete algorithm" in search?
 - o A) An algorithm that finds any solution
 - o B) An algorithm that guarantees finding a solution if one exists
 - o C) An algorithm that works in all situations
 - o D) An algorithm that is fully implemented

Answer: B) An algorithm that guarantees finding a solution if one exists

- 20. What is an "optimal solution" in search problems?
 - o A) The fastest solution
 - B) The solution with the fewest steps
 - C) The solution with the lowest cost
 - D) The most recently found solution

Answer: C) The solution with the lowest cost