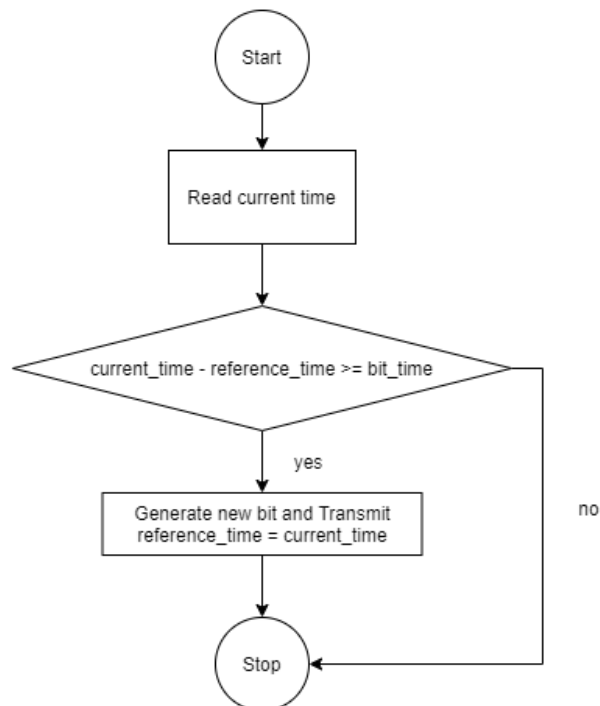
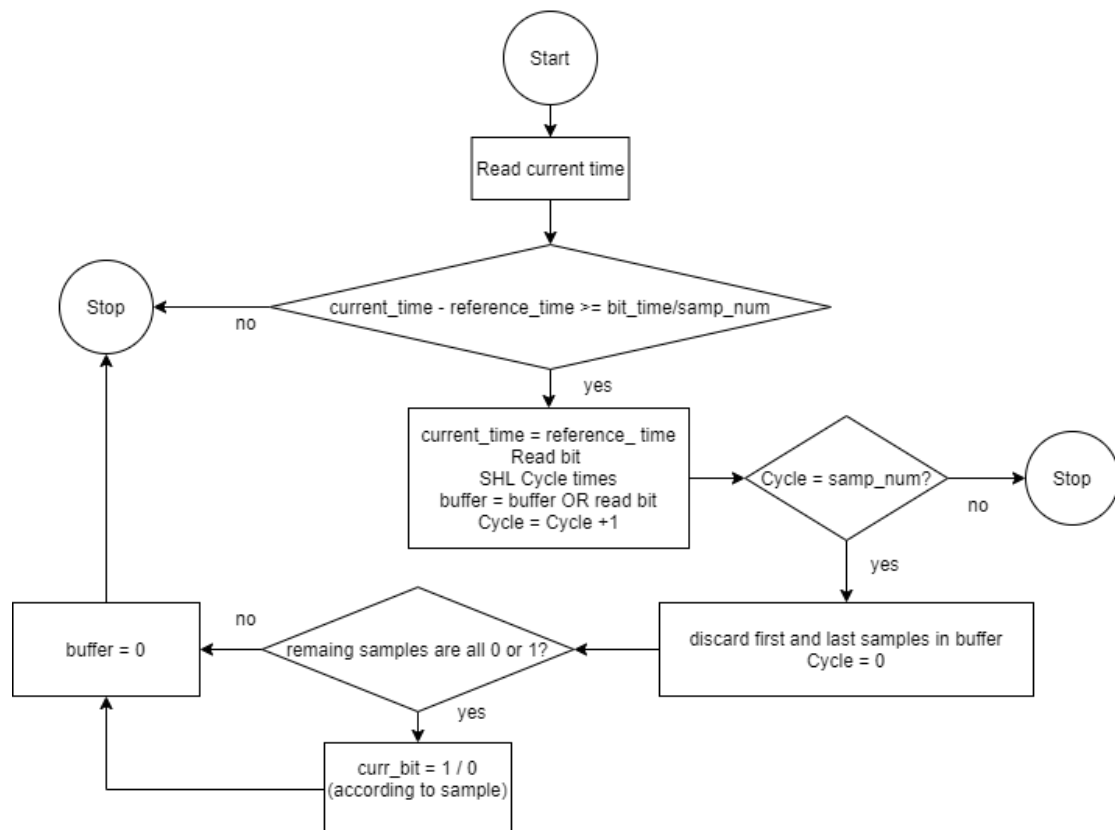


NRZ - Tx

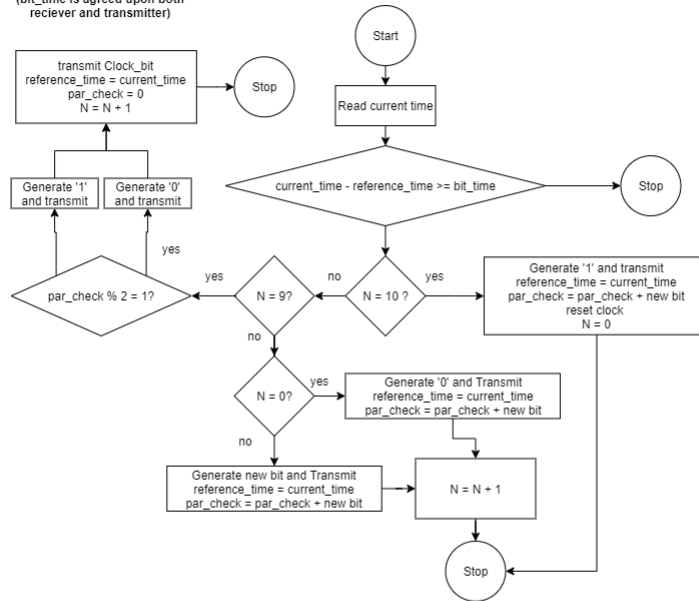


NRZ - Rx



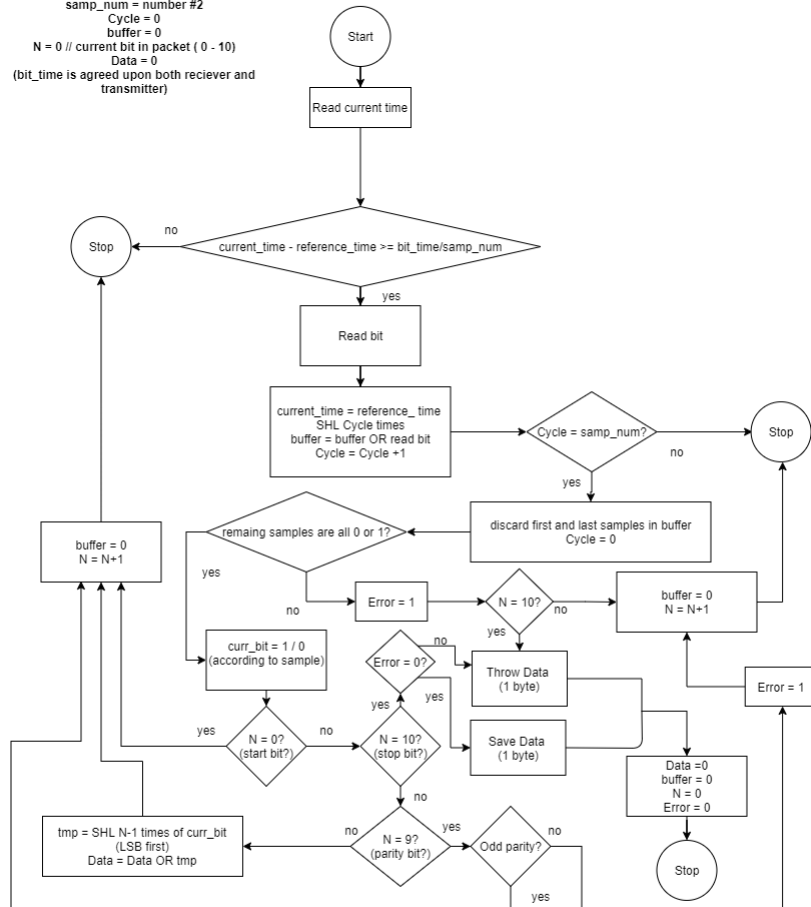
Init :
reference_time = 0
bit_time = number
N = 0 // current bit in packet
par_check = 0
(bit_time is agreed upon both
reciever and transmitter)

UART - Tx



Init :
reference_time = 0
bit_time = number #1
samp_num = number #2
Cycle = 0
buffer = 0
N = 0 // current bit in packet (0 - 10)
Data = 0
(bit_time is agreed upon both reciever and
transmitter)

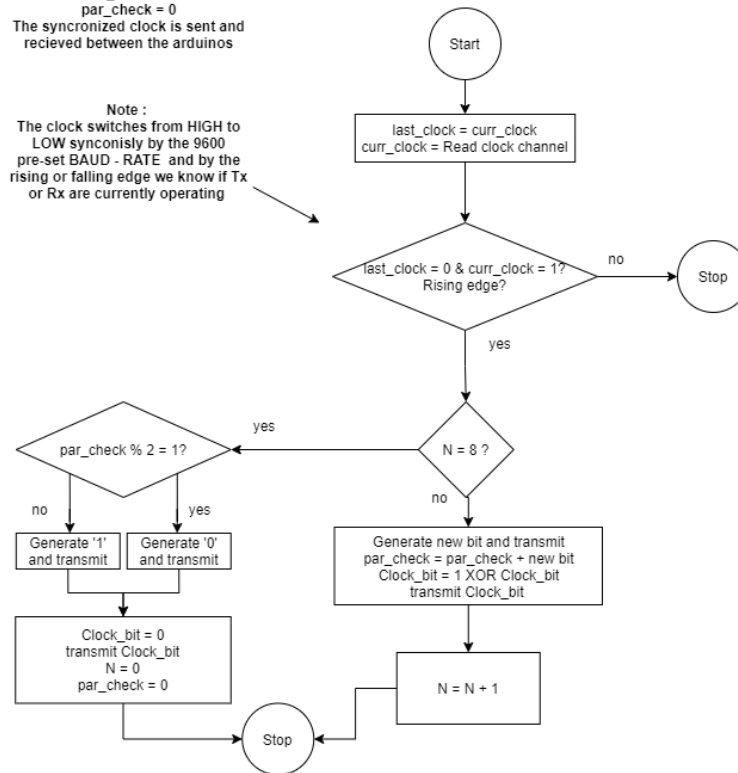
UART - Rx



*Note : we do not check if the stop bit is '1', it does not affect the 8 data bits and we assume that after every packet the transmitter sends a '1' signal by default (for the next falling edge - start)

Init :
 bit_time = number
 N = 0 // current bit in packet
 curr_clock = 1
 last_clock = 1
 par_check = 0
 The synchronized clock is sent and received between the arduinos

USART - Tx



Init :
 bit_time = number #1
 samp_num = number #2
 curr_clock = 1
 last_clock = 1
 Error = 0
 N = 0 // current bit in packet (0 - 8)
 Data = 0

USART - Rx

