

# Convexity Theorem and Integrable Systems

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November 30, 2020

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# **Introduction and required definitions**

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# Exponential map

Let  $G$  be a Lie group. By a one-parameter subgroup of  $G$  we mean homomorphism  $\mathbb{R} \rightarrow G$ .

$$\text{hom}_{\text{Lie}}(\mathbb{R}, G) \ni \theta \mapsto \left. \frac{d}{dt} \right|_0 \theta(t) \in T_e G$$

We define the Lie group exponential map to be:

$$T_e G \ni X \mapsto \exp X = \theta(1) \in G,$$

where  $\theta$  is the one-parameter subgroup of  $G$  corresponding to  $X$ .

# Exponential map

## Proposition

*The exponential map is smooth and natural, i.e.*

$$\begin{array}{ccc} T_e G & \xrightarrow{T_e \phi} & T_{e'} G' \\ \downarrow \exp & & \downarrow \exp \\ G & \xrightarrow{\phi} & G' \end{array}$$

where  $\phi \in \text{hom}(G, G')$ .

Moreover if  $X \in T_e G$  then  $\exp(t+s)X = (\exp tX) \cdot (\exp sX)$  for all  $t, s \in \mathbb{R}$ , where  $\cdot$  stands for Lie group product.

## Riemannian analogue of exponential map

Let  $(M, g)$  be a Riemannian manifold and let  $p \in M$  be a point of  $M$ . The Riemannian exponential map starting at  $p$  is defined by:

$$T_p M \ni X \mapsto \exp_p X = \gamma_X(1) \in M$$

where  $\gamma_X$  is the unique geodesic starting at  $p$  with tangent vector  $X$

### Proposition

*The exponential map is smooth and natural, i.e.*

$$\begin{array}{ccc} T_p M & \xrightarrow{T_p \phi} & T_{p'} M' \\ \downarrow \exp_p & & \downarrow \exp_{p'} \\ M & \xrightarrow{\phi} & M' \end{array}$$

### Proposition

*There exist  $U$  and  $V$  open neighborhoods respectively of  $o \in T_p M$  and  $p \in M$ , s.t.  $\exp_p : U \rightarrow V$  is a diffeomorphism. Furthermore if we fix an orthonormal basis of  $T_p M$  we obtain an isomorphism  $F$  with  $\mathbb{R}^n$ , combined with  $\exp^{-1}$  gives normal coordinate chart.*

### Proposition

*Let  $G$  be a Lie group equipped with bi-invariant riemannian metric. Then the Lie group exponential map is precisely the reimannian exponential map starting at the identity.*

Let  $f : M \rightarrow \mathbb{R}$  be a Morse-Bott function on a compact riemannian manifold whose critical submanifolds have all index and coindex different from one. The the level sets of  $f$  are connected.

# Convexity theorem

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# Convexity theorem

Let  $(M, \omega)$  be a compact connected symplectic manifold, and let  $\mathbb{T}^m$  be an  $m$ -torus. Suppose that  $\psi : \mathbb{T}^m \rightarrow \text{Symp}(M, \omega)$  is a hamiltonian action with moment map  $\mu : M \rightarrow \mathbb{R}^m$ . Then:

1. the levels of  $\mu$  are connected
2. the image of  $\mu$  is convex
3. the image of  $\mu$  is convex hull of the images of the fixed points of the action