

# ...Machine Learning...

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# Fork e Join

- $(\triangle) :: \text{Cartesian } k \Rightarrow (a \text{ 'k' } c) \rightarrow (a \text{ 'k' } d) \rightarrow (a \text{ 'k' } (c \times d))$
- $(\nabla) :: \text{Cartesian } k \Rightarrow (c \text{ 'k' } a) \rightarrow (d \text{ 'k' } a) \rightarrow ((c \times d) \text{ 'k' } a)$

# instancia de $\rightarrow^+$

**`newtype`**  $a \rightarrow^+ b = \text{AddFun } (a \rightarrow b)$

**`instance`** `Category`  $(\rightarrow^+)$  **`where`**

`type` `Obj`  $(\rightarrow^+) = \text{Additive}$

`id` = `AddFun id`

`AddFun g`  $\circ$  `AddFun f` = `AddFun (g  $\circ$  f)`

**`instance`** `Monoidal`  $(\rightarrow^+)$  **`where`**

`AddFun f`  $\times$  `AddFun g` = `AddFun (f  $\times$  g)`

**`instance`** `Cartesian`  $(\rightarrow^+)$  **`where`**

`exl` = `AddFun exl`

`exr` = `AddFun exr`

`dup` = `AddFun dup`

# instancia de $\rightarrow^+$

**instance** Cocartesian ( $\rightarrow^+$ ) **where**

inl = AddFun inlF

inr = AddFun inrF

jam = AddFun jamF

inlF :: Additive b  $\Rightarrow$  a  $\rightarrow$  a  $\times$  b

inrF :: Additive a  $\Rightarrow$  b  $\rightarrow$  a  $\times$  b

jamF :: Additive a  $\Rightarrow$  a  $\times$  a  $\rightarrow$  a

inlF =  $\lambda a \rightarrow (a, 0)$

inrF =  $\lambda b \rightarrow (0, b)$

jamF =  $\lambda(a, b) \rightarrow a + b$

# definição de NumCat

**class** NumCat k a **where**

negateC :: a 'k' a

addC :: (a × a) 'k' a

mulC :: (a × a) 'k' a

...

**instance** Num a  $\Rightarrow$  NumCat ( $\rightarrow$ ) a **where**

negateC = negate

addC = uncurry (+)

mulC = uncurry (·)

...



$$D (\text{negate } u) = \text{negate } (D u)$$

$$D (u + v) = D u + D v$$

$$D (u \cdot v) = u \cdot D v + v \cdot D u$$

- Impreciso na natureza de  $u$  e  $v$ .
- Algo mais preciso seria defenir a diferenciação das operações em si.

**class** Scalable k a **where**

scale :: a  $\rightarrow$  (a 'k' a)

**instance** Num a  $\Rightarrow$  Scalable ( $\rightarrow^+$ ) a **where**

scale a = AddFun ( $\lambda da \rightarrow a \cdot da$ )

**instance** NumCat D **where**

negateC = linearD negateC

addC = linearD addC

mulC = D ( $\lambda(a, b) \rightarrow (a \cdot b, \text{scale } b \nabla \text{scale } a)$ )

# Generalizing Automatic Differentiation

`newtype  $D_k$  a b = D (a  $\rightarrow$  b  $\times$  (a 'k' b))`

`linearD :: (a  $\rightarrow$  b)  $\rightarrow$  (a 'k' b)  $\rightarrow D_k$  a b`

`linearD f f' = D ( $\lambda$ a  $\rightarrow$  (f a, f'))`

**instance** Category k  $\Rightarrow$  Category  $D_k$  **where**

    type Obj  $D_k$  = Additive  $\wedge$  Obj k ...

**instance** Monoidal k  $\Rightarrow$  Monoidal  $D_k$  **where** ...

**instance** Cartesian k  $\Rightarrow$  Cartesian  $D_k$  **where** ...

**instance** Cocartesian k  $\Rightarrow$  Cocartesian  $D_k$  **where**

    inl = linearD inlF inl

    inr = linearD inrF inr

    iam = linearD iamF iam

**instance** Scalable k s  $\Rightarrow$  NumCat  $D_k$  s **where**  
negateC = linearD negateC negateC  
addC = linearD addC addC  
mulC = D ( $\lambda(a, b) \rightarrow (a \cdot b, \text{scale } b \nabla \text{scale } a)$ )

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# Exemplos

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