

Instance of \rightarrow^+

`newtype` $a \rightarrow^+ b = \text{AddFun } (a \rightarrow b)$

`instance` *Category* (\rightarrow^+) **`where`**

`type` *Obj* $(\rightarrow^+) = \text{Additive}$

$\text{id} = \text{AddFun id}$

$\text{AddFun } g \circ \text{AddFun } f = \text{AddFun } (g \circ f)$

`instance` *Monoidal* (\rightarrow^+) **`where`**

$\text{AddFun } f \times \text{AddFun } g = \text{AddFun } (f \times g)$

`instance` *Cartesian* (\rightarrow^+) **`where`**

$\text{exl} = \text{AddFun exl}$

$\text{exr} = \text{AddFun exr}$

$\text{dup} = \text{AddFun dup}$

Fork and Join

- $\nabla :: \text{Cartesian } k \Rightarrow (a' \text{ k}' c) \rightarrow (a' \text{ k}' d) \rightarrow (a' \text{ k}' (c \times d))$
- $\Delta :: \text{Cartesian } k \Rightarrow (c' \text{ k}' a) \rightarrow (d' \text{ k}' a) \rightarrow ((c + d)' \text{ k}' a)$

...Machine Learning...

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Fork e Join

- $(\Delta) :: \text{Cartesian } k \Rightarrow (a \text{ 'k' } c) \rightarrow (a \text{ 'k' } d) \rightarrow (a \text{ 'k' } (c \times d))$
- $(\nabla) :: \text{Cartesian } k \Rightarrow (c \text{ 'k' } a) \rightarrow (d \text{ 'k' } a) \rightarrow ((c \times d) \text{ 'k' } a)$

instancia de \rightarrow^+

newtype $a \rightarrow^+ b = \text{AddFun } (a \rightarrow b)$

instance Category (\rightarrow^+) **where**

type Obj (\rightarrow^+) = Additive

id = AddFun id

AddFun $g \circ \text{AddFun } f = \text{AddFun } (g \circ f)$

instance Monoidal (\rightarrow^+) **where**

AddFun $f \times \text{AddFun } g = \text{AddFun } (f \times g)$

instance Cartesian (\rightarrow^+) **where**

exl = AddFun exl

exr = AddFun exr

dup = AddFun dup

instancia de \rightarrow^+

instance Cocartesian (\rightarrow^+) **where**

inl = AddFun inlF

inr = AddFun inrF

jam = AddFun jamF

inlF :: Additive b \Rightarrow a \rightarrow a \times b

inrF :: Additive a \Rightarrow b \rightarrow a \times b

jamF :: Additive a \Rightarrow a \times a \rightarrow a

inlF = $\lambda a \rightarrow (a, 0)$

inrF = $\lambda b \rightarrow (0, b)$

jamF = $\lambda(a, b) \rightarrow a + b$

definição de NumCat

class NumCat k a **where**

negateC :: a 'k' a

addC :: (a × a) 'k' a

mulC :: (a × a) 'k' a

...

instance Num a \Rightarrow NumCat (\rightarrow) a **where**

negateC = negate

addC = uncurry (+)

mulC = uncurry (·)

...

$$D (\text{negate } u) = \text{negate } (D u)$$

$$D (u + v) = D u + D v$$

$$D (u \cdot v) = u \cdot D v + v \cdot D u$$

- Impreciso na natureza de u e v .
- Algo mais preciso seria definir a diferenciação das operações em si.

class Scalable k a **where**

scale :: a \rightarrow (a 'k' a)

instance Num a \Rightarrow Scalable (\rightarrow^+) a **where**

scale a = AddFun ($\lambda da \rightarrow a \cdot da$)

instance NumCat D **where**

negateC = linearD negateC

addC = linearD addC

mulC = D ($\lambda(a, b) \rightarrow (a \cdot b, \text{scale } b \nabla \text{scale } a)$)

Generalizing Automatic Differentiation

`newtype D_k a b = D (a \rightarrow b \times (a 'k' b))`

`linearD :: (a \rightarrow b) \rightarrow (a 'k' b) \rightarrow D_k a b`

`linearD f f' = D (λ a \rightarrow (f a, f'))`

instance Category k \Rightarrow Category D_k **where**

 type Obj D_k = Additive \wedge Obj k ...

instance Monoidal k \Rightarrow Monoidal D_k **where** ...

instance Cartesian k \Rightarrow Cartesian D_k **where** ...

instance Cocartesian k \Rightarrow Cocartesian D_k **where**

 inl = linearD inlF inl

 inr = linearD inrF inr

 iam = linearD iamF iam

instance Scalable k s \Rightarrow NumCat D_k s **where**
negateC = linearD negateC negateC
addC = linearD addC addC
mulC = D ($\lambda(a, b) \rightarrow (a \cdot b, \text{scale } b \nabla \text{scale } a)$)

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