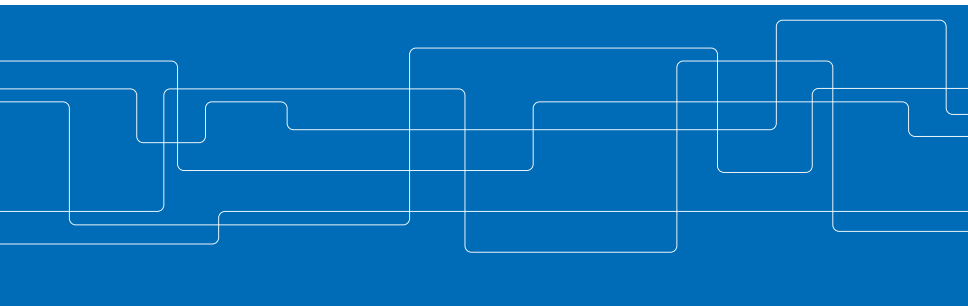




# EAD: Elastic-Net Attacks to Deep Neural Networks via Adversarial Examples

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## Elastic Net Regularization

- ▶ Elastic-net regularization is widely used in solving high-dimensional feature selection
- ▶ Can be viewed as a regularizer linearly combines two penalty functions  $L_1$  and  $L_2$
- ▶ Used in following minimization problem

$$\underset{z \in Z}{\text{minimize}} \quad f(z) + \lambda_1 \|z\|_1 + \lambda_2 \|z\|_2^2$$

- ▶ where  $z$  is a vector of  $p$  optimization variables
- ▶  $Z$  the set of feasible solutions
- ▶  $f(z)$  denotes a loss function
- ▶  $\|z\|_q$  denotes  $L_q$  norm
- ▶  $0 \leq \lambda_1, \lambda_2$  are the regularization parameters



## Elastic Net Regularization

$$\underset{z \in Z}{\text{minimize}} \quad f(z) + \lambda_1 \|z\|_1 + \lambda_2 \|z\|_2^2$$

- ▶  $0 \leq \lambda_1, \lambda_2$  are the regularization parameters
- ▶ The elastic-net regularization yields LASSO when  $\lambda_2 = 0$
- ▶ Becomes ridge regression formulation when  $\lambda_1 = 0$
- ▶ Elastic-net regularization is able to select a group of highly correlated features overcomes the shortcoming of high dimensional feature selection



## EAD Formulation and Generalization

- ▶ Same loss function with Carlini and Wagner
- ▶ Given an image  $x_o$  and correct label denoted by  $t_o$
- ▶ Adversarial example  $x$  of image  $x_o$  with a target  $t \neq t_o$
- ▶ The loss function  $f(x)$  defined as

$$f(x, t) = \max\{\max_{j \neq t} [\mathbf{Logit}(x)]_j - [\mathbf{Logit}(x)]_t, -\kappa\} \quad (1)$$

- ▶ where  $\mathbf{Logit} = [[\mathbf{Logit}]_1, \dots, [\mathbf{Logit}]_K] \in \mathbb{R}^K$  is the layer before the softmax
- ▶  $K$  is the number of classes
- ▶  $0 \leq \kappa$  is the confidence parameter guarantees a constant gap between  $\max_{j \neq t} [\mathbf{Logit}(\mathbf{x})]_j$  and  $[\mathbf{Logit}(\mathbf{x})]_t$



## EAD Formulation and Generalization

- ▶  $[\mathbf{Logit}]_t$  is proportional to the probability of predicting  $x$  as label  $t$

$$Prob(Label(x) = t) = \frac{\exp([\mathbf{Logit}]_t)}{\sum_{j=1}^K \exp([\mathbf{Logit}]_j)} \quad (2)$$

- ▶ The loss function aims to render label  $t$  the most probable outcome for  $x$  and the parameter  $\kappa$  controls the separation between  $t$  and most likely prediction other than  $t$ .
- ▶ For untargeted,

$$f(x) = \max\{[\mathbf{Logit}(x)]_{t_o} - \max_{j \neq t} [\mathbf{Logit}(x)]_j, -\kappa\} \quad (3)$$

- ▶ Focus of the paper is targeted
- ▶ Can be applied to targeted by replacing  $f(x, t)$  by  $f(x)$



## EAD Formulation and Generalization

$$\begin{aligned} \underset{x}{\text{minimize}} \quad & c \cdot f(x, t) + \beta \|x - x_o\|_1 + \|x - x_o\|_2^2 \\ \text{subject to} \quad & x \in [0, 1]^p \end{aligned}$$

- ▶ where  $0 \leq c, \beta$  are regularization parameters of the loss function and  $L_1$  penalty respectively
- ▶ The box constraint  $x \in [0, 1]^p$  restricts  $x$  to be a properly scaled image space
- ▶ EAD formulation aims to find
  - ▶ An adversarial example  $x$
  - ▶ Classified as target class  $t$
  - ▶ While minimizing the distortion  $\delta = x - x_o$



## EAD Formulation and Generalization

- ▶  $\delta$  is the loss
  - ▶  $\beta ||\delta||_1 + ||\delta||_2^2$
  - ▶ Linear combination of  $L_1$  and  $L_2$  metrics
- ▶ CW is a special case of EAD
  - ▶ when  $\beta = 0$  disregards the  $L_1$  penalty on  $\delta$
- ▶  $L_1$  penalty is an intuitive regularizer
- ▶  $||\delta||_1 = \sum_{i=1}^p |\delta_i|$  represents the total variation of the perturbation
- ▶ Surrogate function for promoting sparsity
- ▶ Improves attack transferability
- ▶ Complements adversarial learning



## EAD Algorithm

- ▶ CW used change-of-variable (COV) approach via  $\tanh$  transformation on  $x$  remove the box constraint  $x \in [0, 1]^p$
- ▶ When  $0 < \beta$  COV is not effective
- ▶ Since the corresponding adversarial examples are insensitive to the changes in  $\beta$
- ▶  $L_1$  penalty is non-differentiable, yet piece-wise linear function
- ▶ The failure of COV approach can be explained by inefficiency in subgradient based optimization problems.
- ▶ Paper propose iterative shrinkage thresholding algorithm (ISTA)
- ▶ ISTA regular first order optimization algorithm with an additional shrinkage thresholding step on each iteration





## Iterative Shrinkage Thresholding algorithm (ISTA)

- ▶ Let  $g(x) = c \cdot f(x) + \|x - x_o\|_2^2$  and  $\nabla g(x)$  be the numerical gradient computed by DNN
- ▶ At  $k + 1$  iteration the adversarial example  $x^{k+1}$  of  $x_o$

$$x^{(k+1)} = S_\beta(x^{(k)} - \alpha_k \nabla g(x^{(k)})) \quad (4)$$

- ▶  $\alpha_k$  denotes the step size at the  $k + 1$  iteration
- ▶  $S_\beta : \mathbb{R}^p \rightarrow \mathbb{R}^p$  element-wise projected shrinkage thresholding function

$$[S_\beta(z)]_i = \begin{cases} \min \{z_i - \beta, 0\} & z_i - x_{oi} > \beta \\ x_{oi} & |z_i - x_{oi}| \leq \beta \\ \max \{z_i + \beta, 0\} & z_i - x_{oi} < -\beta \end{cases}$$



## Iterative Shrinkage Thresholding Algorithm (ISTA)

$$[S_{\beta}(z)]_i = \begin{cases} \min \{z_i - \beta, 1\} & z_i - x_{oi} > \beta \\ x_{oi} & |z_i - x_{oi}| \leq \beta \\ \max \{z_i + \beta, 0\} & z_i - x_{oi} < -\beta \end{cases}$$

- ▶ For any  $i \in \{1, 2, \dots, p\}$
- ▶ Shrinks to element  $z_i$  by  $\beta$  when  $z_i - x_{oi} > \beta$
- ▶ Thresholds  $z_i$  by setting  $[S_{\beta}(z)]_i = x_{oi}$  when  $|z_i - x_{oi}| \leq \beta$
- ▶  $g(x)$  is the attack objective function of the C&W method
- ▶ ISTA can be seen as robust version of C&W
- ▶ Where shrinks a pixel value of the adversarial example if the deviation to the original image is greater than  $\beta$  and keeps a pixel value unchanged if the deviation is less than  $\beta$

# Elastic-Net Attacks to DNNs (EAD)

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## Algorithm 1 Elastic-Net Attacks to DNNs (EAD)

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**input:** Original labeled image  $x_o, t_o$ , target attack class  $t$ , attack transferability parameter  $\kappa, L_1$  regularization parameter  $\beta$ , step size  $\alpha_k$ , # of iteration  $I$

**output:** An adversarial example  $x$

Initialization:  $x^{(0)} = y^{(0)} = x_o$

**for**  $k = 0:I-1$  **do**

$$x^{(k+1)} = S_{\beta}(y^{(k)} - \alpha_k \nabla g(y^{(k)}))$$

$$y^{(k+1)} = x^{(k+1)} + \frac{k}{k+3}(x^{k+1} - x^{(k)})$$

**end for**

Decision rule: determine  $x$  from successful examples in  $\{x^{(k)}\}_{k=1}^I$  (EN rule or  $L_1$  ) rule

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- ▶ The slack vector  $y^{(k)}$  incorporates the momentum  $x^{(k)}$  for acceleration
- ▶ Learning rate set to  $\alpha_o = 0.01$
- ▶ During the EAD iterations  $x^{(k)}$  considered as successful adversarial example of  $x_o$
- ▶ If the model predicts its most likely class to be the target class  $t$
- ▶ The final adversarial example is selected from all successful examples based on distortion metrics.
- ▶ Authors consider two decision rules for selecting  $x$  the least elastic-net and  $L_1$  relative to  $x_o$



## Evaluation

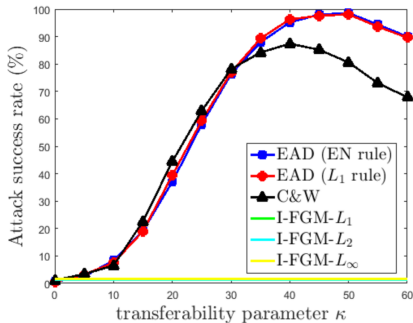
- ▶ EAD performance similar to C&W performance since C&W is the special case of EAD
- ▶ Compared to existing  $L_1$  based FGM and I-FGM
  - ▶ Significantly lower  $L_1$  distortion
  - ▶ Better attack success rate
- ▶  $L_1$  based adversarial examples crafted by EAD improves attack transferability and complements adversarial training.

## Evaluation

Attack method	MNIST				CIFAR10				ImageNet			
	ASR	$L_1$	$L_2$	$L_\infty$	ASR	$L_1$	$L_2$	$L_\infty$	ASR	$L_1$	$L_2$	$L_\infty$
C&W ( $L_2$ )	<b>100</b>	22.46	<b>1.972</b>	0.514	<b>100</b>	13.62	<b>0.392</b>	0.044	<b>100</b>	232.2	<b>0.705</b>	0.03
FGM- $L_1$	39	53.5	4.186	0.782	48.8	51.97	1.48	0.152	1	61	0.187	0.007
FGM- $L_2$	34.6	39.15	3.284	0.747	42.8	39.5	1.157	0.136	1	2338	6.823	0.25
FGM- $L_\infty$	42.5	127.2	6.09	0.296	52.3	127.81	2.373	0.047	3	3655	7.102	0.014
I-FGM- $L_1$	<b>100</b>	32.94	2.606	0.591	<b>100</b>	17.53	0.502	0.055	77	526.4	1.609	0.054
I-FGM- $L_2$	<b>100</b>	30.32	2.41	0.561	<b>100</b>	17.12	0.489	0.054	<b>100</b>	774.1	2.358	0.086
I-FGM- $L_\infty$	<b>100</b>	71.39	3.472	<b>0.227</b>	<b>100</b>	33.3	0.68	<b>0.018</b>	<b>100</b>	864.2	2.079	<b>0.01</b>
EAD (EN rule)	<b>100</b>	<b>17.4</b>	2.001	0.594	<b>100</b>	<b>8.18</b>	0.502	0.097	<b>100</b>	<b>69.47</b>	1.563	0.238
EAD ( $L_1$ rule)	<b>100</b>	<b>14.11</b>	2.211	0.768	<b>100</b>	<b>6.066</b>	0.613	0.17	<b>100</b>	<b>40.9</b>	1.598	0.293

- ▶ Authors show that adversarial examples crafted by EAD can be successful as the state-of-the-art  $L_2$  and  $L_\infty$  attacks in breaking and undefended and defensively distilled networks.
- ▶ Furthermore, it improves the attack transferability and complements the adversarial training.

## Evaluation



- Attack transferability (average case) from the undefended network to the defensively distilled network on MNIST by varying  $\kappa$ . EAD can attain nearly 99% attack success rate (ASR) when  $\kappa = 50$ , whereas the top ASR of the C&W attack is nearly 88 % when  $\kappa = 50$ .



## Evaluation

Attack method	Adversarial training	Average case			
		ASR	$L_1$	$L_2$	$L_\infty$
C&W ( $L_2$ )	None	100	22.46	1.972	0.514
	EAD	100	26.11	2.468	0.643
	C&W	100	24.97	2.47	0.684
	EAD + C&W	100	27.32	2.513	0.653
EAD ( $L_1$ rule)	None	100	14.11	2.211	0.768
	EAD	100	17.04	2.653	0.86
	C&W	100	15.49	2.628	0.892
	EAD + C&W	100	16.83	2.66	0.87

- Adversarial training using the C&W attack and EAD ( $L_1$  rule) on MNIST. ASR means attack success rate. Incorporating  $L_1$  examples complements adversarial training and enhances attack difficulty in terms of distortion.