

Yeadon Measurements

For use with the **yeadon** python module by C. Dembia (fitze)

Key:

● denotes a joint centre

L (on the left) denotes a level at which a stadium solid or circle is defined (except for **Ls8**)

L (on the right) denotes a length measurement

Ls1L-Ls5L measured from **Ls0**; **Ls6L-Ls8L** measured from **Ls5L**

La2L-La4L measured from **La0**; **La5L-La7L** measured from **La4L** (some for **b**)

Lj1L,Lj3-5L measured from **Lj0**; **Lj6L,Lj8L-Lj9L** measured from **Lj5L** (same for **k**)

p denotes a perimeter measurement, must have $2w < p < \pi w$

w denotes a width (medio-lateral, or side to side) measurement

d denotes a depth (anterior-posterior, or front to back) measurement

level, name, measurements needed

Ls8¹ top of head L

Ls7 above ear L,p

Ls6 beneath nose L,p

Ls5² acromion L,p

Ls4³ shoulder joint centre L,w,d

Ls3 nipple L,p,w

Ls2 lowest front rib L,p,w

Ls1 umbilicus L,p,w

Ls0 hip joint centre L,p,w

La0 shoulder joint centre p

La1⁴ mid-arm p

La2 elbow-joint centre L,p

La3 maximum forearm perimeter L,p

La4 wrist joint centre L,p,w

La5 base of thumb L,p,w

La6 knuckles L,p,w

La7 fingernails L,p,w

Lj0⁵ hip joint centre

Lj1 crotch L,p

Lj2⁶ mid-thigh p

Lj3 knee joint centre L,p

Lj4 maximum calf perimeter L,p

Lj5 ankle joint centre L,p

Lj6⁷ heel L,p,d

Lj7⁸ arch p

Lj8 ball L,p,w

Lj9 toe nails L,p,w

segment, name, solids⁹

P pelvis **s0-s1**

T thorax **s2**

C chest-head **s3-7**

A1 left upper arm **a0-a1**

A2 left forearm-hand **a2-6**

B1 right upper arm **b0-b1**

B2 right forearm-hand **b2-b6**

J1 left thigh **j0-j2**

J2 left shank-foot **j3-j8**

K1 right thigh **k0-k2**

K2 right shank-foot **k3-k8**

Notes:

Total mass can be measured and provided to "correct" the densities used.

1 **s0** is the only semi-ellipsoidal solid (with circular cross section)

2 two stadia at this level, one for **s4** and one for **s5**. **s4** stadium's parameters are calculated from **Ls4**'s stadium. **Ls5** perimeter measured around neck

3 depth is measured in lieu of perimeter since arms interfere

4 **La1L** is set as half of **La2L**

5 stadium (circle) parameter calculated from **Ls0**'s stadium

6 **Lj2L** is set as the average of **Lj1L** and **Lj3L**

7 **Lj6**'s (and **Lk6**'s) stadia are the only stadium oriented anterior-posteriorly

8 **Lj7L** is set as the average of **Lj6L** and **Lj8L**

9 Yeadon's 1990 paper indexes the solids from 1, while this formulations indexes from 0

Yeadon, M. R. (1990c). The simulation of aerial movement-ii. a mathematical inertia model of the human body. Journal of Biomechanics, 23:67-74.