Lab 6

1a.) By simulation, the probability that Thursday is a medium day is 0.41233. Mathematically, that probability is 0.412

import numpy as np

```
P = np.array([[.5, .3, .2], [.2, .6, .2], [.3, .2, .5]])
trials = 100000
mediumDays= 0
rolls = np.random.rand(trials,3)
ThursdayState = np.zeros(trials)
for i in range(trials):
        state = 1
        for j in range(3):
                 sum = 0
                 for k in range(3):
                         sum = sum + P[state, k]
                          #print(rolls[i,j])
                         #print(P[state,k])
                         if(rolls[i,j] <= sum):</pre>
                                  state = k
                                  #print(state)
                                  break
                          #print(state)
        #print(state)
        if(state == 1):
                 mediumDays = mediumDays + 1
```

```
ThursdayState[i] = state
print(" By simulation, P(Thursday is a medium day) = " + str( mediumDays / trials))
MediumDay = np.array([0,1,0])
P3 = np.copy(P)
for i in range(2):
        P3 = np.dot(P3,P)
Thursday = np.dot(MediumDay, P3)
print(" By math, P(Thursday is a medium day) = " + str( Thursday[1]))
1b.) By simulation, the expected number of good days is 2.28339. Mathematically, the answer is 2.0612.
import numpy as np
trials = 100000
P = np.array([[.5, .3, .2], [.2, .6, .2], [.3, .2, .5]])
rolls = np.random.rand(trials,7)
numGoodDaysA = np.zeros(trials)
for i in range(trials):
        state = 2
        goodDays = 0
        for j in range(7):
                sum = 0
                for k in range(3):
                         sum = sum + P[state, k]
                        if(rolls[i,j] <= sum):</pre>
                                 state = k
                                 break
```

```
if(state == 0):
                        goodDays = goodDays + 1
        numGoodDaysA[i] = goodDays
mean = np.mean(numGoodDaysA)
print(" By simulation, the expected number of good days = " + str(mean))
P0 = np.array([[0, .3, .2], [0, .6, .2], [0, .2, .5]])
I = np.identity(3)
diff = np.subtract(I,P0)
inverse = np.linalg.inv(diff)
M = [[1],[1],[1]]
m = np.dot(inverse,M)
mathmean = float((7 - m[2])/m[0] + 1)
print("By math, the expected number of good days = " + str(mathmean))
1.c) By simulation, the percentage of good days over the long run is 0.326602. Mathematically that
answer is 0.32653
import numpy as np
trials = 1000000
P = np.array([[.5, .3, .2], [.2, .6, .2], [.3, .2, .5]])
rolls = np.random.rand(trials)
numGoodDays = 0
state = 2
for i in range(trials):
        sum = 0
        for k in range(3):
                sum = sum + P[state, k]
                if(rolls[i] <= sum):</pre>
                        state = k
```

```
break
        if(state == 0):
                numGoodDays = numGoodDays + 1
percentGoodDays = numGoodDays / trials
print(" By simulation, the \% of good days over the long run = " + str(percentGoodDays))
P10000 = np.copy(P)
for i in range(9999):
        P10000 = np.dot(P10000, P)
p = np.array([0,0,1])
A = np.dot(p,P10000)
ans = float(A[0])
print(" By math, the \% of good days over the long run = " + str(ans))
1d.) By simulation, the expected number of days until it gets good is 3.74306. Mathematically, the
expected number of days until it gets good is 3.75
import numpy as np
trials = 1000000
P = np.array([[.5, .3, .2], [.2, .6, .2], [.3, .2, .5]])
rolls = np.random.rand(trials)
daysElapsed = 0
daysElapsedA = list()
state = 2
for i in range(trials):
       sum = 0
       for k in range(3):
                sum = sum + P[state, k]
```

```
if(rolls[i] <= sum):</pre>
                         state = k
                         break
        daysElapsed = daysElapsed + 1
        if(state == 0):
                daysElapsedA.append(daysElapsed)
                daysElapsed = 0
                state = 2
mean = np.mean(daysElapsedA)
print(" By simulation, the expected number days until it gets good = " + str(mean))
P0 = np.array([[0, .3, .2], [0, .6, .2], [0, .2, .5]])
I = np.identity(3)
diff = np.subtract(I,P0)
inverse = np.linalg.inv(diff)
M = [[1],[1],[1]]
m = np.dot(inverse,M)
mathmean = float(m[2])
print(" By math, the expected number days until it gets good= " + str(mathmean))
1e) By simulation, the expected number of days until it gets better is 1.99733. Mathematically, the
expected number of days until it gets better is 1.9835
import numpy as np
trials = 1000000
P = np.array([[.5, .3, .2], [.2, .6, .2], [.3, .2, .5]])
rolls = np.random.rand(trials)
daysElapsed = 0
daysElapsedA = list()
state = 2
```

```
for i in range(trials):
        sum = 0
        for k in range(3):
                sum = sum + P[state, k]
                if(rolls[i] <= sum):</pre>
                         state = k
                         break
        daysElapsed = daysElapsed + 1
        if(state != 2):
                daysElapsedA.append(daysElapsed)
                 daysElapsed = 0
                state = 2
mean = np.mean(daysElapsedA)
print(" By simulation, the expected number days until it gets better = " + str(mean))
P0 = np.array([[0, .3, .2], [0, .6, .2], [0, .2, .5]])
I = np.identity(3)
diff = np.subtract(I,P0)
inverse = np.linalg.inv(diff)
M = [[1],[1],[1]]
m0 = np.dot(inverse,M)
P1 = np.array([[.5, 0, .2], [.2, 0, .2], [.3, 0, .5]])
I = np.identity(3)
diff = np.subtract(I,P1)
inverse = np.linalg.inv(diff)
M = [[1],[1],[1]]
m1= np.dot(inverse,M)
mathmean = float(1/(1/m0[2] + 1/m1[2]))
print(" By math, the expected number days until it gets better= " + str(mathmean))
```

2.) By simulation, the probability of at least 8 flips until 3 consecutive heads is 0.63435 and the average number of flips until this condition is 13.998. Mathematically, the average number of flips until 3 consecutive heads is 14. And the probability of absorption vector is [[1][1][1]]. That is the probability of 3 consecutive heads approaches 1 as the number of flips approaches infinity.

```
import numpy as np
trials = 3000009
flips = np.random.rand(trials)
numFlipsUntilSuccss = 0
numFlipsUntilSuccssArr = list()
cnscHeads = 0
atLeast8 = 0
numSuccesses = 0
for i in range(trials):
        numFlipsUntilSuccss = numFlipsUntilSuccss + 1
        if(flips[i] < .5):
               cnscHeads = cnscHeads + 1
               if(cnscHeads == 3):
                        numSuccesses = numSuccesses + 1
                        if(numFlipsUntilSuccss >= 8):
                                atLeast8 = atLeast8 + 1
                        numFlipsUntilSuccssArr.append(numFlipsUntilSuccss)
                        numFlipsUntilSuccss = 0
                        cnscHeads = 0
        if(flips[i] >= .5):
                cnscHeads = 0
mean = np.mean(numFlipsUntilSuccssArr)
pAtLeast8 = atLeast8 / numSuccesses
print("By simulation, the probability of at least 8 flips until 3 consecutive heads = " + str(pAtLeast8))
```

```
print("By simulation, the average number of flips until 3 consecutive heads = " + str(mean))
Q = np.array([[1/2, 1/2, 0], [1/2, 0, 1/2], [1/2, 0, 0]])
I = np.identity(3)
diff = np.subtract(I,Q)
inverse = np.linalg.inv(diff)
M = np.array([[1],[1],[1]])
A = np.dot(inverse, M)
mathmean = float(A[0])
print("By Markov Chain analysis, the average number of flips until 3 consective heads = " + str(mathmean))
R = np.array([[0],[0],[1/2]])
B = np.dot(inverse, R)
print("The probabities of absortion are given by the following vector")
print(B)
```