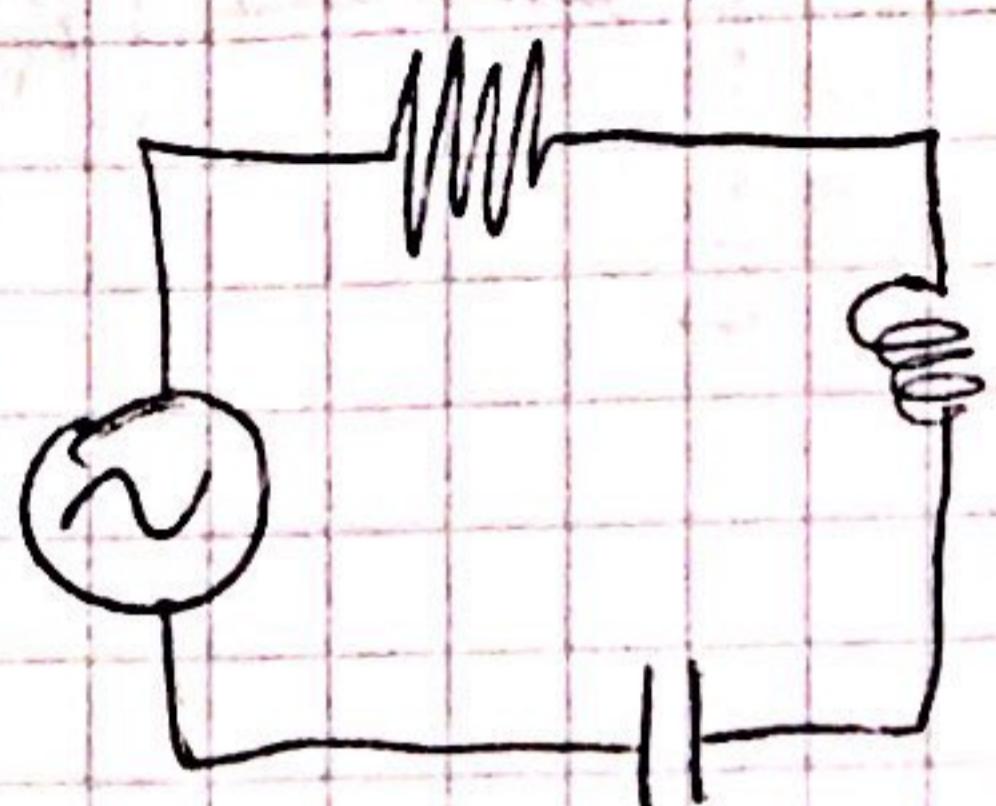


PRACTICO 9

(1)

a)



$$V_o \cos(\omega t) = \frac{q}{C} + R \frac{dq}{dt} + L \frac{d^2 q}{dt^2}$$

Propuesto $q(t) = A \cos(\omega t) + B \sin(\omega t)$

(Luego:

$$\begin{aligned} V_o \cos(\omega t) &= \frac{1}{C} [A \cos(\omega t) + B \sin(\omega t)] + R [-A \omega \sin(\omega t) + B \omega \cos(\omega t)] + L [-A \omega^2 \cos(\omega t) - B \omega^2 \sin(\omega t)] \\ &= \sin(\omega t) [\frac{B}{C} - RA\omega - BL\omega^2] + \cos(\omega t) [\frac{A}{C} + RB\omega - LA\omega^2] \end{aligned}$$

Soluciones

$$(x) \quad V_o = \frac{A}{C} + RB\omega - LA\omega^2$$

$$(y) \quad \frac{B}{C} - RA\omega - BL\omega^2 = 0$$

De (y):

$$B \left(\frac{1}{C} - L\omega^2 \right) = RA\omega \implies B = \frac{RA\omega}{\frac{1}{C} - L\omega^2}$$

(Luego en (x))

$$A \left(\frac{1}{C} + \frac{(RA\omega)^2}{\frac{1}{C} - L\omega^2} - L\omega^2 \right) = V_o \implies A = V_o \cdot \left(\frac{1}{C} + \frac{(RA\omega)^2}{\frac{1}{C} - L\omega^2} - L\omega^2 \right)^{-1}$$

$$= V_0 \left[\left(\frac{1}{C} - L\omega^2 \right) + \left(\frac{(R\omega)^2}{\frac{1}{C} - L\omega^2} \right) \right]^{-1} = V_0 \left[\frac{1}{\frac{1}{C} - L\omega^2} \cdot \left[\left(\frac{1}{C} - L\omega^2 \right)^2 + (R\omega)^2 \right] \right]^{-1}$$

$$= V_0 \left[\frac{\omega^2}{\frac{1}{C} - L\omega^2} \left[\left(\frac{1}{C\omega} - L\omega \right)^2 + R^2 \right] \right]^{-1} = V_0 \left[\frac{\omega}{\frac{1}{C\omega} - L\omega} \left[R^2 + \left(\frac{1}{C\omega} - L\omega \right)^2 \right] \right]^{-1}$$

$$= V_0 \left[\frac{\omega}{X_C - X_L} [Z^2] \right]^{-1} = \frac{V_0 (X_C - X_L)}{\omega Z^2}$$

$$\rightsquigarrow A = \frac{V_0 (X_C - X_L)}{\omega Z^2}$$

y por lo tanto:

$$B = A \cdot \frac{R\omega}{\frac{1}{C} - L\omega^2} = A \cdot \frac{R}{\frac{1}{C\omega} - L\omega} = A \cdot \frac{R}{X_C - X_L} = \frac{V_0 (X_C - X_L)}{\omega Z^2} \cdot \frac{R}{X_C - X_L} = \frac{VR}{\omega Z^2}$$

Finalmente:

$$q(t) = \frac{V_0 (X_C - X_L)}{\omega Z^2} \cos(\omega t) + \frac{VR}{\omega Z^2} \sin(\omega t)$$

$$\Rightarrow i(t) = - \underbrace{\frac{V (X_C - X_L)}{Z^2} \sin(\omega t)}_{\alpha} + \underbrace{\frac{VR}{Z^2} \cos(\omega t)}_{\beta}$$

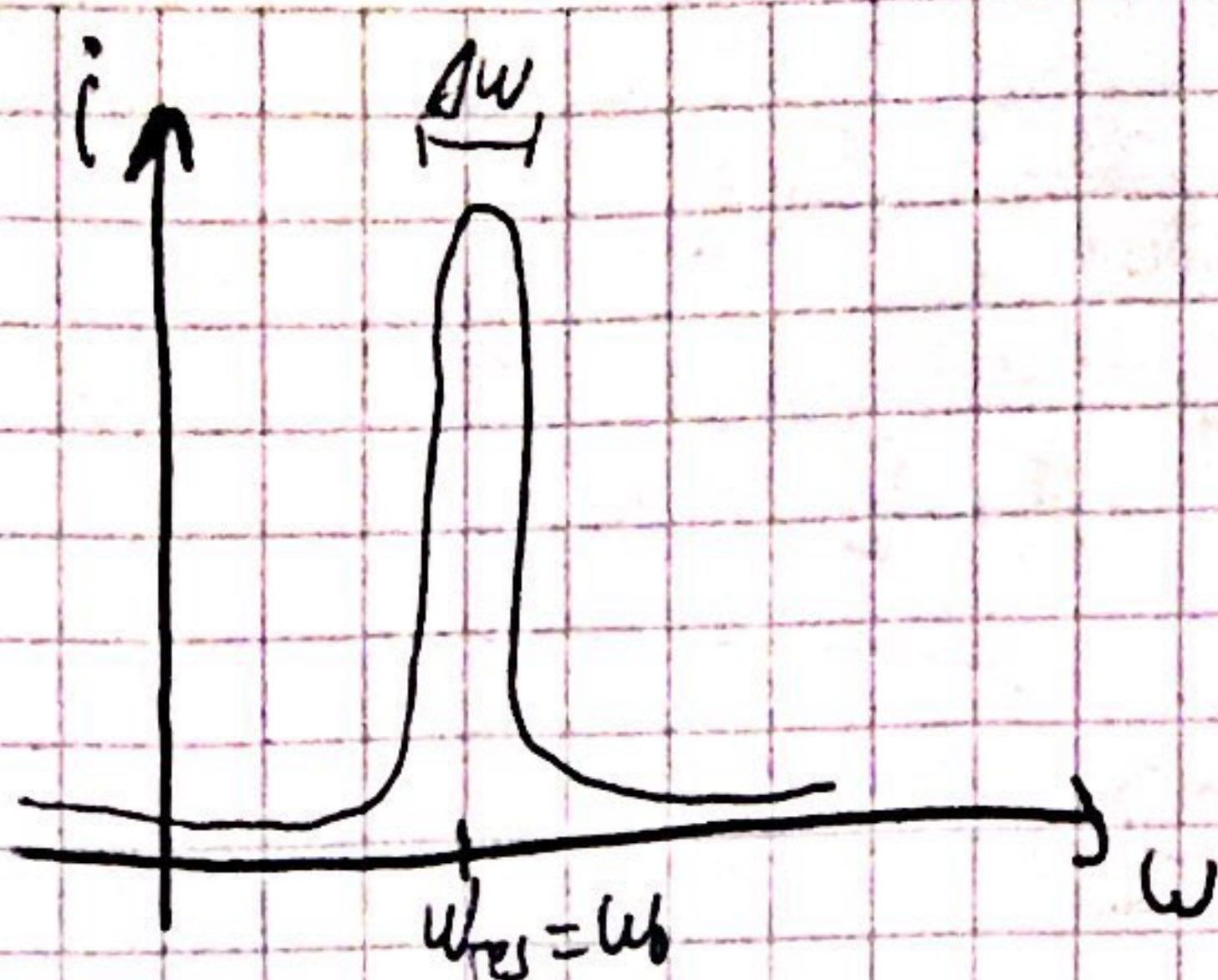
Se puede demostrar que el \max de esta función es $\sqrt{\alpha^2 + \beta^2}$. Luego:

$$I_{\max} = \sqrt{\frac{V^2 (X_C - X_L)^2}{Z^4} + \frac{V^2 R^2}{Z^4}} = \frac{V}{Z^2} \cdot \sqrt{(X_C - X_L)^2 + R^2} = \frac{V}{Z^2} \cdot Z = \frac{V}{Z}$$

Z depende de ω , por lo tanto I es máxima cuando Z es mínima,

pero esto $\rightsquigarrow X_C = X_L \Rightarrow \boxed{\omega = \frac{1}{\sqrt{LC}}}$

b)



$$I_o(\omega) = \frac{I_{\max}}{\sqrt{2}}$$

$$I_o(\omega)^2 = \frac{I_{\max}^2}{2} = \frac{V_o^2}{2Z_{\min}}$$

Por lo tanto buscamos ω tal que $Z(\omega)^2 = Z_{\min}^2$

$$Z(\omega) = \sqrt{R^2 + (X_C - X_L)^2} \Rightarrow Z(\omega)^2 = R^2 + (X_C - X_L)^2$$

Z es mínimo cuando $X_C = X_L \Rightarrow Z_{\min} = R$

Entonces:

$$R^2 + (X_C - X_L)^2 = 2R^2$$

$$\frac{1}{\omega_C} - L\omega = \pm R \quad (\alpha)$$

Desarrollo por Taylor a $\frac{1}{\omega} = f(\omega)$ de orden 1 centrado en ω_0 .

$$T_{\omega_0}(\omega) = f(\omega_0) + f'(\omega_0)(\omega - \omega_0) = \frac{1}{\omega_0} - \frac{(\omega - \omega_0)}{\omega_0^2}$$

luego:

$$\pm R \approx \left[\frac{1}{\omega_0} - \frac{\omega - \omega_0}{\omega_0^2} \right] \frac{1}{C} - L\omega$$

$$\text{Uso } \underline{\omega = \omega_0 + \Delta\omega}$$

$$\pm R \approx \frac{1}{4} C - \frac{\Delta \omega}{C \omega_0^2} - (\omega_0 - \Delta \omega) L$$

$$\approx \frac{\sqrt{LC}}{C} - \frac{\Delta \omega \cdot LC}{C} = \frac{1}{\sqrt{LC}} - \Delta \omega L$$

$$\approx \sqrt{\frac{L}{C}} - \Delta \omega \cdot L = \sqrt{\frac{L}{C}} - \Delta \omega \cdot L$$

$$\approx -2L \cdot \Delta \omega \Rightarrow \boxed{\Delta \omega \approx \pm \frac{R}{2L}}$$

C)

$$Q = \frac{\omega_0}{2 \Delta \omega}$$

$$= \frac{\omega_0}{2} \cdot \pm \frac{2L}{R} = \pm \frac{1}{\sqrt{LC}} \cdot \frac{L}{R} = \pm \frac{1}{R} \cdot \sqrt{\frac{L}{C}}$$

2)

a)



$$i = i_C + i_L + i_R = \frac{V_o}{R} + \frac{V_o}{X_L} + \frac{V_o}{X_C}$$

b)

$$i = \frac{V_o}{R} + \frac{V_o}{X_L} + \frac{V_o}{X_C} = \frac{V_o}{R} + \frac{V_o}{\omega L} + V_o \omega C$$

c) Veamos cuando para que ωI es mínima:

$$I = V_o \sqrt{\frac{1}{R^2} + \left(\frac{1}{X_L} - \frac{1}{X_C}\right)^2} \Rightarrow I^2 = V_o^2 \left[\frac{1}{R^2} + \left(\frac{1}{X_L} - \frac{1}{X_C} \right)^2 \right]$$

$$= V_o^2 \left[\frac{1}{R^2} + \frac{1}{(\omega L)^2} - \frac{2C}{L} + (\omega C)^2 \right]$$

$\xrightarrow{\text{sumando}}$

$$\frac{\partial(I^2)}{\partial \omega} = 0 \Rightarrow -\frac{2}{\omega^3 L^2} + 2 \omega C^2 = \frac{2}{\omega^3 L^2}$$

$$\Rightarrow \omega^4 = \frac{1}{C^2 L^2} \Rightarrow \boxed{\omega = \frac{1}{\sqrt{LC}}}$$

(3)

a)

$$I_o = V \cdot \frac{1}{Z} = V_0 \sqrt{\frac{1}{R^2} + \left(\frac{1}{X_L} - \frac{1}{X_C} \right)^2}$$

$$= V_0 \sqrt{\frac{1}{R^2} + \left(\frac{1}{\omega L} - \omega C \right)^2}$$

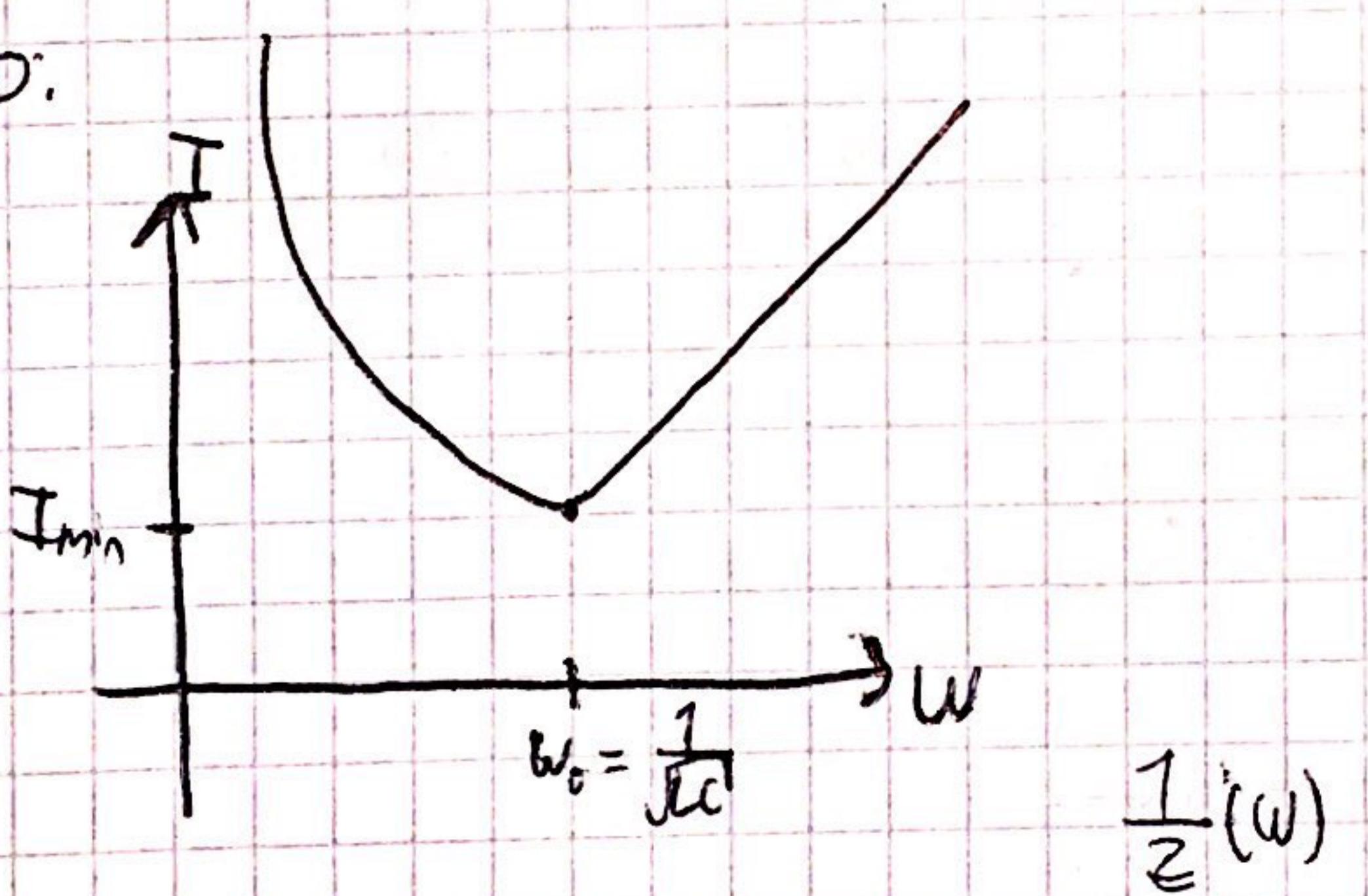
→ Cuand ω es chico crece como $\frac{1}{X}$, cuando ω es grande crece como X

Adem \tilde{s} :

$$\omega \rightarrow \infty \implies \begin{cases} \frac{1}{\omega L} \rightarrow 0 \\ \omega C \rightarrow \infty \end{cases}$$

$$\omega \rightarrow 0 \implies \begin{cases} \frac{1}{\omega L} \rightarrow \infty \\ \omega C \rightarrow 0 \end{cases}$$

Uejos:



b)

I es minimo cuand $\sqrt{\frac{1}{R^2} + \left(\frac{1}{X_L} - \frac{1}{X_C} \right)^2}$ es minimo. ej decir cuand ω

$$X_L = X_C$$

$$\frac{1}{Z}(\omega) = \frac{1}{Z} \min \cdot \frac{1}{\sqrt{2}}$$

$$\left(\frac{1}{Z}(\omega) \right)^2 = \frac{1}{Z} \min^2 \cdot \frac{1}{2}$$

Luego:

$$\frac{1}{R^2} + \left(\frac{1}{\omega_0} - \omega_c\right)^2 = \frac{1}{R^2} \cdot \frac{1}{2}$$

$$\left(\frac{1}{\omega_0} - \omega_c\right)^2 = \frac{1}{2R^2}$$

$$\left(\frac{1}{\omega_0} - \omega_c\right) = \frac{1}{\sqrt{2}R}$$

Usa Taylor: $\frac{1}{w} \approx \frac{1}{w_0} - \frac{w-w_0}{w_0^2}$:

$$\frac{1}{\omega_0 L} - \frac{w-w_0}{w_0^2 L} - \omega_c = \frac{1}{\sqrt{2}R}$$

Usa $w = w_0 + \Delta w$, si que $w_0 = \frac{1}{\sqrt{2}}$

$$\frac{\sqrt{L}}{L} - \frac{\Delta w \cdot L C}{L} - \frac{C}{\sqrt{2}} - \Delta w \cdot C = \frac{1}{\sqrt{2}R}$$

$$\sqrt{\frac{C}{L}} - \Delta w \cdot C - \sqrt{\frac{C}{2}} - \Delta w \cdot C = \frac{1}{\sqrt{2}R}$$

$$-2\Delta w \cdot C = \frac{1}{\sqrt{2}R} \Rightarrow \Delta w = -\frac{1}{CR} \cdot \frac{1}{\sqrt{2}}$$

Luego:

$$Q = \frac{w_0}{2\Delta w} = \frac{1}{2\sqrt{2}C} \cdot \frac{CR\sqrt{2}}{R} = R\sqrt{\frac{C}{2}} \cdot R$$

C) En serie $Q = \frac{1}{R} \sqrt{\frac{L}{C}}$

en paralelo $Q = R\sqrt{LC}$

4

$$V(t) = V_0 \cos(\omega t)$$

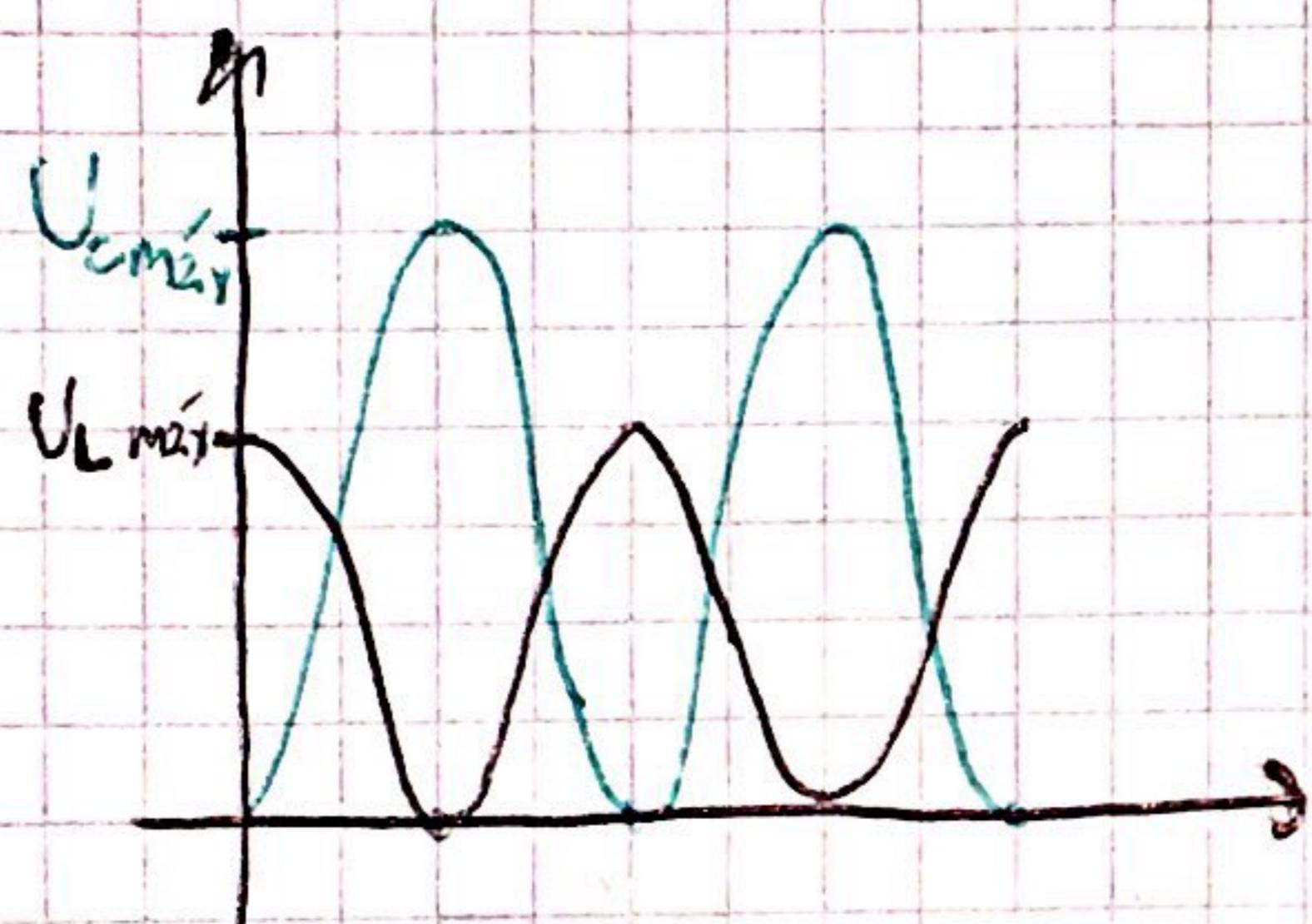
$$i(t) = I_0 \cos(\omega t - \phi)$$

$$q(t) = \int i(t) dt = \frac{I_0}{\omega} \sin(\omega t - \phi)$$

$$U_C = \frac{q(t)}{2C} = \frac{I_0^2}{\omega^2 C} \cdot \sin^2(\omega t - \phi)$$

$$U_L = \frac{1}{2} L \cdot i(t)^2 = \frac{L I_0^2}{2} \cdot \cos^2(\omega t - \phi)$$

Por seno & coseno sabemos que si U_C es max, U_L es minimo & viceversa. Es decir

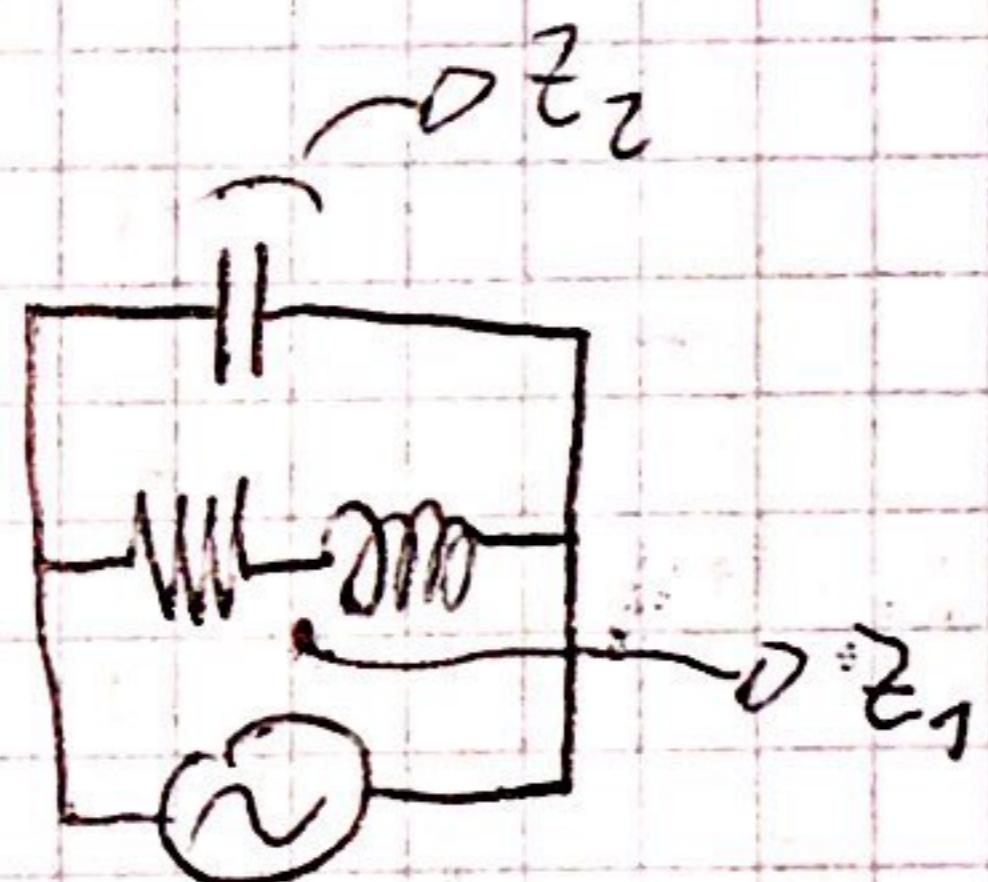


suponiendo $U_C > U_L$

5

$$V(t) = V_0 \cdot e^{j\omega t} \cdot e^{j\varphi_1}$$

$$i(t) = I_0 \cdot e^{j\omega t} \cdot e^{j\varphi_2}$$



$$Z = \frac{V(t)}{i(t)} = \frac{V_0}{I_0} e^{j(\varphi_1 - \varphi_2)}$$

Es de notar que $Z \in \mathbb{R} \Leftrightarrow e^{j(\varphi_1 - \varphi_2)} \in \mathbb{R} \Leftrightarrow \varphi_1 = \varphi_2$
↳ en fase

$$Z_{eq} = \left(\frac{1}{Z_1} + \frac{1}{Z_2} \right)^{-1} = \left(\frac{1}{R+j\omega L} - \frac{j\omega C}{j} \right)^{-1}$$

$$= \left(\frac{R-j\omega L}{R^2+j\omega RL} + j\omega C \right)^{-1} = \left(\frac{R}{R^2+\omega^2 L^2} + j \left(-\frac{\omega L}{R^2+\omega^2 L^2} + \omega C \right) \right)^{-1}$$

Es de notar que $Z_{eq} \in \mathbb{R} \Leftrightarrow -\frac{\omega L}{R^2+\omega^2 L^2} + \omega C = 0$

Luego:

$$\omega_c = \frac{\omega L}{R^2 + \omega^2 L^2}$$

$$C = \frac{L}{R^2 + \omega^2 L^2}$$

$$R^2 + \omega^2 L^2 = \frac{L}{C}$$

$$\omega^2 L^2 = \frac{L}{C} - R^2$$

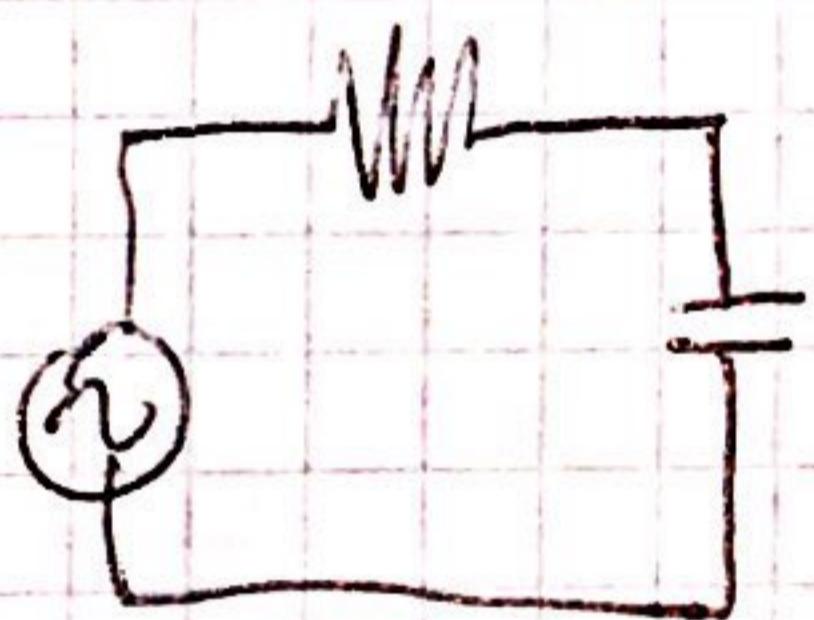
$$\omega = \sqrt{\frac{1}{LC} - \left(\frac{R}{L}\right)^2}$$

6

a)

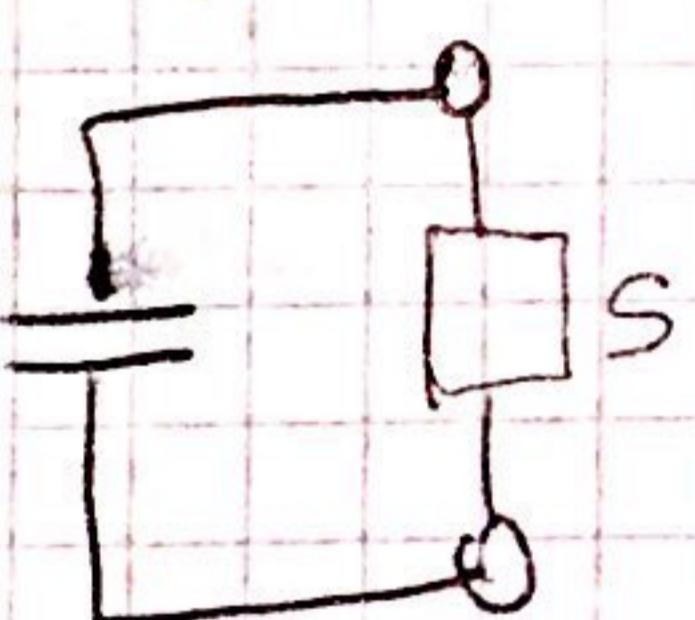
Veamos por separado:

(1º)



$$I_1 = \frac{V_o}{Z} = \frac{V_o}{\sqrt{R^2 + X_L^2}} = \frac{V_o}{\sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2}}$$

(2º)



$$I_2 = \frac{V_C}{Z} = \frac{V_1}{X_C} = \frac{V_1}{\frac{1}{\omega C}} = V_1 \omega C$$

La corriente que pase por (1º) es la misma que pase por el C del (2º), pues por S no pasa corriente, hay un corte. Entonces:

$$I_1 = I_2$$

$$\frac{V_o}{\sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2}} = V_1 \omega C$$

$$\frac{V_o}{V_1} = \omega C \sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2} \Rightarrow \frac{V_o^2}{V_1^2} = (\omega C)^2 \left[R^2 + \left(\frac{1}{\omega C}\right)^2 \right]$$

$$= (\omega CR)^2 + 1 \Rightarrow \frac{V_1^2}{V_0^2} = \frac{1}{(\omega CR)^2 + 1}$$

b)

Cuando $\omega \gg 1 \Rightarrow \frac{V_1^2}{V_0^2} = \frac{1}{(\omega CR)^2}$

Luego si $\omega = 2\omega'$

$$\frac{V_1^2}{V_0^2} = \frac{1}{(2\omega' CR)^2} = \frac{1}{4} \cdot \frac{1}{(\omega' CR)^2}$$

c) $f = 5000 \text{ Hz} , f = \frac{\omega}{2\pi} \Rightarrow \omega = 10000\pi \text{ rad/s}$

Luego:

$$((\omega CR)^2 + 1)^{-1} = 0,01$$

$$\omega^2 C^2 R^2 + 1 = 100$$

$$\omega^2 C^2 R^2 = 99$$

$$C^2 R^2 = \frac{99}{\omega^2}$$

$$(CR)^2 = \frac{99}{10\pi^2 \text{ Hz}^2}$$

$$C.R = \frac{\sqrt{99}}{10^4 \pi \text{ Hz}}$$

\rightarrow elegimos $C = 1 \text{ F}$

$$R = \frac{\sqrt{99}}{10^4 \pi} \Omega$$